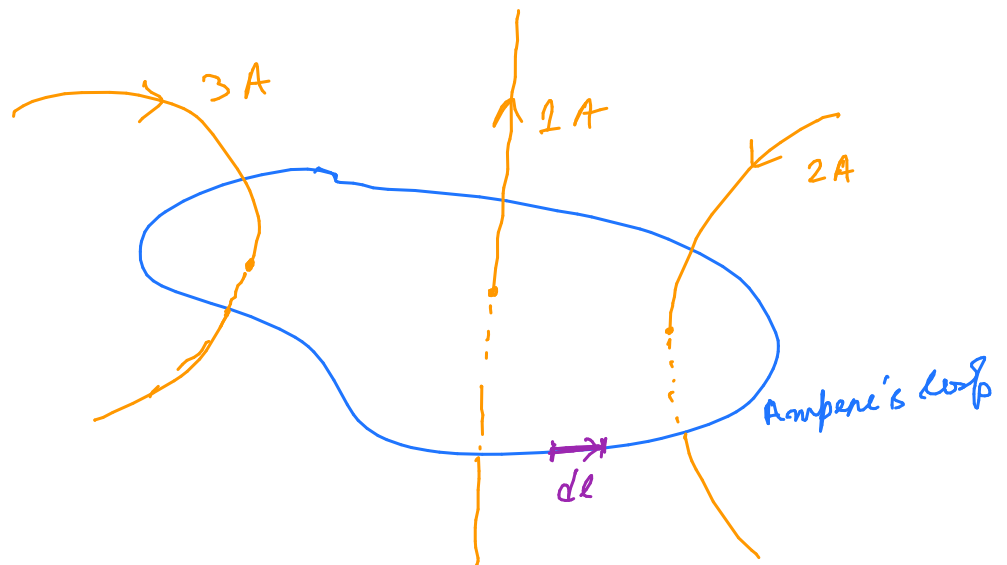
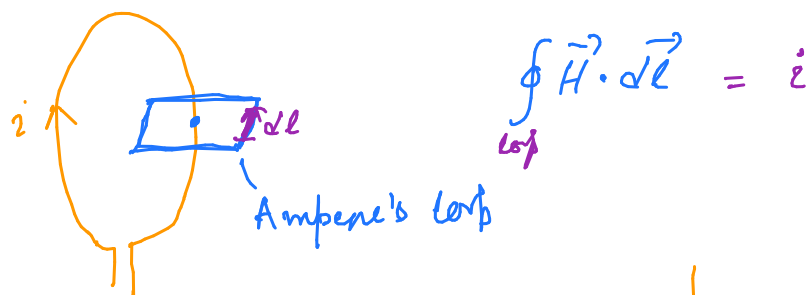


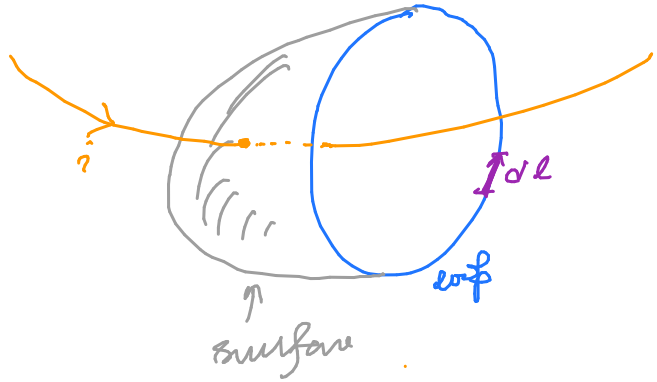
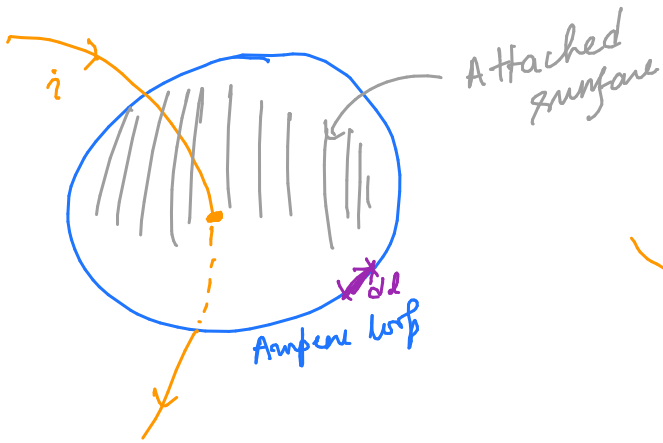
$$H = \frac{I}{2\pi R} \quad \checkmark$$

