Name:

MIDTERM

Closed book except for one 8½ x 11 sheet. No calculators or electronics devices. All work is to be your own - **show your work** for maximum partial credit.

- 1) (4pts) Circle True or False for the following:
 - a. **True/False** An advantage of a Moore machine is the output(s) can't glitch.
 - b. **True/False** An unconnected input signal to a module will be assigned a "z" (high impedance) value by the simulator.
 - c. **True/False** It is possible to infer latch behavior with a continuous assign statement (dataflow verilog).
 - d. **True/False** It is good practice to have the master reset signal de-assert on the opposite clock edge than the style of flops you use.

2) (6pts) Multiple Choice

- a. System verilog offers an **always_ff** block. This differs from standard **always** block in the following way:
 - i. It ensures the signals assigned within it will synthesize to flops.
 - ii. It does not differ that much, only ensures synthesis will throw a warning if the assignments within it do not form a flop.
 - iii. It does not need a sensitivity list because it knows flops are being inferred.
- b. System verilog offers an **always_comb** block. This differs from standard **always** block in the following way:
 - i. You are allowed to use * in the sensitivity list as opposed to individually specifying each signal.
 - ii. It does not need a sensitivity list because it knows combinational logic is being inferred.
 - iii. Synthesis will ensure the logic inferred by the block has no sequential elements (latches or flops).
- c. We favor HDL's over schematic capture because:
 - i. Data path widths (8,16,32,...) can be abstracted
 - ii. Synthesis does the bulk of the tedious work
 - iii. Design files (ASCII text) are very portable between different CAD vendors
 - iv. All of the above
 - v. i & ii.
- d. Meta-stability:
 - i. Occurs when alpha particles impart charge on a node of a latch or flop
 - ii. Much like the Loch ness monster, is an elaborate hoax
 - iii. Can occur when the input of a flop changes coincident with the clock
 - iv. Can be solved by using a high gain inverter.

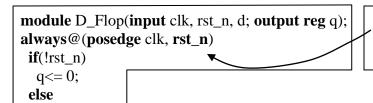
3) (5pts) Which of the following clock generators will work best, why?

Which of these 3 is best and why?

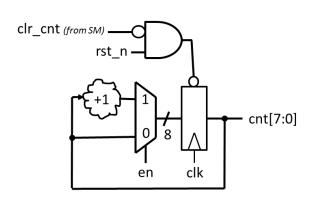
4) (5pts) In the table below fill in the result of the expressions (include bit width of the result). A = 6'h01, and B = 6'h2A

Expression:	Result (include width i.e. 4'bxxxx)
{A,B[4:0]}	
^B	
~A	
{{2{B[5]}},B}	

5) (4pts) A lazy digital designer tries to infer an **active low asynchronous reset D-flop** in the following manner. Does this work? Explain **why** or **why not**.



q<=d; endmodule Lazy Digital Designer Thinks: "Why write negedge when specifying sensitivity list, simply rst_n should also work **6) (5pts)** Complete the verilog code to implement the counter shown.

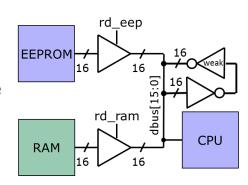


7) (4pts) In the counter shown above. Given clr_cnt is coming from a state machine, describe in detail what might go wrong with this implementation. module cntr(clk,rst_n,clr_cnt,en,cnt);
input clk,rst_n,clr_cnt,en;
output reg [7:0] cnt;

endmodule

- **8) (4pts)** Realize the tri-state bus indicated in the diagram using **dataflow** (not structural) Verilog in space provided.
 - (2pts) What would happen if both *rd_eep* and *rd_ram* were asserted at the same time?

