Fundamental Definitions

- Reliability
 - → Probability that the system has not experienced any failures within a given time period.
- Availability
 - \rightarrow The probability that the system is operational at a given time t.

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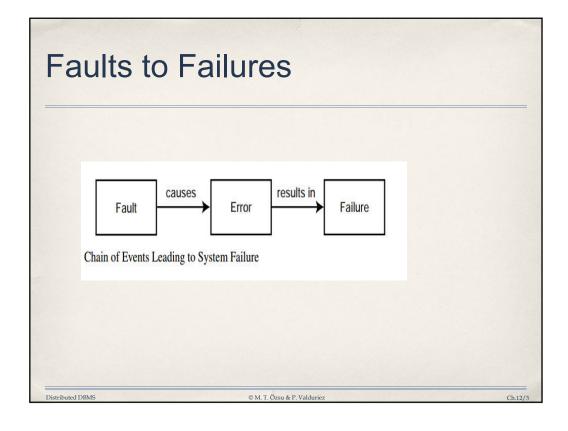
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Fundamental Definitions

- Failure
 - → Failure in a system can be attributed to deficiencies either in the components that make it up, or in the design
- Erroneous state
 - → The transitions from this state would eventually cause a system failure
- Error
 - → The part of the state which is incorrect.
- Fault
 - → An error in the internal states of the components of a system or in the design of a system.

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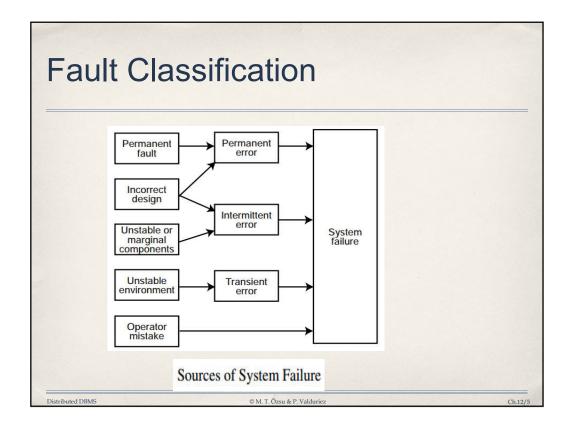


Types of Faults

- Hard faults
 - → Commonly called as Permanent faults
 - → Permanent faults cause permanent errors that result in permanent failures
 - → Recovery from such fault requires repairing the system
- Soft faults
 - → Transient or intermittent faults jointly called soft faults
 - → An intermittent fault refers to fault that demonstrates itself occasionally due to unstable hardware or varying hardware or software states.
 - → Transient fault describes fault that results from temporary environmental conditions.

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Fault-Tolerance Measures

Reliability R(t) refer to the probability that the system under consideration does not experience any failures in a given interval

The mean number of failures in time
$$[0, t]$$
 can be computed as
$$E[k] = \sum_{k=0}^{\infty} k \frac{e^{-m(t)}[m(t)]^k}{k!} = m(t)$$

and the variance can be be computed as

$$Var[k] = E[k^2] - (E[k])^2 = m(t)$$

Thus, reliability of a single component is

$$R(t) = e^{-m(t)}$$

and of a system consisting of n non-redundant components as

$$R_{sys}(t) = \prod_{i=1}^{n} R_i(t)$$

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Fault-Tolerance Measures

Availability A(t) refers to the probability that system is operational according to its specification at a given point in time t

 $A(t) = \Pr{\text{system is operational at time } t}$

Assume

- \bullet Poisson failures with rate λ
- \bullet Repair time is exponentially distributed with mean $1/\mu$

Then, steady-state availability

$$A = \lim_{t \to \infty} A(t) = \frac{\mu}{\lambda + \mu}$$

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Fault-Tolerance Measures

MTBF

Mean time between failures

$$MTBF = \int_{0}^{\infty} R(t) dt$$

MTTR

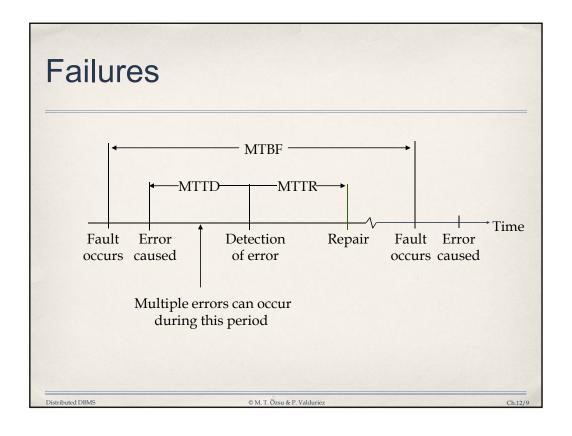
Mean time to repair

Availability

 $\frac{\text{MTBF}}{\text{MTBF} + \text{MTTR}}$

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Failures in Distributed DBMS

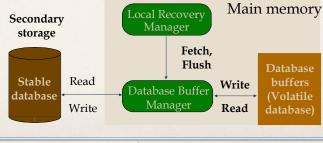
- Transaction failures
 - → Transaction aborts (unilaterally or due to deadlock)
 - → Avg. 3% of transactions abort abnormally
- System (site) failures
 - → Failure of processor, main memory, power supply, ...
 - → Main memory contents are lost, but secondary storage contents are safe
 - → Partial vs. total failure
- Media failures
 - Failure of secondary storage devices such that the stored data is lost
 - → Head crash/controller failure (?)
- Communication failures
 - → Lost/undeliverable messages
 - → Network partitioning

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Local Recovery Management – Architecture

- Volatile storage
 - → Consists of the main memory of the computer system (RAM).
- Stable storage
 - → Resilient to failures and loses its contents only in the presence of media failures (e.g., head crashes on disks).
 - → Implemented via a combination of hardware (non-volatile storage) and software (stable-write, stable-read, clean-up) components.



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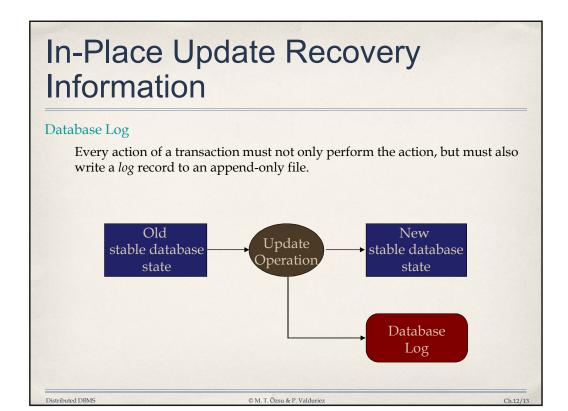
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Update Strategies

- In-place update
 - → Each update causes a change in one or more data values on pages in the database buffers
- Out-of-place update
 - → Each update causes the new value(s) of data item(s) to be stored separate from the old value(s)

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Logging

The log contains information used by the recovery process to restore the consistency of a system. This information may include

- → transaction identifier
- type of operation (action)
- → items accessed by the transaction to perform the action
- → old value (state) of item (before image)
- → new value (state) of item (after image)

. . .

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Why Logging? Upon recovery: - all of T_1 's effects should be reflected in the database (REDO if necessary due to a failure) - none of T_2 's effects should be reflected in the database (UNDO if necessary) $\begin{array}{c|c} system \\ crash \\ Begin \\ T_2 \end{array}$ t time

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