- Ampere's Law :

$$\oint_{\text{loop}} \vec{H} \cdot d\vec{\ell} = I_{\text{enclosed}}.$$

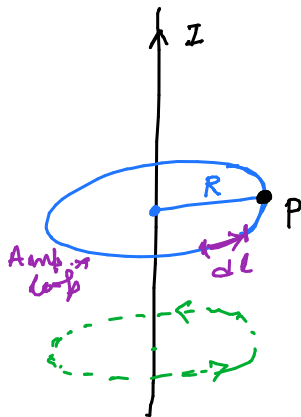


$$\oint_{\text{loop}} \vec{H} \cdot d\vec{\ell} = 3 + 2 - 1 = 4 \text{ A}.$$



✓ $\oint_{\text{loop}} \vec{H} \cdot d\vec{l} = I_{\text{penetrated}}$
 ↑
 through the surface (open)
 attached to the Ampere loop

- Ampere's law can be used to compute magnetic field intensity H by appropriately choosing the path.



$$\oint_{\text{loop}} \vec{H} \cdot d\vec{l} = I_{\text{enclosed}}$$

- H is constant over the entire path/loop that we have chosen

$$H \oint_{\text{loop}} d\vec{l} = I$$

$$\Rightarrow H(2\pi R) = I$$

$$\Rightarrow H = \frac{I}{2\pi R}$$

\oint_{loop} : loop integral

ML100

• Some guidelines to choose Ampere's path:

→ choose a loop s.t. the point of observation P lies on the loop

→ if possible, choose a loop s.t. the magnetic field intensity H is constant along the closed path.

→ if possible, choose a loop s.t. H is parallel to the loop & $d\vec{l}$ is in the same direction as \vec{H} .

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enc}}$$

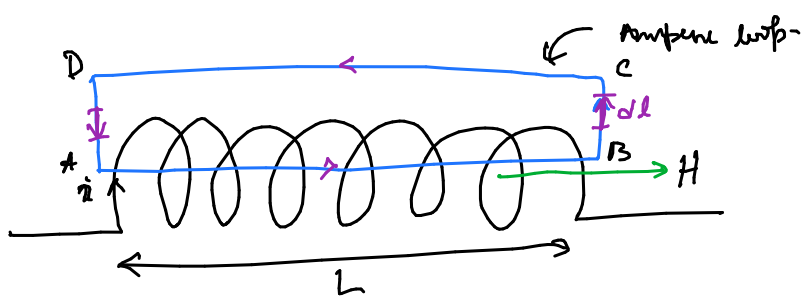
$$\Rightarrow \oint H dl = I_{\text{enc}} \quad (\text{since } \vec{H} \text{ \& } d\vec{l} \text{ are in same direction})$$

$$\Rightarrow H \oint dl = I_{\text{enc}} \quad (\text{since } H \text{ is const. over the entire closed path})$$

→ if possible, choose some on part of the closed path s.t. it is perpendicular to H .



→ choose a very simple path (circle or rectangle)



$$\oint_{\text{loop}} \vec{H} \cdot d\vec{l}$$

AB \rightarrow \vec{H} & $d\vec{l}$ are in same dirn't
H is constant.

