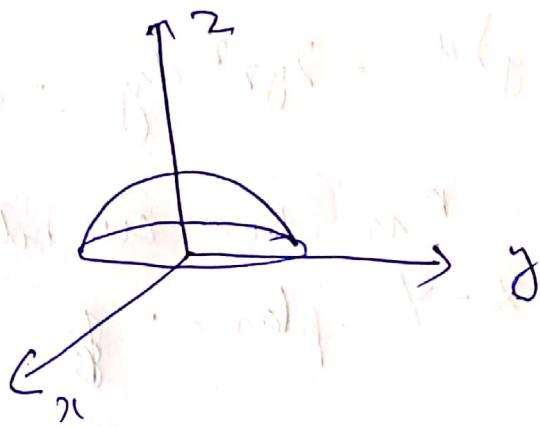


1) The Stokes' theorem states that :

$$\int \int (\vec{V} \times \vec{J}) \cdot d\alpha = \oint_P \vec{P} \cdot d\vec{U}$$

$$\text{Given: } \vec{V} = \vec{A} = (2x-y)\hat{x} - 2y^2(\hat{y}) - 2z\hat{z}$$

We need to verify this with the upper hemispherical surface of sphere centered at origin, having radius 2.



$$\text{LHS} = \vec{\nabla} \times \vec{V} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{d}{dx} & \frac{d}{dy} & \frac{d}{dz} \\ 2x-y & -2y^2 & -2z^2 \end{vmatrix}$$

$$= \hat{x} (-4zy - (-4zy)) - \hat{y} (0-0) + \hat{z} (0-(-1))$$

$$\vec{\nabla} \times \vec{V} = \hat{z}$$

$$da = r d\theta (r \sin \phi d\phi) \hat{r}$$

where $\hat{r} = \sin \phi \cos \theta \hat{x} + \sin \phi \sin \theta \hat{y} + \cos \theta \hat{z}$

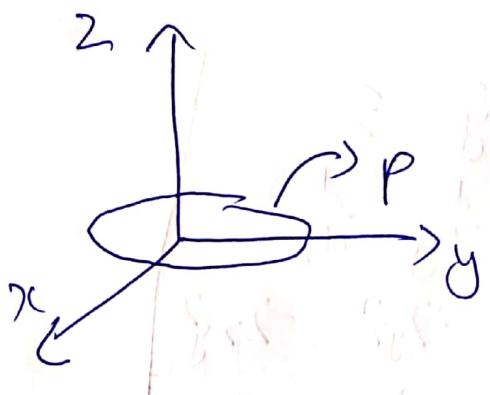
$$\therefore (\vec{\nabla} \times \vec{v}) \cdot da = r_0^2 \sin \phi \cos \theta d\phi d\theta$$

$$\int (\vec{\nabla} \cdot \vec{v}) \cdot da = \int_{\theta=0}^{\pi/2} \int_{\phi=0}^{2\pi} r_0^2 \sin \phi \cos \theta d\phi d\theta$$

$$RHS = \vec{d}\vec{l} = dr \hat{x} + dy \hat{y} + dz \hat{z}$$

$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P ((2x-y) dx - 2y^2 dy - 2xy^2 dz)$$

Now our periphery P is the circular projection of hemisphere in $x-y$ plane.



(i) For (our) periphery, $z=0$ implying:

$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P (2x-y) dx$$

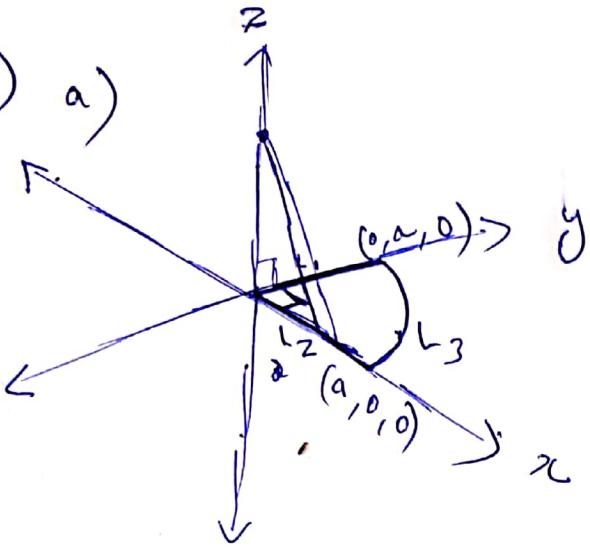
$$x = r_0 \cos \theta \Rightarrow dr = -r_0 \sin \theta d\theta$$

