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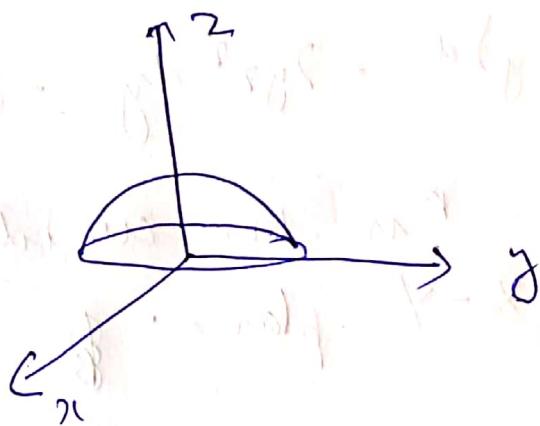
Harsit Mawandia 2020 CS 10348 Group - 4

1) The Stokes' theorem states that :

$$\int \int (\vec{V} \times \vec{U}) \cdot d\alpha = \oint_P \vec{P} \cdot d\vec{U}$$

$$\text{Given: } \vec{V} = \vec{A} = (2x-y)\hat{x} - 2y^2(\hat{y}) - 2z\hat{z}$$

We need to verify ~~this~~ with the upper hemispherical surface of sphere centered at origin, having radius 2.



$$LHS = \vec{\nabla} \times \vec{U} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{d}{dx} & \frac{d}{dy} & \frac{d}{dz} \\ 2x-y & -2y^2 & -2z^2 \end{vmatrix}$$

$$= \hat{x} (-4zy - (-4zy)) - \hat{y} (0-0) + \hat{z} (0-(-1))$$

$$\vec{\nabla} \times \vec{U} = \hat{z}$$

$$da = r d\theta (r \sin \phi d\phi) \hat{r}$$

where  $\hat{r} = \sin \phi \cos \theta \hat{x} + \sin \phi \sin \theta \hat{y} + \cos \theta \hat{z}$

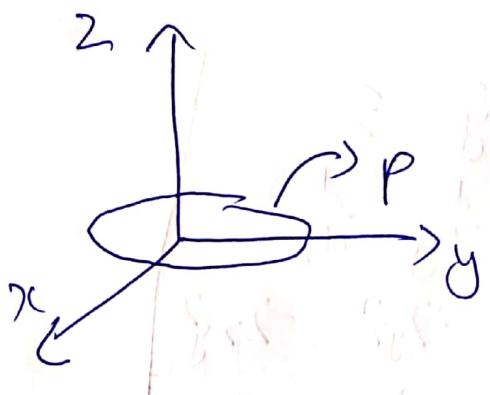
$$\therefore (\vec{\nabla} \times \vec{v}) \cdot da = r_0^2 \sin \phi \cos \theta d\phi d\theta$$

$$\int (\vec{\nabla} \cdot \vec{v}) \cdot da = \int_{\theta=0}^{\pi/2} \int_{\phi=0}^{2\pi} r_0^2 \sin \phi \cos \theta d\phi d\theta$$

$$RHS = d\vec{l} = dr \hat{x} + dy \hat{y} + dz \hat{z}$$

$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P ((2x-y) dx - 2y^2 dy - 2xy^2 dz)$$

Now our periphery  $P$  is the circular projection of hemisphere in  $x-y$  plane.



(i) For (our) periphery,  $z=0$  implying:

$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P (2x-y) dx$$

$$x = r_0 \cos \theta \Rightarrow dr = -r_0 \sin \theta d\theta$$

$$y = r_0 \sin \theta$$

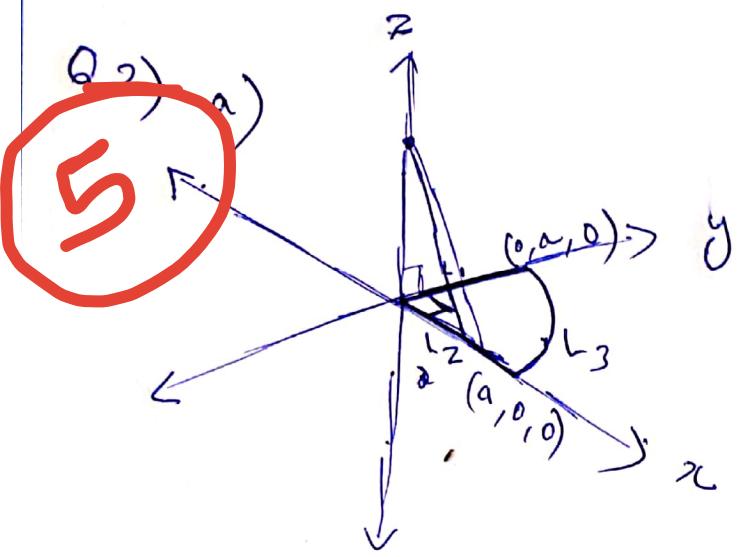
$$\oint_P \vec{v} \cdot d\vec{l} = \oint_P (2\pi - y) dr =$$
$$= \oint_P (2r_0 \cos \theta - r_0 \sin \theta) (-r_0 \sin \theta d\theta)$$

$$= r_0^2 \int_0^{2\pi} (\sin^2 \theta - 2 \sin \theta \cos \theta) d\theta$$

$$= r_0^2 \int_0^{2\pi} \sin^2 \theta d\theta$$

$$= \pi r_0^2 = 4\pi \quad (\text{since } r_0 = 2)$$

$$\therefore LHS = RHS \quad \checkmark$$



$$V = \int \frac{dq}{4\pi\epsilon_0 r}$$

= ~~Σ~~ summation of potentials due to 3 line charges, 2 straight line + 1 arc.

$$= \int_0^a \frac{dz \, dr}{4\pi\epsilon_0 \sqrt{z^2 + r^2}} + \int_0^a \frac{dy \, dr}{4\pi\epsilon_0 \sqrt{y^2 + r^2}}$$

$$+ \int_0^{\pi/2} \frac{dr \, d\theta}{4\pi\epsilon_0 \sqrt{r^2 + z^2}}$$

Both are same

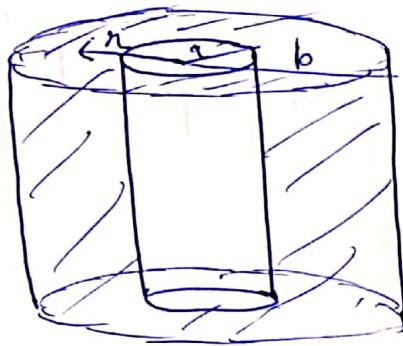
$$= \frac{1}{4\pi\epsilon_0} \left( \frac{1}{2} \left[ \ln \left( x + \sqrt{x^2 + z^2} \right) \right]_0^a + \frac{\pi r}{2 \sqrt{r^2 + z^2}} \right)$$

~~$\frac{1}{2} \ln \left( \frac{a + \sqrt{a^2 + z^2}}{z} \right)$~~

b) No, we cannot determine  $E$  from  $V(0,0,z)$  because we have already assumed  $x$  and  $y$  to be 0 and while calculating  ~~$E$~~ , we ~~also~~ won't get the partial derivatives with respect to  $x$  and  $y$ .

6

3)  
a)



$$i) E \cdot 2\pi r \lambda = \frac{\rho_0 \pi (r^2 - a^2)}{\epsilon} \lambda$$

$$E = \frac{f(r^2 - a^2)}{2 \pi r \epsilon_0}$$

$$V = \dots$$

$$= - \int_a^r \frac{\rho_0 (r^2 - a^2)}{2 \pi r \epsilon_0} dr$$

$$= - \frac{\rho_0}{2 \epsilon_0} \int_a^r \left( r - \frac{a^4}{r} \right) dr$$

$$= - \frac{\rho_0}{2 \epsilon_0} \left[ \frac{r^2 - a^2}{2} - a^2 \ln \frac{r}{a} \right]$$

2

b)  $(E \times 2\pi r) \lambda$

$$\frac{\rho_0 \pi (b^2 - a^2)}{\epsilon_0} \lambda = \frac{\rho_0 (b^2 - a^2)}{2 \pi r \epsilon_0}$$

