

HW12

Problems due Friday November 16 (**LAST DAY** before midterm)

12.1 CONCEPT: Characterizing ODEs (3 pts)

For each of the following three ODEs ...

- characterize its **order** (e.g. 1st-order, 2nd-order, etc.),
- characterize it as an **IVP** (Initial Value Problem) or **BVP** (Boundary Value Problem),
- write the ODE in **standard** form.

$$(A) \quad x + \frac{dy}{dx} \left(\frac{d^3 y}{dx^3} + 1 \right) = \frac{d^2 y}{dx^2}, \quad y(1) = 1, \quad y'(2) = 2, \quad y''(1) = 3$$

$$(B) \quad t + y \sqrt{\frac{dt}{dy}} = t \log \left(\frac{d^2 t}{dy^2} \right), \quad t(2) = 1, \quad t'(1) = 2$$

$$(C) \quad 1 + \frac{1}{y} \frac{d(y^2 t)}{dt} = t \left(\frac{dy}{dt} \right), \quad y(5) = 2$$

Modeling Factory Production (IVP)

Let's evaluate the productivity of a factory by predicting the number of machines operating (**Y**) over the course of two months (60 days). On the first day (**t₀ = 0**) you observe **Y₀ = 20** machines are operating.

Then Y will change over time (**dY/dt**, for **t** in days) according to the following 3 factors:

- The owner hopes to buy 3 new machines each day (**dY/dt = +3**),
- The machines have a natural failure rate (**dY/dt = -0.1 Y**),
- External fluctuating factors affecting machine purchasing and operation (**dY/dt = sin[2πt/25]**).



Combining all these factors leads to the first-order IVP $\frac{dY}{dt} = 3 - 0.1Y + \sin\left(\frac{2\pi t}{45}\right)$ with I.C. $Y(0) = 20$

The goal of your analysis to make a plot of number of machines working each day **Y(t)**, and to specifically predict the number of machines working at the end of 2 months (**t_{end} = 60** days).

Let's tackle this two ways on the next page:

- By-hand* comparing the Euler, Modified Euler (Heun's), and Midpoint method,
- Writing your own **MATLAB** code for just the Modified Euler method.

HW12

Problems due Friday November 16 (**LAST DAY** before midterm)

12.2 APPLICATION: Solving 1st-order IVP, “By-Hand” (14 pts)

- a) Solve the production model at right using the **EULER** method over the range $t = [0, 20]$ days with step size $\Delta t = 10$ days (i.e. calculate Y_i at $t_0 = 0$, $t_1 = 10$, and $t_2 = 20$).

$$\frac{dY}{dt} = 3 - 0.1Y + \sin\left(\frac{2\pi t}{45}\right)$$
$$Y(0) = 20$$

Show all your work in table form, like we did in class and seen below, showing how you calculate each t_{i+1} , Y_{i+1} , and “slope” that you use to get each point, with all values accurate to **three** decimals.

i	t_i	Y_i (known)	$Slope_i = \dots$	t_{i+1}	$Y_{i+1} = \dots$
0	0	$Y_0 = 20$?	?	$Y_1 = \dots$
1	10	$Y_1 = \dots$?	?	$Y_2 = \dots$
2	20	$Y_2 = \dots$	DONE	DONE	DONE

- b) Repeat the work from (a), this time using the **MODIFIED EULER** (Heun’s) method to calculate Y_1 , Y_2 .
- c) Repeat the work from (a), this time using **MIDPOINT** method to calculate Y_1 , Y_2 .
- d) Given the exact solution for $Y(10) = 30.5795$, and $Y(20) = 34.8952$, calculate:
- the *global* error (to three decimals) in Y_2 for *just* the Euler method from part (a).
 - the *local* error for *just* the single step going from t_1 to t_2 for *just* the Euler method from part (a).

12.3 CODING: Solving the productivity model with your own Modified Euler method **IN MATLAB** (7 pts)

Go look in the Carmen HW12 folder. You have been given four files: HW12.m, ModEuler.m, f.m and Y_exact.m, each described below:

f.m outputs the right-hand side of the given factory production IVP in standard form, $dY/dt = f(t, Y)$:

```
function dYdt = f(t, Y)
    dYdt = 3 - 0.1*Y + sin(2*pi*t/45);
```

Do **not** change anything in this function. Notice that this function ...

