

Laplace Transforms

Lecture 33



Connection between Laplace and Fourier Transform

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$s = \sigma + j\omega \quad X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$X(j\omega) = X(s) \big|_{s=j\omega} = \mathfrak{F}\{x(t)\} = X(\omega)$$

$$X(j\omega) = \mathfrak{F}\{x(t)\}$$

New notation



Connection between Laplace and Fourier Transform

$$X(s) \big|_{s=j\omega} = X(j\omega)$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-(\sigma + j\omega)t} dt$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-\sigma t} e^{-j\omega t} dt$$

$$X(s) = \mathfrak{F}\{x(t) e^{-\sigma t}\}$$

\mathcal{L} may converge when \mathfrak{F} does not



Difference between Laplace and Fourier Transform

- $X(s) = \mathbb{F}\{x(t)e^{-\sigma t}\}$
 - In Laplace transforms, we play with σ to achieve convergence
 - In Fourier transforms, we allowed impulses.



Inverse Laplace Transform

$$x(t)e^{-\sigma t} = \mathcal{F}^{-1}\{X(s)\}$$

$$x(t)e^{-\sigma t} = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(s)e^{j\omega t} d\omega$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(s)e^{(\sigma+j\omega)t} d\omega$$

$$x(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} X(s)e^{st} ds$$



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Example 9.1

$$x(t) = e^{-at}u(t)$$

$$X(s) = \int_{-\infty}^{\infty} e^{-at}u(t)e^{-st}dt$$

$$X(s) = \int_0^{\infty} e^{-at}e^{-st}dt$$

$$X(s) = \int_0^{\infty} e^{-(s+a)t}dt$$

$$\begin{aligned} X(s) &= \frac{-1}{s+a} [e^{-(s+a)t}]_0^{\infty} \\ &= \frac{-1}{s+a} [0 - 1] = \frac{1}{s+a} \end{aligned}$$



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$$X(s) = \int_0^{\infty} e^{-(\sigma + j\omega + a)t}dt$$

$$= \int_0^{\infty} e^{-(\sigma + a)t} e^{-j\omega t}dt$$

$$\operatorname{Re}\{s\} > -a$$



Example 9.1

$$e^{-at}u(t) \xleftrightarrow{\mathcal{L}} \frac{1}{s+a}$$

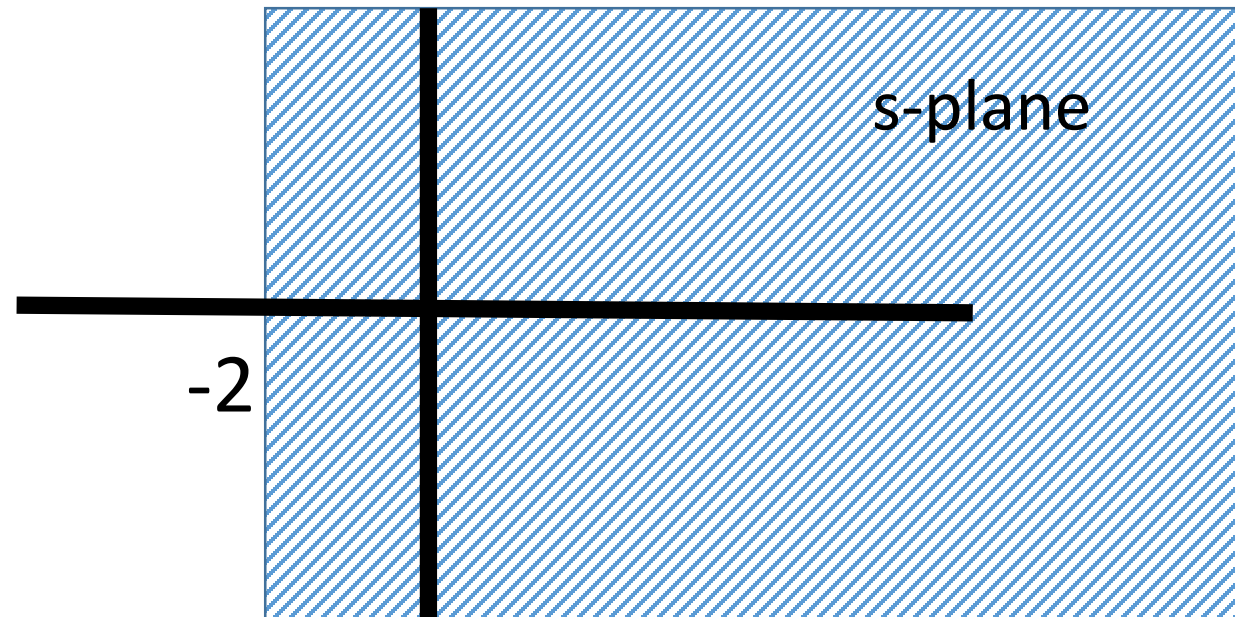
$$\operatorname{Re}\{s\} > -a$$



Example 9.1

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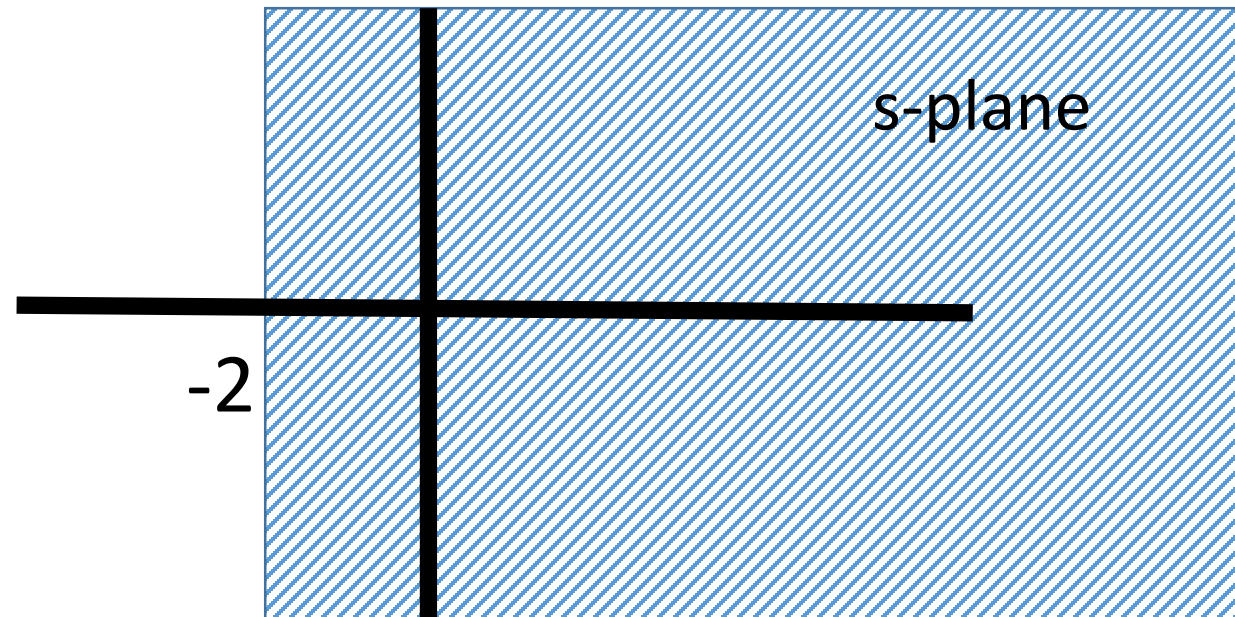
If $a = 2$



