Title: Learning Rules

Aim: Develop a Python script to execute various learning rules commonly employed in deep learning, including the Hebbian Learning Rule, Perceptron Learning Rule, Delta Learning Rule, Correlation Learning Rule, and OutStar Learning Rule.

Tools: None

Procedure:

- 1) Initialize the input vectors associated with the target values.
- 2) Initialize the weights and bias.
- 3) Set learning rules.
- 4) Input layer has a unique activation function.
- 5) Calculate the output.
- 6) Make adjustments of weights comparing the desired output and target values.
- 7) Continue the iterations until there is no change of weights.

Program:

import numpy as np

Hebbian Learning Rule

def hebbian_learning_rule(input_pattern, weight_matrix):

return weight matrix + np.outer(input pattern, input pattern)

Perceptron Learning Rule

```
def perceptron learning rule(input pattern, target, weight vector, learning rate):
  prediction = np.dot(weight vector, input pattern)
      error = target - prediction
  return weight vector + learning rate * error * input pattern
# Delta Learning Rule
def delta learning rule(input pattern, target, weight matrix, learning rate):
  prediction = np.dot(weight matrix, input pattern)
      error = target - prediction
  return weight matrix + learning rate * np.outer(error, input pattern)
# Correlation Learning Rule
def correlation learning rule(input pattern, weight matrix):
  return weight matrix + np.outer(input pattern, input pattern)
# Out Star Learning Rule
def out star learning rule(input pattern, weight matrix, learning rate):
  return weight matrix + learning rate * np.outer(input pattern, input pattern)
input size = 3
# Initialize weights with random values
```

```
hebbian weights = np.random.rand(input size, input size)
perceptron weights = np.random.rand(input size)
delta weights = np.random.rand(input size, input size)
correlation weights = np.random.rand(input size, input size)
out star weights = np.random.rand(input size, input size)
print("Hebbian Weights:",hebbian weights)
print("\nPerceptron Weights:",perceptron weights)
print("\nDelta Weights:",delta weights)
print("\nCorrelation Weights:",correlation weights)
print("\nOut Star Weights:",out star weights)
output:
# Sample input and target data
input pattern = np.array([0.2, 0.5, 0.8])
target = 1
# Apply learning rules
hebbian weights updated = hebbian learning rule(input pattern, hebbian weights)
perceptron weights updated
                                       perceptron learning rule(input pattern,
                                                                                 target,
perceptron weights, learning rate=0.1)
delta_weights_updated
                              delta learning rule(input pattern,
                                                                target,
                                                                          delta_weights,
learning rate=0.1)
correlation weights updated = correlation learning rule(input pattern, correlation weights)
```

```
out_star_weights_updated = out_star_learning_rule(input_pattern, out_star_weights, learning_rate=0.1)

# Display updated weights
print("Hebbian Updated Weights:", hebbian_weights_updated)
print("\nPerceptron Updated Weights:", perceptron_weights_updated)
print("\nDelta Updated Weights:", delta_weights_updated)
print("\nCorrelation Updated Weights:",correlation_weights_updated)
print("\nOut Star Updated Weights:",out_star_weights_updated)
```

Output:

Title: Activation functions to train Neural Network

Aim: Develop a Python program to implement various activation functions, including the sigmoid, tanh (hyperbolic tangent), ReLU (Rectified Linear Unit), Leaky ReLU, and softmax. The program should include functions to compute the output of each activation function for a given input. Additionally, it should be capable of plotting graphs representing the output of each activation function over a range of input values.

```
Tools: None
Procedure:
1) Check data that is linearly separable or not.
2) Analyze the activation functions.
3) Set up code for plotting
Program:
import numpy as np
import matplotlib.pyplot as plt
def plot sigmoid():
  x = np.linspace(-10, 10, 100)
  y = 1 / (1 + np.exp(-x))
  plt.plot(x, y)
  plt.xlabel('Input')
  plt.ylabel('Sigmoid Output')
  plt.title('Sigmoid Activation Function')
  plt.grid(True)
  plt.show()
```

```
def plot_tanh():
  x = np.linspace(-10, 10, 100)
  tanh = np.tanh(x)
  plt.plot(x, tanh)
  plt.title("Hyperbolic Tangent (tanh) Activation Function")
  plt.xlabel("x")
  plt.ylabel("tanh(x)")
  plt.grid(True)
  plt.show()
def plot relu():
  x = np.linspace(-10, 10, 100)
  relu = np.maximum(0, x)
  plt.plot(x, relu)
  plt.title("ReLU Activation Function")
  plt.xlabel("x")
  plt.ylabel("ReLU(x)")
  plt.grid(True)
  plt.show()
def plot leaky relu():
  x = np.linspace(-10, 10, 100)
   def leaky relu(x, alpha=0.1):
```

```
return np.where(x \ge 0, x, alpha * x)
  # Compute leaky ReLU values for corresponding x
  leaky relu values = leaky relu(x)
  # Plot the leaky ReLU function
  plt.plot(x, leaky relu values)
  plt.title("Leaky ReLU Activation Function")
  plt.xlabel("x")
  plt.ylabel("Leaky ReLU(x)")
  plt.grid(True)
  plt.show()
def softmax(z):
  exp z=np.exp(z)
  class labels = ["Seal", "Panda", "Duck"]
  soft ac = [i/sum(exp z) \text{ for } i \text{ in } exp z]
  plot softmax(soft ac, class labels)
# Example usage:
  x = np.array([1, 2, 3])
  result = softmax act(x)
  print(result)
  def plot softmax(probabilities, class labels):
    plt.bar(class labels, probabilities)
```

```
plt.xlabel("Class")
    plt.ylabel("Probability")
    plt.title("Softmax Output")
    plt.show()
# calling the function
while True:
  print("\nMAIN MENU")
  print("1. Sigmoid")
  print("2. Hyperbolic tangent")
  print("3.Rectified Linear Unit")
  print("4.Leaky ReLU")
  print("5.Softmax")
  print("6.Exit")
  choice = int(input("Enter the Choice:"))
  if choice == 1:
    plot_sigmoid()
  elif choice ==2:
    plot tanh()
  elif choice ==3:
    plot relu()
  elif choice ==4:
    plot leaky relu()
  elif choice ==5:
```

```
softmax()
elif choice ==6:
  break
else:
  print("Oops! Incorrect Choice.")
```