BC \rightarrow \vec{H} & $d\vec{l}$ are perpendicular
 $\int_B^C \vec{H} \cdot d\vec{l} = 0$

CD \rightarrow Field intensity is almost zero

DA \rightarrow \vec{H} & $d\vec{l}$ are perpendicular

$$\oint_{\text{loop}} \vec{H} \cdot d\vec{l} = H \int_A^B dl = Ni \quad N : \text{Number of turns in the coil.}$$

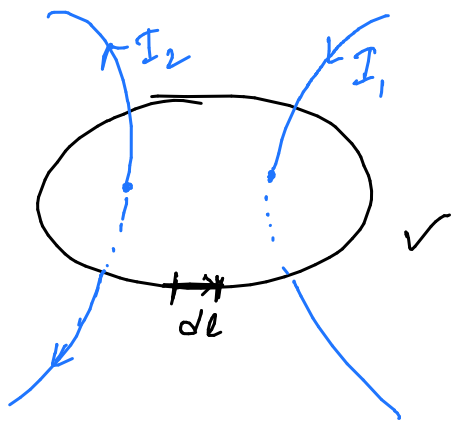
$$\Rightarrow HL = Ni$$

$$\Rightarrow H = \frac{N}{L} i$$

• For air B : Magnetic flux density

$$B = \mu_0 H$$

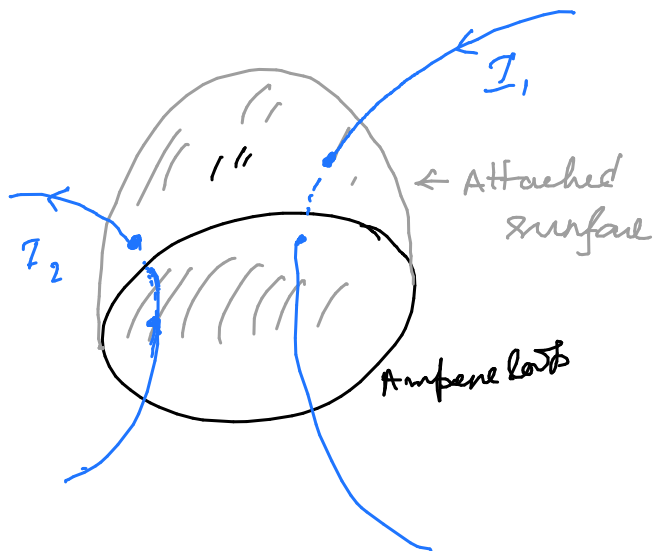
μ_0 : Permeability of free space.



$$\oint_{\text{loop}} \vec{H} \cdot d\vec{l} = I_{\text{enclosed}} \quad \checkmark$$

$$= I_{\text{penetrated}}$$

↑
th. the surface (open)
attached.

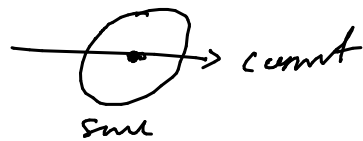


• Current density: J

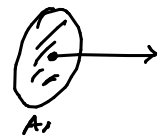
↑
current per unit
area.