Example 9.1

$$e^{-at}u(t) \xleftrightarrow{\mathcal{L}} \frac{1}{s+a} \quad \text{Re}\{s\} > -a$$

If $a = 2$



ROC (Region of Convergence)



Example 9.2

$$x(t) = -e^{-at}u(-t)$$

$$X(s) = \int_{-\infty}^{\infty} -e^{-at}u(-t)e^{-st}dt$$

$$X(s) = \int_0^{-\infty} e^{-at}e^{-st}dt$$

$$X(s) = \int_0^{-\infty} e^{-(s+a)t}dt$$

$$X(s) = \frac{-1}{s+a} [e^{-(s+a)t}]_0^{-\infty}$$

$$= \frac{-1}{s+a} [0 - 1] = \frac{1}{s+a}$$



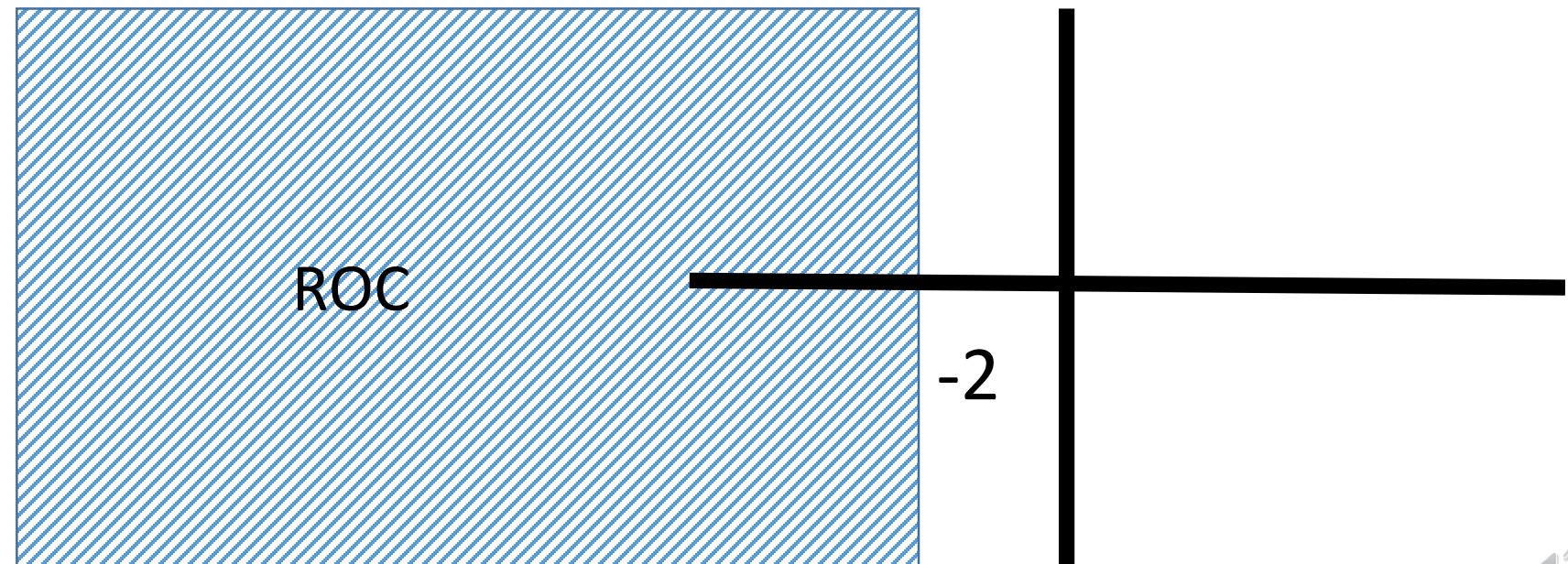
Example 9.2

$$-e^{-at}u(-t) \xleftrightarrow{\mathcal{L}} \frac{1}{s+a}$$

$$a + \sigma < 0$$

$$\sigma < -a$$

$$\operatorname{Re}\{s\} < -a$$



Importance of ROC

$$e^{-at}u(t) \xleftrightarrow{\mathcal{L}} \frac{1}{s+a} \quad \text{Re}\{s\} > -a$$

$$-e^{-at}u(-t) \xleftrightarrow{\mathcal{L}} \frac{1}{s+a} \quad \text{Re}\{s\} < -a$$



Importance of ROC

$$\underbrace{e^{-at}u(t)} \xleftrightarrow{\mathcal{L}} \frac{1}{s+a} \quad \underbrace{\operatorname{Re}\{s\} > -a}$$

right

right

$$\underbrace{-e^{-at}u(-t)} \xleftrightarrow{\mathcal{L}} \frac{1}{s+a} \quad \underbrace{\operatorname{Re}\{s\} < -a}$$

left

left



Example 9.3

$$e^{-t}u(t) + e^{-2t}u(t) \quad \xleftrightarrow{\mathcal{L}} \quad \frac{1}{s+1}$$



Example 9.3

$$e^{-t}u(t) + e^{-2t}u(t) \quad \xleftrightarrow{\mathcal{L}} \quad \frac{1}{s+1}$$

$$\operatorname{Re}\{s\} > -1$$



Example 9.3

$$e^{-t}u(t) + e^{-2t}u(t) \quad \xleftrightarrow{\mathcal{L}} \quad \frac{1}{s+1} +$$

$$\operatorname{Re}\{s\} > -1$$



Example 9.3

$$e^{-t}u(t) + e^{-2t}u(t) \quad \xleftrightarrow{\mathcal{L}} \quad \frac{1}{s+1} + \frac{1}{s+2}$$

