# Harshil Bhatt

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• harshilbhatt2001

**3** 831-030-0564

# **EDUCATION**

### Manipal Institute of Technology

Manipal, KA

BTech in Electronics and Communication Engineering

Expected Graduation: May 2023

Minor in Embedded Systems

# **EXPERIENCE**

#### BeagleBoard, Google Summer of Code

Remote, KA

Developer

May 2022 - Present

- Develop Linux kernel drivers for mikrobus boards
- o Enhance native POSIX target on Zephyr for Greybus message handling
- Improve logging and loopback test modules

Nokia Bell Labs Remote, KA

Feb 2022 - Present Intern

- Built applications for autonomous robots
- Added middleware for non-ROS robots to utilise ROS algorithms

ReTiSense Bengaluru, KA

Embedded Systems Engineer

Aug 2021 - Oct 2021

- Worked with BLE 5.0
- Added support for various peripherals to firmware
- Power management of nRF52 microcontrollers
- o Optimised memory management and data compression onboard nRF52

#### Mars Rover Manipal

Manipal, KA

Senior Research Engineer

May 2020 - Present

- o Published a paper on wireless sensor networks at a flagship conference organized by IEEE.
- o Developed system drivers for sensors and actuators for ROS1/2 and freeRTOS
- Guided a team of juniors towards research and academic publications

Sensegrass Bengaluru, KA

Firmware Engineer Intern

Jan 2021 - Mar 2021

- Diagnosed feasibility of new products
- Prepared BOM for upcoming products
- Analyzed working of existing products and devised improvements

# **PUBLICATIONS**

#### Wireless Sensor Networks for Search and Rescue Management in Floods

IEEE-CONECCT

- o Proposed novel routing algorithm with over twice better throughput in sensor networks
- Designed cost-effective sensor node capable of human detection
- Developed scalable solution able to support 512 nodes over  $7.5km^2$

# Increasing Physical Layer Security through Hyperchaos in VLC Systems

Peer-Review

- o Proposed a system utilising a 4D Henon Map to generate hyperchaos in the transmitter.
- o Designed a sliding mode controller for chaos synchronisation between the transmitter and receiver.
- o Increased physical layer security in VLC systems to prevent eavesdropping.
- o Achieved satisfactory BER and throughput using a single channel regular LED

# **HONORS & AWARDS**

# IEEE ComSoc Bangalore "Protsahan"

Dec 2021

IEEE

The Bangalore ComSoc chapter, Protsahan drive, was launched to recognize contributions in the Communication Sector by granting awards to any paper published / Tutorial offered in recognized conference/journals (during Jan 2020 - Sep 2021) by IEEE student member/member/non-member (as the first author to be IEEE member, non-Member).

#### **International Rover Design Challenge**

Feb 2021

Mars Society South Asia

Finished 3rd worldwide at IRDC 2021. The International Rover Design Challenge is a competition for university students which challenges to design Mars rovers which shall be fully equipped and mission ready for Operation on Mars.

### ONGOING RESEARCH

#### Energy Balancing in Swarm Robots using Wireless Power Transmission

Mar 2021 - Present

- o Built custom wireless charging circuit based on magnetic induction
- o Programmed low level drivers of sensors and actuators for ROS2
- Devised novel algorithm for peer-to-peer charging
- Designed navigation and path planning algorithm for swarm control

#### Improving Security in Wireless Body Area Networks

Oct 2021 - Present

- Formulated novel algorithm for encrypting sensor data
- Designed a scalable sensor network
- Optimised the sensor nodes for low power

### Adaptive Routing Algorithm for Underwater Wireless Sensor Networks

Nov 2021 - Present

- o Proposed novel routing algorithm with improved BER and throughput
- Develop algorithm for acoustic communications
- o Optimise node distribution based on tetrahedral deployment

### PAST PROJECTS

#### 7 Degree of Freedom Robotic Arm

May 2020 - Oct 2020

- Built motor control interface
- Designed end-effector position control system
- Developed firmware for PIC18 and ATtiny

# Self-Balancing Inverted Pendulum

Apr 2020 - May 2020

- o Designed control system using Simulink
- o Simulated in Gazebo with ROS1 interface
- Implemented controller on STM32

# TECHNICAL SKILLS

- o Programming Languages: C, C++, Python, Rust, Verilog, ARM Assembly
- o Protocols/Interfaces: UART/USART, SPI, I<sup>2</sup>C, CAN, MQTT, FreeRTOS, Zephyr
- o Software: MATLAB, Simulink, Altium Designer, EagleCAD, LabVIEW, Proteus Design Suite, ROS, Gazebo

# EXTRA CURRICULARS

#### **Manipal Open Source Society**

 $Technical\ Moderator$ 

Oct 2021 - Present

- Worked with other members to incubate projects, contribute to new projects.
- Coordinate any and all events held by the society.
- Grew the community to over 60 members.

# Research Society Manipal

Robotics division Sep 2021 - Present

 $\circ$  Worked with multi-agent systems and swarm robotics

# RedX Manipal

Volunteer Sep 2019 - Present

o Conducted drives for at-risk population