## SVKM's NMIMS

MUKESH PATEL SCHOOL OF TECHNOLOGY MANAGEMENT & ENGINEERING Programme: B. Tech (COMP) Year: III Semester: V Batch: 2013-14 Academic Year: 2014-2015 Subject: **Digital Signal Processing** Marks: Date: 09/06/2015 Time: 10.00 am to 1.00 Durations: 3 (hrs) Re-Examination Instructions: Candidates should read carefully the instructions printed on the question paper and on the cover of the Answer Book, which is provided for their use. Ouestion No. 1 is compulsory. Out of remaining questions, attempt any 4 questions. 3. In all 5 questions to be attempted. 4. All questions carry equal marks. 5. Answer to each new question to be started on a fresh page. Figures in brackets on the right hand side indicate full marks. Attempt any **FOUR** (Five marks each) Q1 5 Compute 4 point DFT using DIT –FFT algorithm for  $x(n) = \{0,1,2,3\}$ a. 5 Differentiate between Continuous time and discrete time signals. b. 5 Compare IIR and FIR filters, C. 5 Explain ROC. State the properties of ROC of Z-Transform d. 5 State and Prove shifting properties of DFT. e. 10 Explain the steps involved in designing a Chebyshev low pass IIR filter.  $O_2$ a. 10 Implement the cascade and Direct form II structure realization of b. y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)20 Find y(n) = x(n) \* h(n); using overlap add method, where; Q3  $X(n) = \{1,2,-1,2,3,-2,-3,-1,1,1,2,-1\}$  and  $y(n) = \{1,2\}$ Compare the result with overlap and save method. 20 Compute eight point DFT of the sequence Q4  $x(n) = 1; 0 \le n \le 7$ 0; otherwise By using DIF-FFT algorithm 20 Design a filter with Q5  $H_d(e^{jw}) = 3 e^{-j3w}$ ;  $-\pi/4 \le w \le \pi/4$ = 0;  $\pi / 4 \le w \le \pi$ Use hamming window with N=7 20 For the given specifications design an analog Butterworth filter: **Q6** 

Determine the inverse z-transform by the partial fraction expansion method:

 $X(z) = \frac{z+2}{2z^2-7z+3}$ , if ROC are (i)|z|>3 (ii) |z|<1/2 (iii) 1/2 <|z|<3

Explain and discuss the following properties of Z transform (i) Initial Value Theorem (II)Convolution in time domain

Explain Causality and Stability for a LTI system.

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for  $0 \le \Omega \le 0.2\pi$ 

 $|H(j\Omega)| \le 0.2$  for  $0.4\pi \le \Omega \le \pi$ 

 $0.9 \le |H(i\Omega)| \le 1$ 

**Q7**