

# Synthesis of Digital Systems

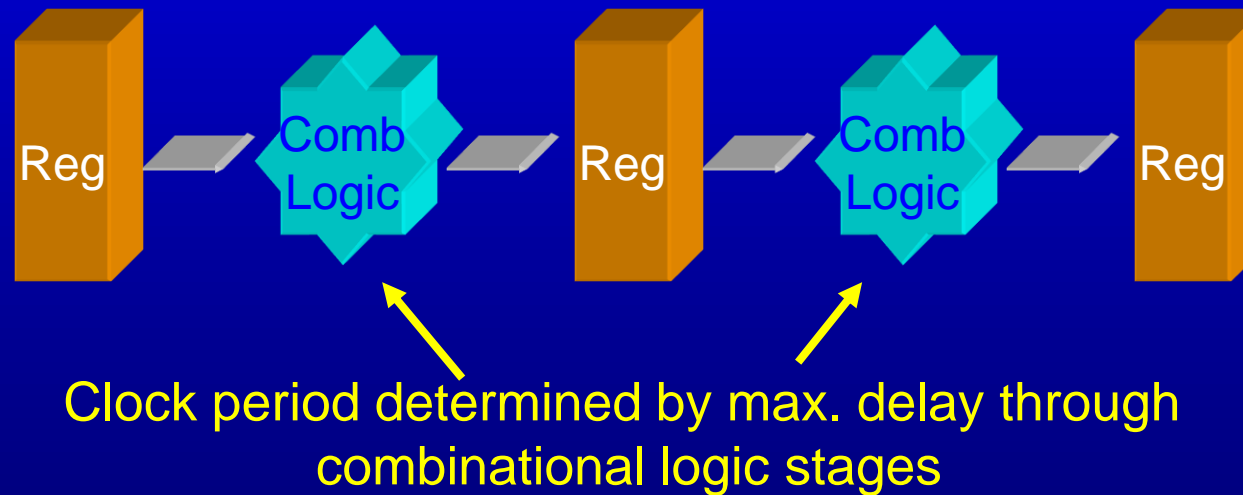
COL 719

## Part 4: Retiming

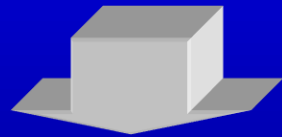
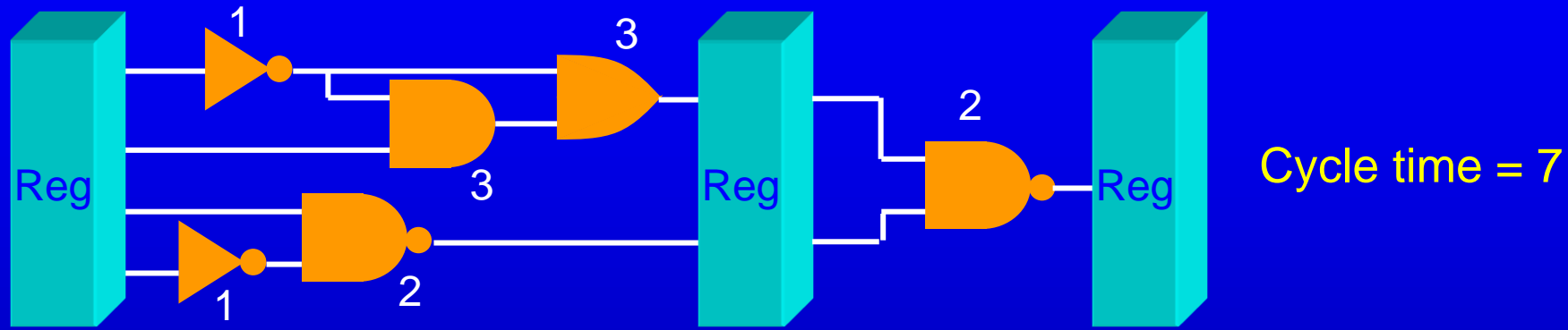
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Indian Institute of Technology Delhi

# Optimising Sequential Circuits

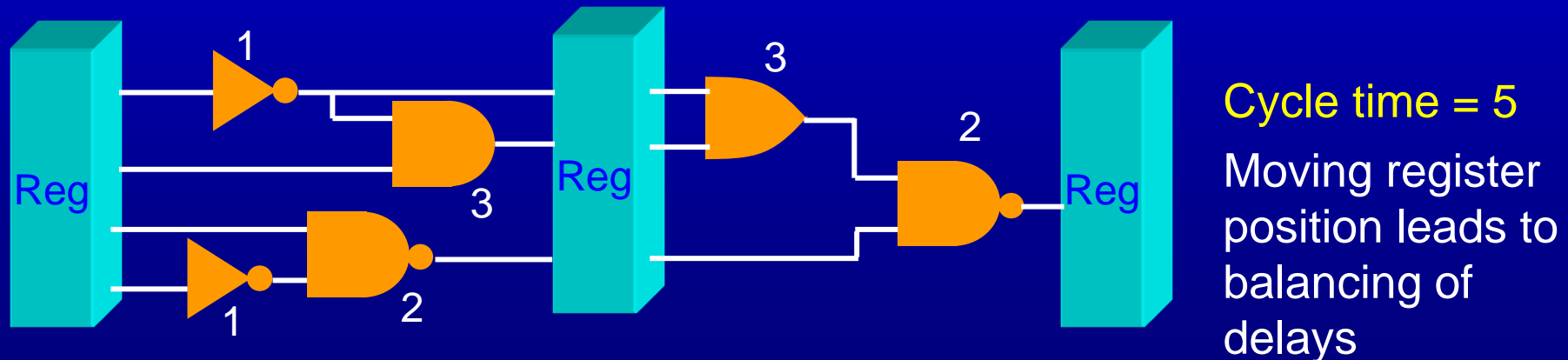
- Minimise area and cycle time
  - Optimise combinational parts independently
  - Retiming by moving registers



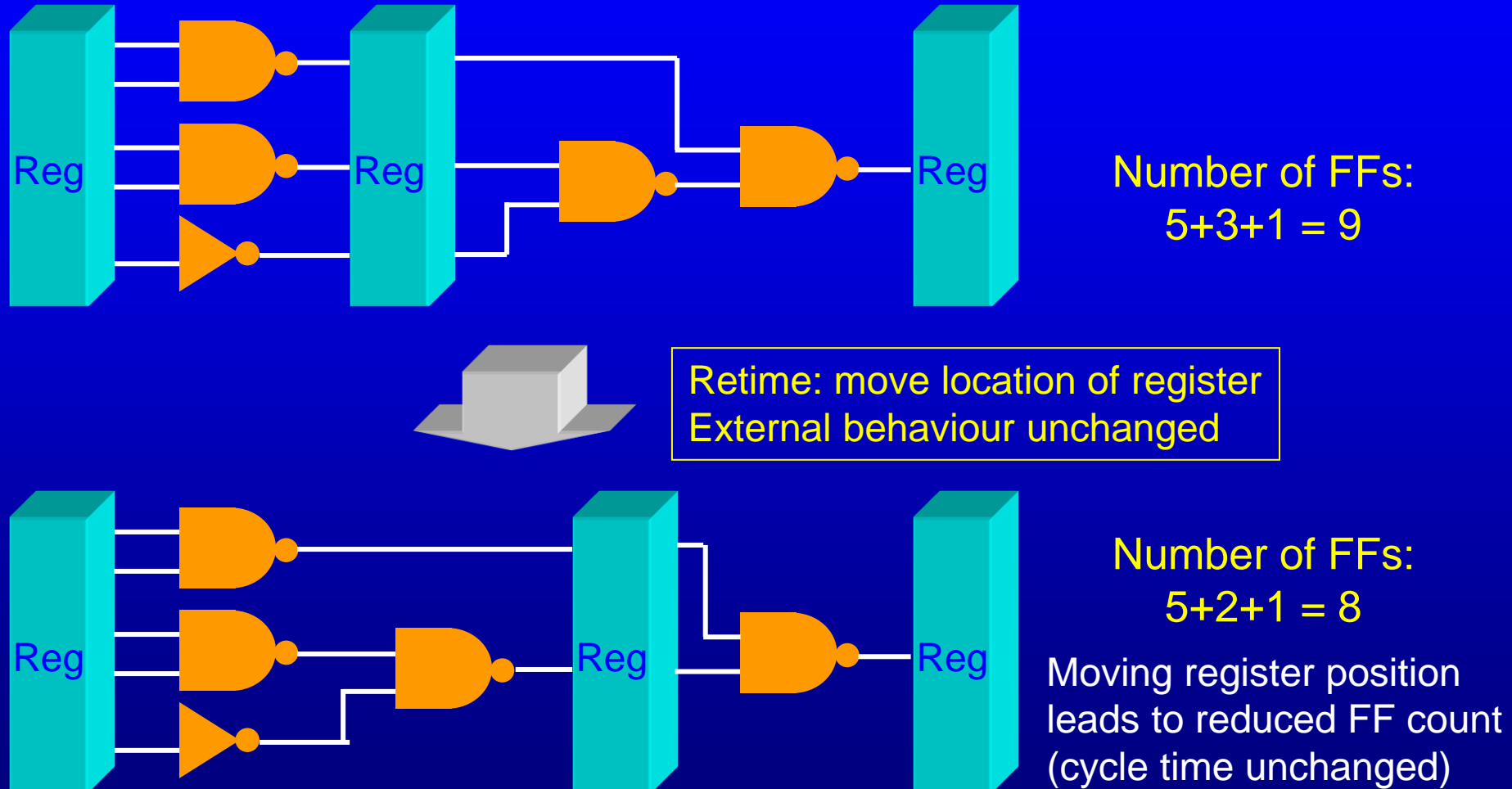
# Reducing Cycle Time by Retiming



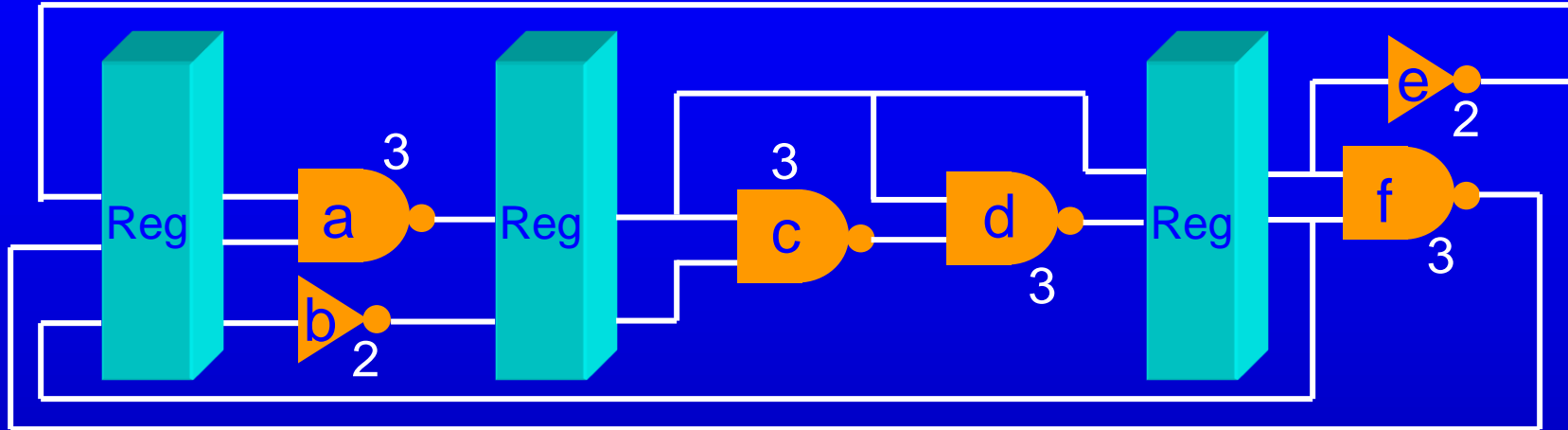
Retime: move location of register



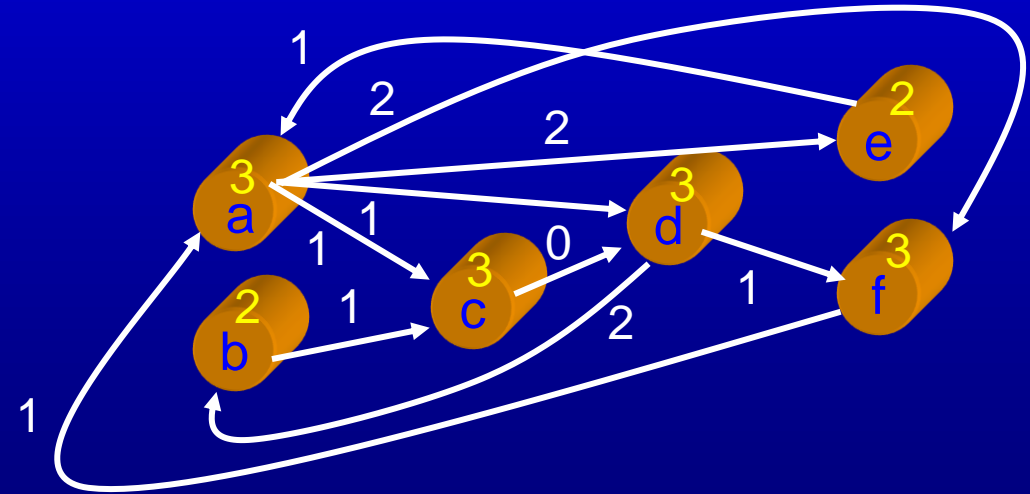
# Reducing Area by Retiming



# Graph Representation of Sequential Circuits for Retiming



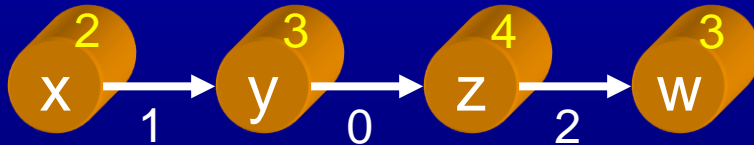
- **Nodes = Gates**
  - weight = gate delay
- **Edges = Registers**
  - weight = #Registers between gates



# Path Delay between Nodes

- Sum of propagation delays of nodes along path (including end-points)
- Let  $d_k$  be path delay of node  $v_k$
- For path  $(v_i, \dots, v_j)$ , path delay:

$$d(v_i, \dots, v_j) = \sum_{v_k \in (v_i, \dots, v_j)} d_k$$



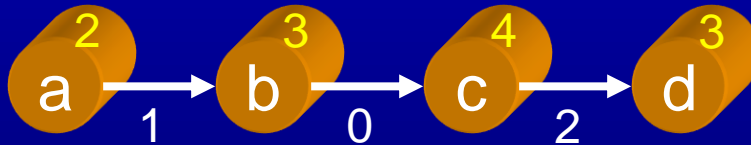
$$d(x, \dots, w) = 2 + 3 + 4 + 3 = 12$$

Path delay is  
independent of registers

# Path Weight between Nodes

- Register count along path (including end-points)
- Let  $w_{kl}$  be weight of edge  $v_k \rightarrow v_l$
- For path  $(v_i, \dots, v_j)$ , path weight:

$$w(v_i, \dots, v_j) = \sum_{v_k \rightarrow v_l \in (v_i, \dots, v_j)} w_{kl}$$

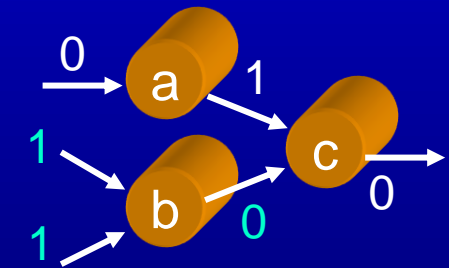
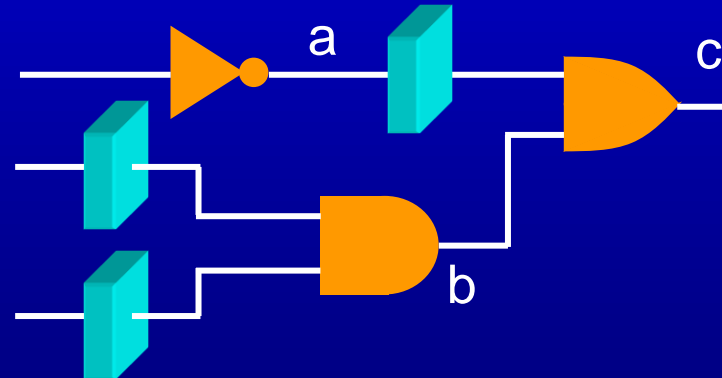
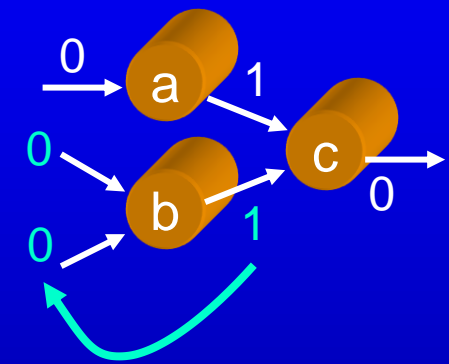
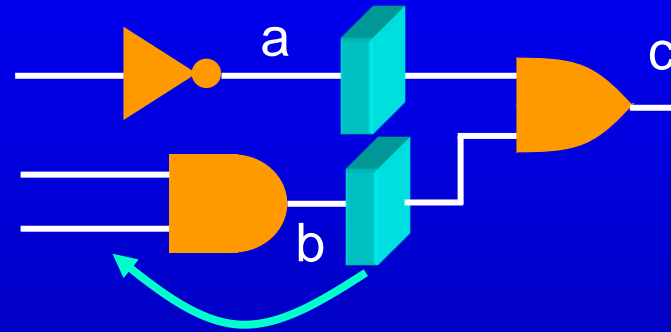


$$w(a, \dots, d) = 1 + 0 + 2 = 3$$

Path weight is independent  
of node delays

# Retiming a Node

- Moving registers from outputs to inputs
  - or vice versa
  - amount of synchronous delay moved past node
  - “register” = “flip flop”
- Positive or negative value





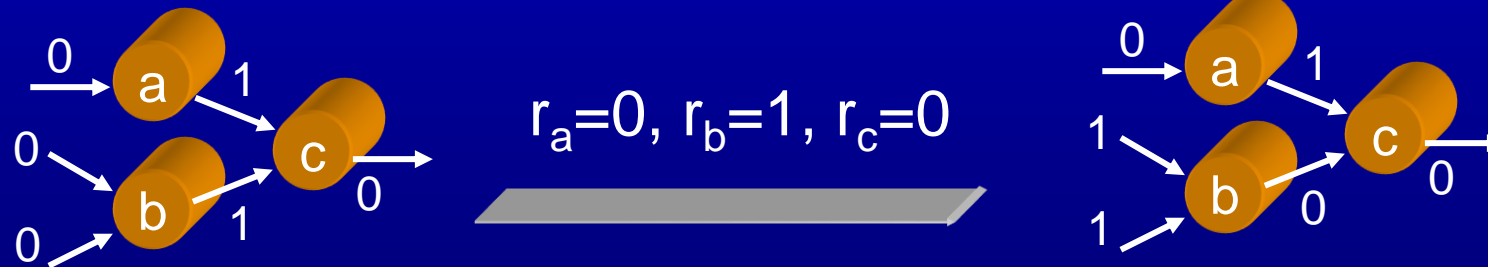
# Retiming the Graph

- Graph transformation:  $G(V,E,W)$  to  $G'(V,E,W')$
- Integer vector  $r:V \rightarrow \mathbb{Z}$
- For all edges  $v_i \rightarrow v_j$

$$W'_{ij} = W_{ij} + r_j - r_i$$

$r_j$  registers added to edge

$r_i$  registers removed from edge

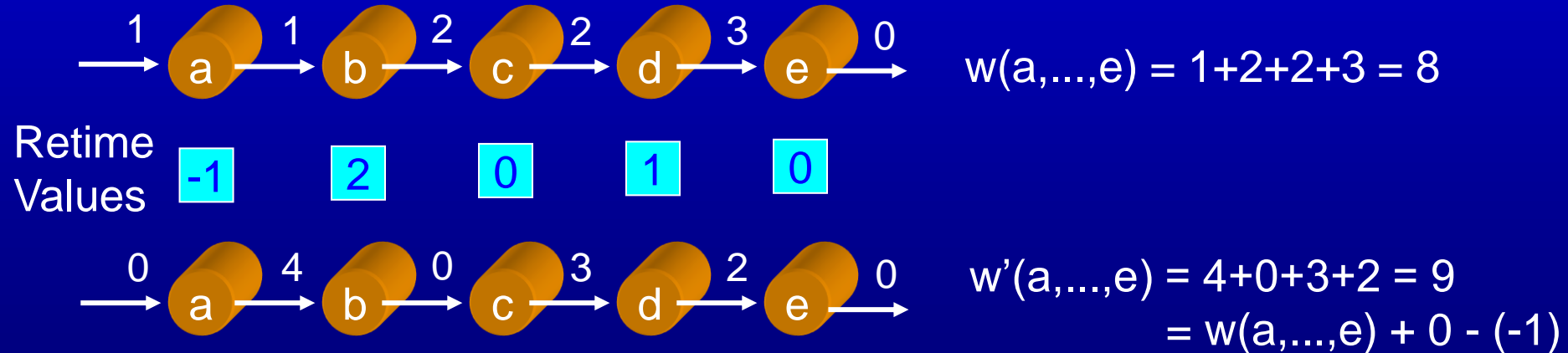


# Path Weights after Retiming

- Path weight depends on retiming of extreme nodes only

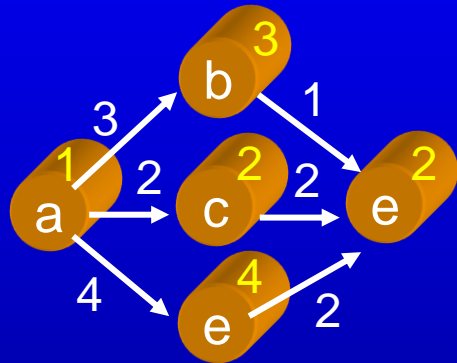
$$w'(v_i, \dots, v_j) = w(v_i, \dots, v_j) + r_j - r_i$$

- Weight of cycle is invariant on retiming



# Definitions

$$W_{ij} = \min w(v_i, \dots, v_j) \text{ for all paths } (v_i, \dots, v_j)$$



$$W_{ae} = w(a, b, e) = w(a, c, e) = 4$$

$$D_{ij} = \max d(v_i, \dots, v_j) \text{ for all paths } (v_i, \dots, v_j) \text{ with weight } W_{ij}$$

$$d(a, b, e) = 1 + 3 + 2 = 6$$

$$d(a, c, e) = 1 + 2 + 2 = 5$$

$$D_{ae} = d(a, b, e) = 6$$

# Legality and Timing Feasibility

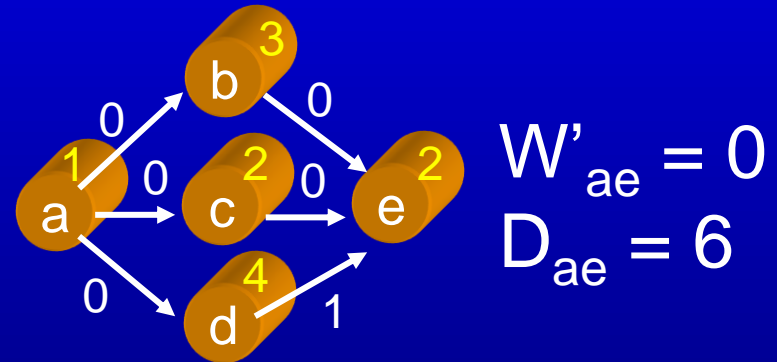
- Legality

- No negative edge weights  
(number of registers  $\geq 0$ )

$$w'_{ij} \geq 0$$

- Timing Feasibility

- given clock period  $\phi$
- Path delay larger than  $\phi$  should be broken by at least one register



$$W'_{ij} \geq 1 \text{ if } D_{ij} > \phi$$

Infeasible for  $\phi = 5$   
Feasible for  $\phi = 6$

# Feasibility of Retiming

- Retiming is feasible if
  - legal
  - retimed graph is timing feasible
- Retiming  $r$  is feasible if

$\forall (v_i, v_j) \in E$

$$w'_{ij} \geq 0 \Rightarrow w_{ij} + r_j - r_i \geq 0 \Rightarrow r_i - r_j \leq w_{ij}$$

Legality Check

$\forall v_i, v_j : D(v_i, v_j) > \phi$

$$W'_{ij} \geq 1 \Rightarrow W_{ij} + r_j - r_i \geq 1 \Rightarrow r_i - r_j \leq W_{ij} - 1$$

Timing Check

# System of Linear Inequalities

- Compute  $W$  and  $D$  matrices
- Build set of linear inequalities
  - Upto 2 inequalities for every pair of nodes
- Solve for vector  $r$

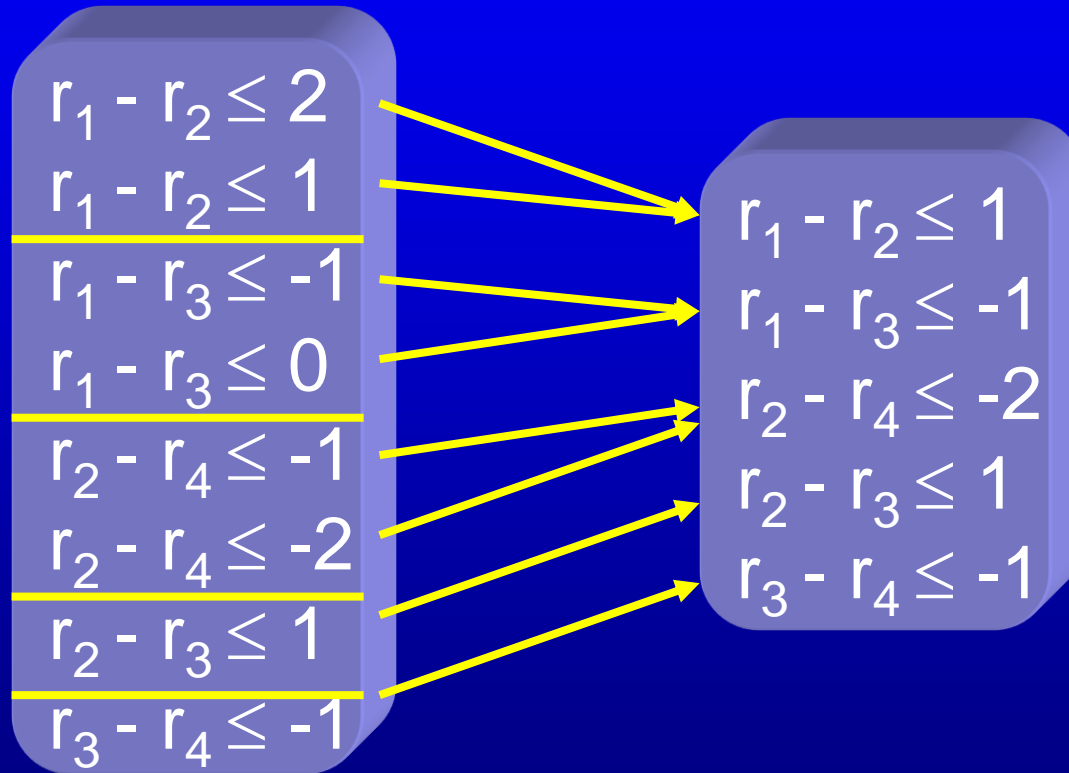
$$\forall (v_i, v_j) \in E$$

$$r_i - r_j \leq w_{ij}$$

$$\forall v_i, v_j : D(v_i, v_j) > \phi$$

$$r_i - r_j \leq W_{ij} - 1$$

# Remove Redundant Inequations and Solve



Retain one equation  
per  $(r_i, r_j)$  pair  
Solve for  $r_1, r_2, r_3, r_4$

# How do we Solve System of Inequalities?

- General problem: Linear Programming (LP)
  - Maximise  $\sum c_i x_i$  given  $Ax \leq b$
  - Simplex method (Exponential time)
  - Ellipsoid/Karmakar (Polynomial time)
- Restricted version: Integer Linear Programming (ILP)
  - Variables restricted to be integers
  - NP-Complete!

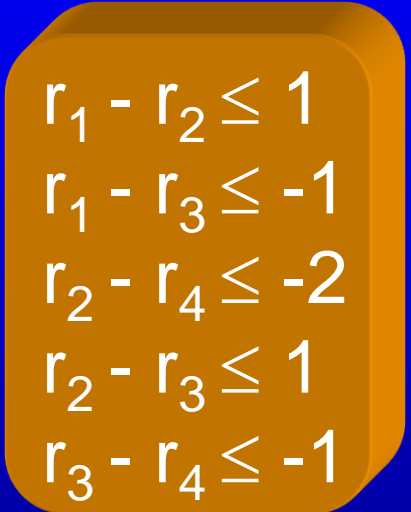
$$\begin{array}{l} r_1 - r_2 \leq 1 \\ r_1 - r_3 \leq -1 \\ r_2 - r_4 \leq -2 \\ r_2 - r_3 \leq 1 \\ r_3 - r_4 \leq -1 \end{array}$$

$$\begin{array}{l} A_{11}x_1 + A_{12}x_2 \leq b_1 \\ A_{21}x_1 + A_{22}x_2 \leq b_2 \\ A_{31}x_1 + A_{32}x_2 \leq b_3 \\ A_{41}x_1 + A_{42}x_2 \leq b_4 \\ A_{51}x_1 + A_{52}x_2 \leq b_5 \end{array}$$



# Inequalities in Retiming Problem

- Restricted system of inequalities
  - Exactly 2 variables in each inequality
  - Coefficients are 1, -1
- Can be solved in Polynomial time!


$$\begin{array}{l} r_1 - r_2 \leq 1 \\ r_1 - r_3 \leq -1 \\ r_2 - r_4 \leq -2 \\ r_2 - r_3 \leq 1 \\ r_3 - r_4 \leq -1 \end{array}$$

# Solution to System of Inequalities

- No solution
- System has infinite solutions
  - if  $r$  is a solution,  $r+c$  is also a solution
- Let  $r_1 = 0$ 
  - Can set arbitrary  $r_i$  to 0
  - For example:
    - if  $(2,3,-1,0)$  is one solution,  
 $(0,1,-3,-2)$  is also a solution

$$r_1 - r_2 \leq 1$$

$$r_1 - r_3 \leq -1$$

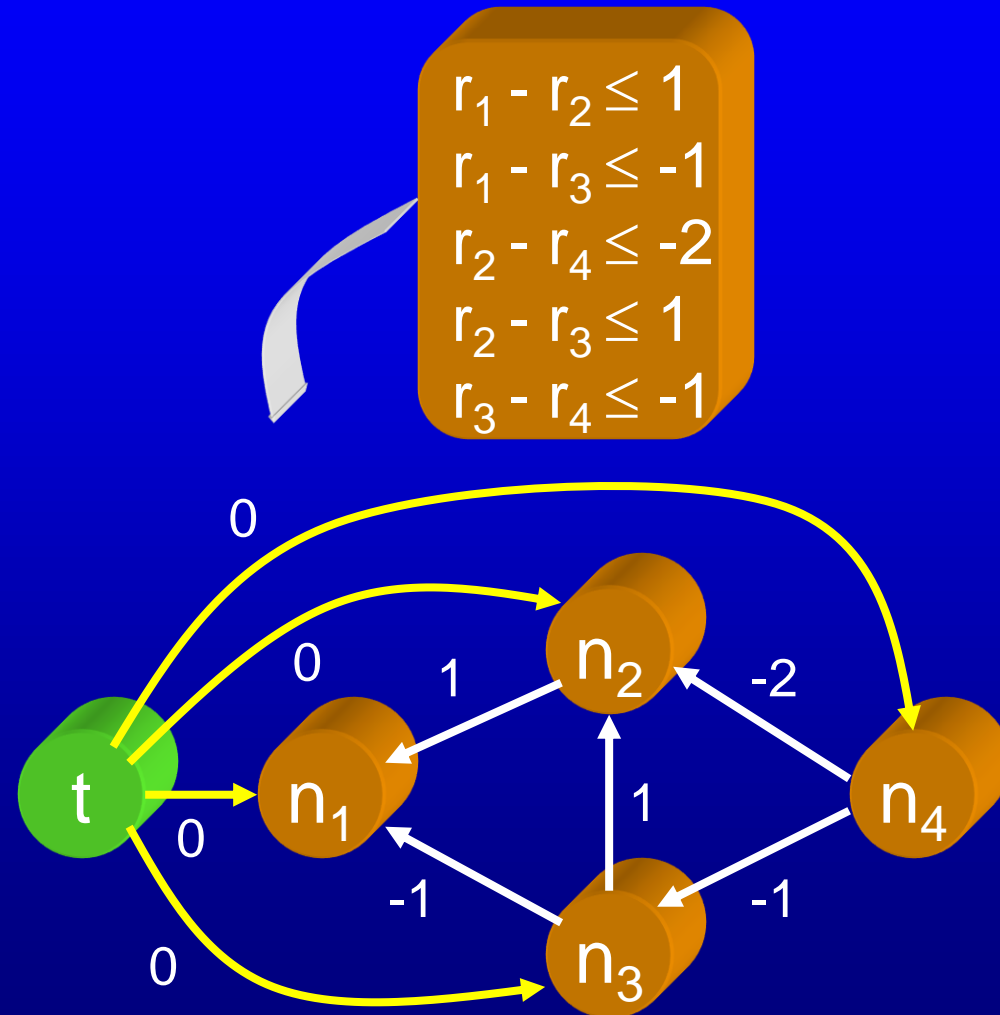
$$r_2 - r_4 \leq -2$$

$$r_2 - r_3 \leq 1$$

$$r_3 - r_4 \leq -1$$

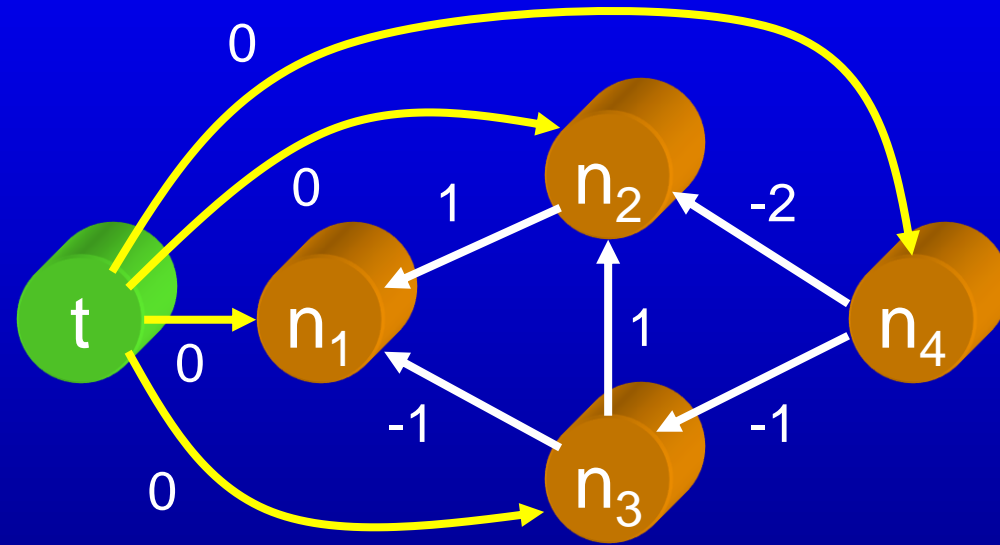
# Build Constraint Graph

- One node  $n_i$  for each  $r_i$
- Constraint  $r_a - r_b \leq k$  implies Edge Weight  $wt(n_b \rightarrow n_a) = k$
- Add auxiliary node  $t$ 
  - zero-weight edges to all other nodes from  $t$



# Solution using Shortest Path Algorithm

- Find shortest path in graph from  $t$  to all other nodes
  - Polynomial time
  - Bellman-Ford algorithm
- This gives  $r_i$  values for other nodes!



