

G V V Sharma*

CONTENTS

1	2019-1	1
2	2019-2	5

Abstract—This manual has exercises based on problems in JEE advanced.

1 2019-1

1.1 Consider the optimization problem

$$\max_z \frac{1}{|z-1|} \quad (1)$$

$$s.t. \quad |z-2+j| \geq \sqrt{5} \quad (2)$$

If the maximum value is obtained at z_0 , find the principal argument of

$$\frac{4-z_0-\bar{z}_0}{z_0-\bar{z}_0+2j} \quad (3)$$

Solution: The optimization problem can be reframed as

$$\min_{\mathbf{x}} \|\mathbf{x} - \mathbf{c}_1\|^2 \quad (4)$$

$$s.t. \quad \|\mathbf{x} - \mathbf{c}_2\|^2 \geq 5 \quad (5)$$

where

$$z = \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \quad (6)$$

$$\mathbf{c}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (7)$$

$$\mathbf{c}_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad (8)$$

Fig. 1.1.1 explains (4) where z_0 is the set of points comprising of the intersection of

the smallest circle Γ : with the largest circle Ω : $r_2 \geq \sqrt{5}$ with radii r_1 and $r_2 \geq \sqrt{5}$ respectively. The Lagrangian is

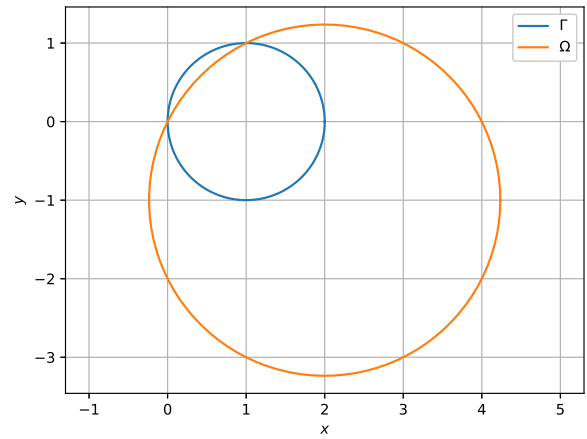


Fig. 1.1.1

$$L(\mathbf{x}, \lambda) = \|\mathbf{x} - \mathbf{c}_1\|^2 - \lambda \{ \|\mathbf{x} - \mathbf{c}_2\|^2 - r_2^2 \} \quad (9)$$

From the KKT conditions,

$$\frac{\partial L(\mathbf{x}, \lambda)}{\partial \mathbf{x}} = 0 \quad (10)$$

$$\Rightarrow \mathbf{x} - \mathbf{c}_1 - \lambda(\mathbf{x} - \mathbf{c}_2) = 0 \quad (11)$$

$$\Rightarrow \mathbf{x} = \frac{\mathbf{c}_1 - \lambda \mathbf{c}_2}{1 - \lambda} \quad (12)$$

and

$$\frac{\partial L(\mathbf{x}, \lambda)}{\partial \lambda} = 0 \quad (13)$$

$$\Rightarrow \|\mathbf{x} - \mathbf{c}_2\|^2 - r_2^2 = 0 \quad (14)$$

*The author is with the Department of Electrical Engineering, Indian Institute of Technology, Hyderabad 502285 India e-mail: gadepall@iith.ac.in. All solutions in this manual is released under GNU GPL. Free and open source.

Substituting from (12) in (17),

$$\left\| \frac{\mathbf{c}_1 - \lambda \mathbf{c}_2}{1 - \lambda} - \mathbf{c}_2 \right\|^2 - r_2^2 = 0 \quad (15)$$

$$\Rightarrow \lambda = 1 \pm \frac{\|\mathbf{c}_1 - \mathbf{c}_2\|}{r_2} \quad (16)$$

$$= 1 \pm \sqrt{\frac{2}{5}} \quad (17)$$

Fig. 1.1.2 plots Γ for

$$\lambda = 1 - \sqrt{\frac{2}{5}} \quad (18)$$

Thus, from (12),

$$\mathbf{x}_0 = \frac{\mathbf{c}_1 - \lambda \mathbf{c}_2}{1 - \lambda} \quad (19)$$

$$\Rightarrow z_0 = \frac{1}{1 - \lambda} (1 - 2\lambda + j\lambda) \quad (20)$$

$$\text{or, } \arg \frac{4 - z_0 - \bar{z}_0}{z_0 - \bar{z}_0 + 2j} = \frac{2 - \Re\{z_0\}}{j(\Im\{z_0\} + 1)} \quad (21)$$

$$= \frac{2(1 - \lambda) - (1 - 2\lambda)}{j} = -j \quad (22)$$

Thus, the principal argument is $-\frac{\pi}{2}$.

