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Approximate and Exact Selection on GPUs

Tobias Ribizel, Hartwig Anzt



Tobias Ribizel

A scenic aerial photograph of Rio de Janeiro, Brazil, featuring the iconic Sugarloaf Mountain rising from the ocean. In the foreground, the city's coastline and several islands are visible. The water is a vibrant blue.

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Brazil 20 - 24 May

**33rd IEEE
International Parallel and
Distributed Processing Symposium**



Selection Problem

Given an unsorted sequence of real numbers $x_0, x_1, x_2, x_3, \dots, x_{n-1}$, we want to find the element x_{i_k} such that in the sorted sequence

$$x_{i_0} \leq x_{i_1} \leq x_{i_2} \leq x_{i_3} \leq \dots \leq x_{i_k} \leq \dots x_{i_{n-1}}$$


 k

the element x_{i_k} is located in position k .

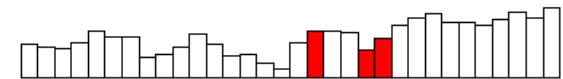
We do not necessarily need to sort the complete sequence!

- Statistics (Quantiles)
- Approximations
- Thresholds

General Approach: Partial Sorting

```
1 double select(data, rank) {
2     if (size(data) <= base_case_size) {
3         sort(data);
4         return data[rank];
5     }
6     // select splitters
7     splitters = pick_splitters(data);
8     // compute bucket sizes n_i
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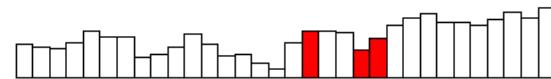
Pick splitters



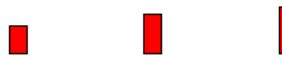
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Pick splitters



Sort splitters

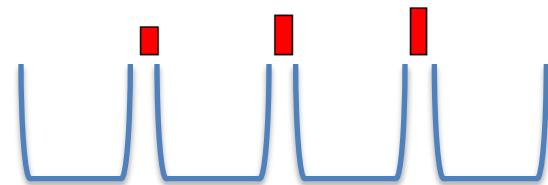
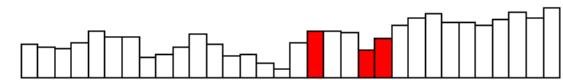


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Pick splitters

Sort splitters



Splitters separate buckets

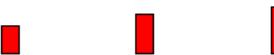
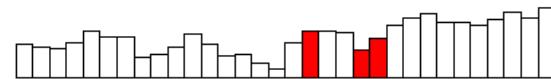
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Pick splitters

Sort splitters

Group by bucket



General Approach: Partial Sorting

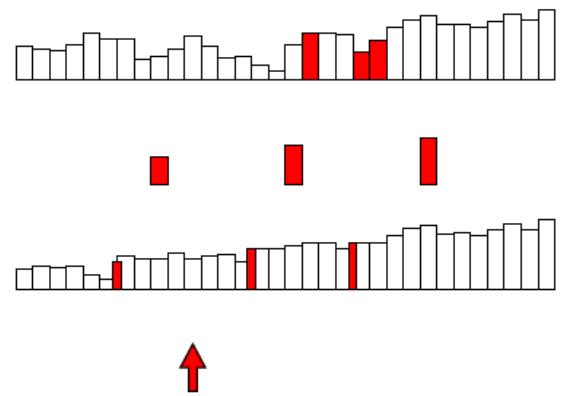
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Sort splitters

Group by bucket

Select bucket



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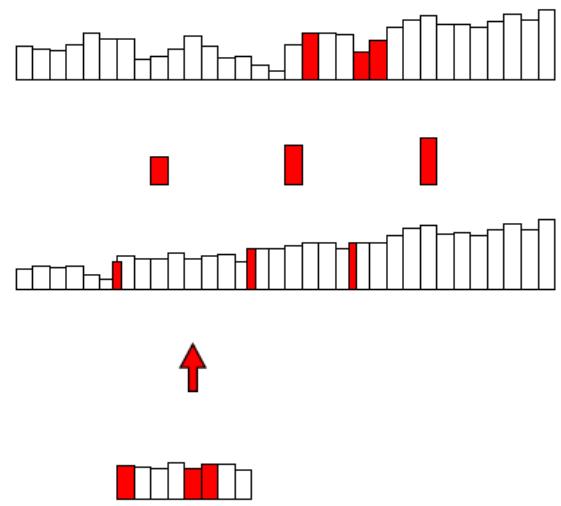
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Sort splitters

