

Higher Order Linear ODEs

ODE — Ordinary differential equation

Plan

- (i) Theory of existence & uniqueness of the solutions of second order linear ODEs
 - (ii) Methods to determine the general solution of homogeneous & non-homogeneous second order linear ODEs
- Extension to n^{th} order ODE ($n \geq 2$)

Prerequisite

- (i) Theory of first order ODEs
- (ii) Linear algebra

Reference Books

- (i) E. Kreyszig
- (ii) G. Simmons

n^{th} order linear ODE

$x \rightarrow$ dependent variable
 $t \rightarrow$ independent variable

The general form

$$\begin{aligned} \underline{x^{(n)}} + a_1(t) x^{(n-1)} + a_2(t) x^{(n-2)} + \dots + a_{n-1}(t) x'(t) \\ + a_n(t) x = f(t) \end{aligned} \quad \text{--- ①}$$
$$x' = \frac{dx}{dt}, \quad x'' = \frac{d^2x}{dt^2} \dots \quad x^{(n)} = \frac{d^n x}{dt^n}$$

In DE ①

- if the r.h.s. $f(t) \equiv 0$ then DE ① is called homogeneous o/w is called non-homogeneous.

$$\bullet \quad b_0(t) x^{(n)} + b_1(t) x^{(n-1)} + \dots + b_n(t) x = f(t)$$

where $b_0 \neq 0$, by dividing by $b_0(t)$, we get

$$x^{(n)} + \underbrace{\frac{b_1(t)}{b_0(t)}}_{a_1(t)} x^{(n-1)} + \dots + \underbrace{\frac{b_n(t)}{b_0(t)}}_{a_n(t)} x = \frac{f(t)}{b_0(t)}$$

$n=2$

Second order linear ODE

$$x'' + a_1(t)x' + a_2(t)x = \underline{f(t)} \quad \text{--- (2)}$$

Exps

$$(i) \quad x'' + x' = e^t \quad (\text{linear})$$

$$(ii) \quad x'' + e^t x' + t^3 x = \tan t \quad (\text{linear})$$

$$(iii) \quad x'' + e^t x' + t^2 x = \tan x \quad (\text{Nonlinear})$$

$$(iv) \quad x'' + \underline{x} x' = e^t \quad (\text{Non-linear})$$

$$(v) \quad x'' + t x' + \underline{x^2} = t^3 \quad (\text{Non-linear})$$

$$x \mapsto x'' + a_1(t)x' + a_2(t)x$$

$$L(x) := \underline{x''} + a_1(t)\underline{x'} + a_2(t)\underline{x} \quad \text{--- (3)}$$

L satisfies :

$$(i) \quad L(cx) = c L(x)$$

$$(ii) \quad L(x_1 + x_2) = L(x_1) + L(x_2)$$

}

We have

$$\begin{aligned} \bullet \quad L(cx) &= \underline{(cx)''} + a_1(t)(cx)' + a_2(t)(cx) \\ &= c(x'' + a_1(t)x' + a_2(t)x) \\ &= c L(x) \end{aligned}$$

$$\begin{aligned} \bullet \quad L(x_1 + x_2) &= (x_1 + x_2)'' + a_1(t)(x_1 + x_2)' + a_2(t)(x_1 + x_2) \\ &= \left. \begin{aligned} &x_1'' + a_1(t)x_1' + a_2(t)x_1 \\ &+ x_2'' + a_1(t)x_2' + a_2(t)x_2 \end{aligned} \right\} \\ &= L(x_1) + L(x_2) \end{aligned}$$