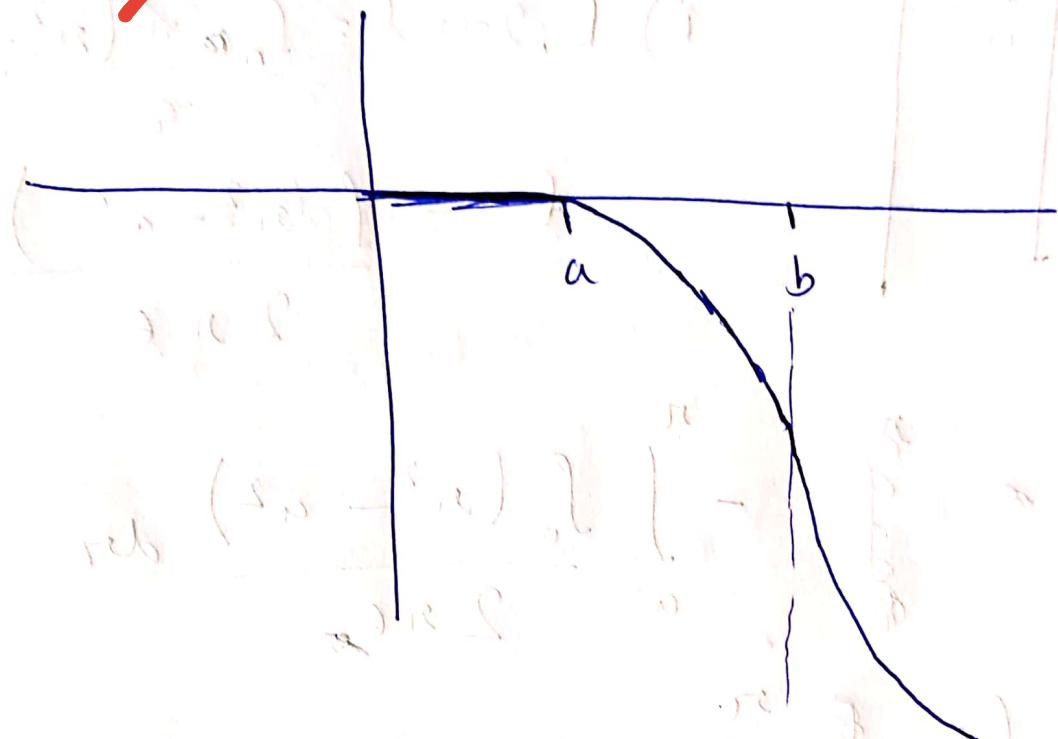
$$V = - \int_a^r E \cdot dr$$

$$= - \int_a^b E \cdot dr - \int_b^r E \cdot dr$$

$$V = - \frac{\rho_0}{2 \epsilon_0} \left( \frac{b^2 - a^2}{2} - a^2 \ln \left( \frac{b}{a} \right) \right) - \frac{\rho_0 (b^2 - a^2)}{2 \epsilon_0} \ln \frac{r}{b}$$

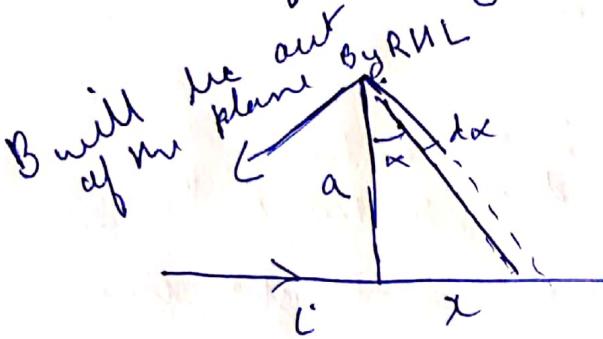
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(c)



(Q4)

We first find magnetic field due to 1 wire of length  $l$  ~~at~~ at a distance  $a$



Consider an element of length  $dn$  along the wire. Set  $d\vec{B}$  be magnetic field induction due to  $dx$ .

By Biot-Savart Law:

$$d\vec{B} = \frac{\mu_0 i}{4\pi} \cdot \hat{r} \left( \frac{dx \times \hat{r}}{r^3} \right) \quad \checkmark$$

$$|d\vec{B}| = \frac{\mu_0 i}{4\pi} dn \left( \frac{dx}{r^2} \right) \sin \left( \frac{\pi}{2} + \alpha \right)$$

$$= \frac{\mu_0 i}{4\pi} \frac{dn \cos \alpha}{\left( \frac{a}{\cos \alpha} \right)^2} \quad \checkmark$$

$$\frac{x}{a} = \tan \alpha$$

$$dn = a \sec^2 \alpha dx$$

$$= \frac{\mu_0 i}{4\pi a^2} \times \cos \alpha \sec^2 \alpha dx$$

$$|d\vec{B}| = \frac{\mu_0 i}{4\pi a} \times \cos \alpha dx$$

$$\text{Total magnetic field} = \int |d\vec{B}| = \int_{-l/2}^{l/2} \frac{\mu_0 i}{4\pi a} \cos \alpha dx$$