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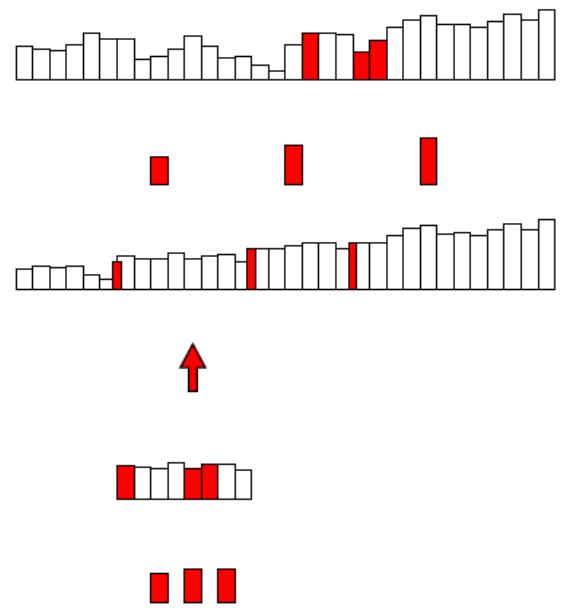
Sort splitters

Group by bucket

Select bucket

Pick splitters

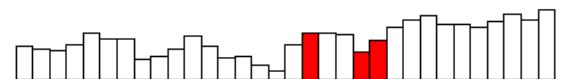
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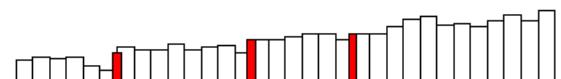
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Sort splitters



Group by bucket



Select bucket



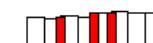
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Sort splitters



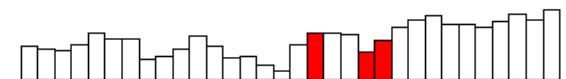
Group by bucket



Implementation Aspects

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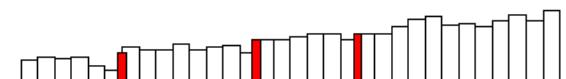
Pick splitters



Sort splitters



Group by bucket



Select bucket



Pick splitters



Sort splitters



Group by bucket



Implementation Aspects

- We only copy elements of the bucket we are interested in;

Pick splitters

Sort splitters

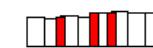
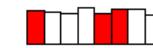
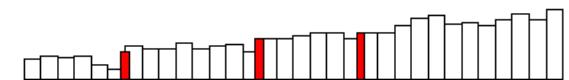
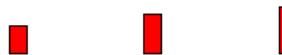
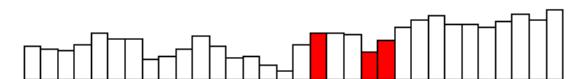
Group by bucket

Select bucket