Output:

EXPERIMENT-3

Title: Perceptron Networks

Aim:Implement a python program for Perceptron Networks by considering the given scenario. A student wants to make a decision about whether to go for a movie or not by looking at 3 parameters using a single neuron. The three inputs are Favorite hero, Exam, and Climate. Each has weights and we have a bias in the perceptron. If the condition is true input is 1 else input is 0, weights for Favorite hero=0.2, Exam=0.4, and Climate=0.2 and bias=-0.5. Output is 1. The decision is to go for a movie. Calculate the Accuracy

Tools: None

Procedure:

- 1) Initialize the input vector.
- 2) Train the network weights for the perceptron.
- 3) Make predictions with the perceptron.
 - import the necessary libraries
 - Assign the input features to x
 - Assign the target features to y
 - Initialize the Perceptron with the appropriate number of inputs
 - Train the model

- Predict from the test dataset
- Find the accuracy of the model

```
Program:
#import library
import numpy as np
class Perceptron:
      A simple perceptron classifier.
       *****
       def ___init___(self, weights=None, bias=o):
      self.weights = weights
       self.bias = bias
       def initialize(self, n_features):
       """Set initial w and b as zeros if not provided"""
      if self.weights is None:
      self.weights = np.zeros(n_features)
       if self.bias is None:
       self.bias = o
      return
```

```
def predict(self, inputs):
*****
Predict the class labels for new input data.
Calculate the step activation function.
activation = np.dot(inputs, self.weights) + self.bias
return 1 if activation > 0 else 0
def train(self, X, y, epochs=100, learning_rate=0.1):
"""Train the perceptron using the input data and target labels."""
# Initialize the weights and bias
self.initialize(X.shape[1])
for epoch in range(epochs):
for inputs, label in zip(X, y):
# Get prediction
y_pred = self.predict(inputs)
# Calculate delta error
error = label - y_pred
# Update weights and bias
self.weights += learning_rate * error * inputs
self.bias += learning_rate * error
return
```

Example usage with customized weights

```
X_train = np.array([[0, 0, 1], [0, 1, 1], [1, 0, 1], [1, 1, 1]])
y_{train} = np.array([0, 0, 0, 1])
custom_weights = np.array([0.2, 0.4, 0.6]) # Customized weights
custom_bias = -0.5 # Customized bias
p = Perceptron(weights=custom_weights, bias=custom_bias)
p.train(X_train, y_train, epochs=100, learning_rate=0.1)
# Test prediction
test_input = np.array([0, 1, 1])
print("Prediction:", p.predict(test_input)) # Output: 0
# Evaluate accuracy
X_{\text{test}} = \text{np.array}([[0, 0, 1], [0, 1, 1], [1, 0, 1], [1, 1, 1]])
y_{test} = np.array([0, 0, 0, 1])
# Predict on test data
pred = np.array([p.predict(x) for x in X_test])
# Calculate accuracy
accuracy = np.mean(pred == y_test) *100
print("Accuracy:", accuracy)
Output:
Prediction: 0
Accuracy: 100.0
```

Title:Image processing operations

Aim: Write a program in deep learning to apply image processing operations such as Histogram equalization, Thresholding, Edge detection, Data augmentation, Morphological Operations.

Tools: library opency-python

Procedure:

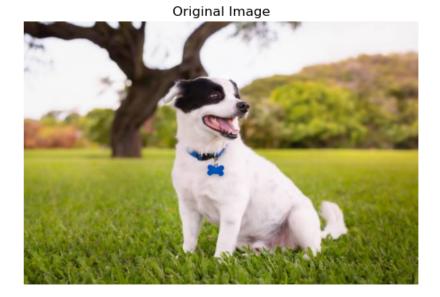
- 1. Load the image as an input
- 2. Apply image processing operations such as Histogram equalization, Thresholding, Edge detection, Data augmentation, Morphological Operations.
- 3. Set up code for plotting

Program:

```
#!pip install opency-python
# Load the libraries
import cv2
import matplotlib.pyplot as plt
import numpy as np
```

```
#uploading an image
img = cv2.imread('puppy.jpg')
plt.axis("off")
plt.title("Original Image")
plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
plt.show()
```