① & ② can be equivalently stated as

$$L(c_1x_1 + c_2x_2) = c_1 L(x_1) + c_2 L(x_2) \quad (\text{verify for ③})$$

Motivation

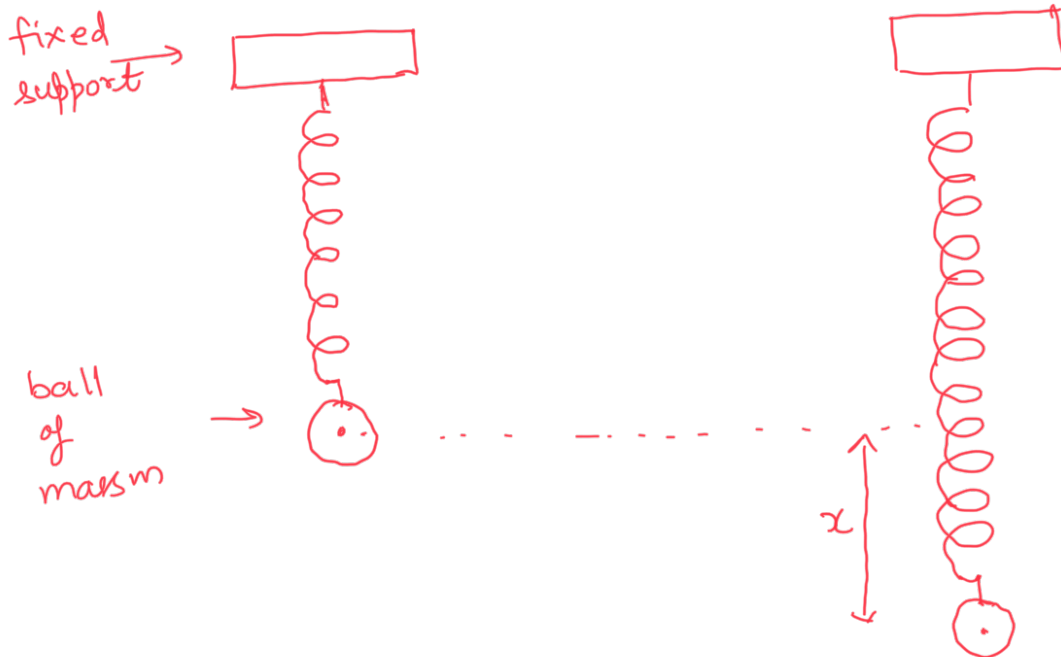
Expl (Vibration of a spring)

Suppose we have a coiled spring which is suspended vertically from a fixed support and

a ball of mass m is attached at its

a ball of mass

lower end.



The spring force

$$= -Kx = m \frac{d^2x}{dt^2}$$

where

$K > 0$ is a constant

By the Hooke's law
spring force
 \propto stretch in the
spring

$$\frac{d^2x}{dt^2} + \frac{K}{m}x = 0$$

Ex 2

(Bending of a beam)

Let's consider a homogeneous elastic beam of length L .



Now we apply a load on beam B in a vertical plane then beam gets bent.



Using the linear elasticity theory, the deflection of the beam is modelled by

$$\frac{d^4 y}{dx^4} = y''''(x) = c f(x)$$

(x -independent variable)

Homogeneous Linear Second order ODE's

IVP \rightarrow Initial value Problem

Consider

$$\text{IVP ①} \quad \begin{cases} x''(t) + a(t)x'(t) + b(t)x(t) = 0 \\ x(t_0) = \alpha \\ x'(t_0) = \beta \end{cases} \quad \text{--- ①}$$

α, β are given

Define

$$\underline{x_1(t) = x(t)}$$

$$\underline{x_2(t) = x'(t) = x'_1(t)}$$

then using ①

$$\begin{aligned}x_2'(t) &= x_1''(t) = -a(t)x_1'(t) - b(t)x_1(t) \\&= -a(t)x_2(t) - b(t)x_1(t)\end{aligned}$$

System
of
first
order ODE's

$$\left. \begin{aligned}x_1'(t) &= x_2(t) \\x_2'(t) &= -a(t)x_2(t) - b(t)x_1(t)\end{aligned} \right\} \text{--- ②}$$

