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clc;
clear;
tic;

Reading images

```
groundTruth = imread("../data/mri_image_noiseless.png");
lowNoiseImg = imread("../data/mri_image_noise_level_low.png");
medNoiseImg = imread("../data/mri_image_noise_level_medium.png");
highNoiseImg = imread("../data/mri_image_noise_level_high.png");

groundTruth = im2double(groundTruth);
lowNoiseImg = im2double(lowNoiseImg);
medNoiseImg = im2double(medNoiseImg);
highNoiseImg = im2double(highNoiseImg);
```

Initial error calculation

Denoising using quadratic loss

```
% hyperparams
```

```
alpha = 0.112;
qamma = 0;
              % any arbitrary value
[denoisedImg11, loss11] = gradientDescent(lowNoiseImg, alpha, gamma,
[denoisedImg12, loss12] = gradientDescent(medNoiseImg, alpha, gamma,
 1);
[denoisedImq13, loss13] = gradientDescent(highNoiseImg, alpha, gamma,
 1);
newRRMSE1 = RRMSE(groundTruth, denoisedImg11);
newRRMSE2 = RRMSE(groundTruth, denoisedImg12);
newRRMSE3 = RRMSE(groundTruth, denoisedImg13);
fprintf("Optimal alpha = %f\n", alpha);
fprintf("Quadratic errors\n----\n");
fprintf("RRMSE between noiseless and denoised img (low noise) :- \n");
fprintf("At alpha = %f\n", newRRMSE1);
[temp, ~] = gradientDescent(lowNoiseImg, 1.2 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, 0.8 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (med noise) :- \n");
fprintf("At alpha = fn", newRRMSE2);
[temp, ~] = gradientDescent(medNoiseImg, 1.2 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, 0.8 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (high noise) :-
 \n");
fprintf("At alpha = %f\n", newRRMSE3);
[temp, ~] = gradientDescent(highNoiseImg, 1.2 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, 0.8 * alpha, gamma, 1);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha = %f\n\n", error);
Optimal alpha = 0.112000
Quadratic errors
RRMSE between noiseless and denoised img (low noise) :-
At \ alpha = 0.049174
At 1.2 * alpha = 0.051767
At 0.8 * alpha = 0.047286
RRMSE between noiseless and denoised img (med noise) :-
```

```
At alpha = 0.114592

At 1.2 * alpha = 0.115834

At 0.8 * alpha = 0.115671

RRMSE between noiseless and denoised img (high noise) :-

At alpha = 0.128276

At 1.2 * alpha = 0.129451

At 0.8 * alpha = 0.129354
```

Denoising using Huber loss

```
% hyperparams
alpha = 0.6;
qamma = 0.02;
[denoisedImg21, loss21] = gradientDescent(lowNoiseImg, alpha, gamma,
 2);
[denoisedImg22, loss22] = gradientDescent(medNoiseImg, alpha, gamma,
[denoisedImg23, loss23] = gradientDescent(highNoiseImg, alpha, gamma,
 2);
newRRMSE1 = RRMSE(groundTruth, denoisedImg21);
newRRMSE2 = RRMSE(groundTruth, denoisedImg22);
newRRMSE3 = RRMSE(groundTruth, denoisedImg23);
fprintf("Optimal alpha = %f\n", alpha);
fprintf("Optimal gamma = %f\n", gamma);
fprintf("Huber errors\n----\n");
fprintf("RRMSE between noiseless and denoised img (low noise) :- \n");
fprintf("At alpha, gamma = %f\n", newRRMSE1);
[temp, ~] = gradientDescent(lowNoiseImg, 1.2 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, 0.8 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, alpha, 1.2 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, alpha, 0.8 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (med noise) :- \n");
fprintf("At alpha = %f\n", newRRMSE2);
[temp, ~] = gradientDescent(medNoiseImg, 1.2 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, 0.8 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
```

```
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, alpha, 1.2 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, alpha, 0.8 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (high noise) :-
 \n");
fprintf("At alpha = fn", newRRMSE3);
[temp, ~] = gradientDescent(highNoiseImg, 1.2 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, 0.8 * alpha, gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, alpha, 1.2 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, alpha, 0.8 * gamma, 2);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n\n", error);
Optimal alpha = 0.600000
Optimal gamma = 0.020000
Huber errors
RRMSE between noiseless and denoised img (low noise) :-
At alpha, qamma = 0.045660
At 1.2 * alpha, gamma = 0.052797
At 0.8 * alpha, gamma = 0.043444
At alpha, 1.2 * gamma = 0.047276
At alpha, 0.8 * gamma = 0.044256
RRMSE between noiseless and denoised img (med noise) :-
At \ alpha = 0.112234
At 1.2 * alpha, gamma = 0.113976
At 0.8 * alpha, gamma = 0.114024
At alpha, 1.2 * gamma = 0.112286
At alpha, 0.8 * gamma = 0.112860
RRMSE between noiseless and denoised img (high noise) :-
At alpha = 0.125533
At 1.2 * alpha, gamma = 0.122617
At 0.8 * alpha, gamma = 0.131138
At alpha, 1.2 * gamma = 0.123993
At alpha, 0.8 * gamma = 0.128150
```