Output:

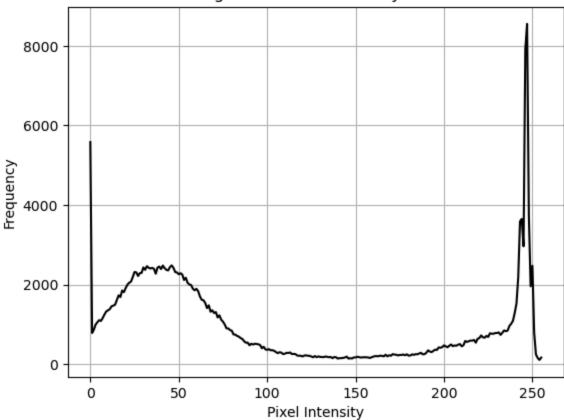


Compute the histogram and plot

histogram = cv2.calcHist([img], [0], None, [256], [0, 256])

plt.plot(histogram, color='black')
plt.xlabel('Pixel Intensity')
plt.ylabel('Frequency')
plt.title('Histogram of Pixel Intensity Values')
plt.grid(True)
plt.show()





#Displaying the Blurred Image

```
gaussian_image = cv2.GaussianBlur(resized_img, (15, 15), 0)
plt.imshow(gaussian_image)
#Canny(image, low_threshold, high_threshold)
```

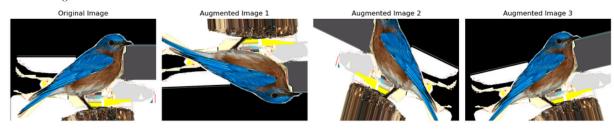
```
edge = cv2.Canny(resized img, 100, 200)
plt.imshow(edge)
brightness = cv2.addWeighted(resized img, 1.2, resized img, 0, 70)
plt.imshow(brightness)
def sharpen image(image):
  kernel = np.array([[-1, -1, -1],
             [-1, 9, -1],
             [-1, -1, -1]
  return cv2.filter2D(image, -1, kernel)
sharpened image = sharpen image(resized img)
plt.imshow(resized img)
original_and_sharpened_image = np.hstack((resized_img, sharpened_image))
plt.figure(figsize = [30, 30])
plt.axis('off')
plt.imshow(original and sharpened image[:,:,::-1])
#data Augmentation
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.preprocessing.image import ImageDataGenerator,
array to img, img to array, load img
input dir = 'data'
# Initialize ImageDataGenerator for augmentation
datagen = ImageDataGenerator(
                        # Rotation angle range (degrees)
  rotation range=20,
```

```
width shift range=0.1, # Fractional shift in the width direction
  height shift range=0.1, # Fractional shift in the height direction
  shear range=0.2,
                        # Shear intensity (angle in radians)
                        # Range for random zoom
  zoom range=0.2,
  horizontal flip=True, # Randomly flip inputs horizontally
                       # Randomly flip inputs vertically
  vertical flip=True,
  fill mode='nearest'
                       # Strategy for filling in newly created pixels
)
# Load an example image to use for augmentation
img = load img('bird.png')
x = img to array(img)
x = np.expand dims(x, axis=0)
# Generate augmented images
num images =10
augmented images = []
# Generate augmented images using the datagen.flow() method
for i, batch in enumerate(datagen.flow(x, batch size=1)):
  augmented images.append(array to img(batch[0]))
  if i \ge num images - 1:
    break
# Display the original image and augmented images
plt.figure(figsize=(15, 6))
plt.subplot(1, num images + 1, 1)
plt.imshow(img)
plt.title('Original Image')
plt.axis('off')
```

```
for i in range(num images):
  plt.subplot(1, num images +1, i + 2)
  plt.imshow(augmented images[i])
  plt.title(f'Augmented Image \{i + 1\}')
  plt.axis('off')
plt.tight layout()
plt.show()
# Histogram
import matplotlib.pyplot as plt
from skimage import io, exposure
# Load an image (replace 'input image.jpg' with your image file path)
input image = io.imread('puppy.jpg', as gray=True)
# Apply histogram equalization
/*Histogram Equalization is a technique used in image processing to enhance the
contrast of an image by adjusting the intensity distribution of its pixels*/
equalized image = exposure.equalize hist(input image)
# Display original and equalized images side by side
plt.figure(figsize=(12, 6))
# Plot the original image
plt.subplot(1, 2, 1)
plt.imshow(input image, cmap='gray')
plt.title('Original Image')
plt.axis('off')
# Plot the equalized image
plt.subplot(1, 2, 2)
plt.imshow(equalized image, cmap='gray')
plt.title('Histogram Equalized Image')
```

plt.axis('off')

plt.tight_layout() plt.show()



#Morphological Operations (Erosion)
kernel = np.ones((5, 5), np.uint8)
eroded_image = cv2.erode(gray_image, kernel, iterations=1)
plt.subplot(2, 3, 6)
plt.imshow(eroded_image, cmap='gray')
plt.title('Morphological Operations (Erosion)')
plt.axis('off')

Morphological Operations (Erosion)



from skimage import filters import matplotlib.pyplot as plt # Thresholding (Simple Binary Thresholding) thresh_value = filters.threshold_otsu(gray_image) binary_image = gray_image > thresh_value plt.subplot(2, 3, 3) plt.imshow(binary_image, cmap='gray') plt.title('Thresholding')

plt.axis('off')

Thresholding



Experiment No: 5

Title: STYLE TRANSFER FOR AN IMAGE

Aim: Implement image style transfer, transforming a given content image to adopt the artistic style of another image, using a pre-trained model.