② can be rewritten as

$$\begin{bmatrix} x_1'(t) \\ x_2'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -b(t) & -a(t) \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

Define $X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$ then last system can be written as

$$\boxed{X'(t) = A X(t)}$$

--- ③

where

$$A = \begin{bmatrix} 0 & 1 \\ -b(t) & -a(t) \end{bmatrix}$$

Recall

first order ODE

$$x' = f(t, x)$$

initial condition

$$x(t_0) = x_0$$

likewise for ③

$$\begin{bmatrix} x_1(t_0) \\ x_2(t_0) \end{bmatrix} = X(t_0) = X_0 = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

$$x(t_0) = x_1(t_0) = \alpha$$

$$x'(t_0) = x_2(t_0) = \beta$$

$$\underline{x'' + a_1(t)x' + a_2(t)x = 0}$$

Defⁿ

A function $x = h(t)$ is said to be a solⁿ of 2nd order ODE ① on some ^{open} interval I if h is twice differentiable in I & it satisfies the DE ①.

Theorem 1 (Existence & Uniqueness theorem)

If $a(t)$ & $b(t)$ are bounded and continuous function on some open interval I then IVP

$$x'' + a(t)x' + b(t)x = 0$$

$$x(t_0) = \alpha, x'(t_0) = \beta, \quad t_0 \in I$$

has a unique solution on I , with given $\alpha, \beta \in \mathbb{R}$.

Exercise Discuss the existence & uniqueness of the solⁿ of the IVP

$$x''(t) + \cos(t) x'(t) + x(t) = 0, t \in (0,1)$$

$$x(1/2) = 0, x'(1/2) = 1$$

Defⁿ (General solⁿ)

A solⁿ of a linear ODE is called a general solution if it involves as many arbitrary constants as the order of DE.

Exp Solve $x''(t) - x(t) = 0$ — (4)

$$\checkmark x_1(t) = e^t$$

$$x_1'' = e^t = x_1$$

$$\checkmark x_2(t) = e^{-t}$$

$$x_2'' = e^{-t} = x_2$$

x_1 & x_2 are solⁿs of (4)

And

$$\checkmark x(t) = c_1 x_1(t) + c_2 x_2(t)$$

$$\boxed{x(t) = c_1 e^t + c_2 e^{-t}}$$

is also a solⁿ of (1)

c_1, c_2
→ arbitrary constant

general solⁿ of (4) since it involves two arbitrary constants.

Observations

- ① If $x_1(t)$ & $x_2(t)$ are two solⁿ of the given 2nd order linear ODE then their linear combination is also a solⁿ of the same DE.
- ② We could get the general solⁿ of the ODE if we could get hold on two suitable solⁿ of same ODE.

Consider
$$x''(t) + a(t)x'(t) + b(t)x(t) = 0$$
 — (5)

Thm 2 If $x_1(t)$ & $x_2(t)$ are two solutions of ODE (5) then $c_1x_1(t) + c_2x_2(t)$ is also a solⁿ of ODE (5) for any constants c_1 & c_2 .

Proof $x_1(t)$ & $x_2(t)$ are solⁿs of DE (5), therefore $x_1(t)$ & $x_2(t)$ satisfies

$$x_1'' + a(t)x_1' + b(t)x_1 = 0 \quad \checkmark$$

$$x_2'' + a(t)x_2' + b(t)x_2 = 0 \quad \checkmark$$

set

$$\underline{y(t) = c_1 x_1 + c_2 x_2} \quad \text{--- (6)}$$

We have

$$y''(t) + a(t)y'(t) + b(t)y(t)$$

$$= (c_1 x_1 + c_2 x_2)'' + a(t)(c_1 x_1 + c_2 x_2)' + b(t)(c_1 x_1 + c_2 x_2)$$

$$= c_1 \underbrace{(x_1'' + a(t)x_1' + b(t)x_1)}_0 + c_2 \underbrace{(x_2'' + a(t)x_2' + b(t)x_2)}_0$$

$$= 0$$

$\Rightarrow y(t)$ is also a solⁿ of ODE (5)

Remark. If we can get hold of any two solⁿs $x_1(t)$ & $x_2(t)$ of DE (5) then

(6) provides another solⁿ of DE (5) which involves two arbitrary constants so it may be the general solⁿ of ODE (5).