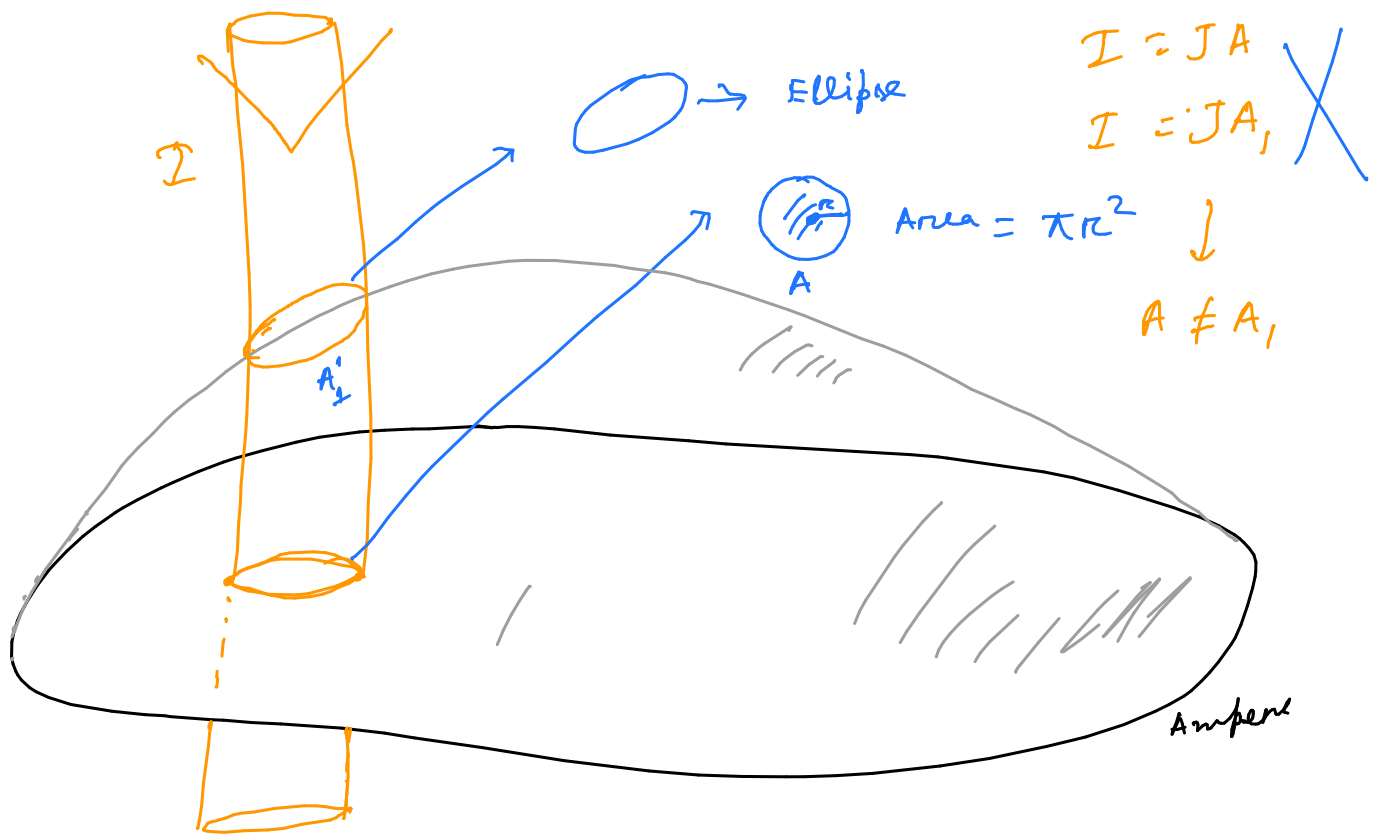


$$I = J A \quad (\text{Area of surface} = A)$$



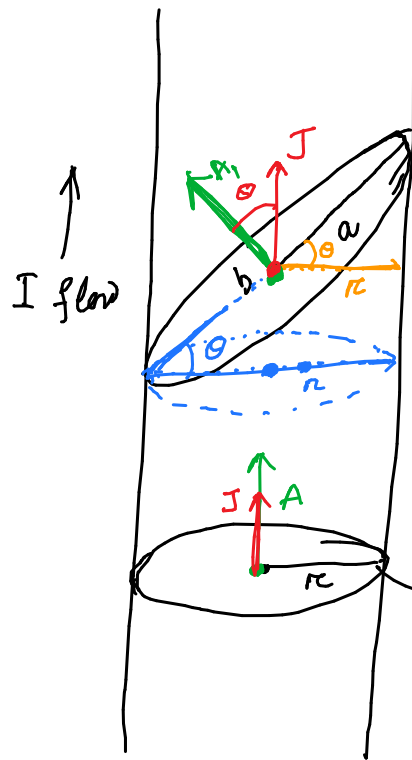
$$I = \vec{J} \cdot \vec{A}$$





$$\cos \theta = \frac{r}{a}$$

$$\Rightarrow a = \frac{r}{\cos \theta}$$



The area of ellipse
 $A_1 = \pi ab$

Circular.