Tools: tensor flow and cv2 library

Procedure:

- 1. Load a STYLE IMAGE and a content Image.
- 2. Use tensor flow and cv2 library
- 3. Resizing the style image
- 4. Apply the Arbitrary Image Stylization" model from TensorFlow Hub
- 5. Display the output image

Program:

#Importing Packages

import tensorflow_hub as hub import tensorflow as tf import cv2 import numpy as np import matplotlib.pyplot as plt from tensorflow.python.ops.numpy_ops import np_config; np_config.enable_numpy_behavior()

#Download and Upload the image.

#I downloaded and uploaded the photos:

• For style: https://imgur.com/900B601

• For content: https://i.imgur.com/F28w3Ac.jpg

```
#Download the image in google colab
!curl https://imgur.com/900B60I.jpeg -o style.jpeg
!curl https://i.imgur.com/F28w3Ac.jpg -o content.jpg
# IOAD THE IMAGE
def load img(path):
  img = cv2.imread(path)
  img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
  img = img/255.
  return img
content_image = load_img('style.jpeg')
style_1 = load_img('content.jpeg')
#content_image = load_img('content.jpeg')
#style_1 = load_img('style.jpeg')
model =
hub.load('https://tfhub.dev/google/magenta/arbitrary-image-stylization-v1-2
56/2')
# Apply the style
def apply style(content image, style):
 content_image = content_image.reshape(1, content_image.shape[0],
content_image.shape[1], content_image.shape[2]).astype('float32')
```

content image = tf.convert to tensor(content image)

```
style = cv2.resize(style, (256,256))
style = style.reshape(1, style.shape[0], style.shape[1],
style.shape[2]).astype('float32')
outputs = model(tf.constant(content_image), tf.constant(style))
stylized_image = outputs[0]
return stylized_image
#display the image
img = apply_style(content_image, style_1)
plt.xticks([])
plt.yticks([])
plt.grid(False)
plt.imshow(img[0])
```

Output:



Aim: Implement in python SVM/Softmax classifier for CIFAR-10 dataset.

Tools:Tensorflow, CIFAR-10

Procedure:

- 1. Load the CIFAR-10
- 2. Preprocess the data
 - a. Normalize the pixel values to be between 0 and 1.
 - b. Convert the class labels to one-hot encoded vectors.
- 3. Train the data with SVM classifier
- 4. Train the data with Softmax classifier using KNN
- 5. Make predictions with the SVM/Softmax classifier.

Program:

#import library

```
import tensorflow as tf
import numpy as np
from tensorflow.keras.datasets import cifar10
from sklearn.preprocessing import OneHotEncoder
```

classify test and train data

#load the cifar data set X-image, y-label for train and test

```
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# define the class name for easier interpretation of predictions.

cifar_10_classes = [
    "Airplane",
```

```
"Airplane",
"Automobile",
"Bird",
"Cat",
"Deer",
"Dog",
"Frog",
"Horse",
"Ship",
"Truck"
```

```
X_train.shape

import matplotlib.pyplot as plt

plt.imshow(x_train[0])
plt.title(cifar_10_classes[y_train[0][0]])
plt.axis("off")

#Normalizing the pixel values to be between 0 and 1

X_train = x_train / 255.0

X_test = x_test / 255.0
```

#Converting the class labels to one-hot encoded vectors. Converting the class labels to one-hot encoded vectors.

```
one_hot_encoder = OneHotEncoder()
y_train = one_hot_encoder.fit_transform(y_train).toarray()
y_test = one_hot_encoder.transform(y_test).toarray()
#build softmax layer
```

- Creating a simple neural network model with a single layer.
- Flatten layer converts the 32x32x3 images into a flat vector.
- Dense layer with softmax activation outputs probabilities for each of the 10 classes.

#Training the model for 20 epochs with a batch size of 64, using a validation split for evaluation.

```
softmax_model.fit(X_train, y_train, epochs=20, batch_size=64,
validation_data=(X_test, y_test))
#Making a prediction using the trained model
```

```
new_image = x_test[10]
plt.imshow(new_image)
plt.axis("off")

img = np.expand_dims(new_image, axis=0)

img.shape

pred = softmax_model.predict(img)

pred

prediction = np.argmax(pred)
Cifar 10 classes[prediction]
```

Output:

Title: MULTI-LAYER NEURAL NETWORKS

Aim: Develop a convolutional neural network (CNN) model to classify handwritten digits using the MNIST dataset. The goal is to train a model that accurately identifies digits (0-9) from images.