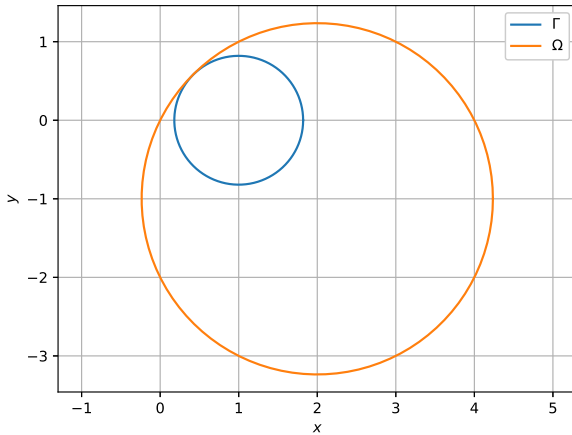


Fig. 1.1.2

1.2 Let

$$\mathbf{M} = \begin{pmatrix} \sin^4 \theta & -1 - \sin^2 \theta \\ 1 + \cos^2 \theta & \cos^4 \theta \end{pmatrix} = \alpha \mathbf{I} + \beta \mathbf{M}^{-1} \quad (23)$$

where α, β are real functions of θ and \mathbf{I} is the

identity matrix. If

$$\alpha^* = \min_{\theta} \alpha(\theta) \quad (24)$$

$$\beta^* = \min_{\theta} \beta(\theta), \quad (25)$$

find $\alpha^* + \beta^*$.

Solution: (23) can be expressed as

$$\mathbf{M}^2 - \alpha \mathbf{M} - \beta \mathbf{I} = 0 \quad (26)$$

which yields the characteristic equation of \mathbf{M} as

$$\lambda^2 - \alpha \lambda - \beta = 0 \quad (27)$$

Since the sum of the eigenvalues is equal to the trace and the determinant is the product of eigenvalues,

$$\alpha = \sin^4 \theta + \cos^4 \theta = 1 - \frac{\sin^2 2\theta}{2} \quad (28)$$

$$-\beta = \sin^4 \theta \cos^4 \theta + (1 + \sin^2 \theta)(1 + \cos^2 \theta) \quad (29)$$

$$= 2 + \frac{\sin^2 2\theta}{4} + \frac{\sin^4 2\theta}{16} \quad (30)$$

$$= \left(\frac{\sin^2 2\theta}{4} + \frac{1}{2} \right)^2 + \frac{7}{4} \quad (31)$$

Thus,

$$\alpha^* = \frac{1}{2}, \beta^* = -\frac{37}{16} \quad (32)$$

$$\Rightarrow \alpha^* + \beta^* = -\frac{29}{16} \quad (33)$$

1.3 The line

$$\Gamma : \mathbf{x} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ m \end{pmatrix} \quad (34)$$

intersects the circle

$$\Omega : \left\| \mathbf{x} - \begin{pmatrix} 3 \\ -2 \end{pmatrix} \right\| = 5 \quad (35)$$

at points \mathbf{P} and \mathbf{Q} respectively. The mid point of PQ is \mathbf{R} such that

$$\begin{pmatrix} 1 & 0 \end{pmatrix} \mathbf{R} = -\frac{3}{5} \quad (36)$$

Find m .

