QuickC IDE - Rhino [RKI-1550]



User Manual

Robokits India

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Quick C IDE - Rhino Installation

- Make sure you have installed WINAVR before installing Rhino software.
- You can download WINAVR Software for free from http://www.robokits.co.in/downloads/WinAVR-20100110-install.exe
- To install QuickC run setup from CD. You will see following wizard once you run it.







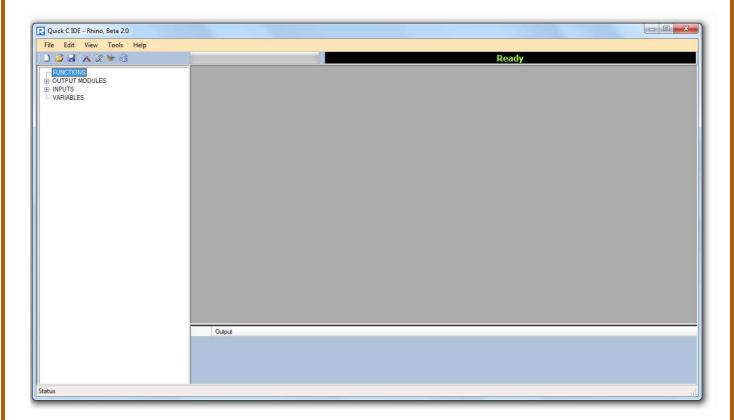
http://www.robokits.co.in
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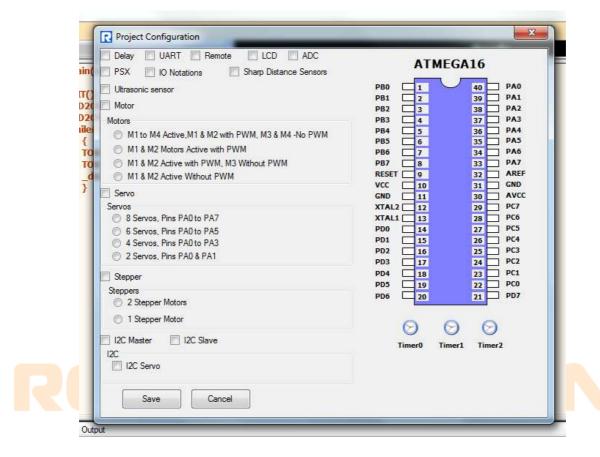


Quick C IDE - Rhino Introduction

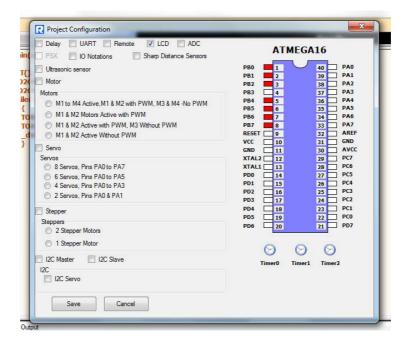
- QuickC IDE Rhino is easy to use software with multiple inbuilt libraries specifically for rhino board.
- The base compiler used for this IDE is winAVR which is a free source compiler.
- All functionality of winAVR software is already built in to this IDE with extra libraries specifically for Rhino board.
- Check QuickC IDE Rhino Library reference file from http://www.robokits.co.in/downloads/quickclibraryref.pdf.
- Run exe file from startup menu or from desktop shortcut.
- · Following screen will be shown up.
- In screen there is a Menu bar on the top.
- Below menu bar you will find shortcuts to few basic functionality just move cursor on top of it to see details.
- On right side of shortcut bar you will find progress bar and status bar which normally shows text "Ready".



- To create a new project click on File->New project or click appropriate shortcut for the same.
- Here you will see Project Configuration wizard as below.



- On left side of the wizard you will find all built in library include options and on right side you will find ATMega16 image with pinouts and used resources.
- You can include whatever libraries you want. You will see ATMega16 pins/timers
 highlighted once you select any library and few libraries will be disabled as you try
 include libraries which shares common resources.
- E.g. check following image where LCD library is used and hence PSX library is disabled.



• Select all libraries you need for a project and click save.

```
Quick C IDE - Rhino, Beta 2.0 - [C:\Users\SIDDHARTH\Desktop\QuickC\QuickC Sample codes\LCD.qcr]
                                                                                                                                                                                                                                                                                     - - X
  File Edit View Tools Help
                                                                                                                                                                                                                                                                                                 _ & ×
 164 8 2 9 6
   FUNCTIONS
DELAYUS(100);
                                                                        int main(void)
      DELAYMS(100);
DELAYMS(2);
LCD_INIT(LCD_DISP_ON_CURSOR_BLINK);
OUTPUT MODULES
                                                                             LED2OFF():
                                                                            LEDZOH();
LEDZOH();
LCD_JIIT(LCD_DISP_ON_CURSOR_BLINK);
LCD_PRINT("ROBOKITS.CO.IN");
LCD_GOTOXY(5,2);
LCD_PRINT("CENTER");
           LEDIONO
          LED10N();

LED10FF();

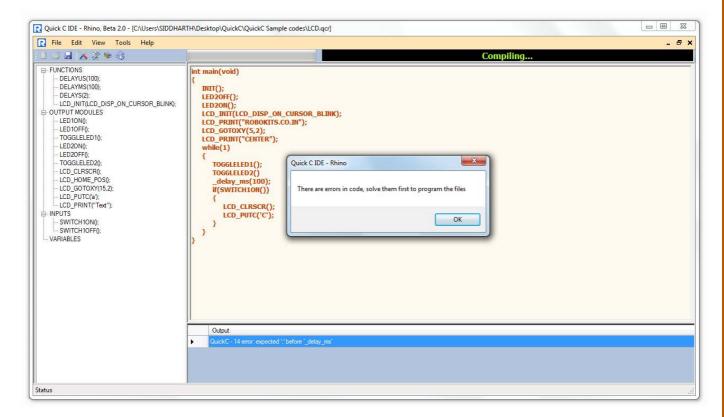
TOGGLELED1();

LED20N();

LED20FF();
                                                                             while(1)
                                                                                 TOGGLELED1();
TOGGLELED2();
           TOGGLELED20:
          -- LCD_CLRSCR():
-- LCD_HOME_POS():
-- LCD_GOTOXY(15.2):
-- LCD_PUTC(a):
                                                                                 _delay_ms(100);
if(SWITCH1ON())
           LCD PRINT("Text"):
                                                                                     LCD_CLRSCR();
LCD_PUTC('C');
       INPUTS
      SWITCH1ON();
SWITCH1OFF();
VARIABLES
                                                                           }
                                                                               Output
```



