Table of Contents

Physical constants

Simulation parameters

```
dt = 1e-12;
                        % Time step (s)
total time = 1e-8/13;
                          % Total simulation time (s)
num steps = ceil(total time/dt);
% Circuit parameters
d = 0.1;
                        % Distance between circuits (m)
circuit radius = 0.01; % Radius of the circular circuits (m)
circuit segments = 100; % Number of segments to discretize each circuit
current magnitude = 1; % Current magnitude (A)
                        % Wire radius (m)
wire radius = 0.001;
n = lectrons = 100;
                    % Number of electrons to visualize per circuit
% Initialize time and arrays
t = 0;
times = zeros(1, num steps);
field reached middle = false;
switch time = d/(2*c); % Time when field reaches middle (s)
```

Create circuit geometries

Circuit 1 (left circuit) - Now in YZ plane

```
theta = linspace(0, 2*pi, circuit_segments);
circuit1_x = -d/2 * ones(size(theta)); % All points at x = -d/2
circuit1_y = circuit_radius * cos(theta);
circuit1_z = circuit_radius * sin(theta);
circuit1_positions = [circuit1_x; circuit1_y; circuit1_z]';
circuit1_segments = [circuit1_positions, circshift(circuit1_positions, -1)];
circuit1_segments(end,:) = [];

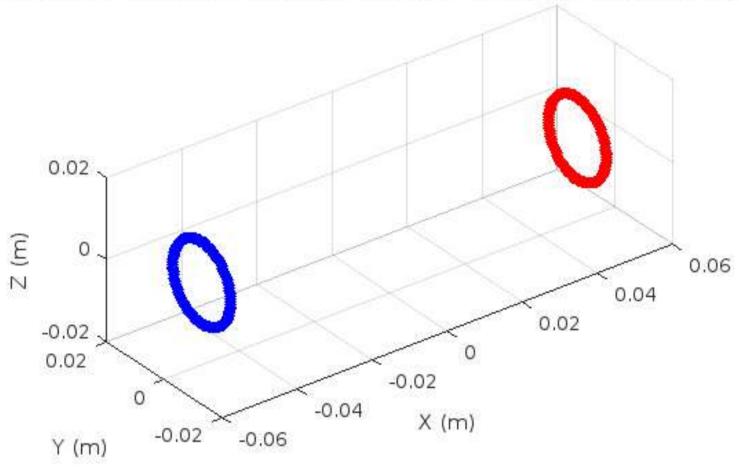
% Circuit 2 (right circuit) - Now in YZ plane
circuit2_x = d/2 * ones(size(theta)); % All points at x = d/2
circuit2_y = circuit_radius * cos(theta);
circuit2_z = circuit_radius * sin(theta);
circuit2_positions = [circuit2_x; circuit2_y; circuit2_z]';
circuit2_segments = [circuit2_positions, circshift(circuit2_positions, -1)];
circuit2_segments(end,:) = [];
```

