

Multiple Integral - Lecture 4

Change of variables in double integral and triple integral.

$$\# \int_a^b f(g(x)) g'(x) dx = \int_{g(a)}^{g(b)} f(y) dy$$

$y = g(x)$
 $y' = g'(x)$

In case of two variables

$$x = f(u, v) \text{ & } y = g(u, v)$$

$$dxdy = (?) du dv$$

In case of polar co-ordinates, we have

seen that

$$dxdy = (r) dr d\theta$$

$$x = r \cos\theta = f(r, \theta)$$

$$y = r \sin\theta = g(r, \theta)$$

In case of Cylindrical co-ordinates

$$d\omega = dx dy dz = (r) dr d\theta dz$$

In case of Spherical co-ordinates

$$dr = dx dy dz = (r^2 \sin \phi) dr d\theta d\phi$$

$$x = r \sin \phi \cos \theta = f(r, \phi, \theta)$$

$$y = r \sin \phi \sin \theta = g(r, \phi, \theta)$$

$$z = r \cos \phi = h(r, \phi, \theta)$$

Why do we do change of variables

- ① To convert given domain into a nicer domain.
- ② Changing variables sometimes makes the integration easy to compute.

Example ① $x^2 + \frac{y^2}{36} = 1$ — eqn ①

Consider $x = \frac{u}{2}$ and $y = 3v$

$$\left(\frac{u}{2}\right)^2 + \frac{(3v)^2}{36} = 1$$

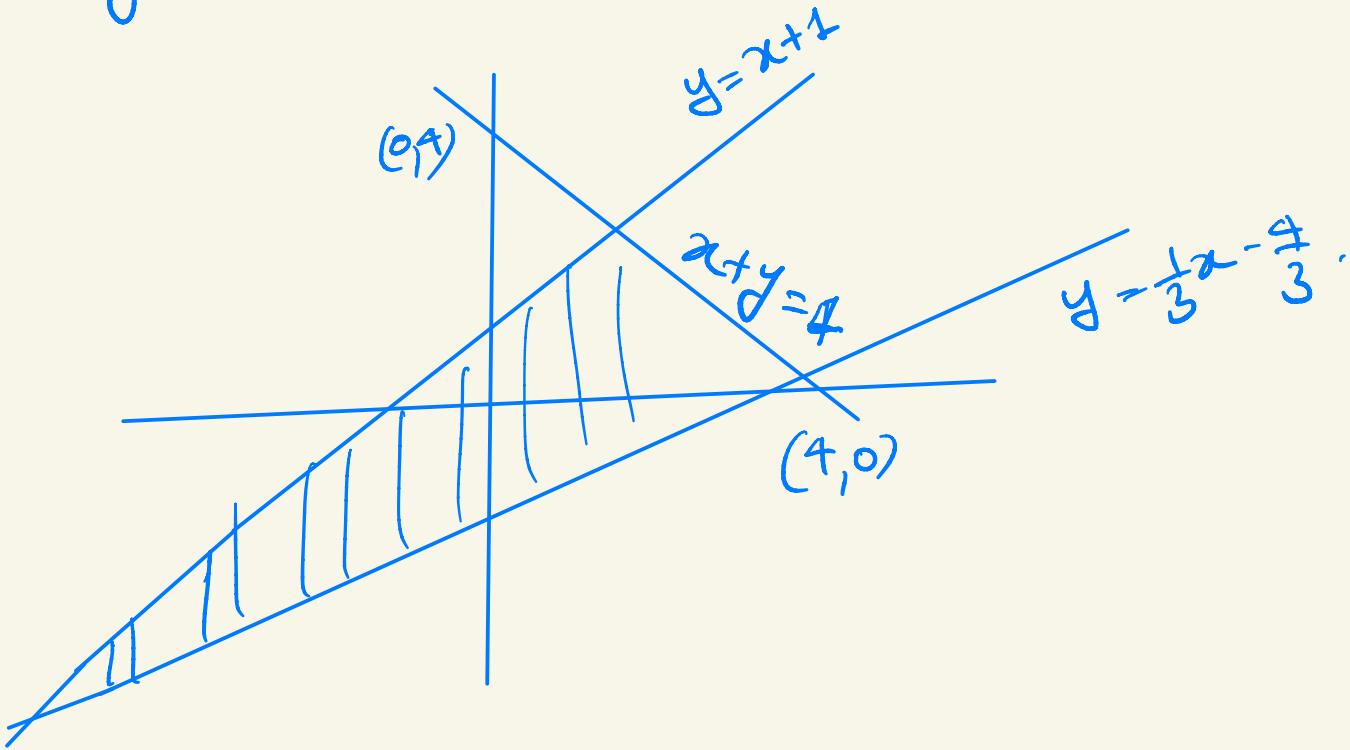
$$\frac{u^2}{4} + \frac{9v^2}{36} = 1$$