The area of
 circle $A = \pi r^2$

For elliptical shape $b = r$
 $a = ?$

$$\begin{aligned} \text{The area of ellipse } A_1 &= \pi ab \\ &= \pi r \cdot r / \cos \theta \\ &= \frac{\pi r^2}{\cos \theta} = \frac{A}{\cos \theta} \end{aligned}$$

$$\boxed{A_1 = A / \cos \theta}$$

$$\checkmark I = \vec{J} \cdot \vec{A} = JA \cos \theta$$

For circular case $\theta = 0^\circ$

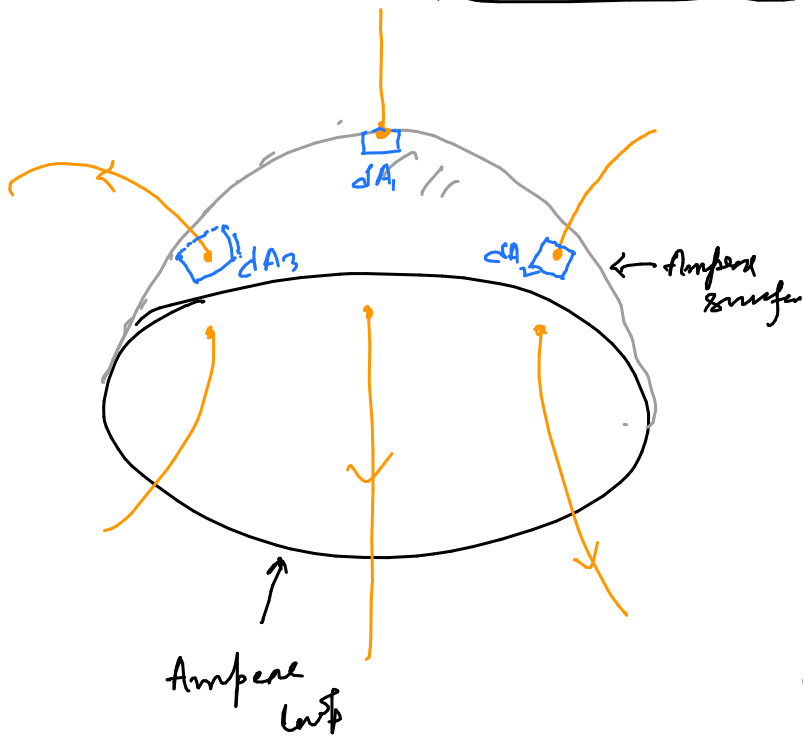
$$I = \underline{\underline{JA}} \quad \checkmark$$

For elliptical case

$$\checkmark I = \vec{J} \cdot \vec{A_1} = JA_1 \cos \theta = J \frac{A}{\cos \theta} \cos \theta$$

$$= \underline{\underline{JA}}$$

$$I = \vec{J} \cdot \vec{A}$$



partition the entire area with very small pieces dA

$$I_{\text{enclosed}} = \iint \vec{J} \cdot d\vec{A}$$

open surface integral

$$\begin{aligned} \oint \vec{H} \cdot d\vec{l} &= I_{\text{enclosed}} \\ &= I_{\text{penetrated}} \\ &= \iint_{\text{surface}} \vec{J} \cdot d\vec{A} \end{aligned}$$

$$\oint_{\text{closed loop}} \vec{H} \cdot d\vec{l} = \iint_{\text{open surface}} \vec{J} \cdot d\vec{A}$$

$$B = \mu_0 H$$

$$\oint_{\text{closed loop}} \vec{B} \cdot d\vec{l} = \mu_0 \iint_{\text{open surface}} \vec{J} \cdot d\vec{A}$$