```
#include <iostream>
#include <vector>
#include <queue>
#include <stack>
#include <omp.h>
using namespace std;
class Graph {
  int V;
  vector<vector<int>> adj;
public:
  Graph(int V): V(V), adj(V) {}
  void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
  }
  // Parallel BFS using OpenMP
  void parallelBFS(int start) {
    vector<bool> vis(V, false);
    queue<int> q;
    q.push(start);
    vis[start] = true;
    while (!q.empty()) {
      int node;
      #pragma omp critical
        if (!q.empty()) {
```

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node = q.front();
         q.pop();
      } else {
         node = -1;
      }
    }
    if (node == -1) continue;
    cout << node << " ";
    #pragma omp parallel for
    for (int i = 0; i < adj[node].size(); i++) {
      int neighbor = adj[node][i];
      bool expected = false;
      #pragma omp critical
      {
         if (!vis[neighbor]) {
           vis[neighbor] = true;
           q.push(neighbor);
        }
      }
    }
  }
// Parallel DFS using OpenMP
void paralleIDFS(int start) {
  vector<bool> vis(V, false);
  stack<int> s;
  s.push(start);
```

}

```
while (!s.empty()) {
  int node;
  #pragma omp critical
  {
    if (!s.empty()) {
       node = s.top();
       s.pop();
    } else {
       node = -1;
    }
  }
  if (node == -1 | | vis[node])
    continue;
  #pragma omp critical
  vis[node] = true;
  cout << node << " ";
  #pragma omp parallel for
  for (int i = 0; i < adj[node].size(); i++) {
    int neighbor = adj[node][i];
    #pragma omp critical
    if (!vis[neighbor]) {
       s.push(neighbor);
    }
  }
}
```

}

```
};
int main() {
  int V, E, u, v, start;
  cout << "Vertices: ";</pre>
  cin >> V;
  Graph g(V);
  cout << "Edges: ";</pre>
  cin >> E;
  cout << "Enter edges:\n";</pre>
  for (int i = 0; i < E; i++) {
     cin >> u >> v;
    g.addEdge(u, v);
  }
  cout << "Start node: ";</pre>
  cin >> start;
  cout << "BFS: ";
  g.parallelBFS(start);
  cout << "\nDFS: ";
  g.parallelDFS(start);
  return 0;
```

}