Denoising using DAF loss

```
% hyperparams
alpha = 0.4;
gamma = 0.065;
```

```
[denoisedImg31, loss31] = gradientDescent(lowNoiseImg, alpha, gamma,
3);
[denoisedImg32, loss32] = gradientDescent(medNoiseImg, alpha, gamma,
[denoisedImg33, loss33] = gradientDescent(highNoiseImg, alpha, gamma,
3);
newRRMSE1 = RRMSE(groundTruth, denoisedImg31);
newRRMSE2 = RRMSE(groundTruth, denoisedImg32);
newRRMSE3 = RRMSE(groundTruth, denoisedImg33);
fprintf("Optimal alpha = %f\n", alpha);
fprintf("Optimal gamma = %f\n", gamma);
fprintf("DAF errors\n----\n");
fprintf("RRMSE between noiseless and denoised img (low noise) :- \n");
fprintf("At alpha, gamma = %f\n", newRRMSE1);
[temp, ~] = gradientDescent(lowNoiseImg, 1.2 * alpha, gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, 0.8 * alpha, gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, alpha, 1.2 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(lowNoiseImg, alpha, 0.8 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (med noise) :- \n");
fprintf("At alpha = %f\n", newRRMSE2);
[temp, ~] = gradientDescent(medNoiseImg, 1.2 * alpha, gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, 0.8 * alpha, gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, alpha, 1.2 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(medNoiseImg, alpha, 0.8 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n", error);
fprintf("RRMSE between noiseless and denoised img (high noise) :-
\n");
fprintf("At alpha = %f\n", newRRMSE3);
[temp, ~] = gradientDescent(highNoiseImg, 1.2 * alpha, gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At 1.2 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, 0.8 * alpha, gamma, 3);
```

```
error = RRMSE(groundTruth, temp);
fprintf("At 0.8 * alpha, gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, alpha, 1.2 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 1.2 * gamma = %f\n", error);
[temp, ~] = gradientDescent(highNoiseImg, alpha, 0.8 * gamma, 3);
error = RRMSE(groundTruth, temp);
fprintf("At alpha, 0.8 * gamma = %f\n\n", error);
Optimal\ alpha = 0.400000
Optimal gamma = 0.065000
DAF errors
RRMSE between noiseless and denoised img (low noise) :-
At alpha, qamma = 0.043564
At 1.2 * alpha, gamma = 0.045085
At 0.8 * alpha, gamma = 0.042841
At alpha, 1.2 * gamma = 0.044675
At alpha, 0.8 * gamma = 0.042884
RRMSE between noiseless and denoised img (med noise) :-
At \ alpha = 0.111874
At 1.2 * alpha, gamma = 0.111291
At 0.8 * alpha, gamma = 0.112522
At alpha, 1.2 * gamma = 0.111437
At alpha, 0.8 * gamma = 0.112003
RRMSE between noiseless and denoised img (high noise) :-
At \ alpha = 0.123704
At 1.2 * alpha, gamma = 0.122073
At 0.8 * alpha, gamma = 0.127085
At alpha, 1.2 * gamma = 0.122707
At alpha, 0.8 * gamma = 0.125797
```

Results

```
%%%% Low Noise
figure;
subplot(1, 5, 1);
imshow(uint8(255 * groundTruth));
title("Without noise");
subplot(1, 5, 2);
imshow(uint8(255 * lowNoiseImg));
title("Low noise");
subplot(1, 5, 3);
imshow(uint8(255 * denoisedImg11));
title("Denoising using quadratic loss");
subplot(1, 5, 4);
imshow(uint8(255 * denoisedImg21));
title("Denoising using huber loss");
subplot(1, 5, 5);
imshow(uint8(255 * denoisedImg31));
```

```
title("Denoising using DAF loss");
colormap('gray');
%%%% Medium noise
figure;
subplot(1, 5, 1);
imshow(uint8(255 * groundTruth));
title("Without noise");
subplot(1, 5, 2);
imshow(uint8(255 * medNoiseImg));
title("Medium noise");
subplot(1, 5, 3);
imshow(uint8(255 * denoisedImg12));
title("Denoising using quadratic loss");
subplot(1, 5, 4);
imshow(uint8(255 * denoisedImg22));
title("Denoising using huber loss");
subplot(1, 5, 5);
imshow(uint8(255 * denoisedImg32));
title("Denoising using DAF loss");
colormap('gray');
%%%% High noise
figure;
subplot(1, 5, 1);
imshow(uint8(255 * groundTruth));
title("Without noise");
subplot(1, 5, 2);
imshow(uint8(255 * highNoiseImg));
title("High noise");
subplot(1, 5, 3);
imshow(uint8(255 * denoisedImg13));
title("Denoising using quadratic loss");
subplot(1, 5, 4);
imshow(uint8(255 * denoisedImg23));
title("Denoising using huber loss");
subplot(1, 5, 5);
imshow(uint8(255 * denoisedImg33));
title("Denoising using DAF loss");
colormap('gray');
```