$$\operatorname{Re}\{s\} > -1 \quad \& \quad \operatorname{Re}\{s\} > -2$$



Example 9.3

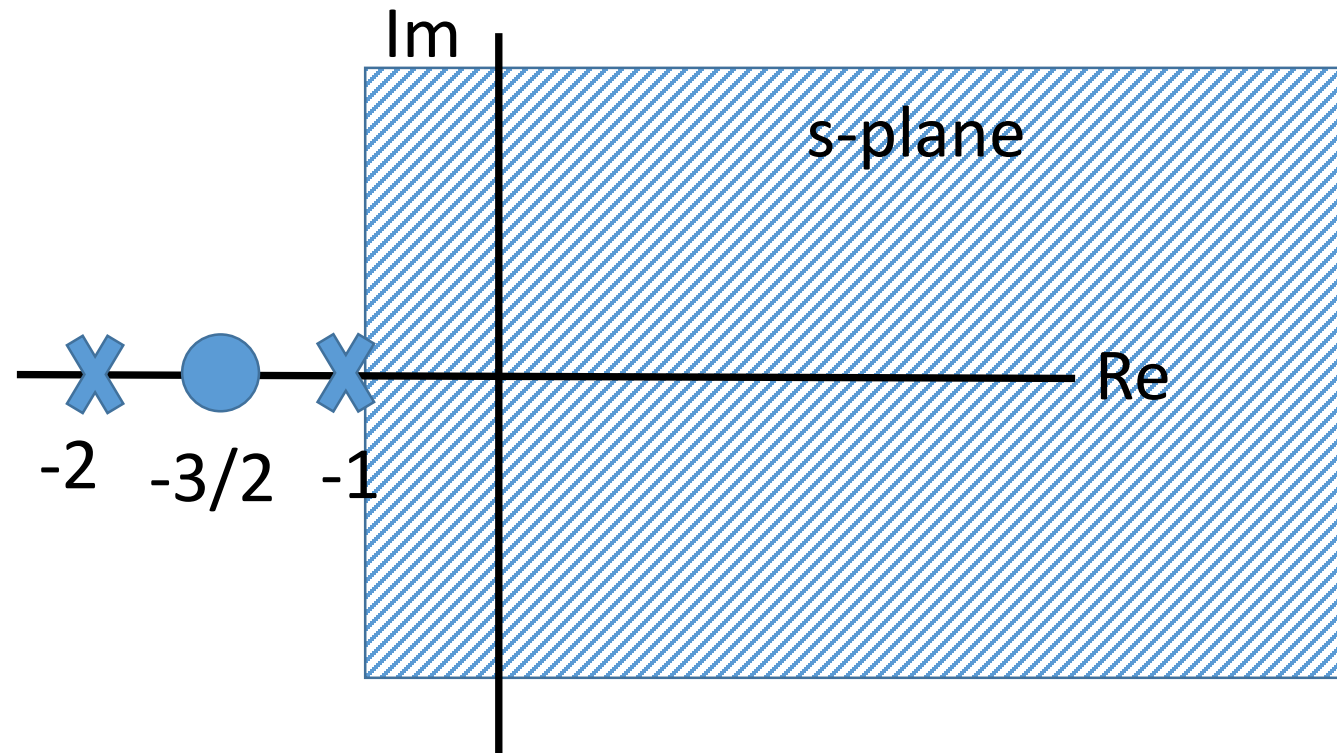
$$e^{-t}u(t) + e^{-2t}u(t) \quad \xleftrightarrow{\mathcal{L}} \quad \frac{2s + 3}{(s + 1)(s + 2)}$$

$$\operatorname{Re}\{s\} > -1$$



Example 9.3

$$e^{-t}u(t) + e^{-2t}u(t) \xleftrightarrow{\mathcal{L}} \frac{2s+3}{(s+1)(s+2)} \quad \text{Re}\{s\} > -1$$



Laplace transform as a rational function

$$X(s) = \frac{N(s)}{D(s)}$$

Describe linear-constant coefficient differential equation

$$N(s) = 0 \quad \text{Zeros of } X(s)$$

$$D(s) = 0 \quad \text{Poles of } X(s)$$

ROC does not contain poles



Properties of the Region of Convergence

- The ROC contains no poles

$$X(s) = \frac{N(s)}{D(s)}$$

Poles of $X(s)$ are where $D(s) = 0$



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- The ROC of $X(s)$ consists of a strip parallel to the $j\omega$ -axis in the s -plane



Properties of the Region of Convergence

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$$X(s) = \frac{N(s)}{D(s)}$$

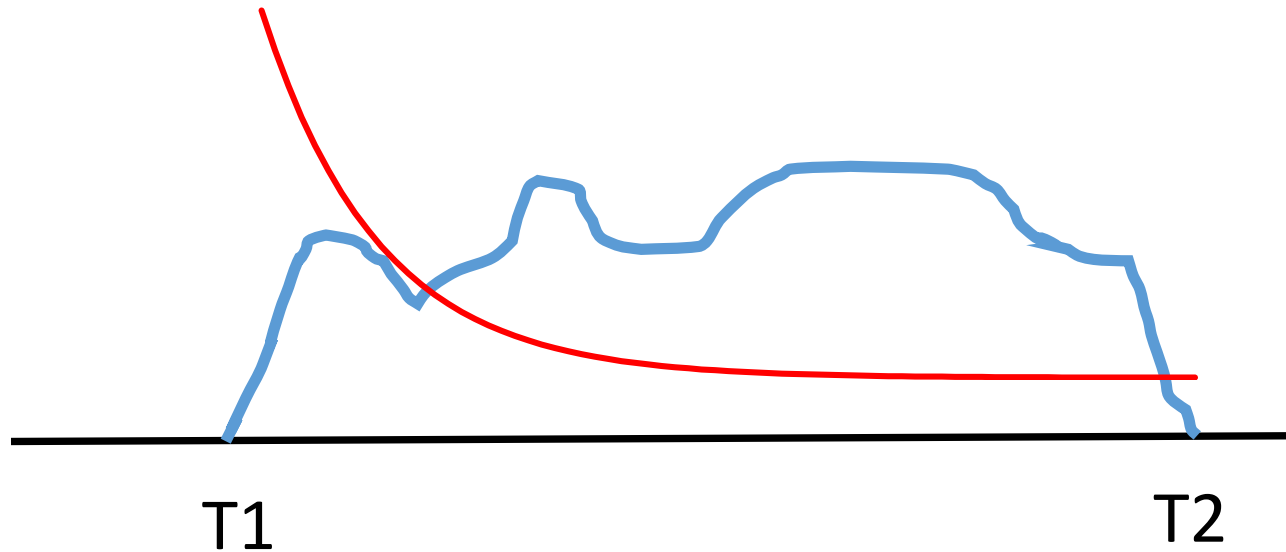
Poles of $X(s)$ are where $D(s) = 0$

- The ROC of $X(s)$ consists of a strip parallel to the $j\omega$ -axis in the s -plane
- $\mathcal{F}\{x(t)\}$ converges implies ROC includes the $j\omega$ -axis in the s -plane