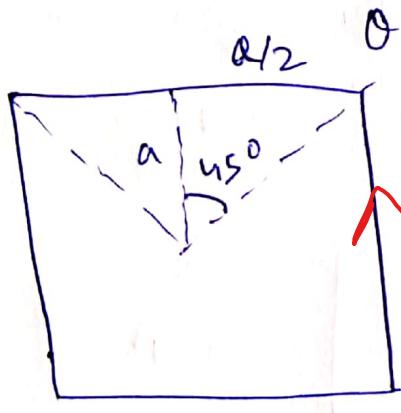
where  $\theta = \tan^{-1} \frac{1}{2a}$

$$\therefore B_{\text{net}} = \int_{-\tan^{-1} \frac{1}{2a}}^{\tan^{-1} \frac{1}{2a}} \frac{\mu_0 i}{2\pi a} \cos \alpha d\alpha$$

$$= \frac{\mu_0 i}{2\pi a} \left[ \sin \alpha \right]_{-\tan^{-1} \frac{1}{2a}}^{\tan^{-1} \frac{1}{2a}}$$

$$= \frac{\mu_0 i}{2\pi a} 2 \sin \theta = \frac{\mu_0 i}{2\pi a} 2 \sin \theta$$

Now for a square



and there are 4 such sides

$$\therefore B_{\text{total}} = \frac{\mu_0 i}{2\pi a} \times \frac{1}{\sqrt{2}} \times 4$$

$$= \frac{4\sqrt{2} \mu_0 i}{\pi a}$$

5) Vector Potential of a single dipole moment

~~m~~ is:

$$A(r) = \frac{\mu_0}{4\pi} \frac{m \times r}{r^2}$$

Let's take  $\bar{M}$  as mass density of m at any general point

-  $m = M dz$  to its total potential is:

$$\Rightarrow A(r) = \frac{\mu_0}{4\pi} \int \frac{m(r') \times r}{r^2} dz$$

$$= \frac{\mu_0}{4\pi} \int \left[ M(r') \times \left( \nabla' \frac{1}{r} \right) \right] dz$$

Using Product rule:

$$A(r) = \frac{\mu_0}{4\pi} \left\{ \int \frac{1}{r} \left( \nabla' \times M(r') \right) dz' - \int \nabla' \times \left[ \frac{M(r')}{r} \right] dz' \right\}$$

using surface integral

$$A(r) = \frac{\mu_0}{4\pi} \int \frac{1}{r} \left[ \nabla' \times M(r') \right] dz' + \frac{\mu_0}{4\pi} \oint \frac{1}{r} \left[ M(r') \times da' \right]$$

$\Phi$

Defining  $\nabla \times M = J_0$  (Volume current)

and  $M \times \hat{n} = K_B$  (surface current) 3

$$\Phi(r) = \frac{\mu_0}{4\pi} \int \underline{J_B}(r') dz' + \frac{\mu_0}{4\pi} \oint \underline{K_B}(r') da'$$

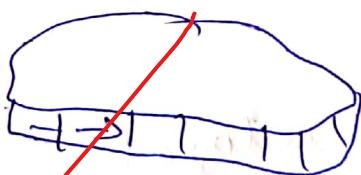
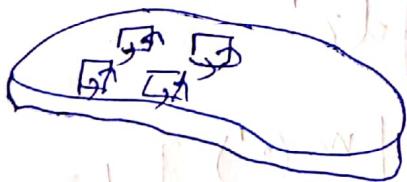
~~(3)~~

Thus means the potential and hence the field of a magnetised object is the same that would be produced by a volume current throughout the material as well as the surface current on the boundary.

This eliminates the need of integrating the contributions of small dipoles.

Physical interpretation : more physical point

Surface Current :



Consider a state of uniform magnetized material. They current loops are like dipoles. It is equivalent to a single solution of current  $I$  along the boundary.

$$\bar{m} = \bar{m}_{\text{at}}$$

$$\bar{m} = I_a$$

$$I_a = M_{\text{at}} \Rightarrow |R_B| = \frac{I}{E} = |m|$$



Volume Current:

This is a different kind of current, as not a single charge makes the ~~whole~~ trip, each charge only moves in a tiny little loop within a single atom.