$$u^2 + v^2 = 4 \quad \text{— circle}$$

Example ②. Domain bounded by $2x+y=4$, $y=x+1$

and $3y = x - 4$.

Solⁿ →



Consider the transformation

$$x = \frac{1}{2}(u+v) \quad \text{and} \quad y = \frac{1}{2}(u-v)$$

of ① $x+y = 4 \Rightarrow \frac{1}{2}(u+v) + \frac{1}{2}(u-v) = 4$
 $\Rightarrow u = 4$.

of ② $y = x+1 \Rightarrow \frac{1}{2}(u-v) = \frac{1}{2}(u+v) + 1$
 $\Rightarrow v = -1$

of ③ $y = \frac{x}{3} - \frac{4}{3} \Rightarrow v = \frac{u}{2} + 2 \quad (\text{see})$

Suppose we have the transformation given by

$$x = f(u, v) \text{ and } y = g(u, v)$$

Then the Jacobian of this transformation is given by

$$J = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}_{2 \times 2}$$

$$dxdy = |J| du dv.$$

Example ③ In polar co-ordinates we have

$$x = r \cos \theta \quad \text{and} \quad y = r \sin \theta$$

$$J = \frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix}_{2 \times 2}$$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r (\cos^2 \theta + \sin^2 \theta) = r$$

$$dxdy = |J| dr d\theta = r dr d\theta.$$

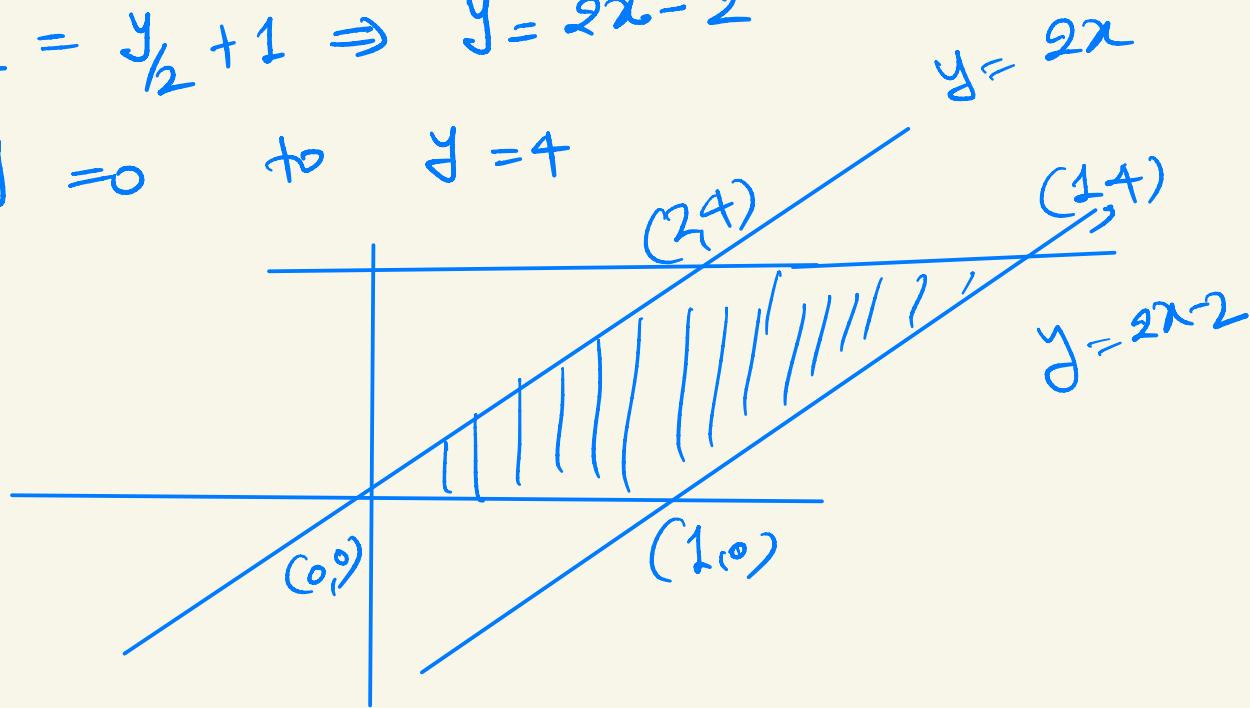
Example ④. Evaluate $\int_0^4 \int_{y/2}^{1+y/2} \frac{2x-y}{2} dA$.