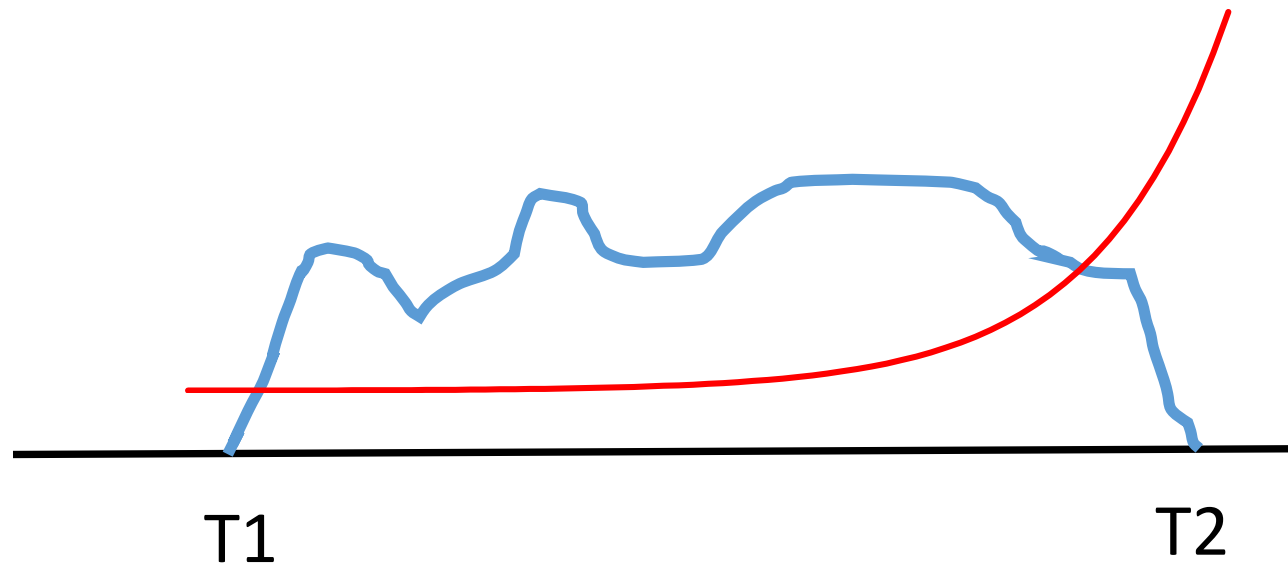
Properties of the Region of Convergence

- If $x(t)$ is of finite duration
 - -ROC is entire s-plane



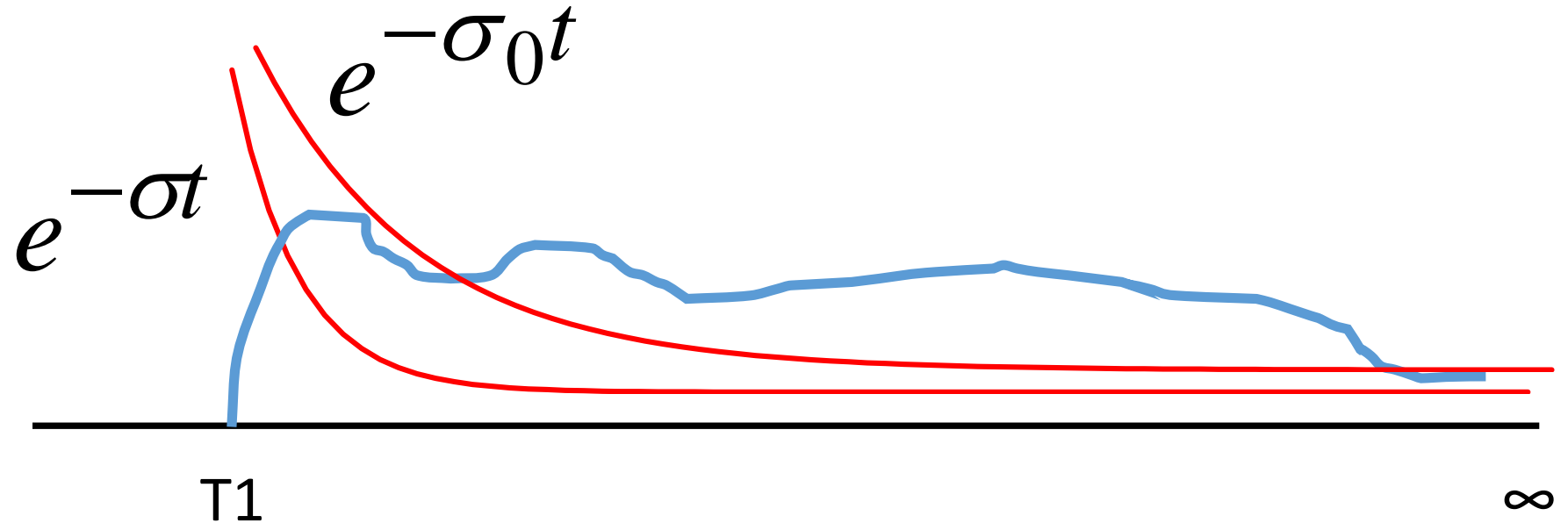
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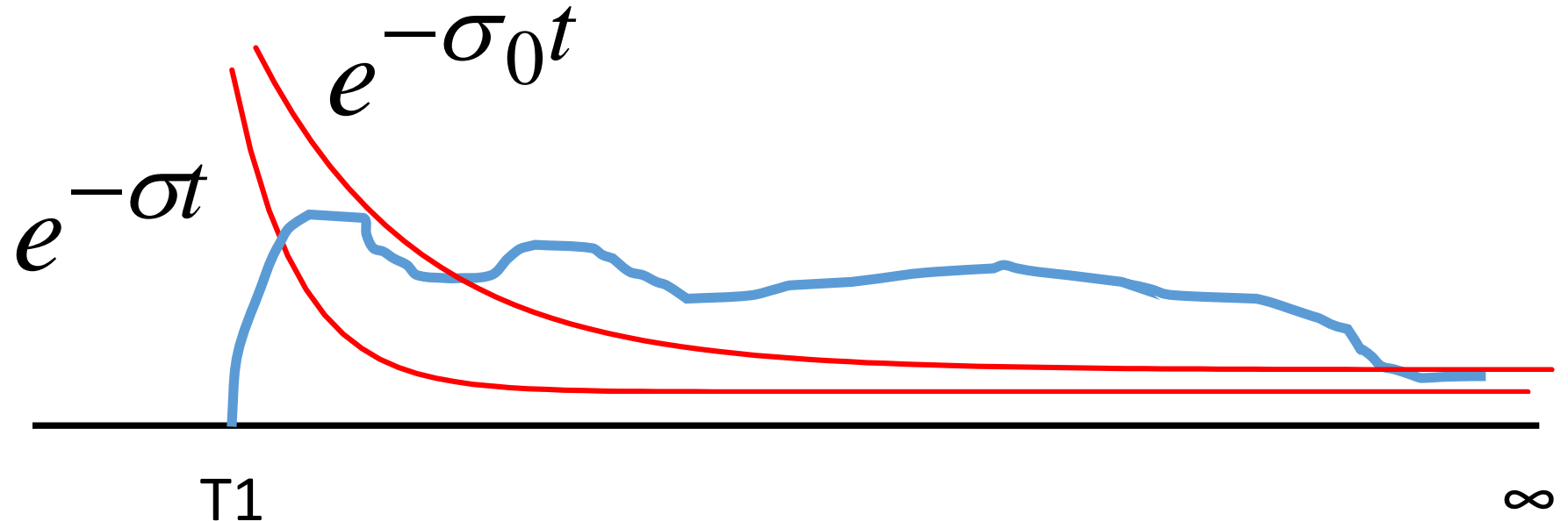
Properties of the Region of Convergence

- If $x(t)$ is right-sided
 - -If σ_0 is in ROC, then $\sigma > \sigma_0$ is also in ROC



Properties of the Region of Convergence

- If $x(t)$ is right-sided
 - -If σ_0 is in ROC, then $\sigma > \sigma_0$ is also in ROC



- If $x(t)$ is right-sided and $X(s)$ is rational
 - -ROC lies to the right of the rightmost pole



Properties of the Region of Convergence

- If $x(t)$ is left-sided and $\text{Re}\{s\} = \sigma_0$ is in ROC
 - -all values for which $\text{Re}\{s\} < \sigma_0$ are in ROC



Properties of the Region of Convergence

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Properties of the Region of Convergence