Solution: Let

$$\mathbf{c} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \mathbf{O} = \begin{pmatrix} 3 \\ -2 \end{pmatrix} \text{ and } \mathbf{m} = \begin{pmatrix} 1 \\ m \end{pmatrix} \quad (37)$$

The intersection of (34) and (35) is

$$\|\mathbf{c} + \lambda \mathbf{m} - \mathbf{O}\|^2 = 25 \quad (38)$$

$$\begin{aligned} \Rightarrow \lambda^2 \|\mathbf{m}\|^2 + 2\lambda \mathbf{m}^T (\mathbf{c} - \mathbf{O}) \\ + \|\mathbf{c} - \mathbf{O}\|^2 - 25 = 0 \end{aligned} \quad (39)$$

Since \mathbf{P}, \mathbf{Q} lie on Γ ,

$$\mathbf{P} = \mathbf{c} + \lambda_1 \mathbf{m} \quad (40)$$

$$\mathbf{Q} = \mathbf{c} + \lambda_2 \mathbf{m} \quad (41)$$

$$\Rightarrow \frac{\mathbf{P} + \mathbf{Q}}{2} = \mathbf{c} + \frac{\lambda_1 + \lambda_2}{2} \mathbf{m} \quad (42)$$

$$\begin{aligned} \Rightarrow (1 \ 0) \frac{\mathbf{P} + \mathbf{Q}}{2} &= (1 \ 0) \mathbf{c} \\ &+ \frac{\lambda_1 + \lambda_2}{2} (1 \ 0) \mathbf{m} \quad (43) \\ &= (1 \ 0) \mathbf{c} - \frac{\mathbf{m}^T (\mathbf{c} - \mathbf{O})}{\|\mathbf{m}\|^2} \end{aligned} \quad (44)$$

using the sum of roots in (39). From (36) and (37),

$$-(1 \ m) \begin{pmatrix} -3 \\ 3 \end{pmatrix} = -\frac{3}{5} (1 + m^2) \quad (45)$$

$$\Rightarrow m^2 - 5m + 6 = 0 \quad (46)$$

$$\Rightarrow m = 2 \text{ or } 3 \quad (47)$$

From (39),

$$\begin{aligned} \lambda &= \frac{-\mathbf{m}^T (\mathbf{c} - \mathbf{O})}{\|\mathbf{m}\|^2} \\ &\pm \frac{\sqrt{(\mathbf{m}^T (\mathbf{c} - \mathbf{O}))^2 - \|\mathbf{c} - \mathbf{O}\|^2 + 25}}{\|\mathbf{m}\|^2} \end{aligned} \quad (48)$$

Fig. 1.3 summarizes the solution for $m = 2$.

1.4 Find the area of the region

$$\begin{pmatrix} x \\ y \end{pmatrix} : xy \leq 8, 1 \leq y \leq x^2 \quad (49)$$