- is already “vectorized” (can accept vector inputs t and Y , and returns a vector output $dYdt$),
- is a general function of t and Y ,
- the order of the input variables has the *independent* variable (t) first, and *dependent* variable (Y) second. This is really crucial later, when we’re using MATLAB’s built-in ODE45 solver.

ModEuler.m is the function you must complete. It currently only has the function declaration line:

```
function [t, Y] = ModEuler(t0, tend, Y0, dt)
% Finish the code here to calculate the two output vectors
% t=[t0 t1 ... tend], Y=[Y0 Y1 ... ] given t0, tend, Y0 and dt.
```

Y_exact.m is also given to provide the exact, analytic solution to $Y(t)$ to compare to the ModEuler method later. It’s really long – don’t worry about how I got the analytic solution from your “real math” differential equations course. Just assume it’s correct. ;)

HW12

Problems due Friday November 16 (**LAST DAY** before midterm)

12.3 continued ...

HW12.m is the master script. Its job is to solve for the number of operational machines $Y(t)$ with initial number $Y_0 = 20$ over the time range $t = [0, 60]$ days using three different time steps: $\Delta t = 30$ days, 3 days, and 0.3 days. It does this by calling your new function `ModEuler.m` three times like so:

```
[t1,Y1]= ModEuler(t0, tend, Y0, 30);    % Δt = 30 d
[t2,Y2]= ModEuler(t0, tend, Y0, 3);     % Δt = 3 d
[t3,Y3]= ModEuler(t0, tend, Y0, 0.3);   % Δt = 0.3 d
```

It also then calculates the exact (analytic) solutions and the error (difference between exact and computational solutions) over the three different time sets:

```
Y1x = Y_exact(t1);    Err1 = abs(Y1x-Y1);
Y2x = Y_exact(t2);    Err2 = abs(Y2x-Y2);
Y3x = Y_exact(t3);    Err3 = abs(Y3x-Y3);
```

Finally, **HW12.m** makes and saves two plots so you can compare the results for different Δt :

- Plot **HW12a** compares the three different computational (t_i, Y_i) with the exact $Y(t)$.
- Plot **HW12b** compares the computational errors in Y_i for the three choices of Δt .

Much of the work has already been done for you. But I still need you to ...

- a) Complete the `ModEuler.m` function so that it uses the Modified Euler method to solve the IVP $dY/dt = f(t,Y)$, where $f(t,Y)$ comes from the “slope” function `f.m` I gave you.

Make sure `ModEuler.m` works with general input variables for `t0` (initial t), `tend` (final t), `Y0` (initial size), and `dt` (time step Δt), like its declaration line shows. The function must output vectors for both the time (t) and the operating machines (Y) at each time-step from `t0` to `tend` inclusive.

- b) Fill in the couple of missing variable names appropriately (currently `xxx`) in **HW12.m** so that it works again. Also replace the plot `titles` with more appropriate text for your plot. Other than that, don't mess much with **HW12.m** – it's already designed to work and make the plot for you just fine. If it gives you any problems, it's because you're making compatibility errors in the `ModEuler.m` function you're writing.
- c) Run the **HW12.m** script to generate the two plots. They *should* show your Euler-method solutions more closely approaching the exact solution (in red) as Δt gets smaller.

SUBMIT EVERYTHING FROM HW12.3 ONLINE:

- Both your plots ([HW12a.pdf](#), [HW12b.pdf](#)) in .pdf form,
- Your functions [ModEuler.m](#) and [HW12.m](#). (But don't submit your `f.m` or `Y_exact.m`, since you're not modifying them from what I already gave you).
- Your answers to the **three questions** below in the comment box:
 - i. Report the predicted number of operating machines Y at $t = 60$ days for each of the three simulations.
 - ii. Report the **global error** at $t = 21$ days for just the last two simulations (using $\Delta t = 3$ and 0.3 days).
 - iii. How does the change between the two errors in (ii) compare with our analytical expectation based on the error “order” for the Modified Euler method? *Hint*: your Δt went down by a factor of 10, from 3 to 0.3 days – by what factor did your observed error go down??)