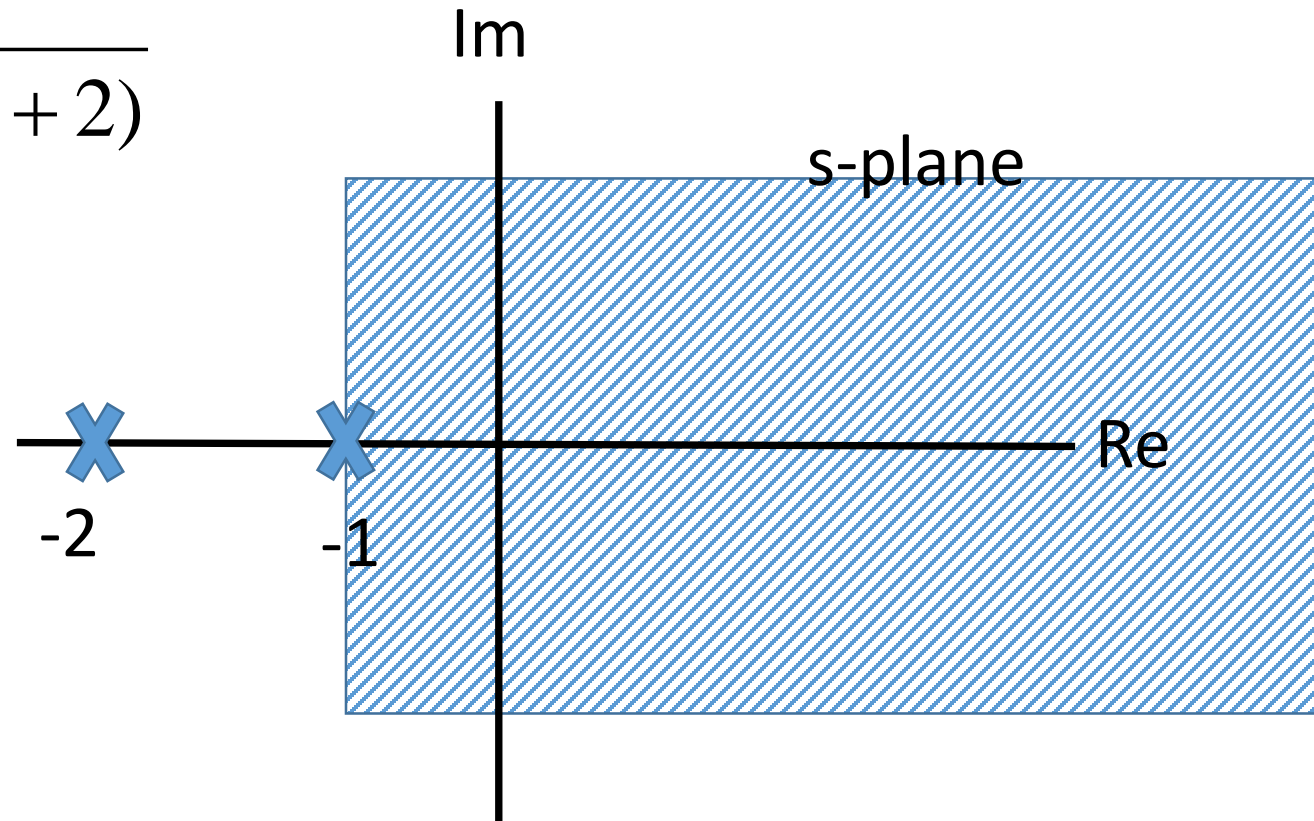
- If $x(t)$ is left-sided and $\text{Re}\{s\} = \sigma_0$ is in ROC
 - -all values for which $\text{Re}\{s\} < \sigma_0$ are in ROC
- If $x(t)$ is left-sided and $X(s)$ is rational
 - -ROC lies to the left of the leftmost pole
- If $x(t)$ is two-sided and $\text{Re}\{s\} = \sigma_0$ is in ROC
 - -ROC is a strip in the s-plane



