

- Existence & Uniqueness of the solⁿ of 2nd order linear ODE.

- General solⁿ

Higher Order Linear ODEs

Let's consider the ^{homogeneous} n^{th} order linear ODE

$$x^{(n)} + a_1(t)x^{(n-1)} + a_2(t)x^{(n-2)} + \dots + a_n(t)x = 0 \quad \text{--- (1)}$$

We can reduce ODE (1) in linear system of first order ODEs by introducing

$$\begin{array}{ccccccc} x_1 = x & , & x_2 = x_1' & , & x_3 = x_2' & , & \dots & , & x_n = x_{n-1}' \\ & & \parallel & & \parallel & & & & \parallel \\ & & x' & & x'' & & & & x^{(n-1)} \end{array}$$

using (1)

$$\begin{aligned} x_n' = x^{(n)} &= -a_1(t)x^{(n-1)} - a_2(t)x^{(n-2)} - \dots - a_n(t)x \\ &= -a_1(t)x_n - a_2(t)x_{n-1} - \dots - a_n(t)x_1 \end{aligned}$$

We have,

$$(2) \quad \begin{cases} x_1' = x_2 \\ x_2' = x_3 \\ \vdots \\ x_{n-1}' = x_n \end{cases}$$

$$\begin{cases} \vdots \\ x_{n-1}' = x_n \\ x_n' = -a_1(t)x_n - a_2(t)x_{n-1} \cdots - a_n(t)x_1 \end{cases}$$

③

$$\begin{bmatrix} x_1' \\ x_2' \\ \vdots \\ x_n' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \\ \vdots & & & & & \\ -a_n & -a_{n-1} & -a_{n-2} & \cdots & -a_1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Define

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}_{n \times 1}, \quad A = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & & & & \vdots \\ -a_n & -a_{n-1} & \cdots & \cdots & -a_1 \end{bmatrix}_{n \times n}$$

then ③ can be written as

✓ $x' = AX$

Initial condition

$$\begin{bmatrix} x_1(t_0) \\ x_2(t_0) \\ \vdots \\ x_n(t_0) \end{bmatrix}_{n \times 1} = \underbrace{x(t_0)}_{= X_0} = \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{bmatrix}$$

$k_i \in \mathbb{R}$, are given
 $1 \leq i \leq n$.

$$x(t_0) = x_1(t_0) = k_1$$

$$x'(t_0) = x_2(t_0) = k_2$$

$$x''(t_0) = x_3(t_0) = k_3$$

\vdots

$$x^{(n-1)}(t_0) = x_n(t_0) = k_n$$

Initial conditions for ① are

$$\textcircled{4} \left\{ \begin{array}{l} x(t_0) = k_1 \\ x'(t_0) = k_2 \\ \vdots \\ x^{(n-1)}(t_0) = k_n \end{array} \right.$$

ODE ① + Initial conditions ④ } IVP

Defⁿ (Solution)

A solution of an n^{th} order ODE on some open interval I is a function $x = h(x)$ which is n -times differentiable on I & satisfies DE ①.

Thm1 (Existence & Uniqueness thm)

If the coefficient f 's $a_1(t), a_2(t) \dots a_n(t)$ of DE ① are continuous & bounded on some open interval I & $t_0 \in I$ then the IVP

$$\text{IVP ①} \left\{ \begin{array}{l} x^{(n)} + a_1(t)x^{(n-1)} + \dots + a_n(t)x = 0 \\ x(t_0) = K_1 \\ x'(t_0) = K_2 \\ \vdots \\ x^{(n-1)}(t_0) = K_n \end{array} \right.$$

has a unique solⁿ on I , where $K_i \in \mathbb{R}$, is given.

Superposition Principle

(verify)

If $x_1, x_2 \dots x_n$ are solⁿs of DE ① then their linear combination $c_1x_1 + c_2x_2 + \dots + c_nx_n$ is also a solⁿ of DE ①, here c_i 's are constants.

(Linear Dependence & Linear Independence of f 's)

Defⁿ

The functions $x_1(t), x_2(t) \dots x_n(t)$ are

L.D. if there exist constants $c_1, c_2 \dots c_n$, not all zero, such that

$$c_1 x_1(t) + c_2 x_2(t) + \dots + c_n x_n(t) = 0.$$

$x_1(t), x_2(t) \dots x_n(t)$ are L.I. if

$$c_1 x_1 + c_2 x_2 + \dots + c_n x_n \Rightarrow c_1 = 0, c_2 = 0 \dots c_n = 0.$$

Defⁿ (Wronskian)

The Wronskian of $x_1(t), x_2(t) \dots x_n(t)$ is defined by

$$W(x_1, x_2, \dots, x_n)(t) = \begin{vmatrix} x_1 & x_2 & \dots & x_n \\ x_1' & x_2' & \dots & x_n' \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(n-1)} & x_2^{(n-1)} & \dots & x_n^{(n-1)} \end{vmatrix}.$$

