```
t = solution.phase.time;
EQsol = solution.phase.state;
control = solution.phase.control;
\$ please remove comment below, if you are using this code, after the code of minimum wind m{arksigma}
% beta = solution.parameter;
beta = 0.2;
options = odeset('RelTol', 1e-10, 'AbsTol', 1e-10);
m = length(t);
period = t(m, 1);
                                                        % selected by GPOPS for given nodes
N = 6;
                                                                    %states
K = 0.045;
H = 1.2*4.19/(2*81.7);
CLpp = spline(t, control(:,1));
mupp = spline(t, control(:, 2));
xpp = spline(t, EQsol(:,1));
ypp = spline(t, EQsol(:,2));
zpp = spline(t, EQsol(:,3));
vpp = spline(t, EQsol(:, 4));
gamapp = spline(t, EQsol(:, 5));
psipp = spline(t, EQsol(:, 6));
CL = @(t) (ppval(CLpp, t));
mu = @(t) (ppval(mupp,t));
x = Q(t) (ppval(xpp,t));
y = 0(t) (ppval(ypp,t));
z = Q(t) (ppval(zpp,t));
v = Q(t) (ppval(vpp,t));
gamma = @(t) (ppval(gamapp,t));
psi = @(t)(ppval(psipp,t));
q = 9.81;
Cd0 = 0.00873;
Pertder = Q(t)[0,0,beta,cos(gamma(t)).*sin(psi(t)),(-1).*sin(gamma(t)).*sin(psi(t)).*v
(t),...
    cos(gamma(t)).*cos(psi(t)).*v(t);0,0,0,cos(gamma(t)).*...
  \cos(psi(t)), (-1).*\cos(psi(t)).*sin(gamma(t)).*v(t), (-1).*...
  \cos(\text{gamma}(t)).*\sin(\text{psi}(t)).*v(t);0,0,0,\sin(\text{gamma}(t)),\cos(\text{gamma}(t)).*v(t)...
  0;0,0,0,(-1).*beta.*cos(gamma(t)).*sin(gamma(t)).*sin(psi(t))+...
  (-2).*H.* (Cd0+CL(t).^2.*K).*v(t), (-1).*q.*cos(gamma(t))+(-1).*beta.*...
  cos(gamma(t)).^2.*sin(psi(t)).*v(t)+beta.*sin(gamma(t)).^2.*sin(psi(t))....
  v(t), (-1).*beta.*cos(gamma(t)).*cos(psi(t)).*sin(gamma(t))...
  .*v(t);0,0,0,CL(t).*H.*cos(mu(t))+g.*cos(gamma(t)).*v(t).^(-2),2.* ...
  beta.*cos(gamma(t)).*sin(gamma(t)).*sin(psi(t))+g.*sin(gamma(t)).* ...
  v(t).^{(-1)}, beta.*cos(psi(t)).*sin(gamma(t)).^2;0,0,0,CL(t).*H.*<math>sec(gamma(t))...
  .*sin(mu(t)),(-1).*beta.*cos(psi(t))+sec(qamma(t)).*tan(qamma(t))...
```

```
.*((-1).*beta.*cos(psi(t)).*sin(gamma(t))+CL(t).*H.*sin(mu(t))...
.*v(t)),beta.*sin(psi(t)).*tan(gamma(t))];

odeLinDS = @(tau,xstate)(Pertder(tau)*(xstate));

initial = eye(N);

FTM = zeros(N);

for i = 1:N
[T,X] = ode45(odeLinDS,0:period/4:period,initial(:,i),options);

FTM(:,i) = X(end,:);
end

[V,D] = eig(FTM);
freq = (1/period).*angle(diag(D))
damp = (1/period).*log(abs(diag(D)))
```