Solution: The intersection of $y = 1, y = x^2$ is

$$\mathbf{A} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad (50)$$

The intersection of $y = 1, xy = 8$ is

$$\mathbf{B} = \begin{pmatrix} 8 \\ 1 \end{pmatrix} \quad (51)$$

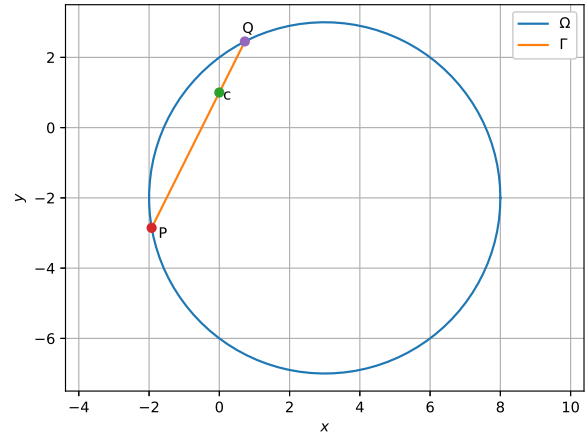


Fig. 1.3

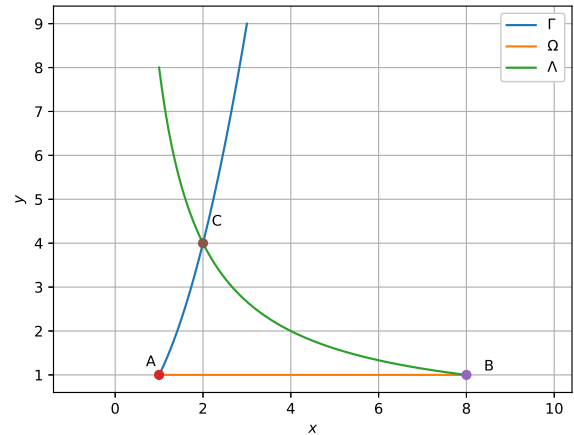


Fig. 1.4

The intersection of $y = x^2, xy = 8$ is

$$\mathbf{C} = \begin{pmatrix} 2 \\ 4 \end{pmatrix} \quad (52)$$

The desired region is enclosed by the vertices \mathbf{A}, \mathbf{B} and \mathbf{C} . Thus, the area is obtained as

$$\int_1^2 x^2 dx + \int_2^8 \frac{8}{x} dx = \left[\frac{x^3}{3} \right]_1^2 + 8 [\ln x]_2^8 - 7 \quad (53)$$

$$= 16 \ln 2 - \frac{14}{3} \quad (54)$$

1.5
1.6
1.7

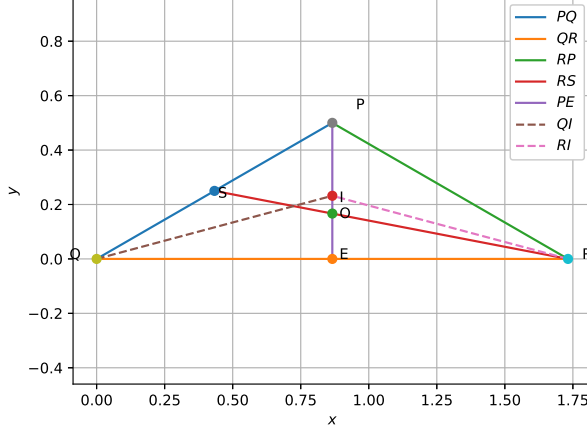


Fig. 1.8

1.8 In $\triangle PQR$, which is not right angled, let

$$PQ = r, QR = p, RP = q \quad (55) \quad 1.9$$

The median RS and the altitude PE intersect at O . $p = \sqrt{3}, q = 1$ and the radius of the circumcircle of $\triangle PQR = k = 1$. Find the length of RS, OE , area of $\triangle SOE$, and radius of the incircle of $\triangle PQR$. 1.10
1.11
1.12 Let

Solution: Using the sine formula,

$$\frac{p}{\sin P} = \frac{q}{\sin Q} = 2k \quad (56)$$

$$\Rightarrow \sin P = \frac{\sqrt{3}}{2}, \sin Q = \frac{1}{2} \quad (57)$$

If $\angle R \neq \frac{\pi}{2}$, the only possible solution is

$$\angle P = \frac{2\pi}{3}, \angle Q = \frac{\pi}{6}, \angle R = \frac{\pi}{6} \quad (58)$$

$\therefore \angle Q = \angle R, q = r = 1$. The given information is shown in Fig. 1.8 Using the cosine formula,

$$RS = \sqrt{q^2 + \left(\frac{r}{2}\right)^2 - qr \cos P} \quad (59)$$

$$= \sqrt{1 + \frac{1}{4} + \frac{1}{2}} = \sqrt{\frac{7}{2}} \quad (60)$$

Also, using Baudhayana's theorem,

$$OE = \sqrt{OR^2 - ER^2} \quad (61)$$

$$= \sqrt{\left(\frac{2RS}{3}\right)^2 - \left(\frac{p}{2}\right)^2} \quad (62)$$

$$= \sqrt{\frac{7}{9} - \frac{3}{4}} = \frac{1}{6} \quad (63)$$

Since PE and RS are medians,

$$\text{ar}(\triangle SOE) = \frac{1}{4} \text{ar}(\triangle POR), \quad (64)$$

$$\text{ar}(\triangle POR) = \frac{2}{3} \text{ar}(\triangle PER), \quad (65)$$

$$\text{ar}(\triangle PER) = \frac{1}{2} \text{ar}(\triangle PQR), \quad (66)$$

$$\Rightarrow \text{ar}(\triangle SOE) = \frac{1}{12} \text{ar}(\triangle PQR) = \frac{\sqrt{3}}{24} \quad (67)$$