Pick splitters

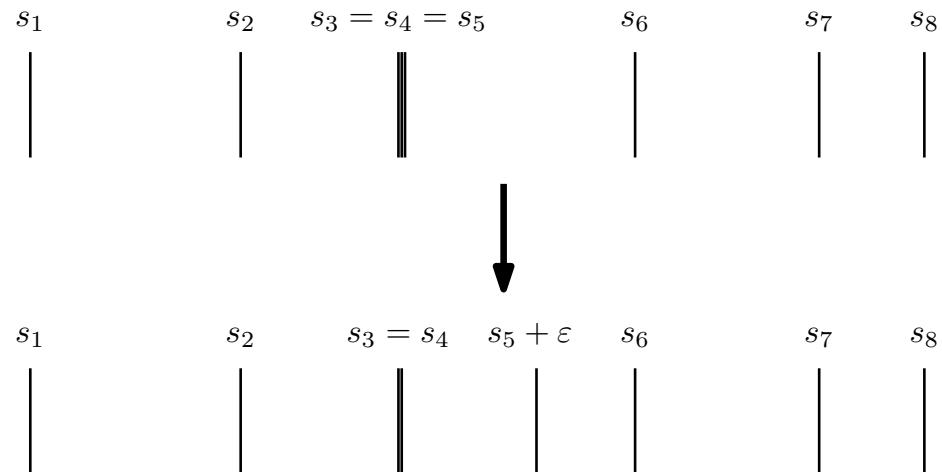
Sort splitters

Group by bucket



Implementation Aspects

- We only copy elements of the bucket we are interested in;
- In case of identical splitter elements, they are placed in an *equality bucket*;
- If target rank is in an *equality bucket*, the algorithm can terminate early by returning lower bound;



Pick splitters

Sort splitters

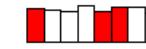
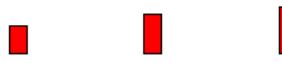
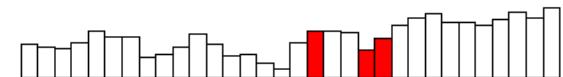
Group by bucket

Select bucket

Pick splitters

Sort splitters

Group by bucket



Implementation Aspects

- We only copy elements of the bucket we are interested in;
- In case of identical splitter elements, they are placed in an *equality bucket*;
- If target rank is in an *equality bucket*, the algorithm can terminate early by returning lower bound;
- For sorting the splitters, small input datasets, and the lowest recursion level a *bitonic sort* in shared memory is used;

Pick splitters

Sort splitters

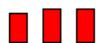
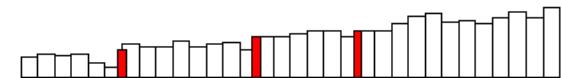