Tools: None

Procedure:

- 1. Prepare the Data
- 2. Define the Model
- 3. Train the Model
- 4. Evaluate the model
- 5. Make predictions

Program:

#importing libraries

import pandas as pd

import tensorflow as tf

import matplotlib.pyplot as plt

import tensorflow.keras as keras

import numpy as np

#load the dataset and divide into train and test print the shape and size

dataset = keras.datasets.mnist

class_names = ['Zero','one','two','three','Four','Five','Six','seven','Eight','nine']

(x_train,y_train),(x_test,y_test) = dataset.load_data()

 $X_{train} = x_{train.reshape}((x_{train.shape}[0], x_{train.shape}[1], x_{train.shape}[2], 1))$

 $X_{\text{test}} = x_{\text{test.reshape}}((x_{\text{test.shape}}[0],x_{\text{test.shape}}[1],x_{\text{test.shape}}[2],1))$

```
print(X train.shape)
print(X test.shape)
# plot five data with its class name
plt.figure(figsize=(10,10))
for i in range(9):
  plt.subplot(3,3,i+1)
  plt.imshow(x train[i])
  plt.title(class names[y train[i]])
  plt.axis("off")
#convert into grayscale
X train=X train/255
X \text{ test=} X \text{ test/} 255
#Model
model = keras.models.Sequential([
  keras.layers.Conv2D(64,(3,3),input shape=(28,28,1),activation="relu"),
  keras.layers.MaxPool2D(pool size=(2,2),strides=1),
  keras.layers.Conv2D(64,(3,3),input shape=(28,28,1),activation="relu"),
  keras.layers.MaxPool2D(pool size=(2,2),strides=1),
  keras.layers.Flatten(),
  keras.layers.Dense(64,activation="relu"),
```

```
keras.layers.Dense(10,activation="softmax")
])
model.compile(optimizer="adam",loss=tf.keras.losses.SparseCategoricalCrossentr
opy(from_logits=True),metrics=["accuracy"])
model.fit(x train,y train,epochs=5,callbacks=keras.callbacks.EarlyStopping(patien
ce=2)
#evaluting the model
model.evaluate(x test,y test)
#Prediction
sample img = X test[0]
sample_img.shape
plt.imshow(sample img)
img = np.expand dims(sample img,axis=0)
img.shape
pred = model.predict(img)
pred
```

Title: Dropout Regularization In Deep Neural Network

Aim: Design and implement a deep learning model to classify underwater sonar signals into two categories (Rocks 'R' or Mines 'M') using the <code>sonar_dataset.csv</code>. Evaluate the performance of the model on unseen test data and demonstrate the impact of incorporating dropout layers to improve generalization.

Tools: Tensorflow

Procedure:

- 1. Load the dataset sonar dataset.csv
- 2. Train the model with configuration drop out
- 3. Evaluate models on test data

Program

#import the libraries import numpy as np import pandas as pd import matplotlib.pyplot as plt import seaborn as sns

import warnings
warnings.filterwarnings('ignore')

df = pd.read_csv("sonar_dataset.csv", header=None)
df.sample(5)

```
df.shape
# check for nan values
df.isna().sum()
df.columns
df[60].value counts() # label is not skewed
X = df.drop(60, axis=1)
y = df[60]
y.head()
y = pd.get dummies(y, drop first=True)
y.sample(5) # R --> 1 and M --> 0
y.value_counts()
X.head()
from sklearn.model selection import train test split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.25,
random state=1)
X train.head()
```

Using Deep Learning Model

Model without Dropout Layer

import tensorflow as tf

```
model = keras.Sequential([
  keras.layers.Dense(60, input dim=60, activation='relu'),
  keras.layers.Dense(30, activation='relu'),
  keras.layers.Dense(15, activation='relu'),
  keras.layers.Dense(1, activation='sigmoid')
])
model.compile(loss='binary crossentropy', optimizer='adam', metrics=['accuracy'])
model.fit(X train, y train, epochs=100, batch size=8)
model.evaluate(X test, y test)
y pred = model.predict(X test).reshape(-1)
print(y pred[:10])
# round the values to nearest integer ie 0 or 1
y pred = np.round(y pred)
print(y pred[:10])
y test[:10]
from sklearn.metrics import confusion matrix, classification report
print(classification report(y test, y pred))
```

Model with Dropout Layer

```
modeld = keras.Sequential([
```

```
keras.layers.Dense(60, input dim=60, activation='relu'),
  keras.layers.Dropout(0.5),
  keras.layers.Dense(30, activation='relu'),
  keras.layers.Dropout(0.5),
  keras.layers.Dense(15, activation='relu'),
  keras.layers.Dropout(0.5),
  keras.layers.Dense(1, activation='sigmoid')
])
modeld.compile(loss='binary crossentropy', optimizer='adam',
metrics=['accuracy'])
modeld.fit(X train, y train, epochs=100, batch size=8)
modeld.evaluate(X test, y test)
Training Accuracy is still good but Test Accuracy Improved
y pred = modeld.predict(X test).reshape(-1)
print(y pred[:10])
# round the values to nearest integer ie 0 or 1
y pred = np.round(y pred)
print(y pred[:10])
from sklearn.metrics import confusion matrix, classification report
print(classification report(y test, y pred))
Output:
```

You can see that by using dropout layer test accuracy increased from 0.77 to 0.81

Title: Image segmentation using mask RCNN

Aim: To implement an object detection and segmentation model using Mask R-CNN on a given image.

Tools:Tensorflow

Procedure:

1. Set Up the Environment:

- Clone the Mask R-CNN repository and set up the necessary libraries and modules.
- Define the root directory for the project and add the Mask R-CNN module to the system path.
- Specify the directory to save logs and the trained model.