Properties of the Region of Convergence

- The ROC is a connected region
 - It cannot have multiple strips

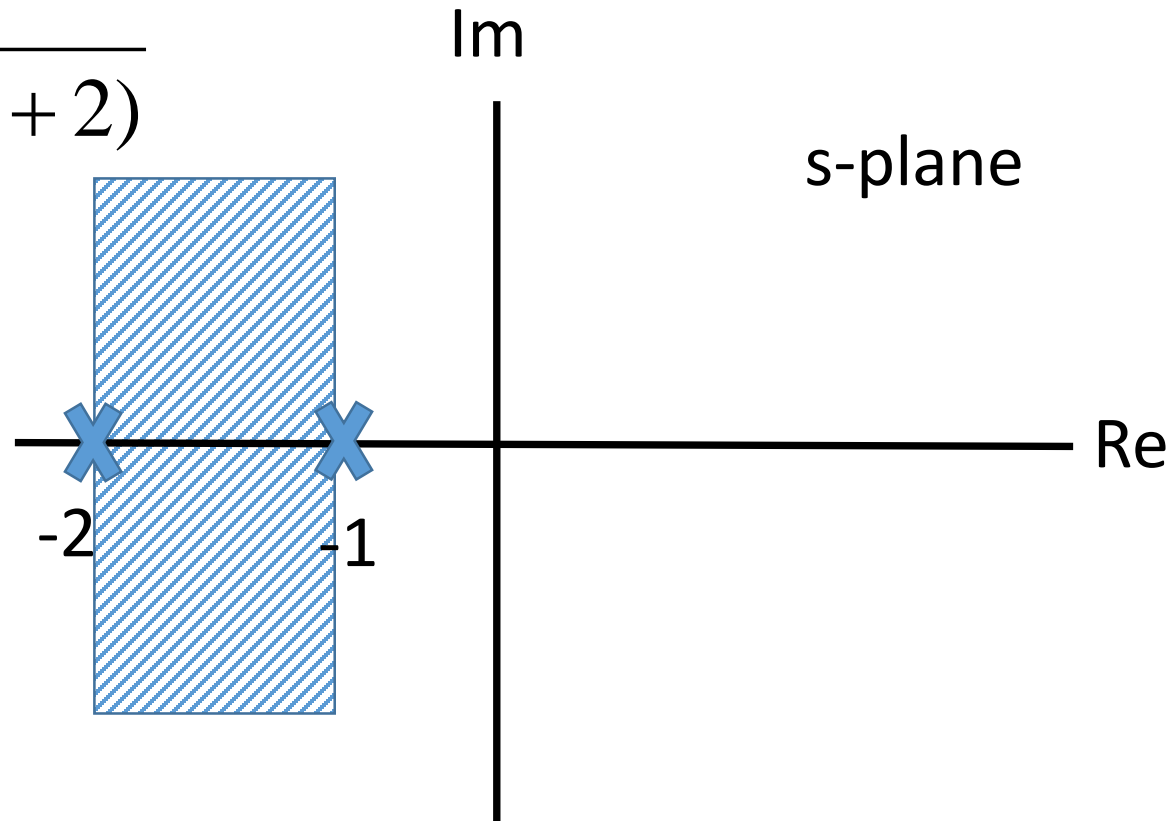
$$X(s) = \frac{1}{(s+1)(s+2)}$$



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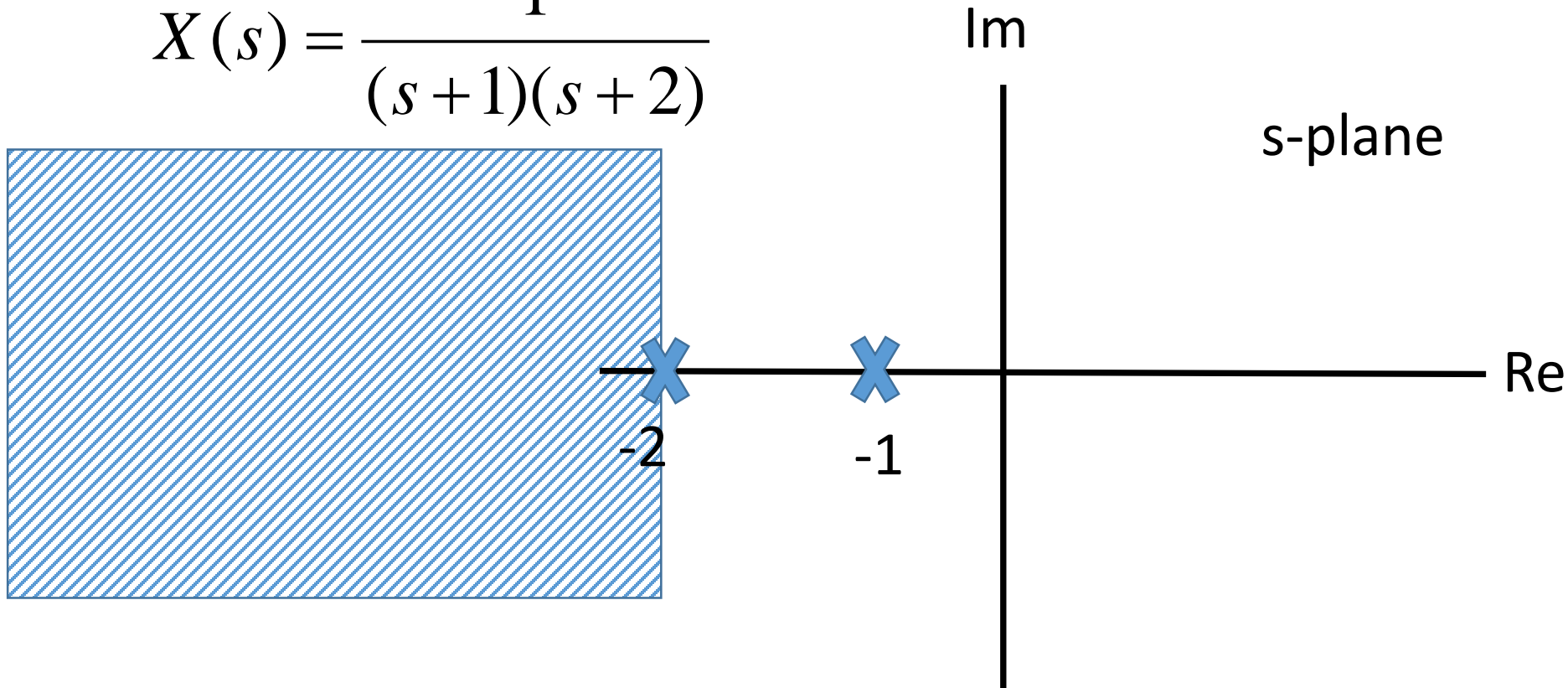
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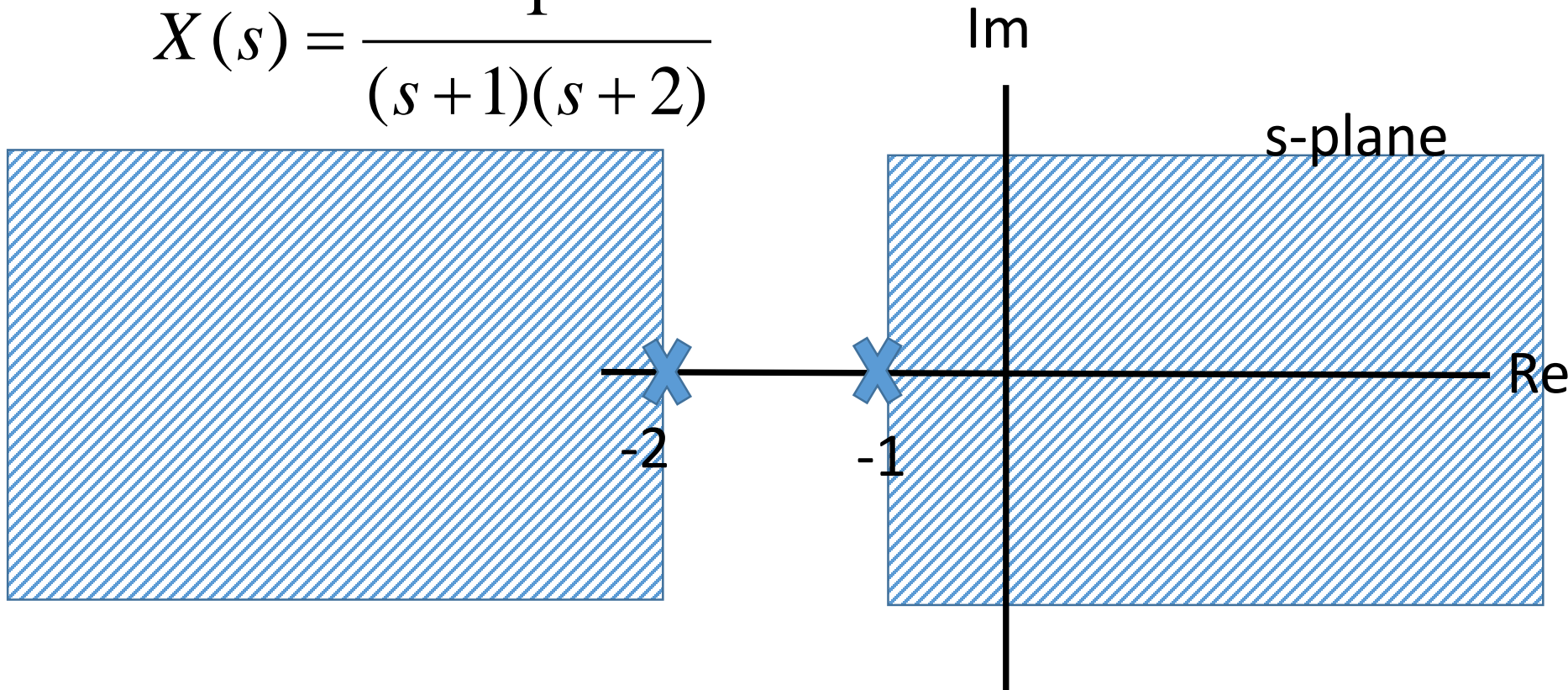
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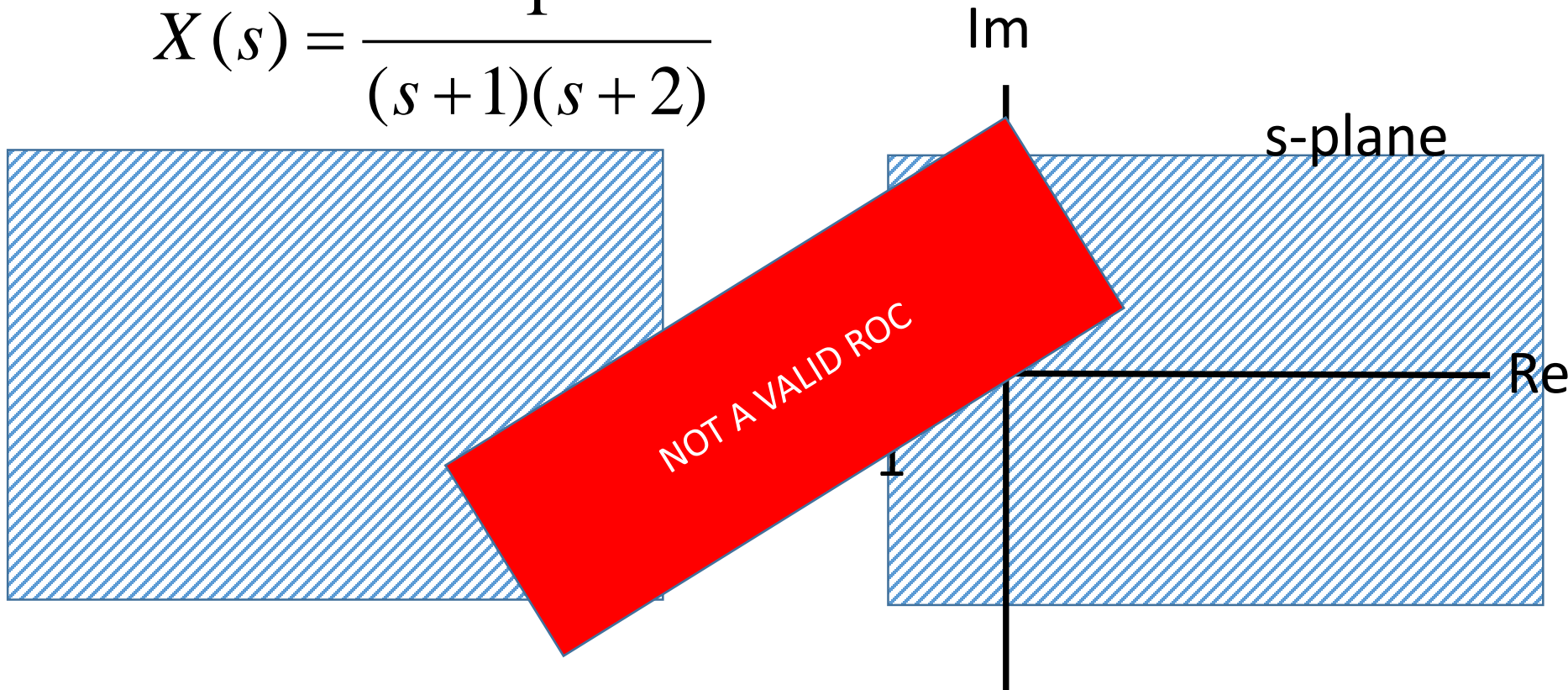
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Properties of the Region of Convergence