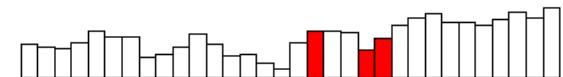
Group by bucket

Select bucket

Pick splitters

Sort splitters

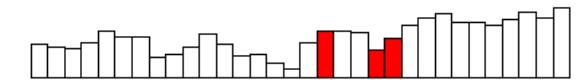
Group by bucket



Implementation Aspects

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- If target rank is in an *equality bucket*, the algorithm can terminate early by returning lower bound;
- For sorting the splitters, small input datasets, and the lowest recursion level a *bitonic sort* in shared memory is used;
- Use a *binary search tree* to sort elements into the buckets;

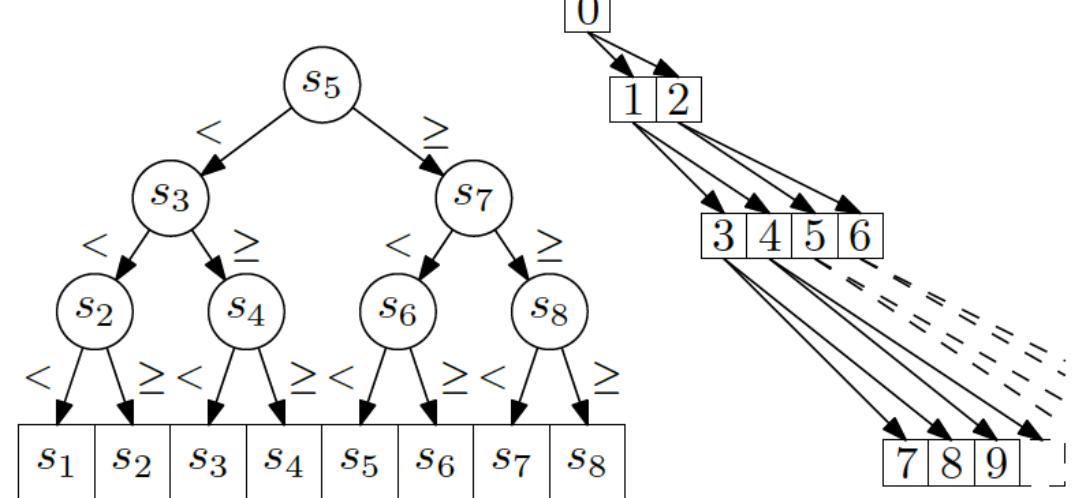
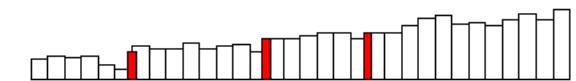
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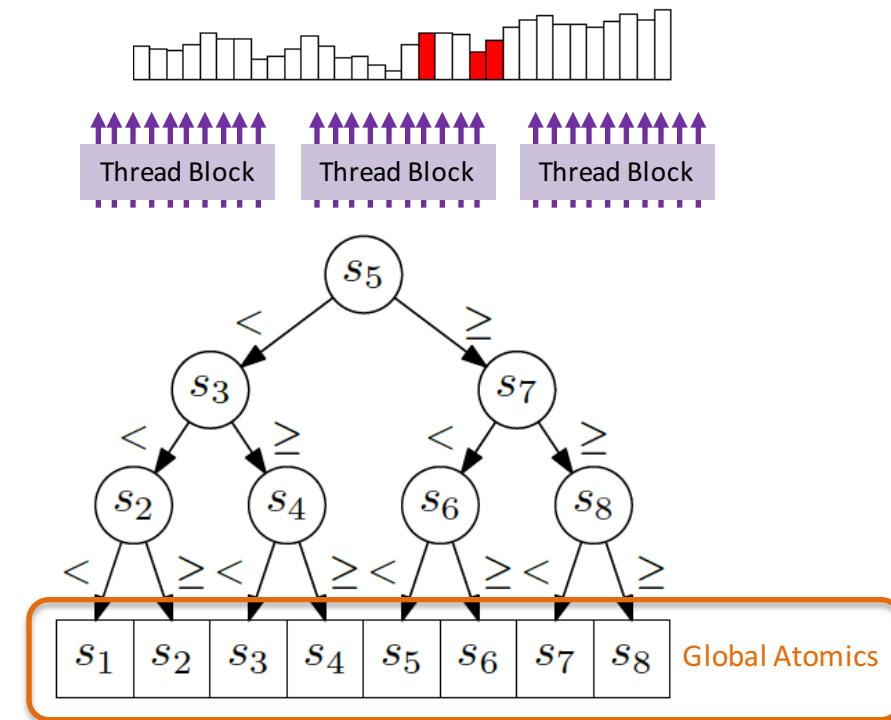


Group by bucket



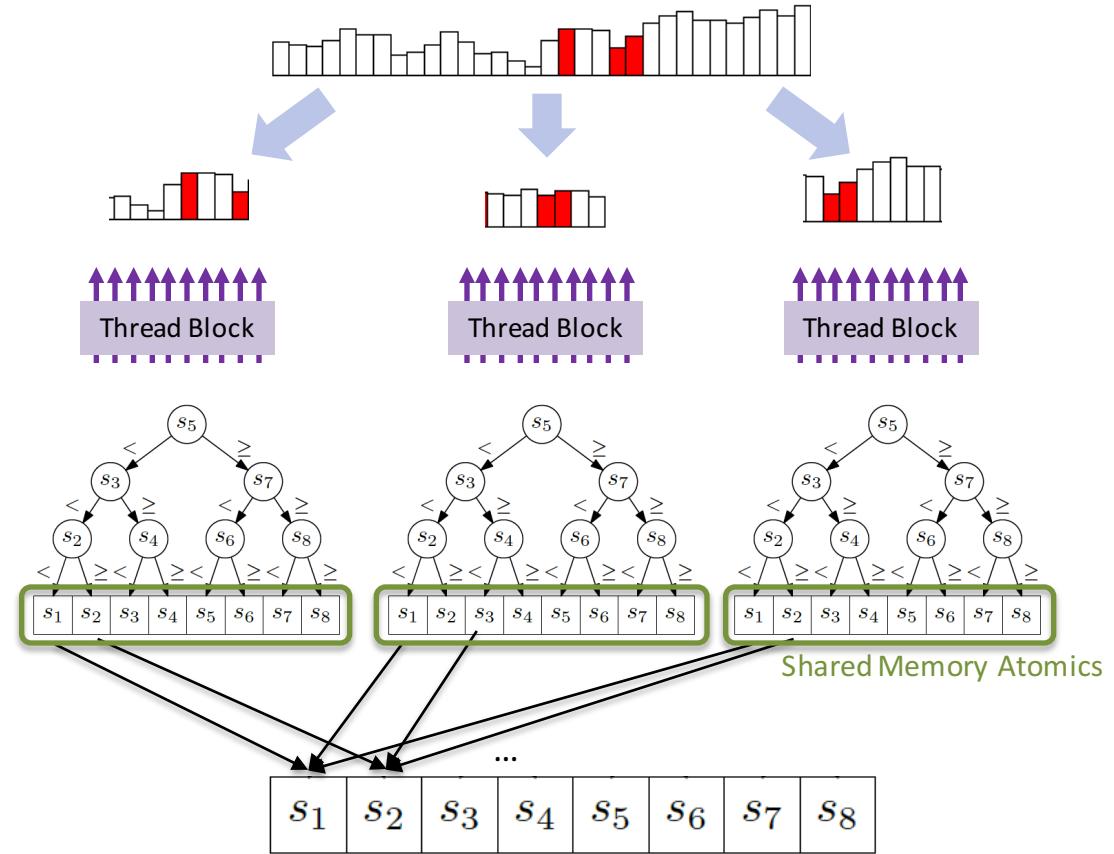
Parallelization & Communication

Global Memory Atomics



- Run SampleSelect using all resources on complete data set;
- Use global atomics to generate bucket counts;

Shared Memory Atomics



- Split data set into chunks, assign to thread blocks;
- Each thread block runs bucket count on its data;
- Use a global reduction to get global bucket counts;

