# Probability and Statistics MA-202

## Moments and Percentiles

#### Reference

 Rohatgi, V. K., & Saleh, A. M. E. (2015). An Introduction to Probability and Statistics. John Wiley & Sons.

## Moments

The study of probability distributions of a random variable is essentially the study of some numerical characteristics associated with them. These characteristics, including moments, their functions, and order parameters, are fundamental in the field of mathematical statistics.

## Expectation

Let X be a discrete random variable probability mass function (PMF)

$$P_k = P(X = x_k), \quad k = 1, 2, \dots$$

If

$$\sum_{k=1}^{\infty} |x_k| p_k < \infty,$$

we say that the expected value (or the mean or the mathematical expectation) of X exists and write

$$E[X] = \sum_{k=1}^{\infty} x_k p_k.$$

Note that the series  $\sum_{k=1}^{\infty} x_k p_k$  may converge but the series  $\sum_{k=1}^{\infty} |x_k| p_k$  may not. In that case we say that E[X] does not exist.

If X is of the continuous type and has PDF  $f(\cdot)$ , we say that E[X] exists and equals  $\int x f(x) dx$  provided that

$$\int |x|f(x)dx < \infty.$$

We denote E[X] by  $\mu$ .

**Remark 1.** Note that the condition  $\int |x| f(x) dx < \infty$  must be checked before it can be concluded that EX exists and equals  $\int x f(x) dx$ . The same holds for discrete random variable. Further, the integral  $\int_{-\infty}^{\infty} f(x) dx$  exists, provided that the limit  $\lim_{b\to\infty}^{a\to\infty} \int_{-b}^{a} f(x) dx$  exists. It is quite possible for the limit

$$\lim_{a\to\infty}\int_{-a}^{a}f(x)dx$$

to exist without the existence of  $\int_{-\infty}^{\infty} f(x)dx$ . As an example, consider the following pdf:

$$f(x) = \frac{1}{\pi} \frac{1}{1 + x^2}, -\infty < x < \infty.$$

Clearly,

$$\lim_{a\to\infty} \int_{-a}^{a} \frac{x}{\pi} \frac{1}{1+x^2} dx = 0.$$

However, E[X] does not exist since the integral  $(1/\pi) \int_{-\infty}^{\infty} |x|/(1+x^2) dx$  diverges.

A similar definition is given for the mean of any function g(X) of X. Thus, we have the following

- If X is of discrete type, we say that E[g(X)] exists and equals  $\sum_{k=1}^{\infty} g(x_k)p_k$ , provided that  $\sum_{k=1}^{\infty} |g(x_k)|p_k < \infty$ .
- If X is of continuous type, we say that E[g(X)] exists and equals  $\int g(x)f(x)dx$ , provided that

$$\int |g(x)|f(x)dx < \infty.$$

#### Some results:

<sup>&</sup>lt;sup>1</sup>Borel-measurable function

a) Let  $X(\omega) = I_A(\omega)$ ,  $\omega \in \Omega$ , where

$$I_A(\omega) = \begin{cases} 1, & \omega \in A \\ 0, & \text{otherwise} \end{cases}$$

for some  $A \in \mathcal{F}$ , the sigma-field. Then E[X] = P(A).

- b) E[X] exists if and only if E[|X|] does.
- c) If a and b are constants and X is an RV with  $E[|X|] < \infty$ , then  $E[|aX + b|] < \infty$  and E[aX + b] = aE[X] + b.
- d) If X is bounded, that is, if  $P\{|X| < M\} = 1, 0 < M < \infty$ , then E[X] exists.
- e) If  $P\{X \ge 0\} = 1$  and E[X] exists, then  $E[X] \ge 0$ .

## **Higher Order Moments**

a) Consider the functions  $g(x) = x^n$ , where n is a positive integer. If  $E[X^n]$  exists for some positive integer n, we call  $E[X^n]$  the nth moment of X about the origin. We use the following notation,

$$m_n = E[X^n]$$

b) Consider the functions  $g(x) = x^{\alpha}$ , where  $\alpha$  is a positive real number. If  $E[|X|^{\alpha}]$  exists for some positive real number  $\alpha$ , we call  $E[|X|^{\alpha}]$  the  $\alpha$ th absolute moment of X about the origin. We use the following notation,

$$\beta_{\alpha} = E[|X|^{\alpha}]$$

c) Let k be a positive integer and c be a constant. If  $E[(X-c)^k]$  exists, we call it the moment of order k about the point c. If we take  $c = E[X] = \mu$ , which exists since  $E[|X|] < \infty$ , we call  $E[(X-\mu)^k]$  the central moment of order k or the moment of order k about the mean. We shall write

$$\mu_k = E[(X - \mu)^k].$$

**Remark 2.** If the moment of order t exists for an RV X, moments of order 0 < s < t exist.

**Remark 3.** If we know  $m_1, m_2, ..., m_k$ , we can compute  $\mu_1, \mu_2, ..., \mu_k$ , and conversely. We have

$$\mu_k = E[(X - \mu)^k] = m_k - {k \choose 1} \mu m_{k-1} + {k \choose 2} \mu^2 m_{k-2} - \dots + (-1)^k \mu^k$$

and

$$m_k = E[(X - \mu + \mu)^k] = \mu_k + {k \choose 1} \mu \mu_{k-1} + {k \choose 2} \mu^2 \mu_{k-2} + \dots + \mu^k.$$