* Does linear combination of any two sol's of ODE (5) yields the general solⁿ?

No

if either $x_1(t)$ or $x_2(t)$ is a constant multiple of the other, say

$$\underline{x_1(t) = K x_2(t)} \quad , K \rightarrow \text{constant}$$

$$\begin{aligned} \underbrace{c_1 x_1(t) + c_2 x_2(t)} &= c_1 K x_2(t) + c_2 x_2(t) \\ &= (c_1 + K c_2) x_2(t) \\ &= \underline{d x_2(t)} \end{aligned}$$

hence no more the general solⁿ of ODE (5)

RK If neither x_1 nor x_2 is constant multiple of other then $c_1 x_1(t) + c_2 x_2(t)$ will be a general solⁿ of ODE (5).

Linear Dependence & linear independence of function

We call $x_1(t)$ & $x_2(t)$ linearly dependent (L.D.) in some interval I if there exists constants c_1 & c_2 not both zero s.t.

$$\underbrace{c_1 x_1(t) + c_2 x_2(t)} = 0 \quad \forall t \in I$$

* $x_1(t)$ & $x_2(t)$ are linearly independent (L.I.) if there are no such non-trivial constants c_1 & c_2 which means if we consider

$$c_1 x_1(t) + c_2 x_2(t) = 0 \quad \Rightarrow \quad c_1 = 0, c_2 = 0.$$

* Suppose $x_1(t)$ & $x_2(t)$ are L.D.

$\Rightarrow \exists$ constants c_1, c_2 not both zero s.t.

$$c_1 x_1 + c_2 x_2 = 0 \quad \text{--- (7)}$$

. If $c_1 \neq 0$ then upon dividing (7) by c_1 , we get

$$x_1(t) = \underbrace{-\frac{c_2}{c_1}}_K x_2(t) = K x_2(t) \text{ on } I$$

• If $c_2 \neq 0$ then (7) yields

$$x_2(t) = -\underbrace{\frac{c_1}{c_2}}_l x_1(t) = l x_1(t) \text{ on } I$$

\Rightarrow If $x_1(t)$ & $x_2(t)$ are L.I. then either $x_1(t)$ or $x_2(t)$ can be written as a constant multiple of other.

Ex show that e^t & $\cos t$ are L.I. on any interval.

solⁿ

$$c_1 e^t + c_2 \cos t = 0 \quad \forall t \in \underline{\underline{\left[-\frac{\pi}{2}, \frac{\pi}{2}\right] = I}}$$

$$\left. \begin{array}{l} \text{for } t=0, \quad c_1 + c_2 = 0 \\ t = \pi/2, \quad c_1 e^{\pi/2} = 0 \end{array} \right\} c_1 = 0, c_2 = 0$$

$\Rightarrow e^t$ & $\cos t$ are L.I.

Exer show that e^t , e^{t+2} & $\sin t$ are L.I. on any interval.

Defⁿ

The Wronskian of two f's $x_1(t)$ & $x_2(t)$ is given by

$$W(x_1, x_2)(t) = \begin{vmatrix} x_1(t) & x_2(t) \\ x_1'(t) & x_2'(t) \end{vmatrix} = x_1(t)x_2'(t) - x_1'(t)x_2(t)$$

Thm 3

Suppose $x_1(t)$ & $x_2(t)$ are L.D. & sufficiently differentiable f's then

$$W(x_1, x_2)(t) = 0 \quad .$$