The net effect is a macroscopic current flowing in the volume.

Q6) For a linear medium,  
in small field limits;

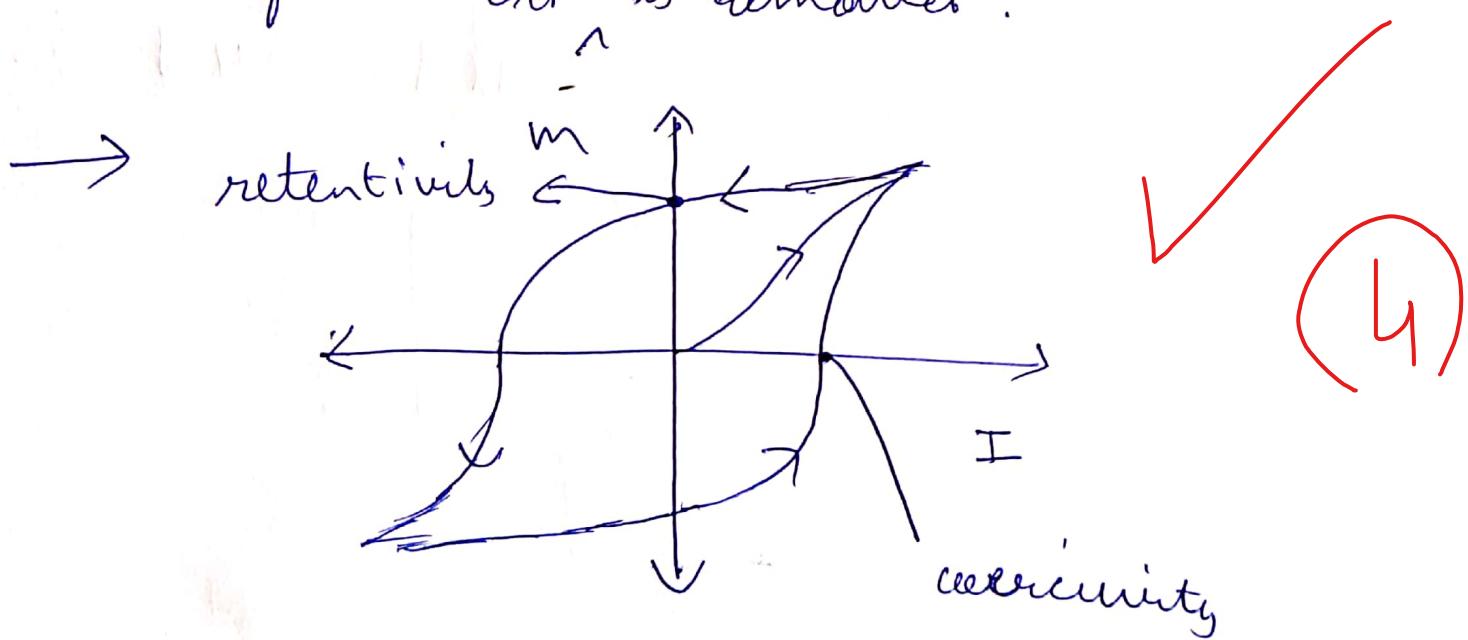
$$\bar{m} = \chi_m \bar{H} \quad (\chi_m \text{ is m magnetic susceptibility})$$

$$\Rightarrow \bar{B} = \mu_0 (\bar{H} + \bar{m}) = \mu_0 (1 + \chi_m) \bar{H}$$

$$\Rightarrow \bar{B} = \mu \bar{H} \quad \text{where } \mu = \mu_0 (1 + \chi_m).$$

$\mu$  is permeability of m in free space

→ In paramagnetic material, magnetisation is lost as soon as  $B_{ext}$  (or I) vanishes whereas in ferromagnetic material, magnetisation persists even after  $B_{ext}$  (or I) is removed.