$$y = r_0 \sin \theta$$

$$\begin{aligned}\oint_P \vec{v} \cdot d\vec{l} &= \oint_P (2\pi - y) dr \\ &= \oint_P (2r_0 \cos \theta - r_0 \sin \theta) (-r_0 \sin \theta d\theta) \\ &= r_0^2 \int_0^{2\pi} (\sin^2 \theta - 2 \sin \theta \cos \theta) d\theta \\ &= r_0^2 \int_0^{2\pi} \sin^2 \theta d\theta \\ &= \pi r_0^2 = 4\pi \quad (\text{since } r_0 = 2)\end{aligned}$$

$$\therefore \text{LHS} = \text{RHS}$$

Q2) a)



$$V = \int \frac{dq}{4\pi\epsilon_0 r}$$

= ~~Σ~~ summation of potentials due to 3 line charges, 2 straight line + 1 arc.

$$= \int_0^a \frac{dz dr}{4\pi\epsilon_0 \sqrt{z^2 + r^2}} + \int_0^a \frac{dy dz}{4\pi\epsilon_0 \sqrt{z^2 + y^2}}$$

$$+ \int_0^{\pi/2} \frac{dr d\theta}{4\pi\epsilon_0 \sqrt{r^2 + z^2}}$$

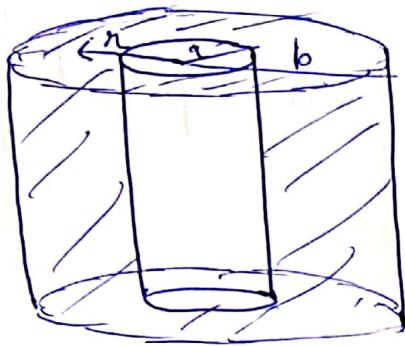
Both are same

$$= \frac{\lambda}{4\pi\epsilon_0} \left(\frac{1}{2} \left[\ln \left(x + \sqrt{x^2 + z^2} \right) \right]_0^a + \frac{\pi r}{2 \sqrt{r^2 + z^2}} \right)$$

$$= \frac{\lambda}{4\pi\epsilon_0} \left[2 \ln \left(\frac{a + \sqrt{a^2 + z^2}}{z} \right) + \frac{\pi r}{2 \sqrt{r^2 + z^2}} \right]$$

b) No, we cannot determine \mathbf{E} from $V(0, 0, z)$ because we have already assumed x and y to be 0 and while calculating ~~E_x~~ , we ~~also~~ won't get the partial derivatives with respect to x and y .

3) a)



$$i) E \cdot 2\pi r \lambda = \frac{\rho_0 \pi (r^2 - a^2)}{\epsilon} \lambda$$

$$E = \frac{f(r^2 - a^2)}{2 \pi r \epsilon_0}$$

$$V = - \int_a^r$$

$$- \int_a^r \frac{\rho_0 (r^2 - a^2)}{2 \pi r \epsilon_0} dr$$

$$= - \frac{\rho_0}{2 \pi \epsilon_0} \int_a^r \left(r - \frac{a^2}{r} \right) dr$$

$$= - \frac{\rho_0}{2 \epsilon_0} \left[\frac{r^2 - a^2}{2} - a^2 \ln \frac{r}{a} \right]$$