Setup visualization

```
figure('Position', [100, 100, 1200, 800]);
view(3);
grid on;
axis equal;
xlabel('X (m)');
ylabel('Y (m)');
zlabel('Z (m)');
title('Relativistic Electromagnetic Simulation - Circuits Facing Each Other');
xlim([-d/2-circuit radius, d/2+circuit radius]);
ylim([-2*circuit radius, 2*circuit radius]);
zlim([-2*circuit radius, 2*circuit radius]);
hold on;
% Plot circuits
circuit1 handle = plot3(circuit1 x, circuit1 y, circuit1 z, 'b', 'LineWidth',
circuit2 handle = plot3(circuit2 x, circuit2 y, circuit2 z, 'r', 'LineWidth',
2);
% Initialize magnetic field visualization
[Y, Z] = meshgrid(linspace(-circuit radius*1.5, circuit radius*1.5, 20), ...
                  linspace(-circuit radius*1.5, circuit_radius*1.5, 20));
X = zeros(size(Y));
Bx = zeros(size(Y));
By = zeros(size(Y));
Bz = zeros(size(Y));
quiver_handle = quiver3(X, Y, Z, Bx, By, Bz, 'g');
% Initialize electron visualization
electron1 positions = zeros(n electrons, 3);
electron2 positions = zeros(n electrons, 3);
for i = 1:n electrons
    theta e = 2*pi*i/n electrons;
    electron1 positions(i,:) = [-d/2, circuit radius * cos(theta e),
circuit radius * sin(theta e)];
```

```
electron2 positions(i,:) = [d/2, circuit radius * cos(theta e),
circuit radius * sin(theta e)];
end
electron1 handle = scatter3(electron1 positions(:,1),
electron1 positions(:,2), electron1 positions(:,3), 'b', 'filled');
electron2 handle = scatter3(electron2 positions(:,1),
electron2 positions(:,2), electron2 positions(:,3), 'r', 'filled');
% Field propagation visualization - Fixed initialization
% Initialize field propagation as an empty array first
field propagation = gobjects(1,2);
% Create the surface objects with valid coordinates
field propagation(1) = surf([-d/2 - d/2; -d/2 - d/2], \dots
                            [0 0; 0 0], ...
                            [0 0; 0 0], ...
                            'FaceColor', [0, 0.7, 0], ... % Only RGB
                            'FaceAlpha', 0.2, ...
                                                            % Separate alpha
                            'EdgeColor', 'none', ...
                            'Visible', 'off');
field propagation(2) = surf([d/2 d/2; d/2 d/2], ...
                            [0 0; 0 0], ...
                            [0 0; 0 0], ...
                            'FaceColor', [0, 0, 0.7], ... % Only RGB
                            'FaceAlpha', 0.2, ...
                                                             % Separate alpha
                            'EdgeColor', 'none', ...
                            'Visible', 'off');
% Force visualization
force_arrow1 = quiver3(0, 0, 0, 0, 0, 0, 'b', 'LineWidth', 2, 'MaxHeadSize',
force arrow2 = quiver3(0, 0, 0, 0, 0, 'r', 'LineWidth', 2, 'MaxHeadSize',
0.5);
% Text for information display
% Text for information display - positioned to avoid overlap
current info = text(-d/2, 2*circuit radius, 0, '', 'FontSize', 8,
'HorizontalAlignment', 'left');
time info = text(0, 2*circuit radius, 0, '', 'FontSize', 8,
'HorizontalAlignment', 'center');
field info = text(d/2, 2*circuit radius, 0, '', 'FontSize', 8,
'HorizontalAlignment', 'right');
force info = text(-d/2, 3*circuit radius, 0, '', 'FontSize', 8,
'HorizontalAlignment', 'left');
```

lelativistic Electromagnetic Simulation - Circuits Facing Each Otl



Main simulation loop

```
for step = 1:num steps
    % Update time
    t = step * dt;
    times(step) = t;
    % Determine current direction in circuit 1
    if t > switch time
        circuit1 current = -current magnitude;
        if ~field reached middle
            field reached middle = true;
            disp(['Field reached middle at t = ', num2str(t), ' s']);
        end
    else
        circuit1 current = current magnitude;
    circuit2 current = current magnitude; % Circuit 2 always has same
direction
    % Calculate relativistic factor for electron drift
    v_drift1 = circuit1_current / (pi * wire_radius^2 * e * n_electrons);
    v drift2 = circuit2 current / (pi * wire radius^2 * e * n electrons);
    gamma1 = 1/sqrt(1-(v drift1/c)^2);
    gamma2 = 1/sqrt(1-(v_drift2/c)^2);
    % Update electron positions (with relativistic corrections)
    for i = 1:n electrons
        theta_e = 2*pi*i/n_electrons + t*v_drift1/circuit_radius;
```

```
electron1 positions(i,:) = [-d/2, circuit radius * cos(theta e),
circuit radius * sin(theta e)];
        theta e = 2*pi*i/n electrons + t*v drift2/circuit radius;
        electron2 positions(i,:) = [d/2, circuit radius * cos(theta e),
circuit radius * sin(theta e)];
    end
    % Calculate magnetic field at grid points
    for i = 1:size(Y, 1)
        for j = 1:size(Y, 2)
            % Now we're visualizing the field in the middle XY plane
            observation point = [0, Y(i,j), Z(i,j)];
            % Initialize field components
            B = [0, 0, 0];
            % Calculate retarded time (time for field to propagate from
source to observation point)
            for k = 1:size(circuit1 segments, 1)
                segment = circuit1 segments(k,:);
                source point = segment(1:3);
                dl = segment(4:6) - segment(1:3);
                r = observation point - source point;
                r_mag = norm(r);
                % Skip if observation point is too close to source to avoid
numerical issues
                if r mag < 1e-6
                    continue;
                end
                % Calculate retarded time
                t_ret = t - r_mag/c;
                % Only contribute if field has had time to propagate
                if t ret > 0
                    % Determine current at retarded time
                    if t ret > switch time
                        I ret = -current magnitude;
                    else
                        I ret = current magnitude;
                    end
                    % Biot-Savart law with relativistic corrections
                    dB = mu_0/(4*pi) * I_ret * cross(dl, r/r_mag) / r_mag^2;
                    % Relativistic correction factor
                    rel factor = 1; % Simplified relativistic factor
                    B = B + dB * rel_factor;
                end
            end
```