(3pts) What is the purpose of the feed forward and feedback inverter structure?



module TRIbus(eeprom, ram, rd_eep, rd_ram, dbus);

input [15:0] eeprom, ram;

input rd_ram, rd_eep;

output [15:0] dbus;

// Write your code here in the space provided

endmodule

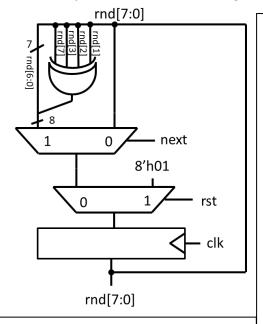
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9) (6pts) A designer wished to make a counter that would count up when enabled. The code they came up with is as follows:

```
assign count = cnt en ? count + 1 : count;
```

Draw how this would synthesize. Describe how you think it would behave in silicon.

10) (6pts) A LFSR is a digital circuit that can be used to obtain a pseudo-random number sequence. Below is a diagram of an LFSR. Complete the Verilog to implement it.



(3pts) Simulate this circuit (in your head) What is the value of rand 2 clocks after reset de-asserts? (assuming *next* is high)

module LFSR (clk,rst,next);
input clk,rst;
input next;
output reg [7:0] rand;

endmodule

11) (2.5pts) Consider the test bench shown:

Circle the correct statement(s).

- a. This code has a race condition on a
- b. This code implies a short in hardware
- c. This code infers a latch on a
- d. This will not compile due to assigns to **a** from two **initial** blocks.
- 12) (2.5pts) To make state machine code more readable one can use **localparam** to give the states meaningful names. In system Verilog one can use enumerated types.

 What advantage does use of enumerated types have over **localparam**?

```
module my_tb();
reg a,b,c,d;

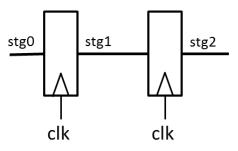
MyDesign iDUT( .a(a),.b(b),.c(c) );
intial begin
  a= 1; b=0; c=0;
  #3 a=0;
end
intial
  a=b;
endmodule
```

13) (8pts) Complete the Verilog to produce a multiply accumulate unit that multiplies two signed 8-bit signed numbers, and adds that product to *accum* to produce *result*. However, the add should be saturating (hence use of intermediate **unsat_sum**). If the value was to exceed 0x7fff it should be pinned at 0x7fff, or if negative if it was going to be more negative than 0x8000 then it should be pinned at 0x8000.

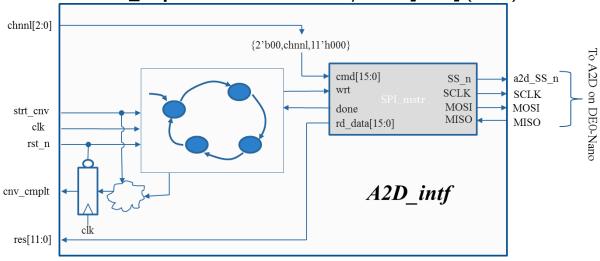
14) (9pts) Write a test bench for the MAC unit of the prior problem. The test bench should test a couple of values and stop if it fails, and display a happy message if it passes. (don't worry about the values used for testing, judging this on structure/format)

(3pts) Your design has a control signal that needs to be pipelined. The **15)** implementation is shown below. Synopsys timing analysis had determined there is a

hold time problem. What will Synopsys do to fix the hold time issue?



- **16) (18 pts)** In HW3 you created a SPI monarch. We are now going to use that SPI monarch to create an interface to the A2D on the DE0-Nano board. The basic steps are:
 - a. When **strt_cnv** is asserted initiate a SPI transaction (assert wrt) to inform the A2D what channel to convert (A2D returns garbage on rd_data during this transaction).
 - b. Wait one clock cycle after the SPI transaction has completed.
 - c. Initiate a 2nd SPI transaction to grab the data returned from the A2D (not important what **cmd** was sent to A2D during this transaction).
 - d. Assert conv_cmplt when A2D data is ready on res[11:0] (result)



SM Function: Send command to A2D via SPI to ask for conversion on channel. Once that transaction completes wait one clock cycle. Then start new transaction to read the result of the A2D conversion back.

Draw a bubble diagram for the state machine:

Finish the code to implement A2D_intf including SM functionality.