Thm 2 (Abel's Formula) Let $x_1(t), x_2(t) \dots x_n(t)$ are solutions of DE (1). Then,

$$\underline{\underline{W(x_1, x_2, \dots, x_n)(t) = c e^{-\int a_1(x) dt}}}, \quad c \rightarrow \text{constant}.$$

$$= \begin{vmatrix} x_1' & x_2' & x_3' \\ -a_1 x_1'' & -a_1 x_2'' & -a_1 x_3'' \end{vmatrix} + \begin{vmatrix} x_1' & x_2' & x_3' \\ -a_2 x_1' & -a_2 x_2' & -a_2 x_3' \end{vmatrix} \\ + \begin{vmatrix} x_1 & x_2 & x_3 \\ x_1' & x_2' & x_3' \\ -a_3 x_1 & -a_3 x_2 & -a_3 x_3 \end{vmatrix} = 0$$

$$= -a_1(t) \begin{vmatrix} x_1 & x_2 & x_3 \\ x_1' & x_2' & x_3' \\ x_1'' & x_2'' & x_3'' \end{vmatrix}$$

$$\parallel \\ w(t)$$

$$\frac{d}{dt} w(t) + a_1(t) w(t) = 0$$

→ first order linear ODE

Solⁿ is

$$w(t) = c e^{-\int a_1(t) dt}$$

Corollary The Wronskian of x_1, x_2, \dots, x_n of solⁿ of DE ① is either identically equal to zero or never zero.

$$w(t) = c e^{-\int a_1(t) dt}$$

\nwarrow
 Never zero

• If $c = 0$ then $W(t) \equiv 0$

• If $c \neq 0$ then $W(t)$ is never zero.

Thm Let x_1, x_2, \dots, x_n be solⁿs of ①.

Then $x_1(t), x_2(t), \dots, x_n(t)$ are l.d.

$$\Leftrightarrow W(x_1, x_2, \dots, x_n)(t) = 0.$$

Pf. (\Rightarrow) Suppose $x_1(t), x_2(t), \dots, x_n(t)$ are l.d.

To show that $W(x_1, x_2, \dots, x_n)(t) = 0$.

\exists c_1, c_2, \dots, c_n (constants), not
all zero s.t.

$$\begin{cases}
 c_1 x_1(t) + c_2 x_2(t) + \dots + c_n x_n(t) = 0 & \text{--- ⑥} \\
 c_1 x_1'(t) + c_2 x_2'(t) + \dots + c_n x_n'(t) = 0 \\
 \vdots \\
 c_1 x_1^{(n-1)}(t) + c_2 x_2^{(n-1)}(t) + \dots + c_n x_n^{(n-1)}(t) = 0
 \end{cases}$$

(*)

We have, the system of eqⁿ

$$\begin{bmatrix} x_1 & x_2 & \dots & x_n \\ x_1' & x_2' & \dots & x_n' \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(n-1)} & x_2^{(n-1)} & \dots & x_n^{(n-1)} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = 0$$

has a non-trivial solⁿ.

$$\Rightarrow \underbrace{\det \left(\begin{matrix} \text{ } \\ \text{ } \end{matrix} \right)}_{\parallel} = 0$$

$$\parallel$$

$$W(x_1, x_2, \dots, x_n)(t)$$

(\Leftarrow) T.S.T.

$$W(t) = W(x_1, x_2, \dots, x_n)(t) = 0 \Rightarrow x_1, x_2, \dots, x_n \text{ are L.D.}$$

It suffices to show that

$$\checkmark W(t_0) = 0 \text{ for some } t_0$$

$$\Rightarrow \underline{x_1, x_2, \dots, x_n \text{ are L.D.}}$$

$$W(t_0) = 0$$

$$\parallel$$

$$\begin{vmatrix} x_1(t_0) & x_2(t_0) & \dots & x_n(t_0) \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(n-1)}(t_0) & x_2^{(n-1)}(t_0) & \dots & x_n^{(n-1)}(t_0) \end{vmatrix}$$

$$| x_1(t_0) \quad x_2(t_0) \quad \dots \quad x_n(t_0) |$$

\Rightarrow the following system of eqⁿs

$$(*) \quad \begin{bmatrix} x_1(t_0) & x_2(t_0) & \dots & x_n(t_0) \\ \vdots & \vdots & & \vdots \\ x_1^{(n-1)}(t_0) & x_2^{(n-1)}(t_0) & \dots & x_n^{(n-1)}(t_0) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

has a non-trivial solⁿ, say

$$c_1 = d_1, c_2 = d_2, \dots, c_n = d_n \quad \left(d_i \text{'s are not all zero} \right)$$

consider the fⁿ

$$\begin{aligned} z(t) &= c_1 x_1 + c_2 x_2 + \dots + c_n x_n \\ &= d_1 x_1 + d_2 x_2 + \dots + d_n x_n \end{aligned}$$