I is the incentre in Fig. 1.8. The radius of the incircle is

$$\frac{p}{2 \cos \frac{Q}{2}} = \frac{p}{\sqrt{2(1 + \cos Q)}} \quad (68)$$

$$= \sqrt{\frac{3}{1 + \sqrt{3}}} \quad (69)$$

$$L_1 : \quad \mathbf{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \lambda_1 \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix} \quad (70)$$

$$L_2 : \quad \mathbf{x} = \lambda_1 \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} \quad (71)$$

Given that $L_3 \perp L_1, L_3 \perp L_2$, find L_3 .

Solution: Let

$$L_3 : \quad \mathbf{x} = \mathbf{c} + \lambda \mathbf{m}_3 \quad (72)$$

Then

$$\begin{pmatrix} -1 & 2 & 2 \\ 2 & -1 & 2 \end{pmatrix} \mathbf{m}_3 = \mathbf{0} \quad (73)$$

Row reducing the coefficient matrix,

$$\begin{pmatrix} -1 & 2 & 2 \\ 2 & -1 & 2 \end{pmatrix} \leftrightarrow \begin{pmatrix} 1 & -2 & -2 \\ 0 & 1 & 2 \end{pmatrix} \quad (74)$$

$$\leftrightarrow \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \end{pmatrix} \Rightarrow \mathbf{m}_3 = \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} \quad (75)$$

Also, $L_1 \perp L_2$, but $L_1 \cup L_2 = \phi$. The given information can be summarized as

$$L_1 : \mathbf{x} = \mathbf{c}_1 + \lambda_1 \mathbf{m}_1 \quad (76)$$

$$L_2 : \mathbf{x} = \lambda_2 \mathbf{m}_2 \quad (77)$$

$$L_3 : \mathbf{x} = \mathbf{c}_3 + \lambda \mathbf{m}_3 \quad (78)$$

where

$$\mathbf{c}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{m}_1 = \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}, \mathbf{m}_2 = \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} \quad (79)$$

The objective is to find \mathbf{c}_3 . Since $L_1 \cup L_3 \neq \phi$, $L_2 \cup L_3 \neq \phi$, from (76)-(78),

$$\mathbf{c}_1 + \lambda_1 \mathbf{m}_1 = \mathbf{c}_3 + \lambda_3 \mathbf{m}_3 \quad (80)$$

$$\lambda_2 \mathbf{m}_2 = \mathbf{c}_3 + \lambda_4 \mathbf{m}_3 \quad (81)$$

Using the fact that $L_1 \perp L_2 \perp L_3$, (80)-(81) can be expressed as

$$\mathbf{m}_1^T \mathbf{c}_1 + \lambda_1 \|\mathbf{m}_1\|^2 = \mathbf{m}_1^T \mathbf{c}_3 \quad (82)$$

$$\mathbf{m}_2^T \mathbf{c}_1 = \mathbf{m}_2^T \mathbf{c}_3 \quad (83)$$

$$\mathbf{m}_3^T \mathbf{c}_1 = \mathbf{m}_3^T \mathbf{c}_3 + \lambda_3 \|\mathbf{m}_3\|^2 \quad (84)$$

$$0 = \mathbf{m}_1^T \mathbf{c}_3 \quad (85)$$

$$\lambda_2 \|\mathbf{m}_2\|^2 = \mathbf{m}_2^T \mathbf{c}_3 \quad (86)$$

$$0 = \mathbf{m}_3^T \mathbf{c}_3 + \lambda_4 \|\mathbf{m}_3\|^2 \quad (87)$$

Simplifying the above,

$$\lambda_1 = -\frac{\mathbf{m}_1^T \mathbf{c}_1}{\|\mathbf{m}_1\|^2} = \frac{1}{9} \quad (88)$$

$$\lambda_2 = \frac{\mathbf{m}_2^T \mathbf{c}_1}{\|\mathbf{m}_2\|^2} = \frac{2}{9} \quad (89)$$

Substituting in (80) and (81),

$$L_3 : \mathbf{x} = \frac{2}{9} \begin{pmatrix} 4 \\ 1 \\ 1 \end{pmatrix} + \lambda_3 \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} \text{ or} \quad (90)$$

$$L_3 : \mathbf{x} = \frac{2}{9} \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} + \lambda_3 \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} \quad (91)$$

The key concept in this question is that orthogonality of L_1 and L_2 doesnot mean that they intersect. They are skew lines.

