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// server.c
/************************************
* Process Management Server: Child Server Process
* Author: Michael Hartung
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* Description: This process begins when execl is called from the master server
* and is responsible for handling it's own child processes.
#include "server.h"
int minProcesses;
int maxProcesses;
int numActive;
pid_t pid[MAX_PROCESSES];
char* serverName;
int sigIntReceived;
int main(int argc, char* argv[])
          serverName = arqv[2];
          sigIntReceived = 0;
          //Register Signals
          signal(SIGINT, sigIntHandler);
signal(SIGUSR1, sigUSR1Handler);
signal(SIGUSR2, sigUSR2Handler);
          numActive = 0;
          minProcesses = atoi(argv[0]);
          maxProcesses = atoi(argv[1]);
          int i = 0:
          // Creates processes until at minProcesses
          for(i = 0; i < minProcesses; i++)</pre>
                    createProcess();
          }
          // Waits for signals
          while(1);
          return 0;
}
// Handles kill command from master server
void sigIntHandler(int sigNum)
          sigIntReceived = 1:
          while(numActive > 0)
                    abortProcess();
                    numActive--;
          printf("%s exiting...\n", serverName);
          exit(0);
}
// Sends SIGUSR1 as a command to create a process
void sigUSR1Handler(int sigNum)
          createProcess();
}
// Sends SIGUSR2 as a command to abort a process
void sigUSR2Handler(int sigNum)
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{
          abortProcess();
}
// Creates a process on server if not already at indicated maximum
void createProcess()
{
          if(numActive < maxProcesses)</pre>
                     if((pid[numActive] = fork()) < 0)</pre>
                                printf("Fork Broke!\n");
                     else if(!pid[numActive])
                                execl("process", NULL);
                     numActive++;
          else
                     printf("Too many processes running on %s\n", serverName);
          }
}
// Aborts a process if not already at indicated minimum
void abortProcess()
{
           if(numActive > minProcesses || sigIntReceived)
                     if(numActive > 0)
                                numActive--;
                                kill(pid[numActive], SIGINT);
                     }
                     else
                     {
                                printf("%s: No Processes to terminate!\n", serverName);
                     }
          else
                     printf("Too few processes in %s to abort!\n", serverName);
          }
}
```