Without noise LovDenoisieing usingDenoisianigculsianigenutisianipsesing DAF loss











Without noise Mediuline molisieng using Deprecolaining decision decision DAF loss











Without noise High Decisioning using Decreate in the Last of the High Decision using Decreate in the High Decreate in the High Decision using Decreate in the High Decision using Decreate in the High Decision using Decreate in the High Decreate in the High Decision using Decreate in the High Decision using Decreate in the High Decreate in the High Decision using Decreate in the High Decision using Decreate in the High De







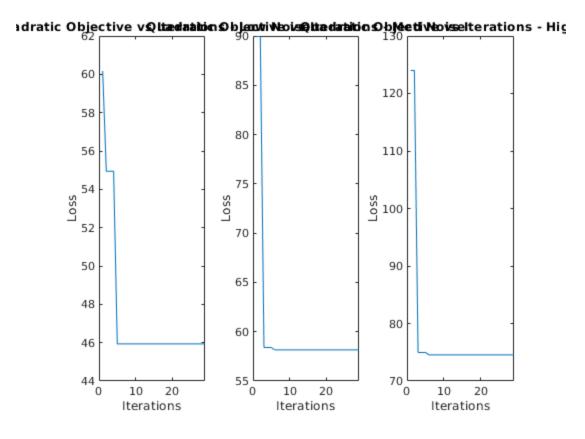


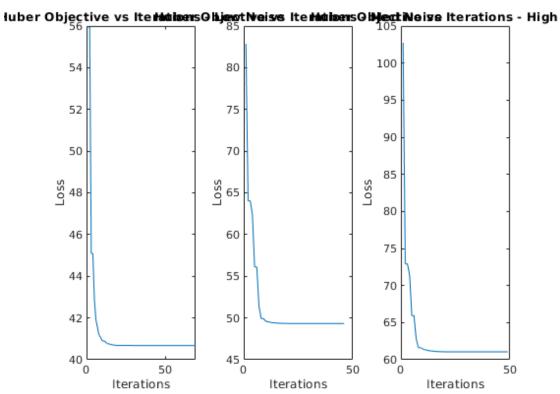


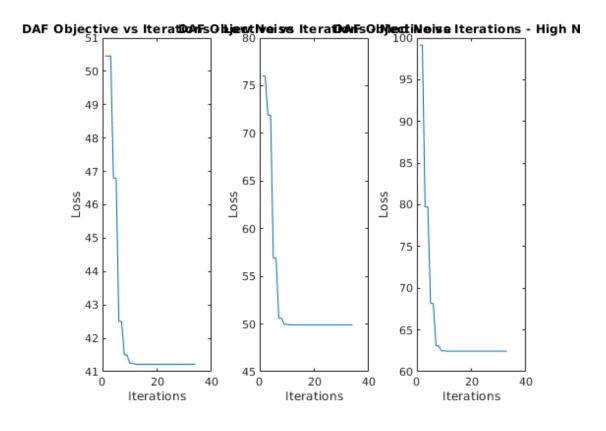
Loss vs Iterations

```
figure;
subplot(1, 3, 1);
plot(loss11);
xlabel("Iterations");
ylabel("Loss");
title("Quadratic Objective vs Iterations - Low Noise");
subplot(1, 3, 2);
plot(loss12);
xlabel("Iterations");
ylabel("Loss");
title("Quadratic Objective vs Iterations - Med Noise");
subplot(1, 3, 3);
plot(loss13);
xlabel("Iterations");
ylabel("Loss");
title("Quadratic Objective vs Iterations - High Noise");
figure;
subplot(1, 3, 1);
plot(loss21);
```

```
xlabel("Iterations");
ylabel("Loss");
title("Huber Objective vs Iterations - Low Noise");
subplot(1, 3, 2);
plot(loss22);
xlabel("Iterations");
ylabel("Loss");
title("Huber Objective vs Iterations - Med Noise");
subplot(1, 3, 3);
plot(loss23);
xlabel("Iterations");
ylabel("Loss");
title("Huber Objective vs Iterations - High Noise");
figure;
subplot(1, 3, 1);
plot(loss31);
xlabel("Iterations");
ylabel("Loss");
title("DAF Objective vs Iterations - Low Noise");
subplot(1, 3, 2);
plot(loss32);
xlabel("Iterations");
ylabel("Loss");
title("DAF Objective vs Iterations - Med Noise");
subplot(1, 3, 3);
plot(loss33);
xlabel("Iterations");
ylabel("Loss");
title("DAF Objective vs Iterations - High Noise");
```







toc;
Elapsed time is 7.050809 seconds.

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