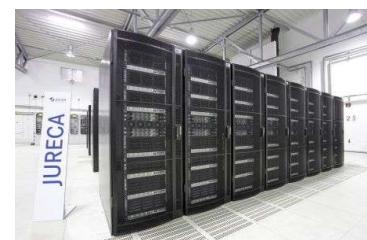
Experiment Setup

- 2 distinct GPU architectures
 - Input datasets with 2^{16} to 2^{28} elements
 - $d = 1, 16, 128, 1024, n$ distinct values
 - All results averaged over 10 runs
 - Single precision input data
-
- Comparison against QuickSelect kernel
 - QuickSelect and SampleSelect have same performance optimization level
 - Correctness check using C++ `std::nth_element`

	NVIDIA K40	NVIDIA V100
Architecture	Kepler	Volta
DP Performance	1.2 TFLOPs	7 TFLOPs
SP Performance	3.5 TFLOPs	14 TFLOPs
HP Performance	–	112 TFLOPs
SMs	13	80
Operating Freq.	0.75 GHz	1.53 GHz
Mem. Capacity	5 GB	16 GB
Mem. Bandwidth	208 GB/s	900 GB/s
Sustained BW	146 GB/s	742 GB/s
L2 Cache Size	1.5 MB	6 MB
L1 Cache Size	64 KB	128 KB

2013

2017



#44@TOP500

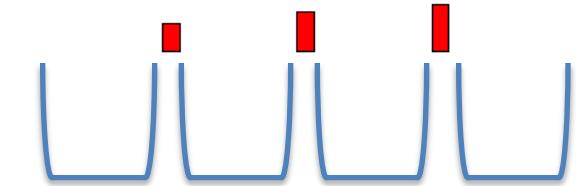
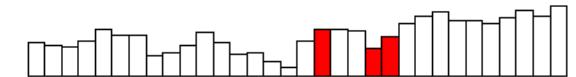


#1@TOP500

Kernel Optimization I: Bucket Count

Pick splitters

Sort splitters



Splitters separate buckets

Kernel Optimization I: Bucket Count

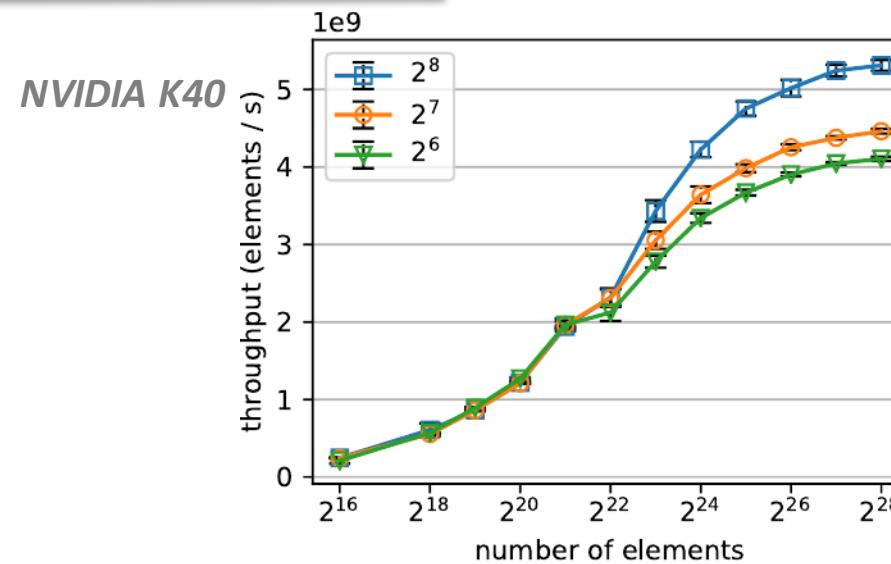
NVIDIA K40

NVIDIA V100

Global memory atomics

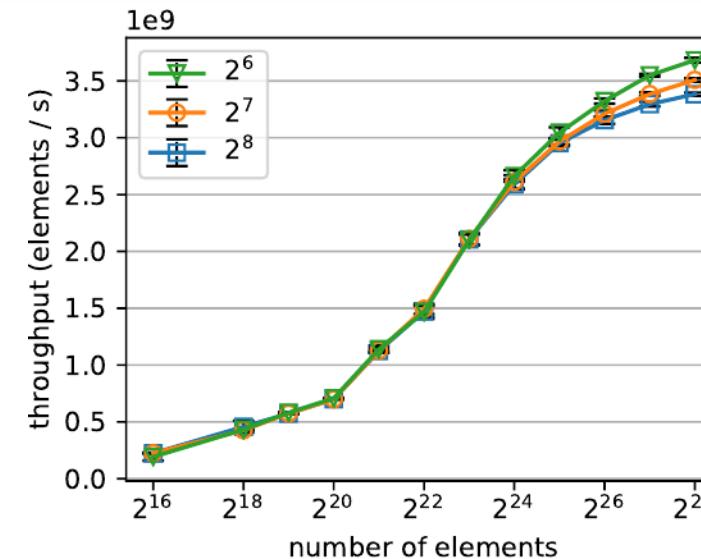