2 2019-2

2.1 Obtain the 3×3 matrices $\{\mathbf{P}_k\}_{k=1}^6$ from the vectors

$$\mathbf{v}_1 = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix} \quad (92)$$

$$\mathbf{v}_2 = \begin{pmatrix} 0 & 1 & 0 \end{pmatrix} \quad (93)$$

$$\mathbf{v}_3 = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \quad (94)$$

and let

$$\mathbf{X} = \sum_{k=1}^6 \mathbf{P}_k \begin{pmatrix} 2 & 1 & 3 \\ 1 & 0 & 2 \\ 3 & 2 & 1 \end{pmatrix} \mathbf{P}_k^T \quad (95)$$

Verify if

- $\lambda = 30$ is an eigenvalue of \mathbf{X} and $\mathbf{x} = \begin{pmatrix} 1 & 1 & 1 \end{pmatrix}^T$ the corresponding eigenvector.
- \mathbf{X} is symmetric.
- $\text{tr}(\mathbf{X}) = 18$.
- $\mathbf{X} - 30\mathbf{I}$ is invertible.

2.2 Let

$$\mathbf{P} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}, \mathbf{Q} = \begin{pmatrix} 2 & x & x \\ 0 & 4 & 0 \\ x & x & 6 \end{pmatrix} \quad (96)$$

Verify if

- $PQ = QP$ for some x .
- $\det R = \det \begin{pmatrix} 2 & x & x \\ 0 & 4 & 0 \\ x & x & 5 \end{pmatrix}$ for all x .
- for $x = 0$, if $\mathbf{R} \begin{pmatrix} 1 \\ a \\ b \end{pmatrix} = 6 \begin{pmatrix} 1 \\ a \\ b \end{pmatrix}$, then $a + b = 5$.

Use property of eigenvector.

- For $x = 1$, there exists a vector \mathbf{y} for which $\mathbf{R}\mathbf{y} = \mathbf{0}$. This implies that the null space of \mathbf{R} is nonempty. Also, \mathbf{R} is noninvertible, $\det(R) = 0$ and has a 0 eigenvalue.

2.3

2.4

2.5

2.6

2.7

2.8 Let

$$L_1 : \quad \mathbf{r} = \lambda_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad (97)$$

$$L_2 : \quad \mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + \lambda_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad (98)$$

$$L_3 : \quad \mathbf{r} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \lambda_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \quad (99)$$

Let $\mathbf{P} \in L_1, \mathbf{Q} \in L_2, \mathbf{R} \in L_3$. Verify if \mathbf{Q} can be

a) $\begin{pmatrix} 0 \\ -\frac{1}{2} \\ 1 \end{pmatrix}$

b) $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

c) $\begin{pmatrix} 0 \\ \frac{1}{2} \\ 1 \end{pmatrix}$

d) $\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

given that $\mathbf{P}, \mathbf{Q}, \mathbf{R}$ are collinear.

Solution: If $\mathbf{P}, \mathbf{Q}, \mathbf{R}$ are collinear,

$$\frac{PQ}{QR} = k, \quad (100)$$

$$(k+1)\mathbf{Q} = k\mathbf{P} + \mathbf{R}, \quad (101)$$

From (97), (98) and (99),

$$\begin{aligned} k\lambda_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \lambda_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \\ = (k+1) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + (k+1)\lambda_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \end{aligned} \quad (102)$$

which can be expressed as

$$\begin{pmatrix} k & 0 & 0 \\ 0 & -(k+1) & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ k+1 \end{pmatrix} \quad (103)$$

Thus,

$$\mathbf{Q} = \begin{pmatrix} 0 \\ \frac{1}{k+1} \\ 1 \end{pmatrix} \quad (104)$$