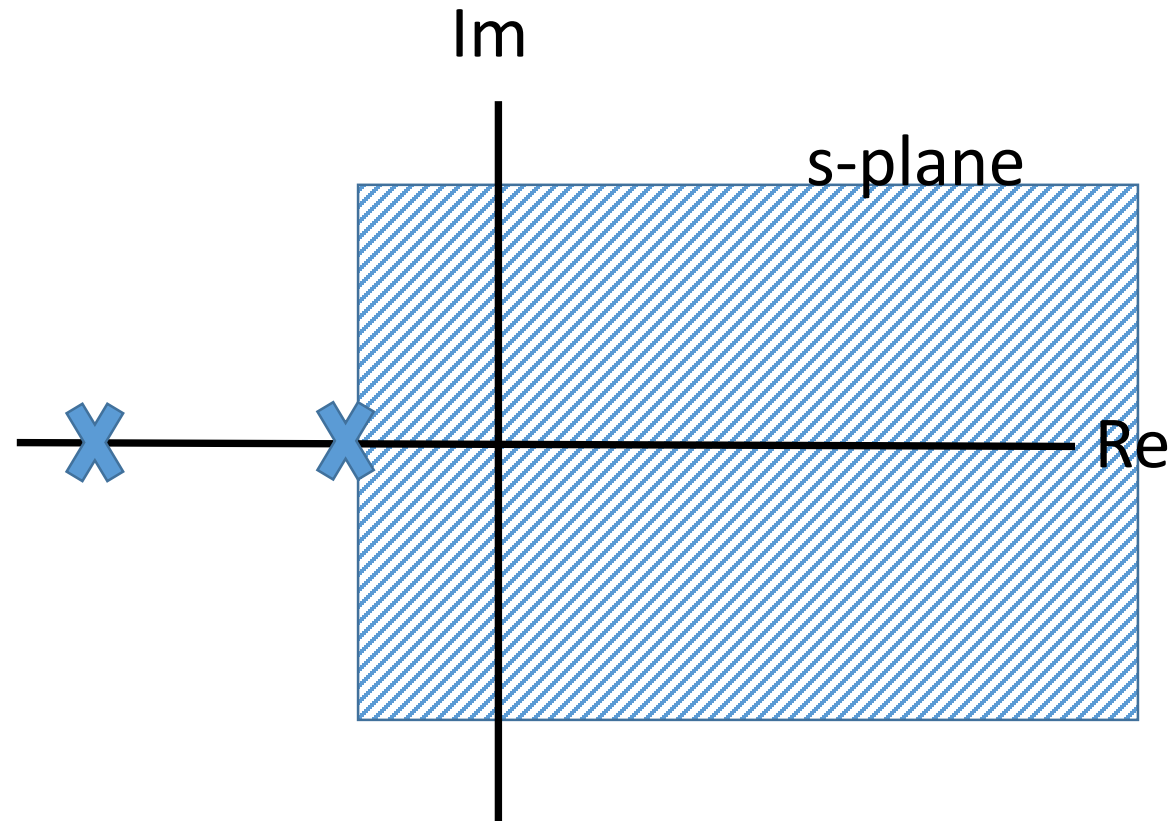
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$$X(s) = \frac{1}{(s+1)(s+2)}$$



Inverse Laplace Transform

$$X(s) = \frac{1}{(s+1)(s+2)}$$



- | | |
|-----|--------------------------------------|
| I | $x(t) = e^{-t}u(t) - e^{-2t}u(t)$ |
| II | $x(t) = -e^{-t}u(-t) - e^{-2t}u(t)$ |
| III | $x(t) = e^{-t}u(t) - e^{-2t}u(-t)$ |
| IV | $x(t) = -e^{-t}u(-t) + e^{-2t}u(-t)$ |



