Warsaw University of Technology Faculty of Mechatronics

Microcontrollers

Lab 04

Report

Analog to Digital Converters

Made by:

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1) Theory

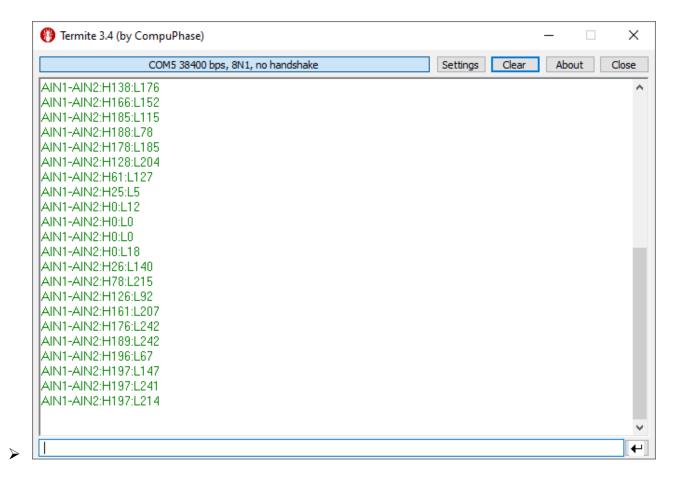
I this course of this exercise, we must create an application to analyze different inputs and outputs on ADuC834 by pressing specific buttons, using Keil uVision5 software.

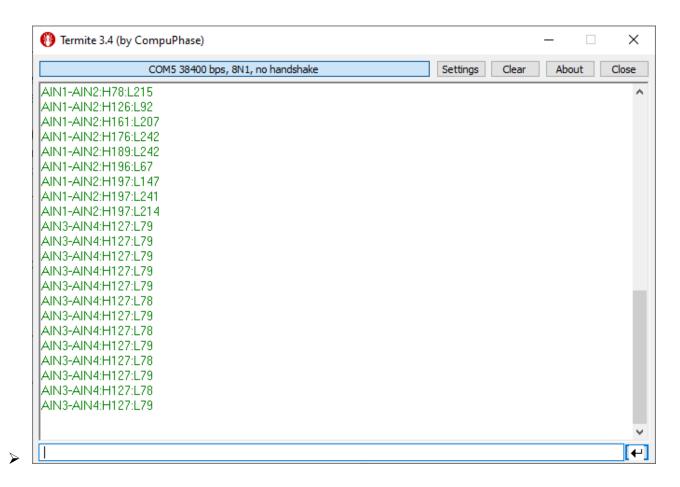
2) Result

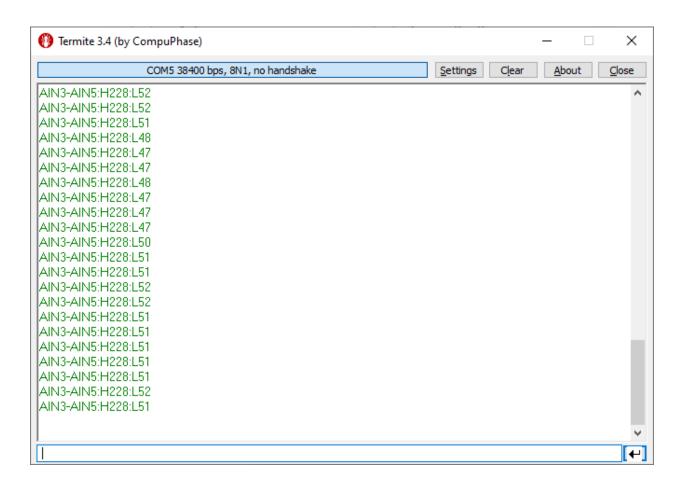
- Screenshots showing the results obtained on the computer's terminal with different signal sources, with discussion:
 - to what extent the values changed:

We observe that

- (1) While the knob is turned clockwise, the values increases and vice-versa; the values changes from H:0 L:0 to H:189 L:242; the values for High and Low parts do not change linearly with respect to each other, but rather there is a lag in both of the values. Overall the values increase linearly.
- (2) While the button is pressed, the value changes from H:0 L:0 to H:127 L:79. The Increase is more like 1 to 0 rather than linearly increasing.
- (3) While the button is pressed and the thermistor is being manipulated, the value changes from H:228 L:47 to H:228 L:52. The change is the Low count is linear.







3) Program code

```
/* a header with definitions of symbols for ADuC834 */
#include <aduc834.h>
#include <stdio.h>
/* optional: declaration of unsigned types of one and two bytes */
typedef unsigned char uint8_t;
typedef unsigned int uint16_t;

char buf[40];

void uart_transmit(char c)
{
```

```
SBUF = c;
    while(TI == 0);
    TI = 0;
}
void uart_string(char *str)
    while (*str!= 0)
        uart_transmit(*str);
         str++;
    }
}
int main(void)
    SM0 = 0;
    SM1 = 1;
    REN = 1;
    T3CON = 0x80;
    T3FD = 0x12;
    ADCMODE = (1 < < 5)|(1 < < 4)|(1 < < 1)|(1 < < 0);
    while (1)
```

```
if (!(P1&(1<<1)))
    {
         ADCOCON = (1 < < 2) |(1 < < 1)|(1 < < 0)|(1 < < 3)|(1 < < 6);
         while (RDY0 != 1){}
         sprintf(buf, "AIN1-AIN2:H%bu:L%bu\n",ADC0H,ADC0L);
         uart_string(buf);
         RDY0 = 0;
    }
    if (!(P2&(1<<0)))
         ADC1CON = (1 < < 6)|(1 < < 4)|(1 < < 5);
         while (RDY1!= 1){}
         sprintf(buf, "AIN3-AIN4:H\%bu:L\%bu\n", ADC1H, ADC1L);\\
         uart_string(buf);
         RDY1 = 0;
    }
    if (!(P3&(1<<5)))
         ADC1CON = (1 < < 6)|(0 < < 4)|(0 < < 5);
         while (RDY1!= 1){}
         sprintf(buf, "AIN3-AIN5:H%bu:L%bu\n",ADC1H,ADC1L);
         uart_string(buf);
         RDY1 = 0;
    }
}
```

```
return 0;
```