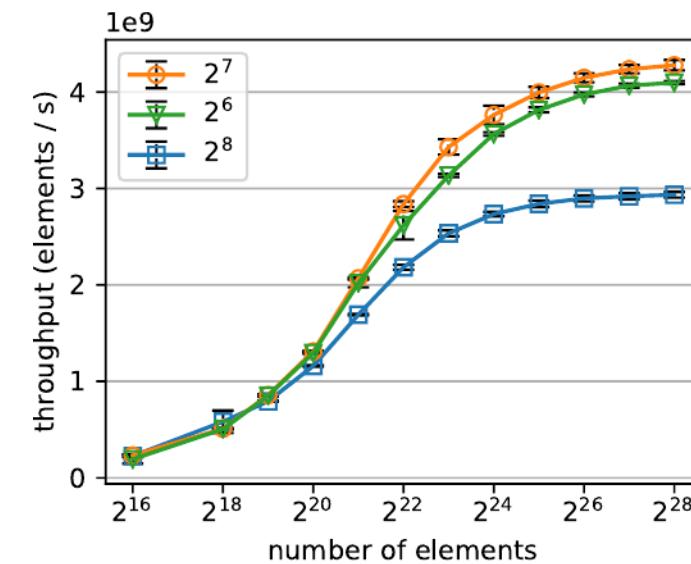
Shared memory atomics

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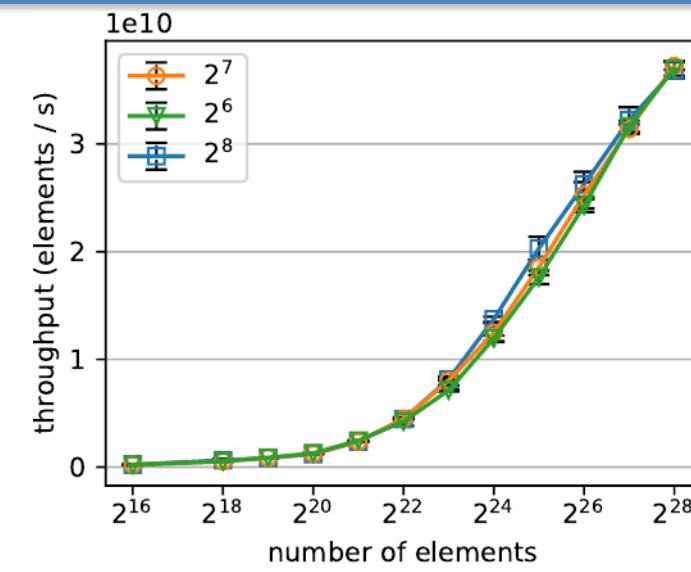


NVIDIA V100

Global memory atomics

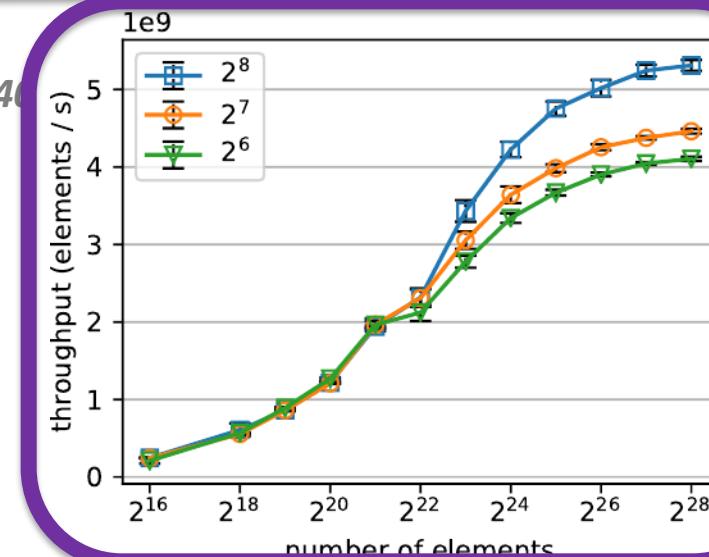


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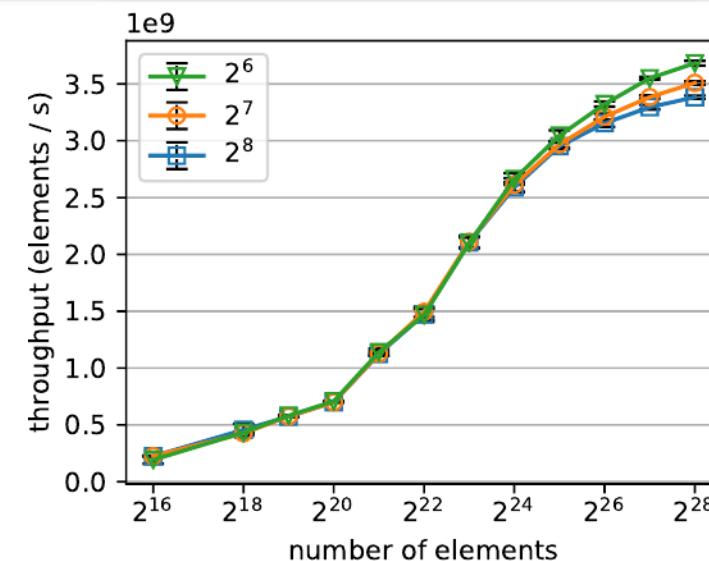
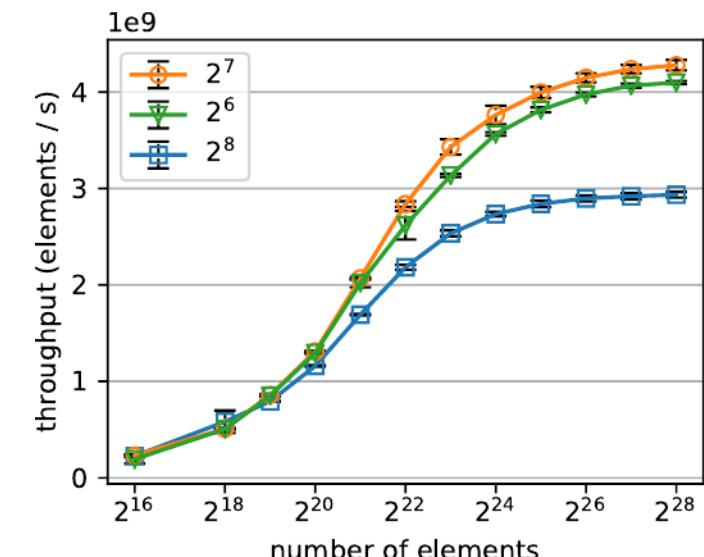
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NVIDIA K40

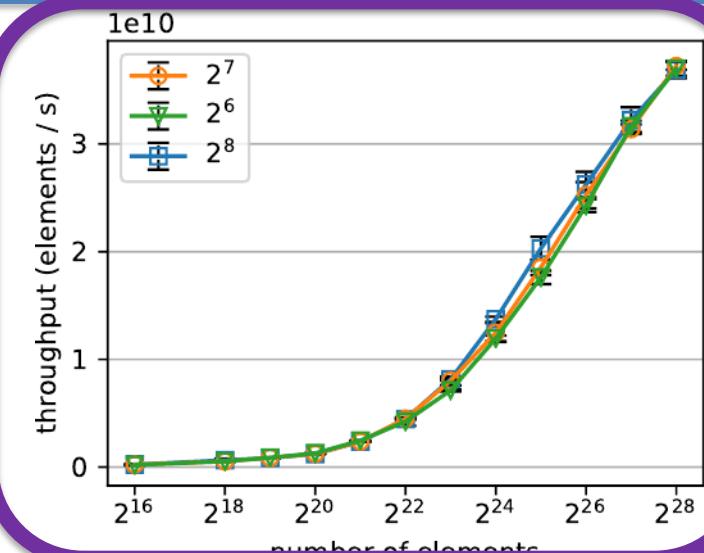


NVIDIA V100

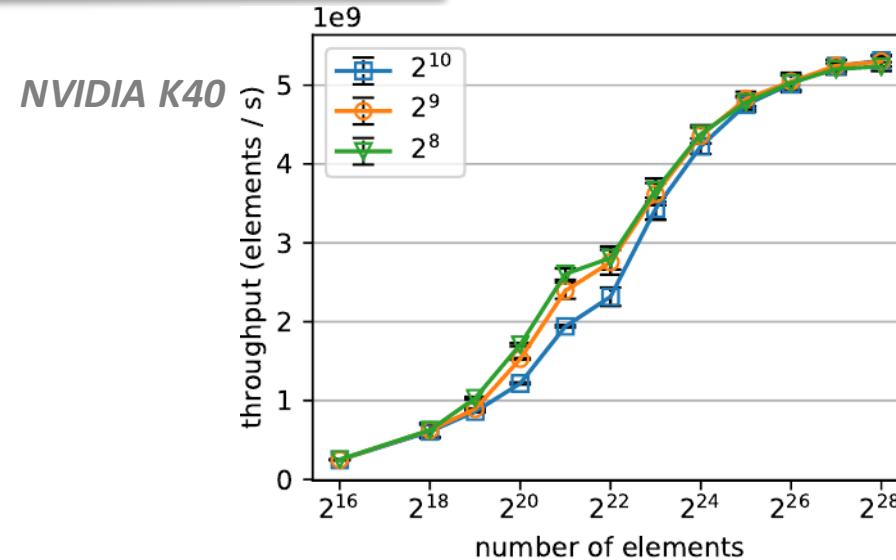
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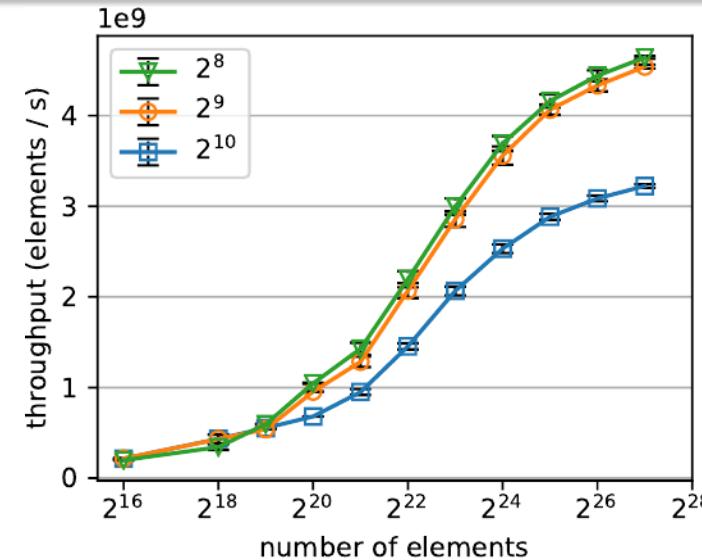
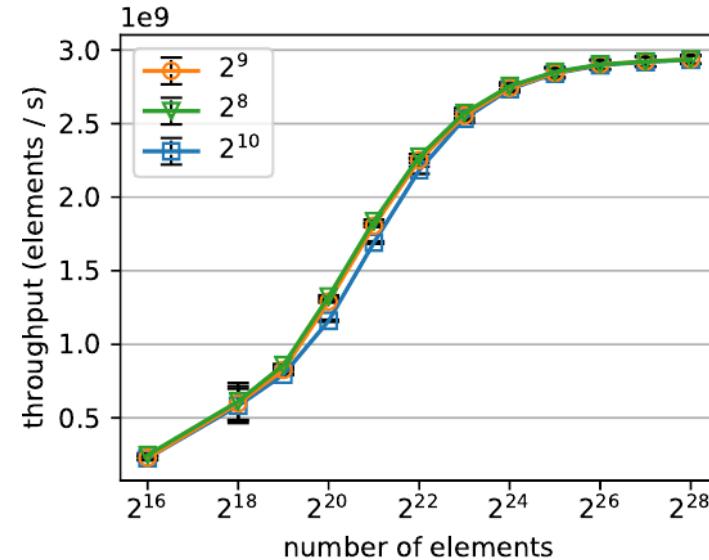


Kernel Optimization II: #Threads per Block

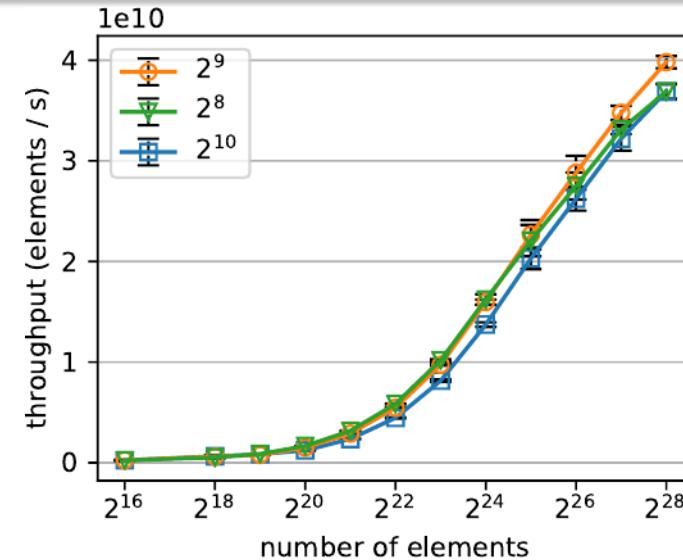


NVIDIA V100

Global memory atomics

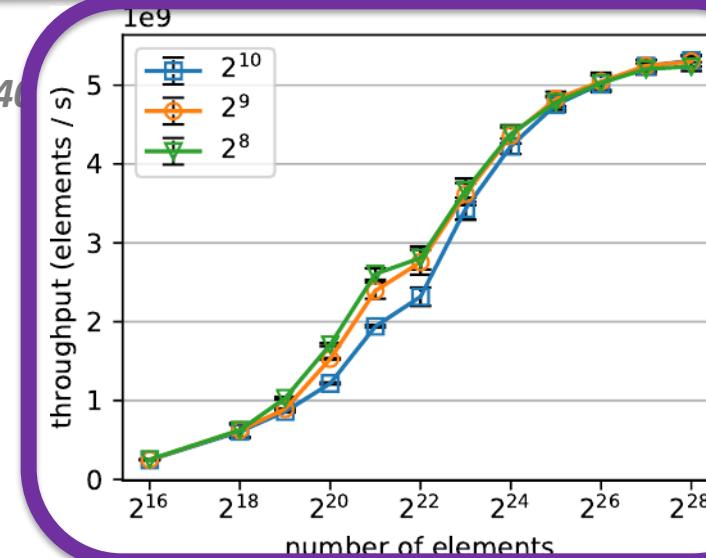


Shared memory atomics



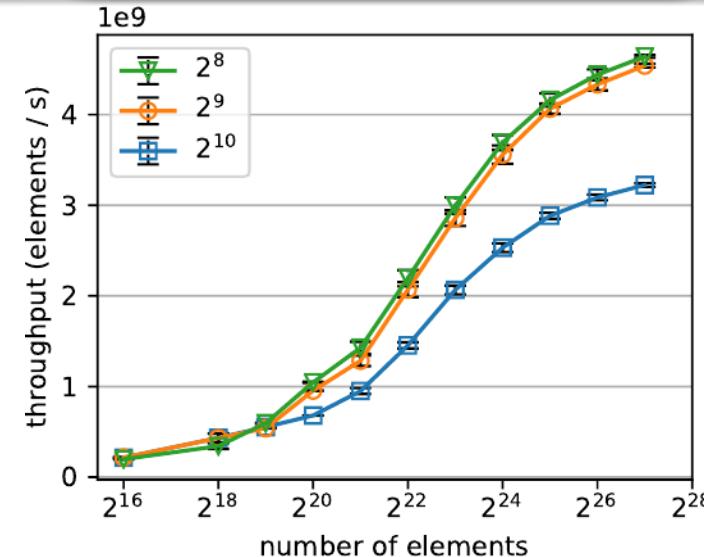
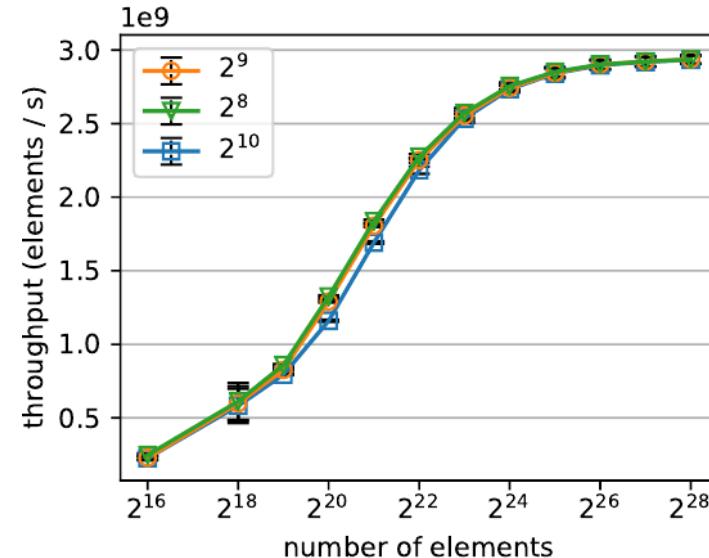
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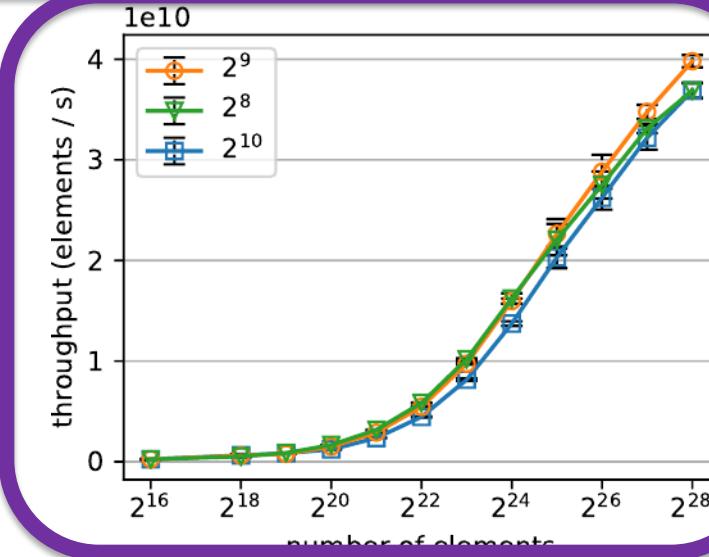


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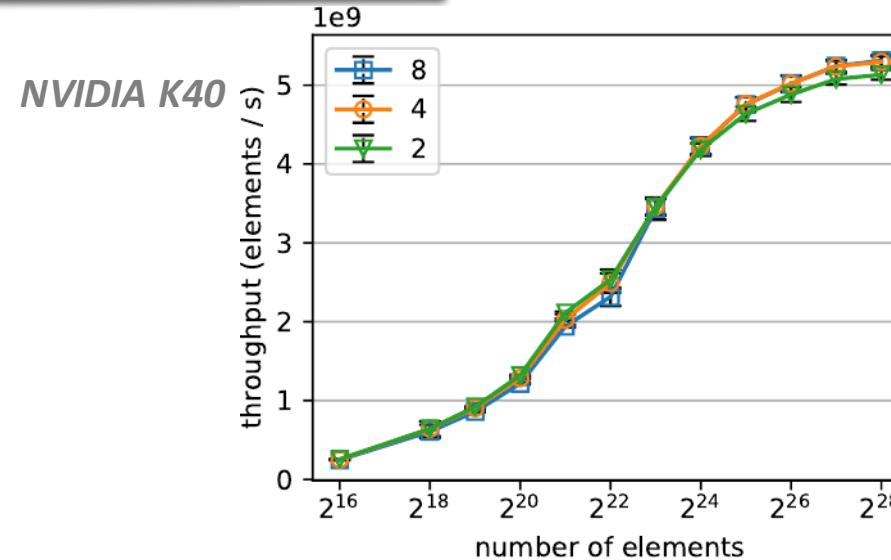