b) $(E \times 2\pi r) \lambda$

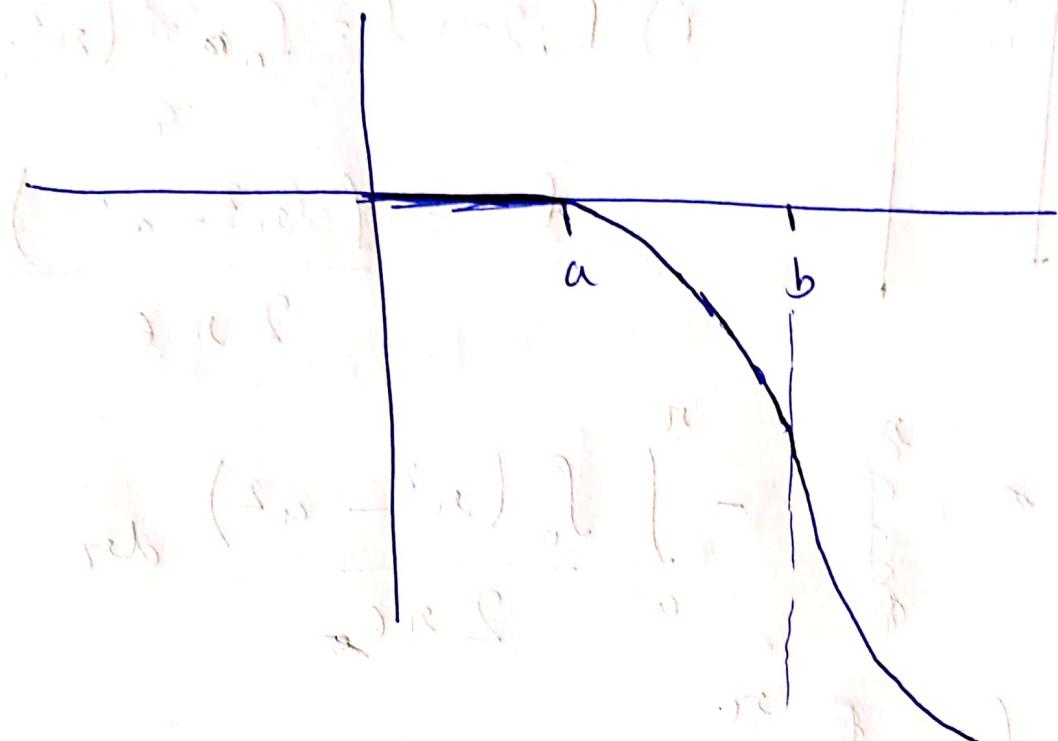
$$\frac{\rho_0 \pi (b^2 - a^2)}{\epsilon_0} \lambda = \frac{\rho_0 (b^2 - a^2)}{2 \pi \epsilon_0}$$

$$V = - \int_a^r E \cdot dr$$

$$= - \int_a^b E \cdot dr - \int_b^r E \cdot dr$$

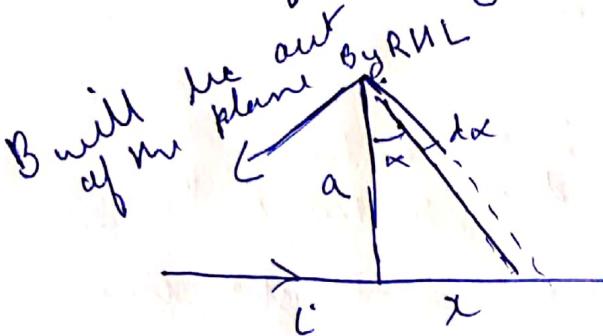
$$V = - \frac{\rho_0}{2 \epsilon_0} \left(\frac{b^2 - a^2}{2} - a^2 \ln \left(\frac{b}{a} \right) \right) - \frac{\rho_0 (b^2 - a^2)}{2 \epsilon_0} \ln \frac{r}{b}$$

(c)



(Q4)

We first find magnetic field due to 1 wire of length l ~~at~~ at a distance a



Consider an element of length dn along the wire. Set $d\vec{B}$ be magnetic field induction due to dn .