Solⁿ →

$$x = y/2 \Rightarrow y = 2x$$

$$x = y/2 + 1 \Rightarrow y = 2x - 2$$

$$y = 0 \text{ to } y = 4$$



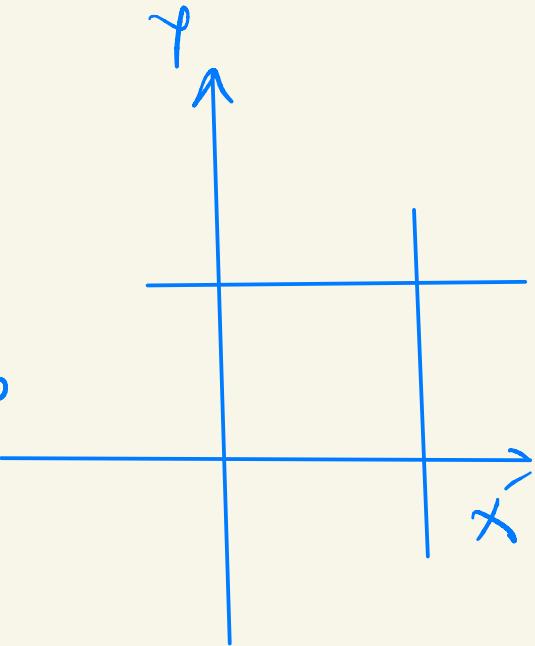
take the transformation $u = \frac{2x-y}{2}$ & $v = \frac{y}{2}$

$$\text{eq } ① \quad y=0 \Rightarrow v=0$$

$$\text{eq } ② \quad y=4 \Rightarrow v=2$$

$$\text{eq } ③ \quad x=\frac{y}{2} \Rightarrow 2x-y=0 \Rightarrow u=0$$

$$\text{eq } ④ \quad x=1+\frac{y}{2} \Rightarrow u=1$$



$$\iint_D \frac{2x-y}{2} dA = \int_0^2 \int_{-\frac{v}{2}}^{1+\frac{v}{2}} u |J| du dv$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \quad \text{Note: } J^{-1} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix}$$

$$\frac{1}{J} = \begin{vmatrix} 1 & -\frac{1}{2} \\ 0 & \frac{1}{2} \end{vmatrix} = \frac{1}{2} \Rightarrow J = 2$$

$$\iint_0^2 2uv dv du = \text{compute.}$$

Example ⑤

$$\int_0^1 \int_{0+x}^{1-x} (\sqrt{xy}) (y - 2x)^2 dA$$

Sol:

$$u = x + y \quad \text{and} \quad v = y - 2x$$

Domain in XY-plane

$$x=0, \quad y=0 \quad \text{and} \quad y=1-x$$

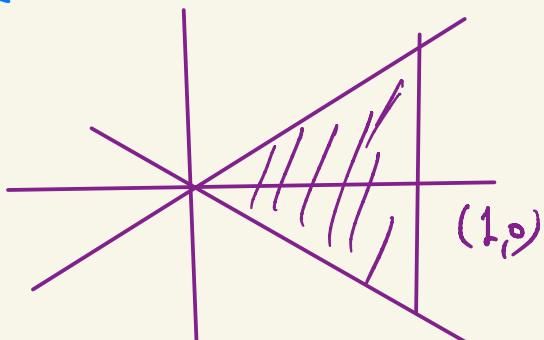
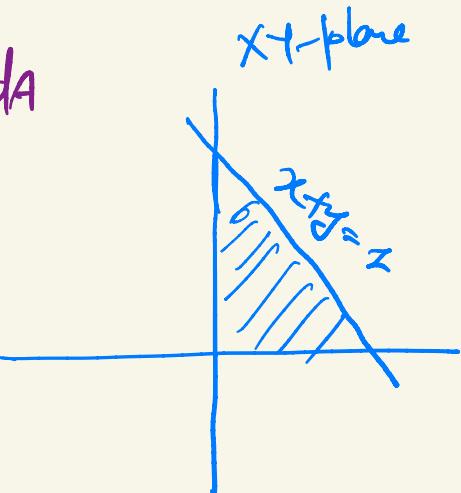
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$$u=v$$