2. Load and Configure the Model:

- Load the Mask R-CNN model in inference mode.
- Download the pre-trained weights if they do not exist in the specified path.
- Configure the model for inference by setting parameters like the number of GPUs and images per GPU.

3. Define Class Names:

• Use the class names from the COCO dataset for easier interpretation of the model's predictions.

4. Load and Visualize the Image:

- Upload and read the input image using skimage.
- Display the original image for reference.

5. Perform Object Detection and Segmentation:

- Use the Mask R-CNN model to detect objects in the image.
- Display the results, including bounding boxes, class labels, segmentation masks, and confidence scores for each detected object.

Program:

!git clone https://github.com/akTwelve/Mask RCNN.git

#import libraries

```
import os
import sys
import skimage.io
import matplotlib.pyplot as plt
import cv2
import time
import numpy as np
import tensorflow as tf

# Root directory of the project
ROOT_DIR = "Mask_RCNN"

# Import maskronn (mronn folder) as module
sys.path.append(ROOT_DIR)
```

Make sure to upload the Image and you need to be inside MASK_RCNN folder

to run from mrcnn. So keep in kind about the path

```
from mrcnn import utils
import mrcnn.model as modellib
from mrcnn import visualize

# Directory to save logs and trained model

MODEL_DIR = os.path.join(ROOT_DIR, "logs")

# upload image path

IMAGE_PATH = "/content/Mask_RCNN/images/1045023827_4ec3e8ba5c_z.jpg"
```

#Download the COCO dataset

```
sys.path.append(os.path.join(ROOT_DIR, "samples/coco/"))
import coco

# Weights oath of Mask RCNN

COCO_MODEL_PATH = os.path.join(ROOT_DIR, "mask_rcnn_coco.h5")

if not os.path.exists(COCO_MODEL_PATH):
    utils.download_trained_weights(COCO_MODEL_PATH)

# Loading the model configuration

class InferenceConfig(coco.CocoConfig):
    GPU_COUNT = 1
    IMAGES_PER_GPU = 1

config = InferenceConfig()

config.display()
```

```
'zebra', 'giraffe', 'backpack', 'umbrella', 'handbag',
'tie',
               'suitcase', 'frisbee', 'skis', 'snowboard', 'sports ball',
               'kite', 'baseball bat', 'baseball glove', 'skateboard',
                    'surfboard', 'tennis racket', 'bottle', 'wine glass',
'cup',
               'fork', 'knife', 'spoon', 'bowl', 'banana', 'apple',
                   'sandwich', 'orange', 'broccoli', 'carrot', 'hot dog',
'pizza',
               'donut', 'cake', 'chair', 'couch', 'potted plant', 'bed',
                      'dining table', 'toilet', 'tv', 'laptop', 'mouse',
'remote',
               'keyboard', 'cell phone', 'microwave', 'oven', 'toaster',
                       'sink', 'refrigerator', 'book', 'clock', 'vase',
'scissors',
               'teddy bear', 'hair drier', 'toothbrush']
```

```
image = skimage.io.imread(IMAGE_PATH)

plt.imshow(image)

plt.title('Original')

plt.axis('off')

plt.show()
```

Original





Title:Study the effect of batch normalization and dropout in neural network classifier

Aim: The aim of the study of the effect of batch normalization and dropout in neural network classifiers is to build, train, and evaluate a deep neural network model for the classification of handwritten digits using the MNIST dataset. The MNIST dataset is a widely recognized benchmark for image classification algorithms, consisting of 60,000 training images and 10,000 test images of handwritten digits (0-9).

Tools: None

Procedure:

1. Load and Preprocess the Data:

- Load the MNIST dataset.
- Normalize the pixel values of the images to be between 0 and 1.
- 2. Build the Neural Network Model

- 3. Compile the Model
- 4. Train the Model
- 5. Evaluate the Model

```
Program:
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Flatten, Dense, BatchNormalization,
Dropout
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.datasets import mnist
(X train, y train), (X test, y test) = mnist.load data()
X train = X train / 255.0
X \text{ test} = X \text{ test} / 255.0
model = Sequential([
        Flatten(input shape=(28, 28)),
        Dense(128, activation='relu'),
        BatchNormalization(), # Adding Batch Normalization layer
        Dropout (0.2),
                                # Adding Dropout layer with dropout rate of
0.2
        Dense(64, activation='relu'),
        BatchNormalization(),
        Dropout (0.2),
        Dense(10, activation='softmax')
    ])
model.compile(optimizer="adam",
              loss='sparse categorical crossentropy',
              metrics=['accuracy'])
history = model.fit(X train, y train, epochs=10, batch size=32,
validation data=(X test, y test))
train loss, train acc = model.evaluate(X train, y train)
print("Train Loss:", train loss)
print("Train accuracy:", train acc)
```

Output:

Aim: Chatbots using bidirectional LSTMs Tools

Tools: LSTMs

Procedure:

- 1. Define a simple dataset of conversation pairs, create a vocabulary from the dataset and convert conversations into numerical sequences.
- 2. Pad sequences have equal lengths.
- 3. Define a bidirectional LSTM model with an embedding layer and a dense output layer.
- 4. Train the model on the conversation data.
- 5. Define a function to generate responses based on user inputs.

```
Program:
import os
from zipfile import ZipFile
from IPython.display import FileLink
# Assuming you manually uploaded the kaggle.json file to your Jupyter
environment
# Check if the kaggle.json file is present
if 'kaggle.json' not in os.listdir():
   print("Please upload your Kaggle API key (kaggle.json).")
# Install the Kaggle package
!pip install -q kaggle
# Create Kaggle directory and move the API key file
!mkdir -p ~/.kaggle
!cp kaggle.json ~/.kaggle/
!chmod 600 ~/.kaggle/kaggle.json
# Download the dataset
!kaggle datasets download -d kausr25/chatterbotenglish
# Unzip the downloaded file
with ZipFile('chatterbotenglish.zip', 'r') as zip ref:
   zip ref.extractall()
# Check the contents of the directory
dir path = '.'
data = os.listdir(dir path)
print(data)
import yaml
```

```
import os
dir path = '/content'
data = os.listdir(dir path + os.sep)
data
files list = []
for i in data:
 if i.endswith(('.yml', '.yaml')):
    files list.append(i)
files list
questions, answers = [], []
for filepath in files list:
    file = open(dir path + os.sep + filepath , 'rb')
   docs = yaml.safe load(file )
   conversations = docs['conversations']
   for con in conversations:
        if len(con) > 2:
            questions.append(con[0])
            replies = con[1 :]
           ans = ''
           for rep in replies:
                ans += ' ' + rep
            answers.append(ans)
       elif len(con) > 1:
            questions.append(con[0])
            answers.append(con[1])
questions
import numpy as np
from tensorflow.keras import layers , activations , models , preprocessing,
answers with tags = []
for i in range(len(answers)):
   if type(answers[i]) == str:
       answers with tags.append(answers[i])
   else:
  questions.pop(i)
answers = []
for i in range(len(answers_with_tags)) :
   answers.append('<START> ' + answers with tags[i] + ' <END>')
tokenizer = preprocessing.text.Tokenizer()
tokenizer.fit on texts(questions + answers)
```

```
VOCAB SIZE = len(tokenizer.word index)+1
from gensim.models import Word2Vec
import re
vocab = []
for word in tokenizer.word index:
   vocab.append(word)
def tokenize (sentences):
  tokens list = []
   vocabulary = []
   for sentence in sentences:
       sentence = sentence.lower()
       sentence = re.sub('[^a-zA-Z]', ' ', sentence)
      tokens = sentence.split()
       vocabulary += tokens
       tokens list.append(tokens)
    return tokens list , vocabulary
tokenized questions = tokenizer.texts to sequences(questions)
maxlen questions = max([len(x) for x in tokenized questions])
padded questions = preprocessing.sequence.pad sequences(tokenized questions ,
maxlen=maxlen questions , padding='post')
encoder input data = np.array(padded questions)
encoder input data = np.array(padded questions)
tokenized questions = tokenizer.texts to sequences(questions)
maxlen questions = max([len(x) for x in tokenized questions])
padded questions = preprocessing.sequence.pad sequences(tokenized questions ,
maxlen=maxlen questions , padding='post')
encoder input data = np.array(padded questions)
tokenized answers = tokenizer.texts to sequences(answers)
for i in range(len(tokenized answers)) :
    tokenized answers[i] = tokenized answers[i][1:]
padded answers = preprocessing.sequence.pad sequences(tokenized answers ,
maxlen=maxlen answers , padding='post')
onehot answers = utils.to categorical(padded answers , VOCAB SIZE)
decoder output data = np.array(onehot answers)
import tensorflow as tf
encoder inputs = tf.keras.layers.Input(shape=(maxlen questions ,))
encoder embedding = tf.keras.layers.Embedding(VOCAB SIZE, 200 , mask zero=True)
(encoder inputs)
encoder outputs , state h , state c = tf.keras.layers.LSTM(200) ,
return state=True) (encoder embedding)
```

```
encoder_states = [ state_h , state_c ]

decoder_inputs = tf.keras.layers.Input(shape=(maxlen_answers , ))
decoder_embedding = tf.keras.layers.Embedding(VOCAB_SIZE, 200 , mask_zero=True)
(decoder_inputs)
decoder_lstm = tf.keras.layers.LSTM(200 , return_state=True ,
return_sequences=True)
decoder_outputs , _ , _ = decoder_lstm (decoder_embedding ,
initial_state=encoder_states)
decoder_dense = tf.keras.layers.Dense(VOCAB_SIZE ,
activation=tf.keras.activations.softmax)
output = decoder_dense (decoder_outputs)

model = tf.keras.models.Model([encoder_inputs, decoder_inputs], output)

model.compile(optimizer=tf.keras.optimizers.RMSprop(),
loss='categorical_crossentropy')

model.summary()
```

Model: "model"

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	[(None, 22)]	0	[]
input_2 (InputLayer)	[(None, 74)]	0	[]
embedding (Embedding)	(None, 22, 200)	378800	['input_1[0][0]']
embedding_1 (Embedding)	(None, 74, 200)	378800	['input_2[0][0]']
lstm (LSTM)	[(None, 200), (None, 200), (None, 200)]	320800	['embedding[0][0]']
lstm_1 (LSTM)	[(None, 74, 200), (None, 200), (None, 200)]	320800	['embedding_1[0][0]', 'lstm[0][1]', 'lstm[0][2]']
dense (Dense)	(None, 74, 1894)	380694	['lstm_1[0][0]']