Inverse Laplace Transform

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Im

s-plane

Re

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Inverse Laplace Transform

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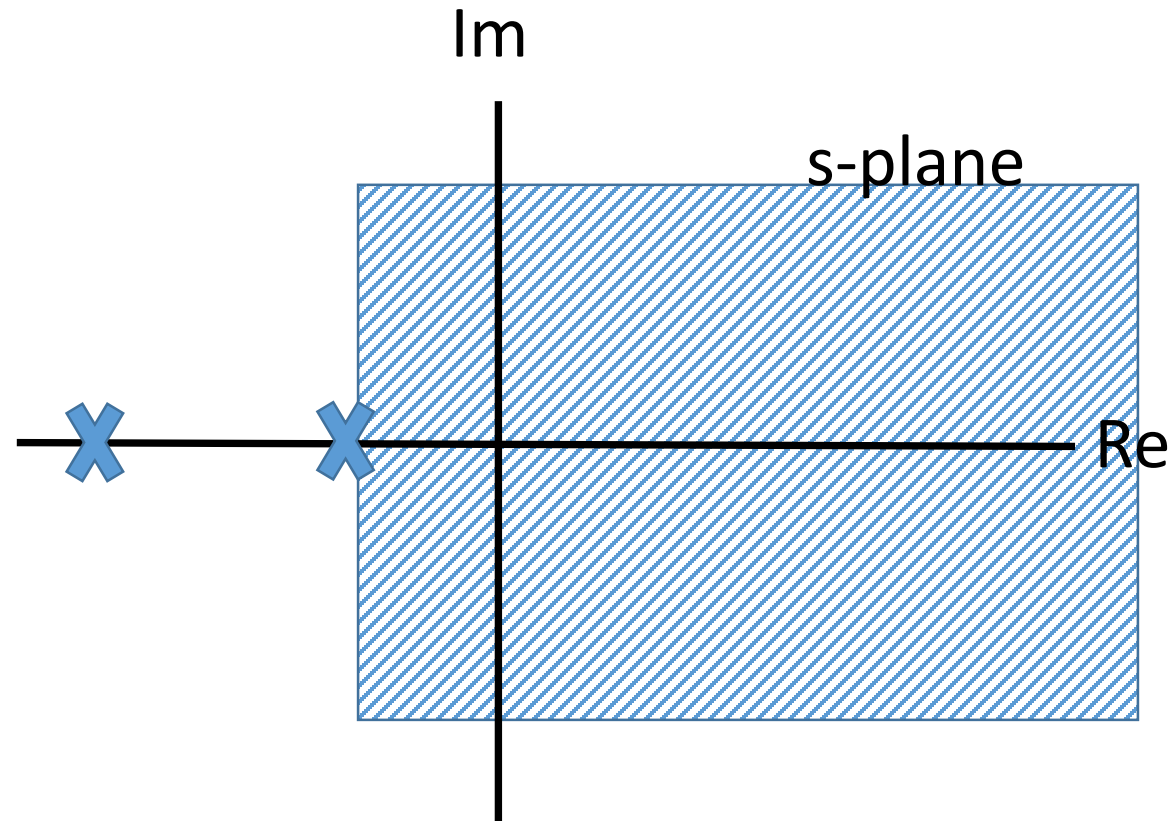
$$X(s) = \frac{A}{s+1} + \frac{B}{s+2}$$

$$(s+2)A + (s+1)B = 1$$

$$s(A+B) + 2A + B = 1$$

$$A + B = 0 \quad 2A + B = 1$$

$$A = 1 \quad B = -1$$

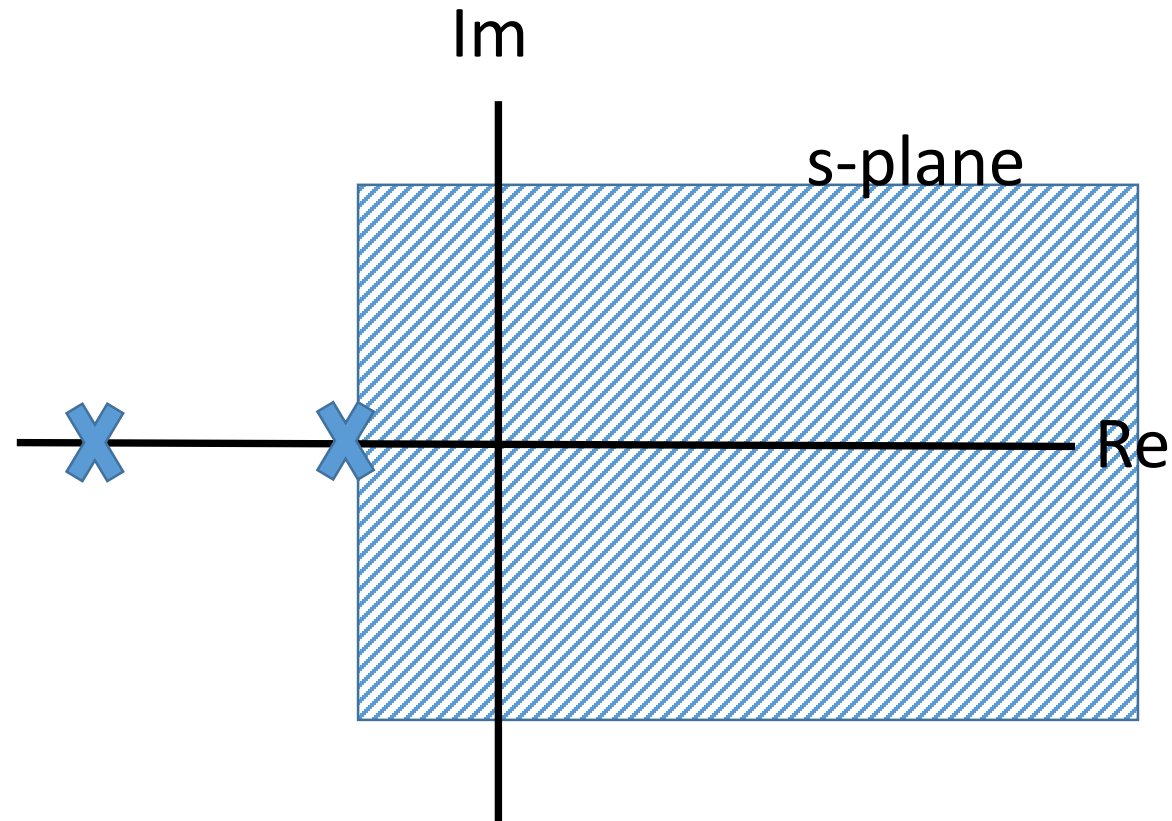


Inverse Laplace Transform

$$X(s) = \frac{1}{(s+1)(s+2)}$$

$$X(s) = \frac{1}{s+1} - \frac{1}{s+2}$$

$$x(t) = e^{-t}u(t) - e^{-2t}u(t)$$



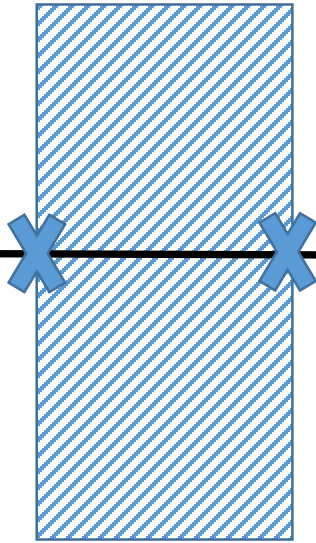
Inverse Laplace Transform

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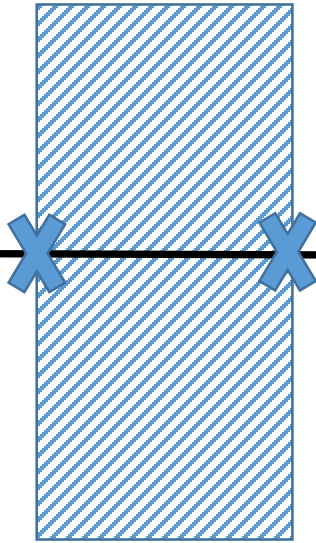
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Properties of Laplace Transforms

- **Linearity** $ax(t) + by(t) \leftrightarrow aX(s) + bY(s) \quad \supset (R_1 \cap R_2)$

- **Time shifting** $x(t - T) \leftrightarrow e^{-sT} X(s) \quad R$

- **Time scaling** $x(at) \leftrightarrow \frac{1}{|a|} X\left(\frac{s}{a}\right) \quad aR$