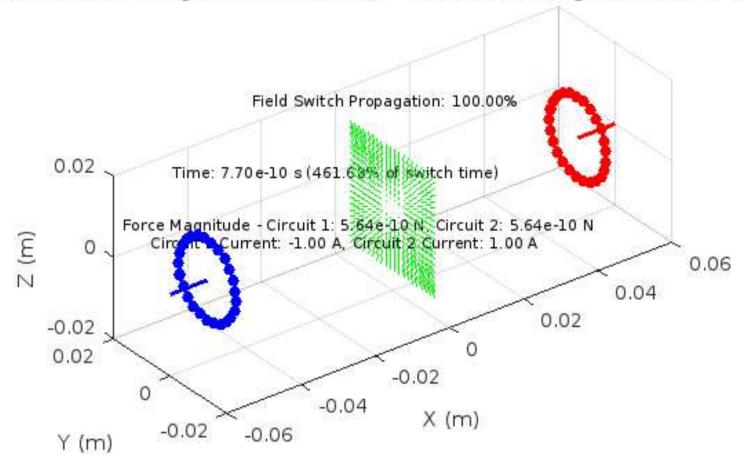
```
% Circuit 2 contribution (similar calculations)
        for k = 1:size(circuit2_segments, 1)
            segment = circuit2 segments(k,:);
            source point = segment(1:3);
            dl = segment(4:6) - segment(1:3);
            r = observation_point - source_point;
            r mag = norm(r);
            if r mag < 1e-6
                continue;
            end
            t ret = t - r mag/c;
            if t ret > 0
                I ret = current magnitude; % Circuit 2 current is constant
                dB = mu_0/(4*pi) * I_ret * cross(dl, r/r_mag) / r_mag^2;
                rel factor = 1; % Simplified relativistic factor
                B = B + dB * rel_factor;
            end
        end
        % Store field components
        Bx(i,j) = B(1);
        By(i,j) = B(2);
        Bz(i,j) = B(3);
    end
end
% Calculate force on each circuit (Lorentz force)
F on circuit1 = [0, 0, 0];
F on circuit2 = [0, 0, 0];
% Force on Circuit 1 due to Circuit 2
for k = 1:size(circuit1 segments, 1)
    segment = circuit1 segments(k,:);
    source point = segment(1:3);
    dl = segment(4:6) - segment(1:3);
    % Calculate magnetic field at this point from Circuit 2
    B at point = [0, 0, 0];
    for m = 1:size(circuit2_segments, 1)
        segment2 = circuit2_segments(m,:);
        source point2 = segment2(1:3);
        d12 = segment2(4:6) - segment2(1:3);
        r = source point - source point2;
        r mag = norm(r);
        if r mag < 1e-6
            continue;
```

```
end
        t_ret = t - r_mag/c;
        if t ret > 0
            I ret = current magnitude;
            \overline{dB} = mu_0/(4*pi) * I_ret * cross(dl2, r/r_mag) / r_mag^2;
            B_at_point = B_at_point + dB;
        end
    end
    % Calculate force element (I \times dl \times B)
    dF = circuit1_current * cross(dl, B_at_point);
    F_on_circuit1 = F_on_circuit1 + dF;
end
% Force on Circuit 2 due to Circuit 1 (similar calculation)
for k = 1:size(circuit2 segments, 1)
    segment = circuit2_segments(k,:);
    source point = segment(1:3);
    dl = segment(4:6) - segment(1:3);
    B_at_point = [0, 0, 0];
    for m = 1:size(circuit1_segments, 1)
        segment1 = circuit1_segments(m,:);
        source_point1 = segment1(1:3);
        dl1 = segment1(4:6) - segment1(1:3);
        r = source point - source point1;
        r_mag = norm(r);
        if r mag < 1e-6
            continue;
        end
        t_ret = t - r_mag/c;
        if t ret > 0
            if t ret > switch time
                I ret = -current magnitude;
            else
                I ret = current magnitude;
            end
            dB = mu_0/(4*pi) * I_ret * cross(dll, r/r_mag) / r_mag^2;
            B \text{ at point} = B \text{ at point} + dB;
        end
    end
    dF = circuit2_current * cross(dl, B_at_point);
    F on circuit2 = F on circuit2 + dF;
end
```

```
% Visualize electromagnetic field propagation
    if t <= switch time*1.5</pre>
        % Calculate propagation radius based on speed of light
        radius = c * t;
        % For circuit 1 - propagating along +X direction
        [Y circle1, Z circle1, X circle1] = cylinder(radius, 50);
        X circle1 = X circle1 * 0.005 - d/2; % Thin disk at x = -d/2
