

Machine Learning II - Assignment 4

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Problem 1 - Binary Image Denoising - The Ising Model

Explain the role of the three factor types h_{xi} , $-\beta x_{ij}$, and $-\eta x_{ij} y_i$. For each of the parameters, explain what happens when they are set to 0.

-> h_{xi} : (Unary clique potential) h controls how much importance is given to Unary prior information. that is $p(x)$. If h is set to 0, it means that we have no unary prior info about each pixel.

-> βx_{ij} : (Interaction clique potential) since x_i and x_j can take values -1 and +1 their product will be either -1 or +1. Since we need to minimize the energy E we need to increase the term βx_{ij} (because its sign is negative). Greater the β value, more we want pixels with same sign to remain (that is we want smoother image, which help in reducing the energy). If β is set to 0, we are not considering the smooth pixels in prior, hence the restored image can have more variation in neighbouring pixels since it is not penalised)

-> $\eta x_{ij} y_i$: This term increases if we choose the observed image (y) to be similar to restored image (x). So η controls the measure of how much the observed pixels dictate the restored image pixels. If we set η to 0, it means that we don't care how much the restored image is similar to observed image

What is the effect of setting β much larger than η ?

Value of β penalises the pixel x_i to be different from its markov blanket (x_j). **Therefore setting β greater than η makes the image more smooth and less like its noisy observed image (y),** since η penalises the image pixel (x_i) if it is different from image pixel (y_i from observed image).

Why does it not make sense to allow $\beta, \eta < 0$?

We need to minimize energy function $E(x, y)$ which in turn increases $p(x, y)$ which is proportional to $(p(x|y))$. Since our objective is to maximise the posterior $p(x|y)$ if we allow $\beta, \eta < 0$, we are increasing the value of energy function and that is NOT what we want. So this does not make sense.

Problem 2 - MAP Estimation with ICM

1. Code
2. Chosen parameters $h = 0.8$; $\beta = 1.2$; $\eta = 2.1$; It was not easy, had to run the program many times with different values and find it out.
3. h is the least important parameter.
4. Tried vertical raster scan and reverse raster scan. Reverse scan took a little longer to converge. And it converged with a slightly higher error rate (3.5%). For forward vertical scan final error percentage was (3.21%)
5. Best result -

$h = 0.800000$ $\beta = 1.200000$ $\eta = 2.100000$
Error percentage = 4.166667

loss value = 0.041667
 Error percentage = 3.267848
 loss value = 0.032678
 Error percentage = 3.216487
 loss value = 0.032165
 Error percentage = 3.210067
 loss value = 0.032101
 Error percentage = 3.216487
 loss value = 0.032165
 End

6. By Initialising the pixels at the start of the inference ICM can be improved. It could happen we happen to be at the global maxima.

Problem 3 - Sampling

1. Not sure whether it is correct (from the first assignment) I have to change the answer for $p(x|y)$.

$$\hat{y} = \arg \min_{y' \in y} [1 - p(y=y'|x)]$$

To minimise \hat{y} it is clear that we should maximise $p(y=y'|x)$ i.e y' must be chosen value which is max value of posterior distribution $p(y|x)$.

- 2.
- 3.
- 4.
- 5.
- 6.
- 7.
- 8.

Problem 4 - Parameter Learning

1.

1. Appearance of an intractable normalizing constant in the likelihood.

2. Number of non-zero entries of B (ferromagnetic coupling). Computational complexity of the log-likelihood.

2.

$$\max_{\mathbf{x}} p(\mathbf{x}|\mathbf{y}) \propto p(\mathbf{x}, \mathbf{y}) \Rightarrow \min_{\mathbf{x}} E(\mathbf{x}, \mathbf{y})$$

3.

4.

5.