By Biot-Savart Law:

$$d\vec{B} = \frac{\mu_0 i}{4\pi} \cdot \hat{\otimes} \left(\vec{dx} \times \vec{r} \right)$$

$$|d\vec{B}| = \frac{\mu_0 i}{4\pi} dn \left(\frac{rx}{r^2} \right) \sin \left(\frac{\pi}{2} + \alpha \right)$$

$$= \frac{\mu_0 i}{4\pi} \frac{dn \cos \alpha}{\left(\frac{a}{\cos \alpha} \right)^2}$$

$$\frac{x}{a} = \tan \alpha$$

$$dn = a \sec^2 \alpha dx$$

$$= \frac{\mu_0 i}{4\pi a^2} \times \cos \alpha \sec^2 \alpha dx$$

$$|d\vec{B}| = \frac{\mu_0 i}{4\pi a} \times \cos \alpha dx$$

$$\text{Total magnetic field} = \int |d\vec{B}| = \int_{-a}^{a} \frac{\mu_0 i}{4\pi a} \cos \alpha dx$$

where $\theta = \tan^{-1} \frac{1}{2a}$

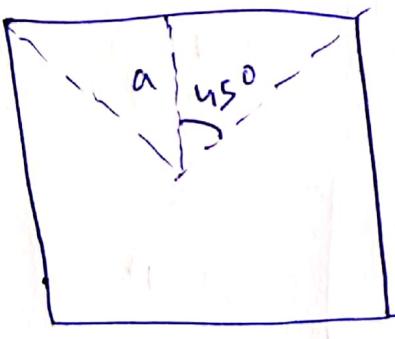
$$\therefore B_{\text{net}} = \int_{-\tan^{-1} \frac{1}{2a}}^{\tan^{-1} \frac{1}{2a}} \frac{\mu_0 i}{2\pi a} \cos \alpha d\alpha$$

$$= \frac{\mu_0 i}{2\pi a} \left[\sin \alpha \right]_{-\tan^{-1} \frac{1}{2a}}^{\tan^{-1} \frac{1}{2a}}$$

$$= \frac{\mu_0 i}{2\pi a} 2 \sin \theta = \frac{\mu_0 i}{\pi a} \sin \theta$$

Now for a square

$$\theta/2 = 45^\circ$$



and there are 4 such sides

$$\therefore B_{\text{total}} = \frac{\mu_0 i}{2\pi a} \times \frac{1}{\sqrt{2}} \times 4$$

$$= \frac{4\sqrt{2} \mu_0 i}{\pi a}$$

5) Vector Potential of a single dipole moment

~~m~~ is:

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\mathbf{r}}}{r^2}$$

Let's take \bar{M} as mass density of m at any general point

- $m = M d\tau$ to its total potential is:

$$\Rightarrow \mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{m(r') \times \hat{\mathbf{r}}}{r^2} d\tau$$

$$= \frac{\mu_0}{4\pi} \int \left[\bar{M}(r') \times \left(\nabla' \frac{1}{r'} \right) \right] d\tau$$

Using Product rule: $\nabla' \cdot \frac{1}{r'} = \frac{\hat{\mathbf{r}}}{r'^2}$

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left\{ \int \frac{1}{r'} \left(\nabla' \times \bar{M}(r') \right) d\tau' - \int \nabla' \times \left[\frac{\bar{M}(r')}{r'} \right] d\tau' \right\}$$

using surface integral

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{1}{r'} \left[\nabla' \times \bar{M}(r') \right] d\tau' + \frac{\mu_0}{4\pi} \oint \frac{1}{r'} \left[\bar{M}(r') \times da' \right]$$

Φ

Defining $\nabla \times M = J_0$ (Volume current)

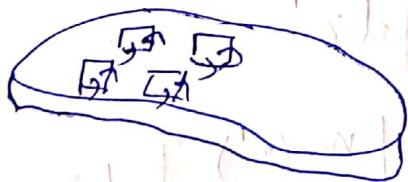
and $M \times \hat{n} = K_B$ (Surface current)

$$\Phi(r) = \frac{\mu_0}{4\pi} \int \tau_B(r') dz' + \frac{\mu_0}{4\pi} \oint K_B(r') da'$$

This means the potential and hence the field of a magnetised object is the same that would be produced by a volume current throughout the material as well as the surface current on the boundary.

This eliminates the need of integrating the contributions of small dipoles.

Physical interpretation :
 Surface Current :



Consider a state of uniform magnetized material. They current loops are like dipoles. It is equivalent to single solution of current I along the boundary.

$$\bar{m} = \bar{m}_{\text{at}}$$

$$\bar{m} = I_a$$

$$I_a = M_{\text{at}} \Rightarrow R_B = \frac{I}{E} = m$$

Volume Current:

This is a different kind of current, as not a single charge makes the whole trip, each charge only moves in a tiny little loop within a single atom.

The net effect is a macroscopic current flowing in the volume.

Q6) For a linear medium,
in small field limits;

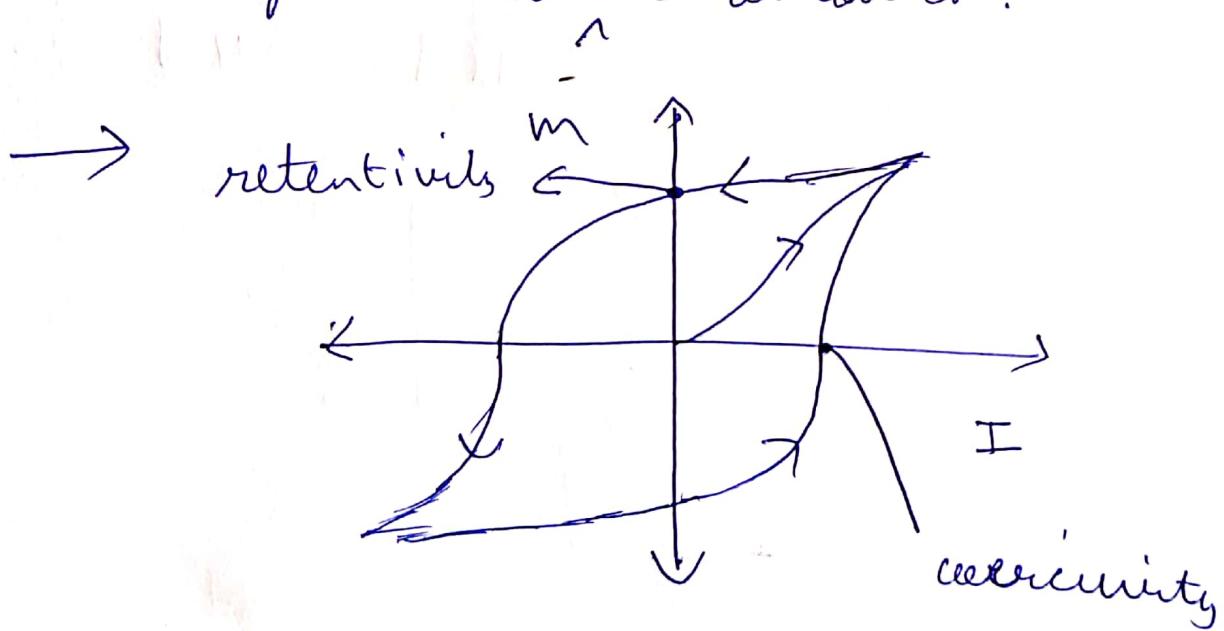
$$\bar{m} = \chi_m \vec{H} \quad (\chi_m \text{ is m magnetic susceptibility})$$

$$\Rightarrow \bar{B} = \mu_0 (\bar{H} + \bar{m}) = \mu_0 (1 + \chi_m) \bar{H}$$

$$\Rightarrow \bar{B} = \mu \bar{H} \quad , \text{ where } \mu = \mu_0 (1 + \chi_m)$$

μ is permeability of m in free space

→ In paramagnetic material, magnetisation is lost as soon as $B_{ext}^{(or I)}$ vanishes whereas in ferromagnetic material, magnetisation persists even after $B_{ext}^{(or I)}$ is removed.



Hysteresis Loop

Q7)

a) Physical Interpretation of Maxwell's eqⁿ

1) ~~the~~ 1st eqⁿ: Gauss's Law

$$\nabla \cdot \vec{E} = \frac{q}{\epsilon_0}$$

$$\nabla \cdot \vec{D} = \rho_f$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

$$\oint \vec{D} \cdot d\vec{a} = q_f$$

It signifies that electric flux through any closed surface is given by $\frac{1}{\epsilon_0}$ times net charge enclosed by it.

2) 3rd eqⁿ: Faraday's law

$$\nabla \times \vec{E} = - \frac{d\vec{B}}{dt}$$

$$\text{or } \oint_L \vec{E} \cdot d\vec{l} = - \frac{d\phi_B}{dt}$$

→ This signifies that a time dependant magnetic field generates an electric field.

Also, uniform electric field cannot exist in time dependant magnetic field.

3) 2nd eq "

$$\nabla \cdot \vec{B} = 0$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

Physically, this means that magnetic flux through a closed surface is always zero.

or, It states that magnetic monopoles ^{isolated} cannot exist. They appear only in pairs.

(4) 4th equation aka Ampere's law

$$\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{d\vec{E}}{dt} + \mu_0 \vec{J}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d\phi_E}{dt} + \mu_0 \epsilon_0 \frac{d\phi_B}{dt}$$

$$\nabla \times \vec{H} = J_F + \frac{d\vec{D}}{dt}$$

$$\oint \vec{H} \cdot d\vec{l} = I_F + \frac{d}{dt} \oint \vec{E} \cdot d\vec{n}$$

It tells us that time varying electric field produces a magnetic field

It also tells that curl of \vec{H} along a closed surface gives the free current passing through it in absence of ~~closed~~ time varying magnetic field.

Physical interpretation of Poynting's theorem:

$$\frac{dw}{dt} = - \frac{d}{dt} \int \frac{1}{2} \left(\epsilon_0 E^2 + \frac{\mu_0}{\mu_0} B^2 \right) dV$$

$$\text{or } \frac{dw}{dt} = - \frac{1}{\mu_0} \oint (\vec{E} \times \vec{B}) \cdot d\vec{A}$$

$$\frac{dw_{\text{em}}}{dt} = - \frac{d}{dt} \int S \cdot dA$$

The rate of work done on charge by EM waves = rate of decrease of total energy stored in fields + the energy flowing out of the surface per unit time.

Q7) b) Given a charge 'q', which moves in a current dI in time dt , due to magnetic force \vec{F}_m acting on it. Then

$$dw = \vec{F}_m \cdot d\vec{u}$$

$$= q (\vec{v} \times \vec{B}) \cdot (v dt) \quad [\text{Lorentz Force}]$$

$$= q dt [(\vec{v} \times \vec{B}) \cdot \vec{v}] = 0$$

$v \times B$ is always \perp to \vec{v} & \vec{B}

\therefore dot product will be 0
 $\cos 90^\circ = 0$

In general, magnetic force is always perpendicular to velocity of the charge.

Hence it cannot do any work on the charge.

$$W_{\text{magnetic}} = 0$$

$$8) a) \vec{B} = \left| \frac{\vec{E}}{c} \right| \left(\hat{z} \times \hat{x} \right) \xleftarrow{\text{direction of propagation in vacuum}}$$

$$\vec{E}(z, t) = E_0 \cos(\omega t) \cos(3kz) \hat{x}$$

$$\vec{B}(z, t) = \frac{E_0}{c} \cos(\omega t) \cos(3kz) \hat{y}$$

$$b) \vec{s} = \frac{\vec{E} \times \vec{B}}{\mu_0} = \frac{E_0^2}{\mu_0 c} \cos^2(\omega t) \cos^2(3kz) \hat{z}$$

$$\langle s \rangle = \frac{E_0^2}{\mu_0 c} \cos^2(3kz) \times \frac{1}{2} \quad (\langle \cos^2 \rangle = \frac{1}{2})$$

$$= \frac{1}{2} \epsilon_0 c E^2 \cos^2(3kz)$$

$$\boxed{\frac{1}{\mu_0} = \epsilon_0 c^2}$$

The average pointing flux is dependant on the position of the point (z) as this is a standing wave not a travelling wave.

$$\begin{aligned}
 10) E_{\text{ref}} &= \operatorname{Re} [E_0 e^{-i(kz - \omega t)}] \\
 &= \operatorname{Re} [E_0 e^{i \frac{(n+i\beta)2\pi z}{\lambda_0} - i\omega t}] \\
 &= e^{-\frac{2\pi z}{\lambda_0}} \operatorname{Re} [E_0 e^{i(kz - \omega t)}]
 \end{aligned}$$

So due to ~~some~~ conducting. No complex refractive index does not induce a phase difference since $n_{\text{rel}} \neq 1 + i\beta$

real Part $\boxed{\text{is}}$ part that accounts for phase change and that is 1.
 Therefore the phase change will be 0 for reflection.

$$\text{Ans 11)} \quad k = \frac{\omega}{c} \left(1 - \frac{\omega_p^2}{\omega^2 \left(1 + \frac{\epsilon v}{\omega} \right)} \right)^{1/2}$$

where $\omega_p = 1.01 \times 10^{12} \text{ Hz}$

and $\gamma = 10^7 \text{ Hz}$

a) case I : $\omega \ll \nu$

$$k^2 = \frac{\omega^2}{c^2} \left(1 - \frac{\omega_p^2}{\omega^2 \left(1 + \frac{\epsilon v}{\omega} \right)} \right) \approx \frac{\omega^2}{c^2} \frac{\omega_p^2}{\omega^2}$$

$$\Rightarrow k^2 = \frac{\omega_p}{c} \left(\frac{\omega}{\nu} \right)^{1/2} \left(1 + \frac{\epsilon}{\Sigma} \right) = k_{\text{real}}^2 + i k_{\text{imaginary}}$$

Skin depth :

$$\delta = \frac{1}{k_i} = \frac{c}{\omega_p} \left(\frac{2\nu}{\omega} \right)^{1/2}$$

Case II : $\nu \ll \omega \Rightarrow \frac{\nu}{\omega} \rightarrow 0$

$$\text{for } \omega < \omega_p \rightarrow k = \frac{\omega}{c} \left(1 - \frac{\omega_p^2}{\omega^2} \right)^{1/2} = i \propto$$

$$\text{where } \propto = \frac{\omega}{c} \left(\frac{\omega_p^2}{\omega^2} - 1 \right)^{1/2}$$

\therefore skin depth

$$\delta = \frac{1}{\propto} = \frac{c}{\sqrt{\omega_p^2 - \omega^2}}$$

b) i) $\omega = 10^3 \text{ rad/s} \ll \nu$

$$\Rightarrow S = \frac{C}{\omega_p} \left(\frac{2\nu}{\omega} \right)^{1/2}$$

$$= \frac{3 \times 10^8}{1.01 \times 10^{12}} \times \left(\frac{2 \times 10^7}{10^3} \right)^{1/2}$$

$$= \frac{3}{1.01} \times 10^{-4} \times \sqrt{2} \times 10^2$$

$$= \left(\frac{3\sqrt{2}}{1.01} \times 10^{-2} \right)$$

$$\approx 4.20 \times 10^{-2} \text{ m} \quad \underline{\text{Ans}}$$

ii) $\omega \gg \nu$
 (10^{12})

$$S = \frac{C}{\sqrt{\omega_p^2 - \omega^2}} = \frac{3 \times 10^8}{\sqrt{(1.01)^2 \times 10^{24} - (1)^2 \times 10^{24}}}$$

$$= \frac{3 \times 10^8}{10^{12} \sqrt{2.01 \times 0.01}}$$

$$= \frac{3 \times 10^8}{10^{12} \sqrt{2.01 \times 0.01}} = \frac{3 \times 10^{-4}}{10^{11} \sqrt{2.01}}$$

$$\approx 2.12 \times 10^{-3} \text{ m} \quad \underline{\text{Ans}}$$