

Education

- M. S. Computer Science, Stony Brook University, New York [2019-Dec 20]
- *Computer Vision, Big Data, Distributed Systems, Visualization, Analysis of Algorithms, Artificial Intelligence*
- B. Tech. Computer Science and Engineering, Indian Institute of Technology, Patna, India, CPI: 8.84/10 [2013-17]
- *Deep Learning, Network Science, Algorithms, Data Structures, Object-oriented Programming, Operating Systems*

Skills and Technologies

Java(*Spring, Hibernate*); Python(*PyTorch, Tensorflow, Opencv, Django, Flask*); MATLAB; MySQL; Go; Spark; C; C++; JavaScript(*D3.js, Query, Chart*); HTML; CSS; RaspberryPi; Arduino; Latex; Linux

Work Experience

Engineer I **Samsung R&D | SRI-Delhi** 2017-2019

- **OPERATING TIME PERFORMANCE for Samsung VD** :- development of software to analyze OS performances, reducing work load from weeks to days, using **deep-learning and Computer Vision** [Python (Tensorflow, OpenCV)]
- **PRODUCT INTELLIGENCE** :- generated statistics and analytics influencing proactive product decisions; monitoring timelines of various products via **Machine Learning models** . [Python(lightgbm, sklearn), Java-Spring, Splunk]
- Setup of **MEMORY and PERFORMANCE TASK FORCE** for profiling Tizen OS ensuring stable software. [C++, Python, Jenkins]

Research Internship **Nanyang Technological University, Singapore** Summer 2016

- Worked at HESL Lab under Prof Vinod Prasad, deployed to propose and verify **authentication using EEG bio metrics** . Collected and preprocessed EEG responses[using EMOTIV Epoc headset] on audio and visual stimuli.[C#, MATLAB]
- Implemented the authentication system, achieving 80% accuracy. Published at IECBES 2016. <https://bit.ly/2m2WKII>

- **Graduate Teaching Assistant**, Data Structures (CSE214) Fall '19, Benevolent Computing (ISE339) Spring '20 , **Stony Brook University**, New York

- **Research Internship, CNeRG lab**, under Prof Niloy Ganguly, **IIT Kharagpur**, India [Summer 2015]

Conference Publications

- **Online Electroencephalogram (EEG) based biometric authentication using visual and audio stimuli, IECBES 2016**
- Road Congestion Sensing via Crowdsourcing and MapReduce, IPSN 2015. <https://bit.ly/2kQQP9B>

Projects

Robust UAV Object Tracking (2020 - Present) *OpenCV, PyTorch*

- Collaborated to largest Single Object Tracking Dataset, **LaSOT** (<https://bit.ly/2S0z6du>). This new dataset is already being used as a standard for benchmarking.
- As a part of Masters project, to train an online **tracking algorithm** for tracking objects with UAV using Correlational Filters/SiamNet,

Sharded Replicated Key-Value Store (2019) *Go*

- Implemented a key value store replicated across multiple machines with **RAFT consensus** for fault tolerance.
- The system also used sharding and snapshots for performance. Done as a part of in-course project in Distributed Systems.

Copter QL: The Q-Learning Helicopter Game (2019) *Deep-learning[Tensorflow], Pygame*

- Aimed to make agent learn to play copter using **deep reinforcement learning** techniques. Implemented a Deep QNetwork (**DQN**) for learning Q-values for approximate state-action pairs.
- Agent balanced exploration and exploitation using **experience replay and update delay** , achieving the best strategy to score after 3000 attempts at gameplay. <https://bit.ly/2m1FWIo>

Adaptive Object Tracking (2016-17) *Python, OpenCV*

- Implemented a pedestrian tracker using **HoG and condensation algorithm** as bachelors final year project. [**Top 6 out of 55 students**].
- Accuracy around 90% on PET 2009 dataset. The system can also track a person through various cameras in surveillance system.

Centrality Metrics in Dynamic Networks (2017) *Python, Bash*

- A new hybrid centrality metric is proposed, consisting of **PageRank**, average importance over time & aging factor.
- Citations network is used as the dataset. Metrics obtained corresponding to important publications in the course of time were obtained as desirable.

Lecture Assistant (2016) *Python[Flask, OpenCV], RPi, Arduino*

- Developed an IoT based device to track the lecturer, and record a video lecture.
- A camera set over a servo motor which was controlled via a Raspberry Pi (or Arduino). The camera rotates towards the moving lecturer and streams its frames over the server.
- The server has a webpage where students can discuss doubts and take quizzes related to the topic. <https://bit.ly/2IJ3ZWK>

Other Experiences And Achievements

- **Google Kickstart '19 Round H [Rank 405]; Competition Expert @ Kaggle** [Currently ranked - 3547]
- **Bronze medal** in IoT Innovation at Inter-IIT tech meet (2016). Runner-up in **IEEE ISED Grand Challenge** December 2016.