- You will see above window with all functions available for all libraries you have selected on left side menu.
- You can right code for rhino board in the text file on right side.
- Code format should be just like C language.
- Generally a basic file will always be populated when you create a new project.
- You can simply add functions by clicking them from left menu and they will be added to main code wherever your cursor is present.
- There are a few sample codes available on CD which will help you understand the IDE in proper way.
- Also check application notes for this board from our website <u>www.robokits.co.in</u>.
- Once you are ready with the code just click Tools->Compile(F7) or you can use a shortcut for the same.
- If there are any errors you will see following screen and you will see all errors in bottom output window section with the line number.
- Click on the error and it will move the cursor to the error line or below that.



- Solve all the errors if there are any and your program will be compiled successfully and then click Tools->Program(F4) to program the Rhino board.
- Make sure your board is connected properly to the USB cable and drivers are installed properly. Check http://robokits.co.in/resources/?page_id=113 for driver installation procedure.

```
- - X
Quick C IDE - Rhino, Beta 2.0 - [C:\Users\SIDDHARTH\Desktop\QuickC\QuickC Sample codes\LCD.qcr]
 File Edit View Tools Help
                                                                                                                                                                                                                                                                                                                           ₽×
         3 H X 2 * 3
                                                                                                                                                                                                      Compile Successful - 2240 Bytes
   B-FUNCTIONS
DELAYUS(100);
DELAYS(20);
DELAYS(20);
LICD_INIT(LCD_DISP_ON_CURSOR_BLINK);
DELAYDUM
                                                                             int main(void)
                                                                                   INIT();
LED2OFF();
                                                                                  LED2OH();

LED2ON();

LCD_DHIT(LCD_DISP_ON_CURSOR_BLINK);

LCD_PRINT("ROBOKTIS.CO.IN");

LCD_GOTOXY(5,2);

LCD_PRINT("CENTER");

while(1)
            - LEDIONO:
            - LED10FF0
             TOGGLELED10:
            -TOGGLELED1():
-LED2ON():
-LED2OFF():
-TOGGLELED2():
-LCD_CLRSCR():
-LCD_HOME_POS():
                                                                                       TOGGLELED1();
TOGGLELED2();
_delay_ms(100);
if(SWITCH10N())
            -LCD_GOTOXY(15,2);
            LCD PUTC('a')
      LCD_PUTC(a);
LCD_PRINT("Text");
I-INPUTS
SWITCH10N();
SWITCH10FF();
-VARIABLES
                                                                                            LCD_CLRSCR();
LCD_PUTC('C');
                                                                                        Output
```

```
_ 0 X
Quick C IDE - Rhino, Beta 2.0 - [C:\Users\SIDDHARTH\Desktop\QuickC\QuickC Sample codes\LCD.qcr]
 File Edit View Tools Help
                                                                                                                                                                                                                                                                                                                                . 5 ×
          B 🔒 🔥 🛠 🏶 😚
                                                                                                                                                                                                                        Programming 67%
    -- FUNCTIONS
--- DELAYUS(100);
--- DELAYMS(100);
                                                                                int main(void)
                                                                                   BUT();
LED2OFF();
LED2ON();
LED2ON();
LCD_BUT(LCD_DISP_ON_CURSOR_BLBIK);
LCD_PRINT("ROBOKTIS.CO.IN");
LCD_GOTOXY(5,2);
LCD_PRINT("CENTER");
while(1)
             DELAYS(2):
       LCD_INIT(LCD_DISP_ON_CURSOR_BLINK);
OUTPUT MODULES
            JIPOT MODULES

LED10N();

LED10FF();

TOGGLELED1();

LED20N();

LED20FF();
                                                                                     while(1)
                                                                                         TOGGLELED1();
TOGGLELED2();
_delay_ms(100);
if(SWITCH10N())
             TOGGLELED20
             LCD CLRSCR():
       LCD_CLRSCH();
LCD_HOME_POS();
LCD_GOTOXY(15.2);
LCD_PUTC(a);
LCD_PRINT("Text");
INPUTS
SWITCH1ON();
SWITCH1OFF();
VARIBAILES
                                                                                               LCD_CLRSCR();
                                                                                              LCD_PUTC('C');
       - VARIABLES
 Status
```



- If everything is fine the board will be programmed and you will get a "Program Complete" message on the status bar.
- Similarly you can write all kind of codes in C very quickly with all functions built in and it will be a very simple way to start with the Rhino robot control board.
- The IDE is made for simple and even advance codes and you can make the board work anyway you want it to be.
- Refer <u>C:\WinAVR-20100110\doc\avr-libc\avr-libc-user-manual\modules.html</u> for details of built in libraries of WINAVR. Also this libraries can be used without any extra efforts with this IDE.





Service and Support

Service and support for this product are available from Robokits India. The Robokits Web site (http://www.robokits.co.in) maintains current contact information for all Robokits products.

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