Total params: 1779894 (6.79 MB)

Trainable params: 1779894 (6.79 MB) Non-trainable params: 0 (0.00 Byte)

model.fit([encoder_input_data , decoder_input_data], decoder_output_data,
batch size=32, epochs=100)

```
: model.fit([encoder_input_data , decoder_input_data], decoder_output_data, batch_size=32, epochs=10
  18/18 [============= ] - 7s 367ms/step - loss: 4.0626
  Epoch 7/100
  18/18 [============ ] - 8s 464ms/step - loss: 4.0389
  Epoch 8/100
  Epoch 9/100
  Epoch 10/100
  18/18 [============ ] - 8s 429ms/step - loss: 3.9757
  Epoch 11/100
  Epoch 12/100
  18/18 [=========== ] - 8s 462ms/step - loss: 3.9360
  Epoch 13/100
  Epoch 14/100
  18/18 [========== ] - 8s 454ms/step - loss: 3.8797
  Epoch 15/100
  Fnoch 16/100
encoder model = tf.keras.models.Model(encoder inputs, encoder states)
decoder state input h = tf.keras.layers.Input(shape=(200 ,))
decoder state input c = tf.keras.layers.Input(shape=(200 ,))
decoder states inputs = [decoder state input h, decoder state input c]
decoder outputs, state h, state c = decoder lstm(
   decoder embedding , initial state=decoder states inputs)
decoder states = [state h, state c]
decoder outputs = decoder dense(decoder outputs)
decoder model = tf.keras.models.Model(
   [decoder inputs] + decoder states inputs,
   [decoder outputs] + decoder states)
def preprocess input (input sentence):
   tokens = input sentence.lower().split()
   tokens list = []
   for word in tokens:
      tokens list.append(tokenizer.word index[word])
   return preprocessing.sequence.pad sequences([tokens list] ,
maxlen=maxlen questions , padding='post')
tests = ['Hello', 'Are you a bot', 'What is your name', 'That is a very long
name', 'see you later']
for i in range(5):
   states values = encoder model.predict(preprocess input(tests[i]))
   empty target seq = np.zeros((1, 1))
   empty target seq[0, 0] = tokenizer.word index['start']
   stop condition = False
   decoded translation = ''
```

```
while not stop condition :
     dec outputs , h , c = decoder model.predict([empty target seq] +
states values)
    sampled word index = np.argmax(dec outputs[0, -1, :])
     sampled word = None
    for word , index in tokenizer.word index.items():
       if sampled word index == index :
          decoded translation += f' {word}'
          sampled word = word
     if sampled_word == 'end' or len(decoded translation.split()) >
maxlen answers:
       stop condition = True
     empty target seq = np.zeros((1 , 1))
     empty target seq[0 , 0] = sampled word index
     states values = [h , c]
  print(f'Human: {tests[i]}')
  print()
  decoded translation = decoded translation.split(' end')[0]
  print(f'Bot: {decoded translation}')
  print('-'*25)
 1/1 [====== ] - 2s 2s/step
 1/1 [======] - 1s 1s/step
 1/1 [======] - 0s 23ms/step
 1/1 [======] - 0s 25ms/step
 1/1 [======] - 0s 24ms/step
 1/1 [====== ] - 0s 24ms/step
 Human: Hello
 Bot: i am not really really stock
 -----
 1/1 [====== ] - 0s 26ms/step
 1/1 [======] - 0s 24ms/step
 1/1 [====== ] - 0s 23ms/step
 1/1 [======] - 0s 24ms/step
 1/1 [======] - 0s 25ms/step
 1/1 [======] - 0s 23ms/step
 1/1 [======] - 0s 23ms/step
 1/1 [======] - 0s 24ms/step
 Human: Are you a bot
```

Aim:

EXPERIMENT-12

Aim: Object detection with single-stage and two-stage detectors (Yolo)

Tools: YOLO Model

Procedure:

- 1. Load the Model
- 2. Pre-process the Image
- 3. Run Object Detection
- 4. Post-processing
- 5. Visualize Results

Aim: Implement image captioning with vanilla RNN using seq2seq model

Tools: None

Procedure:

- 1. Use a simplified version of the model with a single Dense layer as the encoder and a single LSTM layer as the decoder.
- 2. The image features are extracted separately
- 3. Use a <start> token to initiate the decoding process and a <end> token to signal the end of the caption.
- 4. The model learns to generate captions.
- 5. Generate captions for new images.

EXPERIMENT-14

Aim: To Learn and implement the DCGAN model to simulate realistic images, with IanGoodfellow, the inventor of GANS (generative adversarial networks)

Tools: None

Procedure:

- Step 1: Select a number of real images from the training set.
- Step 2: Generate a number of fake images. This is done by sampling random noise vectors and creating images from them using the generator.
- Step 3: Train the discriminator for one or more epochs using both fake and real images. This will update only the discriminator's weights by labelling all the real images as 1 and the fake images as 0.
- Step 4: Generate another number of fake images.

Step 5: Train the full GAN model for one or more epochs using only fake images	3.
This will update only the generator's weights by labelling all fake images as 1.	

Program: