COL 352 Introduction to Automata and Theory of Computation

Nikhil Balaji

Bharti 420 Indian Institute of Technology, Delhi nbalaji@cse.iitd.ac.in

February 23, 2023

Lecture 15: Pushdown Automata

Recap

Definition

A 2DFA $A = (Q, \Sigma \cup \{\#, \$\}, \delta, q_0, q_{\mathsf{acc}}, q_{\mathsf{rej}})$, where

Q: set of states, $\Sigma:$ input alphabet

#: left endmarker \$: right endmarker

 q_0 : start state

 q_{acc} : accept state q_{rej} : reject state

 $\delta: Q \times (\Sigma \cup \{\#, \$\} \to Q \times \{L, R\}$

The following conditions are forced:

$$\forall q \in Q, \ \exists q', q'' \in Q \ \text{s.t.} \ \delta(q, \#) = (q', R) \ \text{and} \ \delta(q, \$) = (q'', L).$$

Recap

Definition

A 2DFA
$$A = (Q, \Sigma \cup \{\#, \$\}, \delta, q_0, q_{\mathsf{acc}}, q_{\mathsf{rej}})$$
, where

Q: set of states, $\Sigma:$ input alphabet

#: left endmarker \$: right endmarker

 q_0 : start state

 $q_{
m acc}$: accept state $q_{
m rej}$: reject state

 $\delta: Q \times (\Sigma \cup \{\#, \$\} \to Q \times \{L, R\}$

The following conditions are forced:

$$\forall q \in Q, \exists q', q'' \in Q \text{ s.t. } \delta(q, \#) = (q', R) \text{ and } \delta(q, \$) = (q'', L).$$

Exercise: Come up with a suitable definition of 2-NFA. Redo closure properties of regular languages, but now using 2-DFA/2-NFA.

Lemma

The class of language recognized by 2DFAs is regular.

Proof.

Let $T_x: Q \cup \{ \bowtie \} \to Q \cup \{ \bot \}$, which is defined as follows:

 $T_x(p) \coloneqq q$ if whenever A enters x on p it leaves x on q.

 $T_x(\bowtie) := q$ q is the state in which A emerges on x the first time.

 $T_x(q) \coloneqq \bot$ if A loops on x forever.



Lemma

The class of language recognized by 2DFAs is regular.

Proof.

Let
$$T_x\colon Q\cup\{\bowtie\} o Q\cup\{\bot\}$$
, which is defined as follows:
$$T_x(p)\coloneqq q \quad \text{if whenever } A \text{ enters } x \text{ on } p$$
 it leaves x on q .
$$T_x(\bowtie)\coloneqq q \quad q \text{ is the state in which } A \text{ emerges }$$
 on x the first time.
$$T_x(q)\coloneqq \bot \quad \text{if } A \text{ loops on } x \text{ forever.}$$

Total number of functions of the type

$$T_x \le (|Q|+1)^{(|Q|+1)}$$

Lemma

The class of language recognized by 2DFAs is regular.

Proof.

Let
$$T_x\colon Q\cup\{{f M}\} o Q\cup\{{f \bot}\},$$
 which is defined as follows:
$$T_x(p)\coloneqq q\quad \text{if whenever }A\text{ enters }x\text{ on }p$$
 it leaves x on q .
$$T_x({f M})\coloneqq q\quad q\text{ is the state in which }A\text{ emerges}$$
 on x the first time.
$$T_x(q)\coloneqq \bot\quad \text{if }A\text{ loops on }x\text{ forever}.$$

Total number of functions of the type

$$T_x \le (|Q|+1)^{(|Q|+1)}$$

$$T_x = T_y \Rightarrow \forall z (xz \in F \Leftrightarrow yz \in F)$$
. Prove this.

Lemma

The class of language recognized by 2DFAs is regular.

Proof.

Let
$$T_x\colon Q\cup\{st\} o Q\cup\{ot\}\}$$
, which is defined as follows:
$$T_x(p)\coloneqq q \quad \text{if whenever } A \text{ enters } x \text{ on } p$$
 it leaves x on q .
$$T_x(st)\coloneqq q \quad q \text{ is the state in which } A \text{ emerges}$$
 on x the first time.
$$T_x(q)\coloneqq \bot \quad \text{if } A \text{ loops on } x \text{ forever.}$$

Total number of functions of the type

$$\begin{split} T_x &\leq (|Q|+1)^{(|Q|+1)} \\ T_x &= T_y \Rightarrow \forall z \big(xz \in F \Leftrightarrow yz \in F \big). \text{ Prove this.} \\ T_x &= T_y \Leftrightarrow x \equiv_A y \end{split}$$



Moving on

How to we add expressive power to DFA/NFA so that we can compute more functions?

$$L_{a,b} = \{a^n b^n \mid n \ge 0\}.$$

- ► $L_{a,b} = \{a^n b^n \mid n \ge 0\}.$
- $PAL = \{ w \cdot w^R \mid w \in \Sigma^* \}.$

- ► $L_{a,b} = \{a^n b^n \mid n \ge 0\}.$
- $PAL = \{ w \cdot w^R \mid w \in \Sigma^* \}.$

- ► $L_{a,b} = \{a^n b^n \mid n \ge 0\}.$
- $PAL = \{ w \cdot w^R \mid w \in \Sigma^* \}.$

NFA needs more memory to solve them.

- $L_{a,b} = \{a^n b^n \mid n \ge 0\}.$
- $PAL = \{ w \cdot w^R \mid w \in \Sigma^* \}.$

NFA needs more memory to solve them. What if the NFA had a stack?

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$

Definition

A non-deterministic pushdown automaton (NPDA)

 $A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states

Definition

A non-deterministic pushdown automaton (NPDA)

A = $(Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

Definition

A non-deterministic pushdown automaton (NPDA)

A = $(Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

 $Q \colon \ \ \, \text{set of states} \qquad \Sigma \colon \ \ \, \text{input alphabet}$

 Γ : stack alphabet

Definition

A non-deterministic pushdown automaton (NPDA)

 $A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

Definition

A non-deterministic pushdown automaton (NPDA)

 $A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

⊥: start symbol

Definition

A non-deterministic pushdown automaton (NPDA)

 $A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

Definition

A non-deterministic pushdown automaton (NPDA)

A = $(Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Definition

A non-deterministic pushdown automaton (NPDA)

$$A$$
 = $(Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$,

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$, then p is the new state and γ replaces X in the stack.

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \bot : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$,

then p is the new state and $\boldsymbol{\gamma}$ replaces \boldsymbol{X} in the stack.

if $\gamma = \epsilon$ then X is popped.

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$,

then p is the new state and γ replaces X in the stack.

if $\gamma = \epsilon$ then X is popped.

if γ = X then X stays unchanges on the top of the stack.

Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \perp : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$,

then p is the new state and γ replaces X in the stack.

if $\gamma = \epsilon$ then X is popped.

if $\gamma = X$ then X stays unchanges on the top of the stack.

if $\gamma = \gamma_1 \gamma_2 \dots \gamma_k$ then X is replaced by γ_k



Definition

A non-deterministic pushdown automaton (NPDA)

$$A = (Q, \Sigma, \Gamma, \delta, q_0, \bot, F)$$
, where

Q: set of states Σ : input alphabet

 Γ : stack alphabet q_0 : start state

 \bot : start symbol F: set of final states

$$\delta \subseteq Q \times \Sigma \times \Gamma \times Q \times \Gamma^*.$$

Understanding δ

For $q \in Q, a \in \Sigma$ and $X \in \Gamma$, if $\delta(q, a, X) = (p, \gamma)$,

then p is the new state and γ replaces X in the stack.

if $\gamma = \epsilon$ then X is popped.

if $\gamma = X$ then X stays unchanges on the top of the stack.

if $\gamma = \gamma_1 \gamma_2 \dots \gamma_k$ then X is replaced by γ_k and $\gamma_1 \gamma_2 \dots \gamma_{k-1}$ are pushed on top of that.

Example:

Example: $L_{a,b} = \{a^n b^n \mid n \ge 0\}.$

Example:
$$L_{a,b} = \{a^nb^n \mid n \ge 0\}.$$
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$

Example:
$$L_{a,b} = \{a^n b^n \mid n \ge 0\}.$$
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$ $\delta(q_0, a, \bot) = (q_0, B \bot)$

$$\begin{split} \text{Example: } & L_{a,b} = \{a^n b^n \mid n \geq 0\}. \\ & N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}). \\ & \delta(q_0, a, \bot) = (q_0, B \bot) \\ & \delta(q_0, a, B) = (q_0, B) \end{split}$$

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}.$$
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$ $\delta(q_0, a, \bot) = (q_0, B \bot)$ $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0

Example:
$$L_{a,b} = \{a^n b^n \mid n \ge 0\}.$$
 $N = \{Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}\}.$ $\delta(q_0, a, \bot) = (q_0, B \bot)$ $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0 $\delta(q_0, b, B) = (q_1, \epsilon)$

Example:
$$L_{a,b} = \{a^nb^n \mid n \ge 0\}.$$

 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$
 $\delta(q_0, a, \bot) = (q_0, B \bot)$
 $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0
 $\delta(q_0, b, B) = (q_1, \epsilon)$ move to q_1 on seeing b

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\})$. $\delta(q_0, a, \bot) = (q_0, B \bot)$ $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0 $\delta(q_0, b, B) = (q_1, \epsilon)$ move to q_1 on seeing b $\delta(q_1, b, B) = (q_1, \epsilon)$

Example:
$$L_{a,b} = \{a^n b^n \mid n \ge 0\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\})$. $\delta(q_0, a, \bot) = (q_0, B \bot)$ $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0 $\delta(q_0, b, B) = (q_1, \epsilon)$ move to q_1 on seeing b $\delta(q_1, b, B) = (q_1, \epsilon)$ pop B while reading b on q_1

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\})$. $\delta(q_0, a, \bot) = (q_0, B \bot)$ $\delta(q_0, a, B) = (q_0, B)$ push B while reading a on q_0 $\delta(q_0, b, B) = (q_1, \epsilon)$ move to q_1 on seeing b $\delta(q_1, b, B) = (q_1, \epsilon)$ pop B while reading b on q_1 $\delta(q_1, b, \bot) = (q', \bot)$

```
Example: L_{a,b} = \{a^nb^n \mid n \geq 0\}. N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}). \delta(q_0, a, \bot) = (q_0, B \bot) \delta(q_0, a, B) = (q_0, B) \text{ push } B \text{ while reading } a \text{ on } q_0 \delta(q_0, b, B) = (q_1, \epsilon) \text{ move to } q_1 \text{ on seeing } b \delta(q_1, b, B) = (q_1, \epsilon) \text{ pop } B \text{ while reading } b \text{ on } q_1 \delta(q_1, b, \bot) = (q', \bot) \text{ extra } b \text{ in the input then go to some state } q'
```

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}$$
.
$$N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$$

$$\delta(q_0, a, \bot) = (q_0, B \bot)$$

$$\delta(q_0, a, B) = (q_0, B) \text{ push } B \text{ while reading } a \text{ on } q_0$$

$$\delta(q_0, b, B) = (q_1, \epsilon) \text{ move to } q_1 \text{ on seeing } b$$

$$\delta(q_1, b, B) = (q_1, \epsilon) \text{ pop } B \text{ while reading } b \text{ on } q_1$$

$$\delta(q_1, b, \bot) = (q', \bot) \text{ extra } b \text{ in the input then go to some state } q'$$

$$\delta(q_1, \epsilon, \bot) = (q_2, \bot)$$

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}$$
.
$$N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$$

$$\delta(q_0, a, \bot) = (q_0, B \bot)$$

$$\delta(q_0, a, B) = (q_0, B) \text{ push } B \text{ while reading } a \text{ on } q_0$$

$$\delta(q_0, b, B) = (q_1, \epsilon) \text{ move to } q_1 \text{ on seeing } b$$

$$\delta(q_1, b, B) = (q_1, \epsilon) \text{ pop } B \text{ while reading } b \text{ on } q_1$$

$$\delta(q_1, b, \bot) = (q', \bot) \text{ extra } b \text{ in the input then go to some state } q'$$

$$\delta(q_1, \epsilon, \bot) = (q_2, \bot) \text{ else go to accepting state } q_2$$

Example:
$$L_{a,b} = \{a^nb^n \mid n \geq 0\}$$
.
$$N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{B\}, q_0, F = \{q_2\}).$$

$$\delta(q_0, a, \bot) = (q_0, B \bot)$$

$$\delta(q_0, a, B) = (q_0, B) \text{ push } B \text{ while reading } a \text{ on } q_0$$

$$\delta(q_0, b, B) = (q_1, \epsilon) \text{ move to } q_1 \text{ on seeing } b$$

$$\delta(q_1, b, B) = (q_1, \epsilon) \text{ pop } B \text{ while reading } b \text{ on } q_1$$

$$\delta(q_1, b, \bot) = (q', \bot) \text{ extra } b \text{ in the input then go to some state } q'$$

$$\delta(q_1, \epsilon, \bot) = (q_2, \bot) \text{ else go to accepting state } q_2$$

Example: $PAL = \{w \cdot w^R \mid w \in \Sigma^*\}.$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}.$$
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\}).$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
.
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$.
 $\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$
 $\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}.$$

$$N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\}).$$

$$\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$$

$$\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$$

$$\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
.
 $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$.
 $\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$
 $\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$
 $\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$
 $\delta(q_0, b, A) = \{(q_0, BA), (q_1, BA)\},$
 $\delta(q_0, b, B) = \{(q_0, BB), (q_1, BB)\}$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$.
$$\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$$

$$\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$$

$$\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$$

$$\delta(q_0, b, A) = \{(q_0, BA), (q_1, BA)\},$$

$$\delta(q_0, b, B) = \{(q_0, BB), (q_1, BB)\}$$

$$\delta(q_1, a, A) = (q_1, \epsilon)$$

$$\delta(q_1, b, B) = (q_1, \epsilon)$$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$.
$$\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$$

$$\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$$

$$\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \ \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$$

$$\delta(q_0, b, A) = \{(q_0, BA), (q_1, BA)\},$$

$$\delta(q_0, b, B) = \{(q_0, BB), (q_1, BB)\}$$

$$\delta(q_1, a, A) = (q_1, \epsilon)$$

$$\delta(q_1, a, A) = (q_1, \epsilon)$$

$$\delta(q_1, a, B) = (q', \epsilon)$$

$$\delta(q_1, a, A) = (q', \epsilon)$$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$. $\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$ $\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$ $\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$ $\delta(q_0, b, A) = \{(q_0, BA), (q_1, BA)\}, \delta(q_0, b, B) = \{(q_0, BB), (q_1, BB)\}$ $\delta(q_1, a, A) = (q_1, \epsilon)$ $\delta(q_1, a, B) = (q', \epsilon)$ $\delta(q_1, a, B) = (q', \epsilon)$ $\delta(q_1, a, \bot) = (q', \epsilon)$ $\delta(q_1, b, \bot) = (q', \epsilon)$ $\delta(q_1, b, \bot) = (q', \epsilon)$ $\delta(q_1, e, \bot) = (q', \epsilon)$

Example:
$$PAL = \{w \cdot w^R \mid w \in \Sigma^*\}$$
. $N = (Q = \{q_0, q_1, q_2, q'\}, \Sigma = \{a, b\}, \Gamma = \{A, B\}, q_0, F = \{q_2\})$. $\delta(q_0, a, \bot) = \{(q_0, A \bot), (q_1, A \bot)\}$ $\delta(q_0, b, \bot) = \{(q_0, B \bot), (q_1, B \bot)\}$ $\delta(q_0, a, A) = \{(q_0, AA), (q_1, AA)\}, \delta(q_0, a, B) = \{(q_0, AB), (q_1, AB)\}$ $\delta(q_0, b, A) = \{(q_0, BA), (q_1, BA)\}, \delta(q_0, b, B) = \{(q_0, BB), (q_1, BB)\}$ $\delta(q_1, a, A) = (q_1, \epsilon)$ $\delta(q_1, a, B) = (q', \epsilon)$ $\delta(q_1, a, B) = (q', \epsilon)$ $\delta(q_1, a, \bot) = (q', \epsilon)$ $\delta(q_1, b, \bot) = (q', \epsilon)$ $\delta(q_1, b, \bot) = (q', \epsilon)$ $\delta(q_1, e, \bot) = (q', \epsilon)$