        % For circuit 2 - propagating along -X direction
        [Y circle2, Z circle2, X circle2] = cylinder(radius, 50);
        X circle2 = X circle2 * 0.005 + d/2; % Thin disk at x = d/2
        % Update the field propagation visualization
        set(field propagation(1), 'XData', X circle1, 'YData', Y circle1,
'ZData', Z circle1, 'Visible', 'on');
        set(field propagation(2), 'XData', X circle2, 'YData', Y circle2,
'ZData', Z circle2, 'Visible', 'on');
    end
    % Update visualization
    set(electron1 handle, 'XData', electron1 positions(:,1), 'YData',
electron1_positions(:,2), 'ZData', electron1_positions(:,3));
    set(electron2 handle, 'XData', electron2 positions(:,1), 'YData',
electron2 positions(:,2), 'ZData', electron2 positions(:,3));
    set (quiver handle, 'XData', X, 'YData', Y, 'ZData', Z, 'UData', Bx,
'VData', By, 'WData', Bz);
    % Update force arrows
    F1 center = [-d/2, 0, 0];
    F2 center = [d/2, 0, 0];
    F1 scale = 0.05 * F on circuit1 / (norm(F on circuit1) + eps);
    F2 scale = 0.05 * F on circuit2 / (norm(F on circuit2) + eps);
    set(force arrow1, 'XData', F1 center(1), 'YData', F1 center(2), 'ZData',
F1 center(3), \dots
        'UData', F1 scale(1), 'VData', F1 scale(2), 'WData', F1 scale(3));
    set(force arrow2, 'XData', F2 center(1), 'YData', F2 center(2), 'ZData',
F2 center(3), \dots
        'UData', F2 scale(1), 'VData', F2 scale(2), 'WData', F2 scale(3));
    % Update text information
    set(current info, 'String', sprintf('Circuit 1 Current: %.2f A, Circuit 2
Current: %.2f A', circuit1 current, circuit2 current));
    set(time info, 'String', sprintf('Time: %.2e s (%.2f%% of switch time)',
t, t/switch time*100));
    set(field info, 'String', sprintf('Field Switch Propagation: %.2f%%',
min(t/switch time*100, 100)));
    set(force info, 'String', sprintf('Force Magnitude - Circuit 1: %.2e N,
Circuit 2: %.2e N', norm(F on circuit1), norm(F on circuit2)));
    drawnow;
    % Optional: Capture frame for video
```

```
frames(step) = getframe(gcf);
    % Display progress
    if mod(step, ceil(num steps/10)) == 0
        disp(['Simulation progress: ', num2str(step/num steps*100), '%']);
    end
end
% Optional: Create video
firstFrame = frames(1).cdata;
targetSize = size(firstFrame);
video = VideoWriter('relativistic circuits.avi', 'Motion JPEG AVI');
video.FrameRate = 30;
open (video);
for i = 1:length(frames)
    currentFrame = frames(i).cdata;
    if ~isequal(size(currentFrame), targetSize)
        resizedFrame = imresize(currentFrame, [targetSize(1), targetSize(2)]);
        tempFrame = frames(i);
        tempFrame.cdata = resizedFrame;
        writeVideo(video, tempFrame);
    else
        writeVideo(video, frames(i));
    end
end
close(video);
% Final display
title ('Relativistic Electromagnetic Simulation - Circuits Facing Each Other
(Complete)');
disp('Simulation complete.');
Simulation progress: 10%
Simulation progress: 20%
Field reached middle at t = 1.67e-10 s
Simulation progress: 30%
Simulation progress: 40%
Simulation progress: 50%
Simulation progress: 60%
Simulation progress: 70%
Simulation progress: 80%
Simulation progress: 90%
Simulation progress: 100%
Simulation complete.
```

istic Electromagnetic Simulation - Circuits Facing Each Other (C



Published with MATLAB® R2024b