Hysteresis Loop

Q7)

a) Physical Interpretation of Maxwell's eq<sup>n</sup>

1) ~~1st~~ 1st eq<sup>n</sup>: Gauss's Law

$$\nabla \cdot \vec{E} = \frac{q}{\epsilon_0}$$

$$\nabla \cdot \vec{D} = \rho_f$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

$$\oint \vec{D} \cdot d\vec{a} = q_f$$

It signifies that electric flux through any closed surface is given by  $\frac{1}{\epsilon_0}$  times net charge enclosed by it.

2) 3rd eq<sup>n</sup>: Faraday's law

$$\nabla \times \vec{E} = - \frac{d\vec{B}}{dt} \quad \text{or} \quad \oint_L \vec{E} \cdot d\vec{l} = - \frac{d\phi_B}{dt}$$

→ This signifies that a time dependant magnetic field generates an electric field.

Also, uniform electric field cannot exist in time dependant magnetic field.

3) 2<sup>nd</sup> eq<sup>n</sup>

$$\nabla \cdot \vec{B} = 0$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

Physically, this means that magnetic flux through a closed surface is always zero.

or, It states that ~~magnetic monopoles~~ isolated cannot exist. They appear only in pairs.

(4) 4<sup>th</sup> equation aka Ampere's law

$$\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{d\vec{E}}{dt} + \mu_0 \vec{J}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d\phi_E}{dt} + \mu_0 \epsilon_0 d\phi_B$$

$$\nabla \times \vec{H} = J_F + \frac{d\vec{D}}{dt}$$

$$\oint \vec{H} \cdot d\vec{l} = I_F + \frac{d}{dt} \oint \vec{E} \cdot d\vec{n}$$

It tells us that time varying electric field produces a magnetic field

It also tells that curl of  $\vec{H}$  along a closed surface gives the free current passing through it in absence of ~~closed~~ time varying magnetic field.

Physical interpretation of Poynting's theorem:

$$\frac{dw}{dt} = - \frac{d}{dt} \int \frac{1}{2} \left( \epsilon_0 E^2 + \frac{\mu_0}{\mu_0} B^2 \right) dV$$

or  $\frac{dw}{dt} = - \frac{1}{\mu_0} \oint (\vec{E} \times \vec{B}) \cdot d\vec{A}$

$$\frac{dw}{dt} = - \frac{d \mu_{\text{em}}}{dt} - \oint S \cdot d\vec{A}$$

The rate of work done on charge by EM waves

(3)

= rate of decrease of total energy stored in fields + the energy flowing out of the surface per unit time.

Q7) b) Given a charge 'q', which moves in a force  $\vec{F}$  amount  $d\vec{r}$  in time  $dt$ , due to magnetic field acting on it. Then

$$dw = \vec{F}_m \cdot d\vec{r}$$

$$= q (\vec{v} \times \vec{B}) \cdot (v dt) \quad [\text{Torsion Force}]$$

$$= q dt [(\vec{v} \times \vec{B}) \cdot \vec{v}] = 0$$

$v \times B$  is always  $\perp$  to  $\vec{v}$  &  $\vec{B}$

$\therefore$  dot product will be 0  
 $\cos 90^\circ = 0$

In general, magnetic force is always perpendicular to velocity of the charge.

Hence it cannot do any work on the charge.

3  $w_{\text{magnetic}} = 0$

$$8) a) \vec{B} = \left| \frac{\vec{E}}{c} \right| \left( \hat{i} \times \hat{z} \right) \xleftarrow{\text{in vacuum}} \begin{array}{l} \text{direction of propagation} \\ \text{in vacuum} \end{array}$$

$\downarrow$

$$\vec{E}(z, t) = E_0 \cos(\omega t) \cos(3kz) \hat{x}$$

$$\vec{B}(z, t) = \frac{E_0}{c} \cos(\omega t) \cos(3kz) \hat{y}$$

use  
Faraday's  
law

$\oplus b)$

$$\vec{s} = \frac{\vec{E} \times \vec{B}}{\mu_0} = \frac{E_0^2}{\mu_0 c} \cos^2(\omega t) \cos^2(3kz) \hat{z}$$

$\circlearrowleft$

$$\langle \vec{s} \rangle = \frac{E_0^2}{\mu_0 c} \cos^2(3kz) \times \frac{1}{2} \quad (\langle \cos^2 \rangle = \frac{1}{2})$$

$$= \frac{1}{2} \epsilon_0 c E^2 \cos^2(3kz)$$



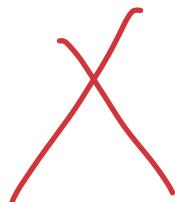
$$\frac{1}{\mu_0} = \epsilon_0 c^2$$

The average pointing flux is dependant on the position of the point ( $z$ ) as this is a standing wave not a travelling wave.

