

# Harshil Bhatt

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## EDUCATION

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### Manipal Institute of Technology

*BTech in Electronics and Communication Engineering*

Minor in Embedded Systems

**Manipal, KA**

*Expected Graduation: May 2023*

## EXPERIENCE

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### BeagleBoard, Google Summer of Code

*Developer*

**Remote, KA**

*May 2022 - Present*

- Develop Linux kernel drivers for mikrobus boards
- Enhance native POSIX target on Zephyr for Greybus message handling
- Improve logging and loopback test modules

### Nokia Bell Labs

*Intern*

**Remote, KA**

*Feb 2022 - Aug 2022*

- Built applications for autonomous robots
- Added middleware for non-ROS robots to utilise ROS algorithms

### ReTiSense

*Embedded Systems Engineer*

**Bengaluru, KA**

*Aug 2021 - Oct 2021*

- Worked with BLE 5.0
- Added support for various peripherals to firmware
- Power management of nRF52 microcontrollers
- Optimised memory management and data compression onboard nRF52

### Mars Rover Manipal

*Senior Research Engineer*

**Manipal, KA**

*May 2020 - Aug 2022*

- Published a paper on wireless sensor networks at a flagship conference organized by IEEE.
- Developed system drivers for sensors and actuators for ROS1/2 and freeRTOS
- Guided a team of juniors towards research and academic publications

### Sensegrass

*Firmware Engineer Intern*

**Bengaluru, KA**

*Jan 2021 - Mar 2021*

- Diagnosed feasibility of new products
- Prepared BOM for upcoming products
- Analyzed working of existing products and devised improvements

## PUBLICATIONS

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### Wireless Sensor Networks for Search and Rescue Management in Floods

*IEEE-CONECCT*

- Proposed novel routing algorithm with over twice better throughput in sensor networks
- Designed cost-effective sensor node capable of human detection
- Developed scalable solution able to support 512 nodes over  $7.5km^2$

### Increasing Physical Layer Security through Hyperchaos in VLC Systems

*Peer-Review*

- Proposed a system utilising a 4D Henon Map to generate hyperchaos in the transmitter.
- Designed a sliding mode controller for chaos synchronisation between the transmitter and receiver.
- Increased physical layer security in VLC systems to prevent eavesdropping.
- Achieved satisfactory BER and throughput using a single channel regular LED

## HONORS & AWARDS

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### IEEE ComSoc Bangalore "Protsahan"

Dec 2021

#### IEEE

The Bangalore ComSoc chapter, Protsahan drive, was launched to recognize contributions in the Communication Sector by granting awards to any paper published / Tutorial offered in recognized conference/journals (during Jan 2020 - Sep 2021) by IEEE student member/member/non-member (as the first author to be IEEE member, non-Member).

### International Rover Design Challenge

Feb 2021

#### Mars Society South Asia

Finished 3rd worldwide at IRDC 2021. The International Rover Design Challenge is a competition for university students which challenges to design Mars rovers which shall be fully equipped and mission ready for Operation on Mars.

## ONGOING RESEARCH

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### Energy Balancing in Swarm Robots using Wireless Power Transmission

Mar 2021 - Present

- Built custom wireless charging circuit based on magnetic induction
- Programmed low level drivers of sensors and actuators for ROS2
- Devised novel algorithm for peer-to-peer charging
- Designed navigation and path planning algorithm for swarm control

### Improving Security in Wireless Body Area Networks

Oct 2021 - Present

- Formulated novel algorithm for encrypting sensor data
- Designed a scalable sensor network
- Optimised the sensor nodes for low power

### Adaptive Routing Algorithm for Underwater Wireless Sensor Networks

Nov 2021 - Present

- Proposed novel routing algorithm with improved BER and throughput
- Develop algorithm for acoustic communications
- Optimise node distribution based on tetrahedral deployment

## PAST PROJECTS

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### 7 Degree of Freedom Robotic Arm

May 2020 - Oct 2020

- Built motor control interface
- Designed end-effector position control system
- Developed firmware for PIC18 and ATtiny

### Self-Balancing Inverted Pendulum

Apr 2020 - May 2020

- Designed control system using Simulink
- Simulated in Gazebo with ROS1 interface
- Implemented controller on STM32

## TECHNICAL SKILLS

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- Programming Languages: C, C++, Python, Rust, Verilog, ARM Assembly
- Protocols/Interfaces: UART/USART, SPI, I<sup>2</sup>C, CAN, MQTT, FreeRTOS, Zephyr
- Software: MATLAB, Simulink, Altium Designer, EagleCAD, LabVIEW, Proteus Design Suite, ROS, Gazebo

## EXTRA CURRICULARS

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### Manipal Open Source Society

#### Technical Moderator

Oct 2021 - Aug 2022

- Worked with other members to incubate projects, contribute to new projects.
- Coordinate any and all events held by the society.
- Grew the community to over 60 members.

**Research Society Manipal***Robotics division*

- Worked with multi-agent systems and swarm robotics

*Sep 2021 - Aug 2022***RedX Manipal***Volunteer*

- Conducted drives for at-risk population

*Sep 2019 - Aug 2022*