$$v=-2u$$

$$u=1$$

(1, 0)



$$I = \int_0^1 \int_0^{1-x} \sqrt{x+y} (y-2x)^2 dA = \int_0^1 \int_{-2u}^u \sqrt{u+v^2} J du dv$$

$$\frac{1}{J} = \begin{vmatrix} 1 & 1 \\ -2 & 1 \end{vmatrix} = 3 \Rightarrow J = \frac{1}{3}$$

$$I = \int_0^1 \int_{-2u}^u \frac{1}{3} \sqrt{u+v^2} J du dv$$

= compute .

In 3-dim, we assume

$x = f(u, v, w)$, $y = g(u, v, w)$ and $z = h(u, v, w)$.

Define

$$J = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}_{3 \times 3}$$

$$dV = dx dy dz = |J| du dv dw.$$

Example ⑥ Consider the transformation

$$x = r \cos \theta, \quad y = r \sin \theta \quad \text{and} \quad z = z.$$

Soln. $J = \frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix}$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 \cdot (r \cos^2 \theta + r \sin^2 \theta) \\ \Rightarrow r (\cos^2 \theta + \sin^2 \theta) \\ \Rightarrow r.$$

Example ⑦. Consider the following transformation

$$x = r \sin \phi \cos \theta, \quad y = r \sin \phi \sin \theta, \quad z = r \cos \phi$$

Solⁿ. $J = \begin{vmatrix} \sin \phi \cos \theta & -r \sin \phi \sin \theta & r \cos \phi \cos \theta \\ \sin \phi \sin \theta & r \sin \phi \cos \theta & r \cos \phi \sin \theta \\ \cos \phi & 0 & -r \sin \phi \end{vmatrix}_{3 \times 3}$

$$\begin{aligned} J &= \cos \phi \left(-r^2 \cos \phi \sin \phi (\cos^2 \theta + \sin^2 \theta) \right)^{\text{||1}} \\ &\quad - r \sin \phi \left(r \sin^2 \phi (\cos^2 \theta + \sin^2 \theta) \right)^{\text{||1}} \end{aligned}$$

$$\begin{aligned}
 J &= -r^2 \sin \phi \cos^2 \phi - r^2 \sin^3 \phi \\
 &= -r^2 \sin \phi (\cos^2 \phi + \sin^2 \phi) \\
 &= -r^2 \sin \phi
 \end{aligned}$$

$$|J| = r^2 \sin \phi$$

$$dxdydz = (r^2 \sin \phi) \cdot dr d\theta d\phi$$

Example 8. Evaluate $\iiint_{\Omega} (x^2y + 3xyz) dV$

Where the domain Ω is given by

$$\Omega = \{(x, y, z) \mid 1 \leq x \leq 2, 0 \leq xy \leq 2, 0 \leq z \leq 1\}$$

Solⁿ: If we take the transformation

$$u = x, \quad v = xy \quad \text{and} \quad w = z$$

Limits

$$1 \leq u \leq 2$$

$$0 \leq v \leq 2$$

$$0 \leq w \leq 1$$

$$\begin{aligned}
 f(x,y,z) &= x^2y + 3xyz \\
 &= x(ay) + 3(xy)z \\
 &= uv + 3vw
 \end{aligned}$$

$$\iiint_{\Omega} (x^2y + 3xyz) dv = \iiint_{\Omega} (uv + 3vw) J dv dw = I$$

$$\frac{1}{J} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ y & x & 0 \\ 0 & 0 & 1 \end{vmatrix} = x = u$$

$$J = \frac{1}{4} u$$

$$I = \int_1^2 \int_0^2 \int_0^1 (uv + 3vw) \frac{1}{4} du dv dw$$

Ends