$$\begin{aligned}
 10) E_0 &= \operatorname{Re} [E_0 e^{-i(kz - \omega t)}] \\
 &= \operatorname{Re} \left[ E_0 e^{i \frac{(n+i\beta)2\pi z}{\lambda_0} - i(kz - \omega t)} \right] \\
 &= e^{-\frac{2\pi\beta z}{\lambda_0}} \operatorname{Re} [E_0 e^{i(kz - \omega t)}]
 \end{aligned}$$

So due to ~~non~~ conducting. No complex refractive index does not induce a phase difference since  $n_{\text{ref}} \neq 1 + i\beta$

real Part  $\rightarrow$  this is the part that accounts for phase change and that is 1.  
 Therefore the phase change will be ~~0~~ for reflection.



$$\text{Ans 11)} \quad k = \frac{\omega}{c} \left( 1 - \frac{\omega_p^2}{\omega^2 \left( 1 + \frac{\epsilon v}{\omega} \right)} \right)^{1/2}$$

where  $\omega_p = 1.01 \times 10^{12} \text{ Hz}$

and  $\gamma = 10^7 \text{ Hz}$

a) case I :  $\omega \ll \nu$

$$k^2 = \frac{\omega^2}{c^2} \left( 1 - \frac{\omega_p^2}{\omega^2 \left( 1 + \frac{\epsilon v}{\omega} \right)} \right) \approx \frac{\omega^2}{c^2} \frac{\omega_p^2}{\omega^2}$$

$$\Rightarrow k^2 = \frac{\omega_p}{c} \left( \frac{\omega}{\nu} \right)^{1/2} \left( 1 + \frac{\epsilon}{\gamma} \right) = k_{\text{real}}^2 + i k_{\text{imaginary}}$$

Skin depth :

$$\delta = \frac{1}{k_i} = \frac{c}{\omega_p} \left( \frac{2\nu}{\omega} \right)^{1/2}$$

Case II :  $\nu \ll \omega \Rightarrow \frac{\nu}{\omega} \rightarrow 0$

$$\text{for } \omega < \omega_p \rightarrow k = \frac{\omega}{c} \left( 1 - \frac{\omega_p^2}{\omega^2} \right)^{1/2} = i \propto$$

$$\text{where } \propto = \frac{\omega}{c} \left( \frac{\omega_p^2}{\omega^2} - 1 \right)^{1/2}$$

$\therefore$  skin depth

$$\delta = \frac{1}{\propto} = \frac{c}{\sqrt{\omega_p^2 - \omega^2}}$$

3

$$\begin{aligned}
 b) i) \quad \omega &= 10^3 \text{ rad/s} \\
 \Rightarrow S &= \frac{C}{\omega_p} \left( \frac{2\gamma}{\omega} \right)^{1/2} \\
 &= \frac{3 \times 10^8}{1.01 \times 10^{12}} \times \left( \frac{2 \times 10^7}{10^3} \right)^{1/2} \\
 &= \frac{3}{1.01} \times 10^{-4} \times \sqrt{2} \times 10^2 \\
 &\stackrel{2}{=} \left( \frac{3\sqrt{2}}{1.01} \times 10^{-2} \right)
 \end{aligned}$$

$$\begin{aligned}
 ii) \quad \omega &> \gamma \\
 &\approx 4.20 \times 10^{-2} \text{ m/s} \quad \text{Ans}
 \end{aligned}$$

$$\begin{aligned}
 S &= \frac{C}{\sqrt{\omega_p^2 - \omega^2}} = \frac{3 \times 10^8}{\sqrt{(1.01)^2 \times 10^{24} - (1)^2 \times 10^{24}}} \\
 &\stackrel{?}{=} \frac{3 \times 10^8}{10^{12} \sqrt{2.01 \times 0.01}} \\
 &= \frac{3 \times 10^8}{10^{12} \sqrt{2.01 \times 0.01}} = \frac{3 \times 10^{-4}}{10^{11} \sqrt{2.01}}
 \end{aligned}$$

$$\approx 2.12 \times 10^{-3} \text{ m} \quad \text{Ans}$$