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**Problem 0**

<b>Points:</b>
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**Acknowledgements**

- (a) I did not work in a group.
- (b) I did not consult without anyone my group members.
- (c) I did not consult any non-class materials.

**Problem 1****Points:****DFS variations**

- (a) **Algorithm:** It is given that the car can only hold enough gas to cover  $L$  miles while any stretch of highway ( $l_e$ )  $e \in E$  may or may not be greater than  $L$ . Therefore, initially we can simply remove edges ( $e$ ) of a greater value. Now, the next step is to see if the city  $t$  is still reachable from  $s$ . To check that, we will be using Breadth First Search (*BFS*) algorithm. So if vertex  $t$  is reachable, then the path is feasible otherwise, it is not feasible.

**Proof:** In order to show correctness of the algorithm, we would have to show two things:

- (1) If a solution exists, the algorithm will find it
- (2) If the algorithm finds a solution, then it's a valid solution

**Runtime:** Running *BFS* will take  $O(|V| + |E|)$ .

- (b) Here, we will modify Dijkstra's algorithm to find paths that minimize the maximum weight of any edge on the path (instead of the path length).

Here, we take minimum of  $\max(\text{visited}, \text{not visited adjacent})$ .

**Algorithm:**

ModifiedDijkstra( $G = (V, E)$ )

for all  $u \in V$  do

$\text{dist}(u) = \infty$

$\text{prev}(u) = \text{nil}$

end

$\text{dist}(s) = 0$

Let  $H$  be a priority queue constructed with all nodes in  $V$  using  $\text{dist}$  as the key

while  $H$  is not empty do

$u = \text{deleteMin}(H)$

for all edges  $(u, v) \in E$  do

if  $\text{dist}(v) > \max(\text{dist}(u), l(u, v))$

$\text{dist}(v) = \max(\text{dist}(u), l(u, v))$

$\text{prev}(v) = u$

$\text{decreaseKey}(H, v)$

end

end

end

end

**Runtime:** Time complexity is same as Dijkstra's algorithm i.e.  $O((|V| + |E|)\log|E|)$ .

**Problem 2**

<b>Points:</b>
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**Shortest bitonic paths**

(a)

(b)

**Problem 3**

<b>Points:</b>
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**Dijkstra's on negative**

(a)

(b)