Solution:  $r_1 = -2, r_2 = -2,$   
 $r_3 = -1, r_4 = 0$

# Why does Shortest Path work?

Consider edge  $n_b \rightarrow n_a$

$sp(t \rightarrow n_a) \leq sp(t \rightarrow n_b) + wt(n_b \rightarrow n_a)$  -- by defn of shortest path

$sp(t \rightarrow n_a) - sp(t \rightarrow n_b) \leq wt(n_b \rightarrow n_a)$

Letting

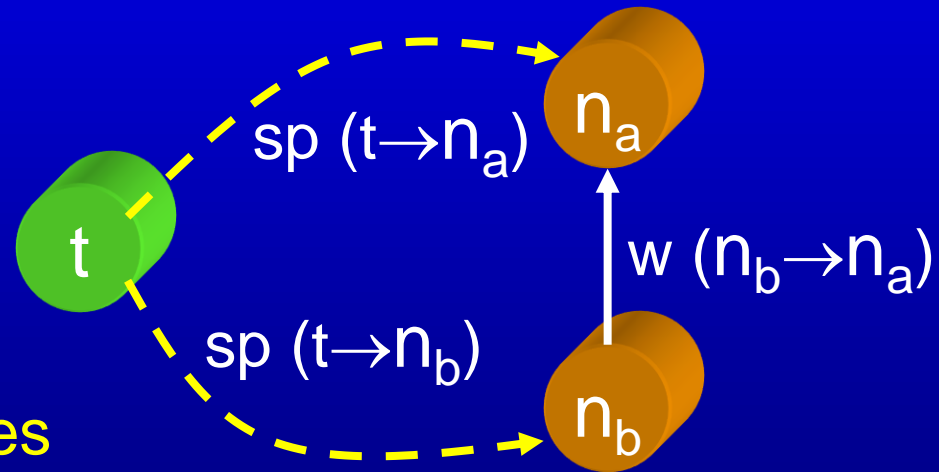
$r_a = sp(t \rightarrow n_a)$

$r_b = sp(t \rightarrow n_b)$

$r_a - r_b \leq wt(n_b \rightarrow n_a)$

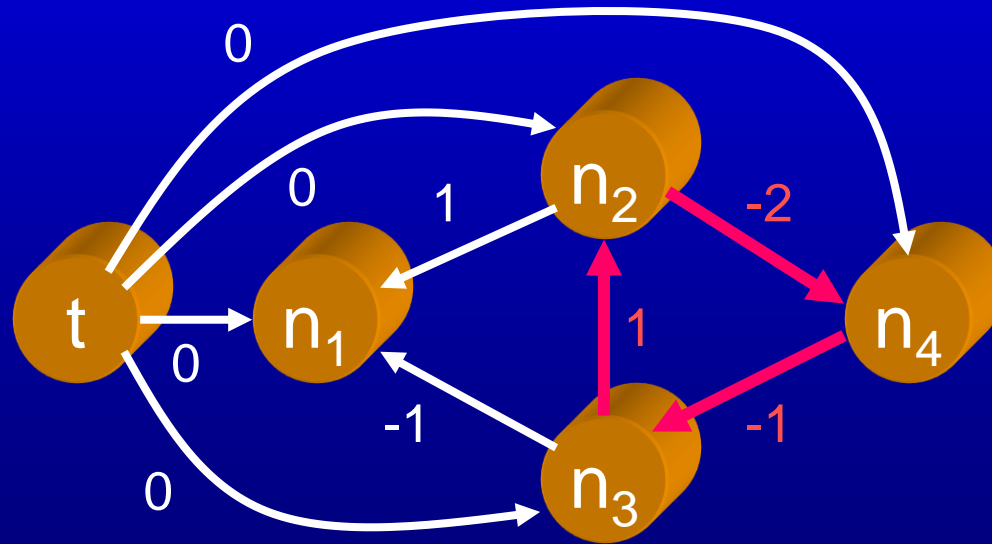
$r_a - r_b \leq k$

Thus, choice of  $sp$  for  $r_i$  satisfies  
constraint represented by edge  $wt$



# What if Graph has Negative Cycle?

- Sum of edge wts in cycle is negative
- Bellman-Ford algorithm returns error
  - shortest path not defined



# Negative Cycle Leads to Infeasible Constraints

$$\begin{aligned}r_2 - r_1 &\leq \text{wt}(n_1 \rightarrow n_2) \\ r_3 - r_2 &\leq \text{wt}(n_2 - n_3) \\ r_4 - r_3 &\leq \text{wt}(n_3 - n_4) \\ &\dots \\ r_k - r_{k-1} &\leq \text{wt}(n_{k-1} - n_k) \\ r_1 - r_k &\leq \text{wt}(n_k - n_1)\end{aligned}$$

Ref: Cormen, Leiserson, and Rivest, "Introduction to Algorithms"

Adding both sides:

$$0 \leq \text{wt}(n_1 \rightarrow n_2) + \text{wt}(n_2 - n_3) + \dots + \text{wt}(n_{k-1} - n_k) + \text{wt}(n_k - n_1)$$

Impossible because RHS is negative

i.e., Bellman-Ford algorithm can be used directly for our problem

Now, we have Retiming values for all nodes (gates)

# Retiming Strategy

- Compute  $D$  and  $W$  of original circuit
- For given  $\phi$  set up inequalities and solve for  $r$

$$\forall (v_i, v_j) \in E$$

$$r_i - r_j \leq w_{ij}$$

$$\forall v_i, v_j : D(v_i, v_j) > \phi$$

$$r_i - r_j \leq W_{ij} - 1$$

- If solution exists reduce  $\phi$  and solve again
- Until no more solution



# How to Choose $\phi$ Values?

- Optimal clock period has to be one of the  $D_{ij}$  values
  - otherwise, we could reduce  $\phi$  to the nearest  $D_{ij}$  value without violating clock period
- First enumerate and sort all  $D_{ij}$  values in decreasing order
  - E.g.: 20, 16.5, 15, 13.2, 10, 8, 7, 5
- Use binary search