

myTELEOP::teleoperate



```
graph LR; A[myTELEOP::teleoperate] --> B[myTELEOP::initiate_robots]
```

A diagram showing a function call. On the left, a white rectangular box with a black border contains the text 'myTELEOP::teleoperate'. A blue arrow points from the right side of this box to the left side of a second box on the right. The second box is gray with a black border and contains the text 'myTELEOP::initiate_robots'.

myTELEOP::initiate
_robots