Since x_1, x_2, \dots, x_n are solⁿ of DE ①

$\Rightarrow z(t)$ is also a solⁿ of DE ①.

from (*)

$$z(t_0) = c_1 x_1(t_0) + \dots + c_n x_n(t_0) = 0$$

$$z'(t_0) = c_1 x_1'(t_0) + \dots + c_n x_n'(t_0) = 0$$

\vdots

$$z^{(n-1)}(t_0) = c_1 x_1^{(n-1)}(t_0) + \dots + c_n x_n^{(n-1)}(t_0) = 0.$$

Thus $z(t)$ is a solⁿ of IVP

$$x^{(n)} + a_1 x^{(n-1)} + \dots + a_n x = 0$$

$$x(t_0) = 0, x'(t_0) = 0, \dots, x^{(n-1)}(t_0) = 0.$$

Note that $x(t) = 0$ is also a solⁿ of same IVP & hence by uniqueness of solⁿ we have

$$z(t) \equiv 0$$

$$c_1 x_1 + c_2 x_2 + \dots + c_n x_n = 0$$

\Rightarrow x_i 's $i=1, 2, \dots, n$ are L.D.

Corollary let x_1, x_2, \dots, x_n be solⁿs of DE ①.

Then

x_1, x_2, \dots, x_n are L.I. $\Leftrightarrow W(x_1, x_2, \dots, x_n)(t) \neq 0$

(verify).

Thm let $x_1(t), x_2(t), \dots, x_n(t)$ are L.I.

solⁿ of DE ① in some open interval I

& let $y(t)$ be any solⁿ of ① then

there exists constants $c_1, c_2 \dots c_n$ s.t.

$$y(t) = c_1 x_1(t) + \dots + c_n x_n(t),$$

i.e. any solⁿ of ① belongs to the linear span of $x_1(t), x_2(t) \dots x_n(t)$.

Proof. Let $y(t)$ be any solⁿ of DE ①.

Given: $x_1(t), x_2(t) \dots x_n(t)$ are L.I.

solⁿ of DE ①.

$x_1(t), x_2(t), \dots x_n(t)$ are L.I.

$$\Rightarrow W(x_1, x_2 \dots x_n)(t) \neq 0$$

i.e.

$$\exists t_0 \in I \text{ s.t. } W(t_0) \neq 0$$

$$\begin{vmatrix} x_1(t_0) & x_2(t_0) & \dots & x_n(t_0) \\ \vdots & \vdots & & \vdots \\ x_1^{(n-1)}(t_0) & x_2^{(n-1)}(t_0) & \dots & x_n^{(n-1)}(t_0) \end{vmatrix}$$

\Rightarrow The system of eqⁿ

$$\begin{bmatrix} x_1(t_0) & x_2(t_0) & \dots & x_n(t_0) \\ \vdots & \vdots & & \vdots \\ x_1^{(n-1)}(t_0) & x_2^{(n-1)}(t_0) & \dots & x_n^{(n-1)}(t_0) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} y(t_0) \\ y'(t_0) \\ \vdots \\ y^{(n-1)}(t_0) \end{bmatrix}$$

$$\underbrace{[x_1(t_0) \ x_2(t_0) \ \dots \ x_n(t_0)]}_{\text{row vector}} \underbrace{[c_1 \ c_2 \ \dots \ c_n]}_{\text{column vector}} = [y^{(n-1)}(t_0)]$$

has a unique solⁿ, say

$$c_1 = \beta_1, c_2 = \beta_2, \dots, c_n = \beta_n.$$

Define

$$z(t) = c_1 x_1 + c_2 x_2 + \dots + c_n x_n$$

Note that $z(t)$ is a solⁿ of DE ① since

it is a linear combination of solⁿ of DE ①.

We have,

$$z(t_0) = c_1 x_1(t_0) + c_2 x_2(t_0) + \dots + c_n x_n(t_0) = y(t_0)$$

$$z'(t_0) = y'(t_0)$$

,

;

$$z^{(n-1)}(t_0) = y^{(n-1)}(t_0).$$

Thus $z(t)$ & $y(t)$ solves the same IVP. Therefore by existence & uniqueness theorem, we have

$$y(t) \equiv z(t) = c_1 x_1 + c_2 x_2 + \dots + c_n x_n$$

General solⁿ

involves n arbitrary constants

of DE ①

Fundamental set of solⁿ $\rightarrow \{x_1, x_2, \dots, x_n\}$

Fundamental set of solⁿ

Any set $\{x_1(t), x_2(t), \dots, x_n(t)\}$ of n -linearly independent solⁿ of DE ① on some interval (open) I is said to be the fundamental set of solⁿ on I .

$\{x_1, x_2, \dots, x_n\} \rightarrow$ fundamental set of solⁿ of ①

then general solⁿ of ① is

$$x(t) = c_1 x_1(t) + \dots + c_n x_n(t)$$