## Variance

If  $E[X^2]$  exists, we call  $E(X - \mu)^2$  the variance of X, and we write  $\sigma^2 = Var(X) = E(X - \mu)^2$ . Note that  $\sigma$  is called the standard deviation (SD) of X.

### Important Properties

- a)  $Var(X) \geq 0$
- b)  $\sigma^2 = \mu_2 = E[X^2](E[X])^2$ .
- c) Var(X) = 0 if and only if X is degenerate (a constant random variable).
- d)  $Var(X) < E[(X-c)^2]$  for any  $c \neq E[X]$ .

*Proof.* We have

$$Var(X) = E[(X - \mu)^2] = E[(X - c + c - \mu)^2] = E[(X - c)^2] + (c - \mu)^2 < E[(X - c)^2].$$

Hence the result.  $\Box$ 

e)

$$Var(aX + b) = a^2 Var(X).$$

#### Remark 4. Note the following

• Standardized RV: Let  $E[|X|^2] < \infty$ . Then define Z as follows:

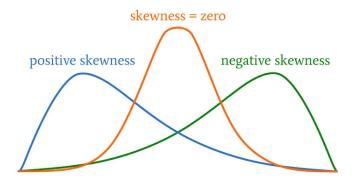
$$Z = \frac{X - E[X]}{\sqrt{Var(X)}} = \frac{X - \mu}{\sigma}$$

We call Z a standardized random variable. Note that it satisfies E[Z] = 0 and Var(Z) = 1.

- Significance of first four moments:
  - Expectation: measures central tendency
  - Variance: measures dispersion (spread)
  - Skewness: symmetry. The coefficient of skewness is given by

$$\alpha_3 = E[Z^3] = E[\frac{(X-\mu)^3}{\sigma^3}] = \frac{E[(X-\mu)^3]}{\sigma^3} = \frac{\mu_3}{\mu_2^{3/2}}.$$

If  $\alpha_3 = 0$ , the distribution is symmetric around mean. If  $\alpha_3 > 0 (< 0)$ , the distribution is asymmetric and positively (negatively) skewed.



- Kurtosis: peakedness (tail behavior). The coefficient of kurtosis is given by

$$\alpha_4 = E[Z^4] = E[\frac{(X-\mu)^4}{\sigma^4}] = \frac{E[(X-\mu)^4]}{\sigma^4} = \frac{\mu_4}{\mu_2^2}.$$

If  $\alpha_4 = 3$ , the distribution is called mesokurtic (corresponds to normal distribution, will discuss in upcoming lectures). If  $\alpha_4 > 3(\alpha_4 < 3)$ , the distribution is called leptokurtic (platykurtic).

• Symmetric random variable: We say that an RV X is symmetric about a point  $\alpha$  if

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$$P(X \ge \alpha + x) = P(X \le \alpha - x), \quad \forall x$$

which is same as

$$F(\alpha - x) = 1 - F(\alpha + x) + P\{X = \alpha + x\}$$

in which case we say that the DF F (or the RV X) is symmetric with  $\alpha$  as the center of symmetry.

## Percentiles

Note that in certain distributions, the mean may not be defined. Moving forward, we'll examine certain parameters known as order parameters, which always exists.

A number x is called a quantile of order p [or (100p)th percentile] for the RV X if it satisfies the following (refer Figure 1)

$$P\{X \le x\} \ge p, \ P\{X \ge x\} \ge 1 - p, \ 0$$

One can write the above conditions as

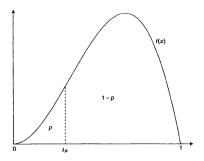


Figure 1: Quantile of order p

$$p \le F(x) \le p + P\{X = x\}.$$

In case of a continuous random variable, we know that  $P\{X = x\} = 0$  for all x, a quantile of order p is a solution of the equation

$$F(x) = p$$

Note that there may be many (even uncountably many) solutions of F(x) = p, each of which is then called a quantile of order p.

**Remark 5.** For  $p = \frac{1}{2}$ , the pth quantile is also called median.