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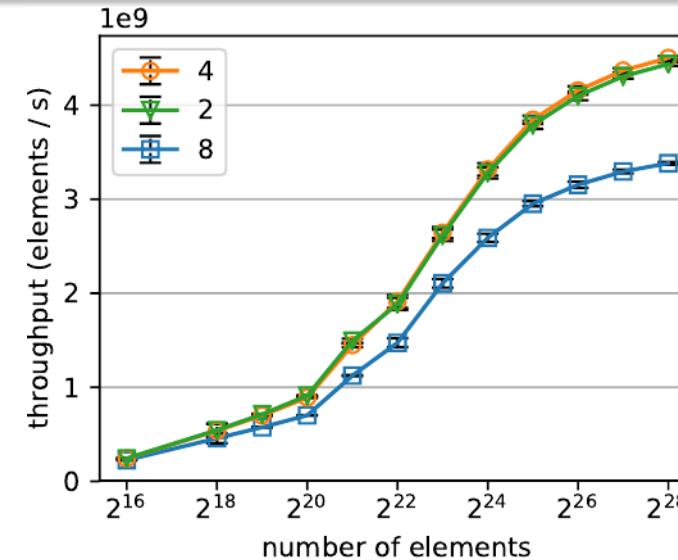
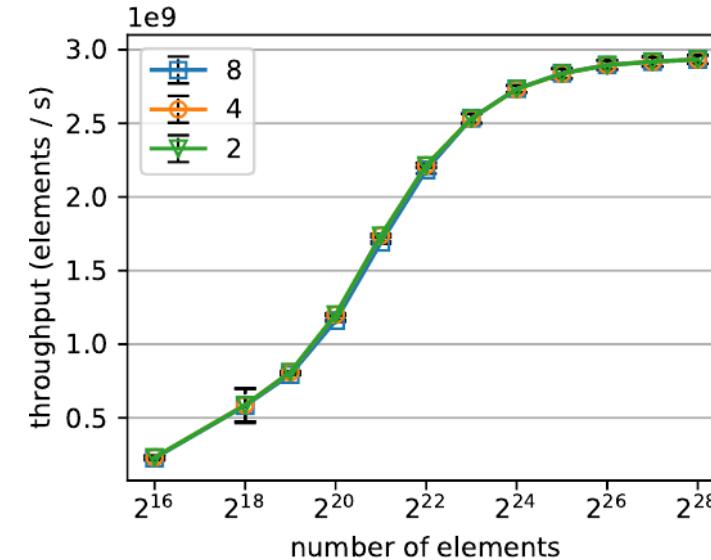


Kernel Optimization III: Loop Unrolling

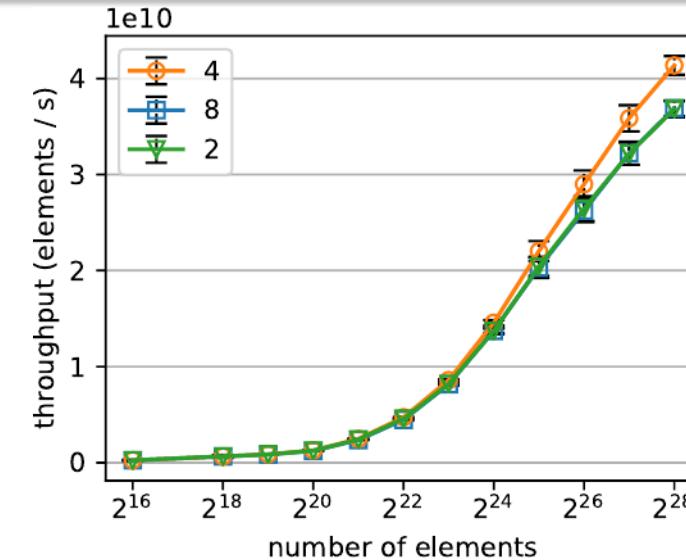


NVIDIA V100

Global memory atomics

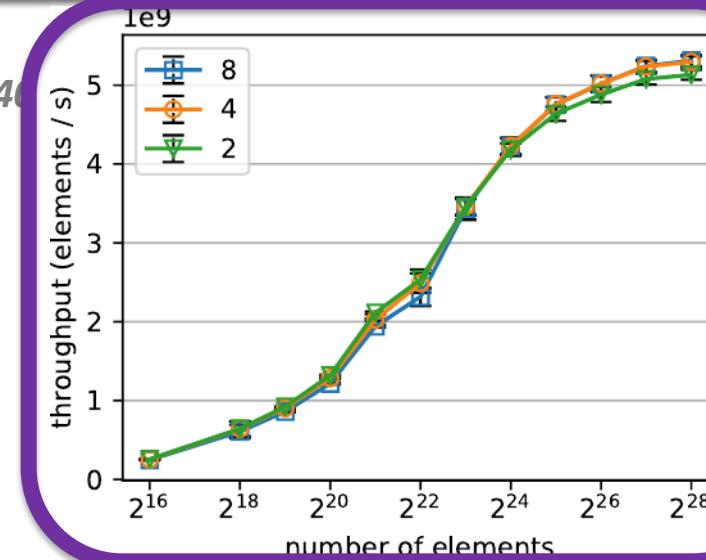


Shared memory atomics

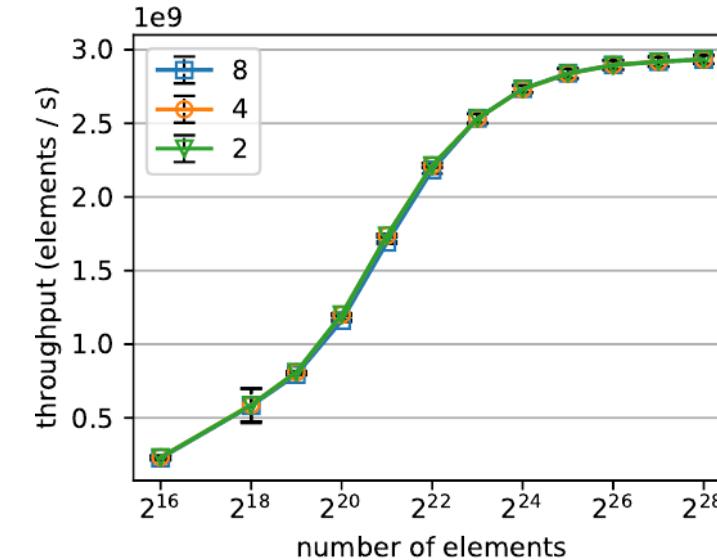


Kernel Optimization III: Loop Unrolling

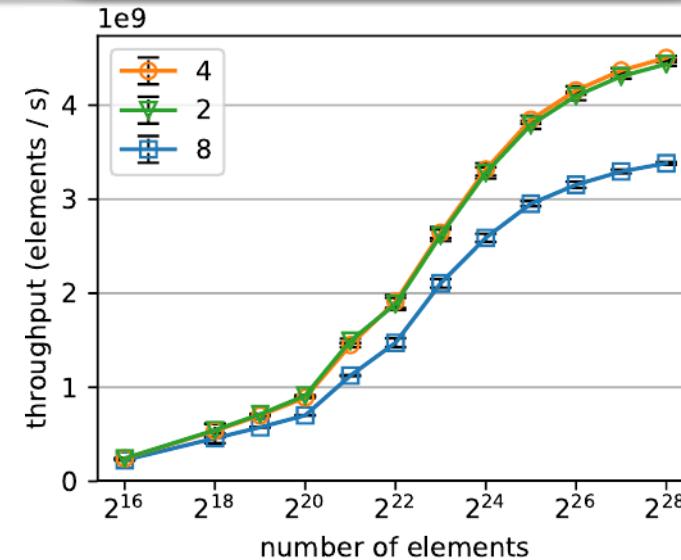
NVIDIA K40



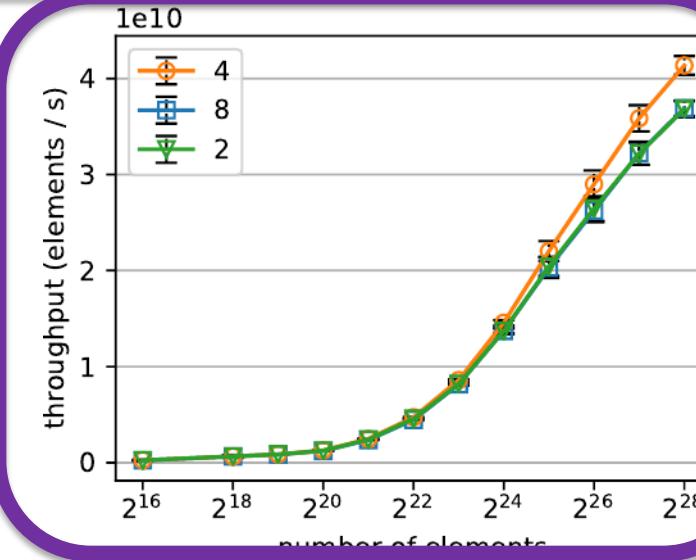
NVIDIA V100



Global memory atomics



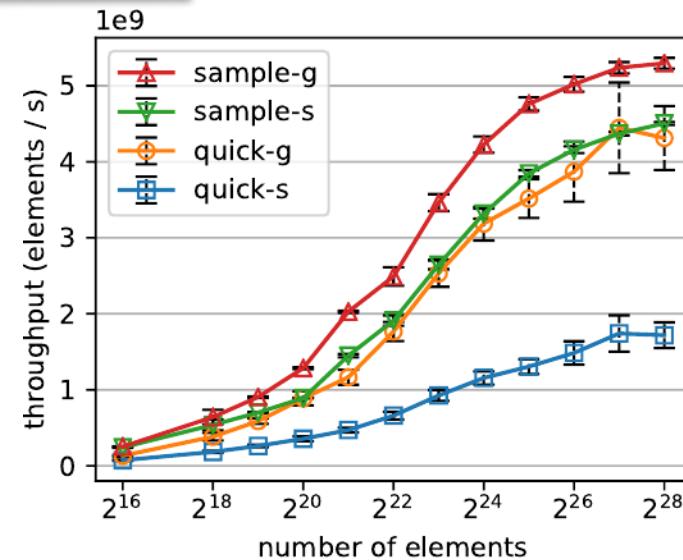
Shared memory atomics



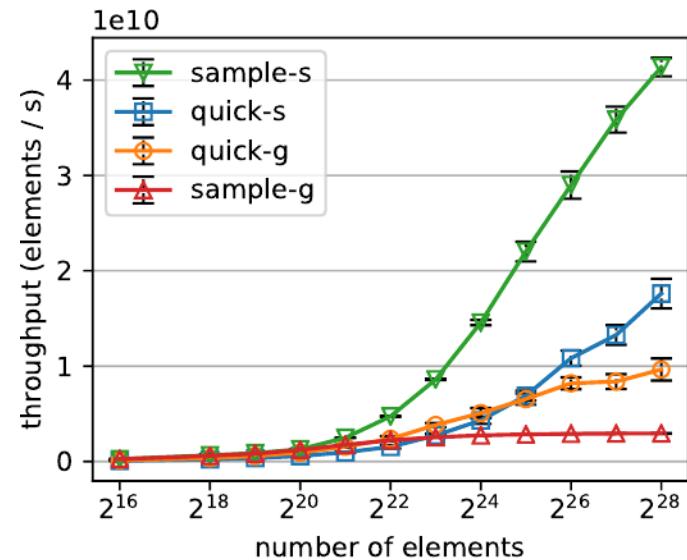
Kernel Optimization IV: Global vs. Local Atomics

-g : global memory atomics
-s: shared memory atomics

NVIDIA K40



NVIDIA V100

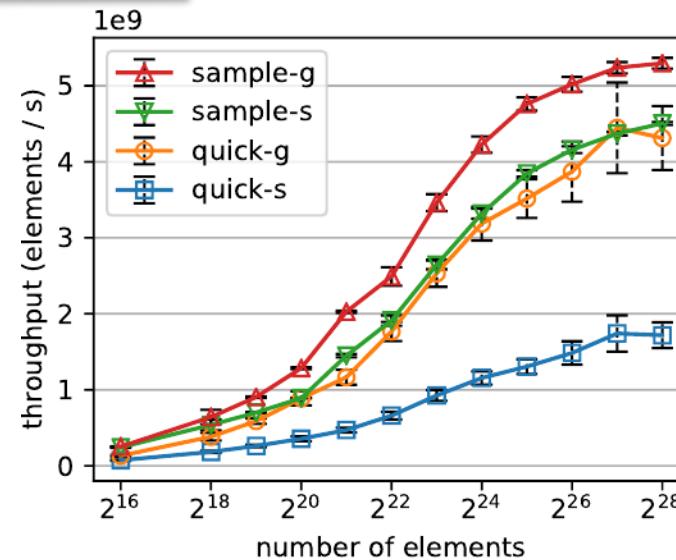


Larger performance variation for QuickSelect as we are more likely to run into the “Worst-Case” performance.

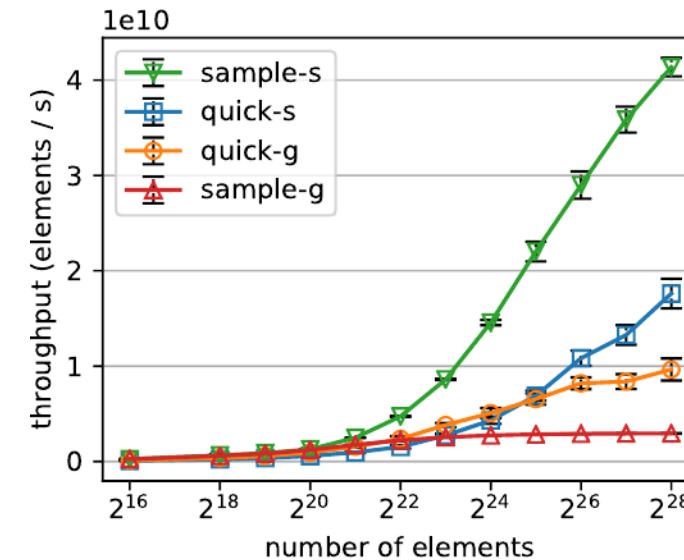
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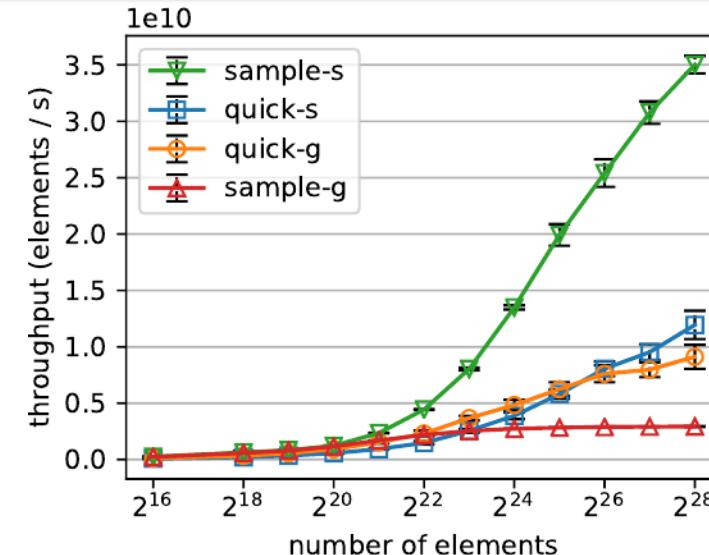
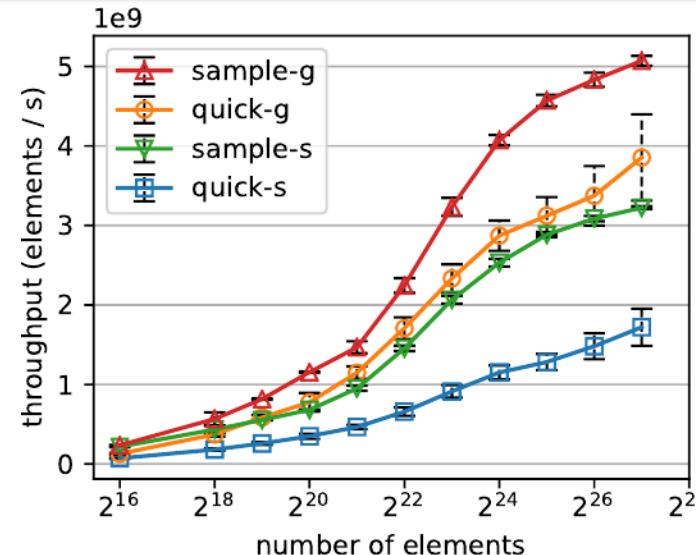
NVIDIA K40



NVIDIA V100

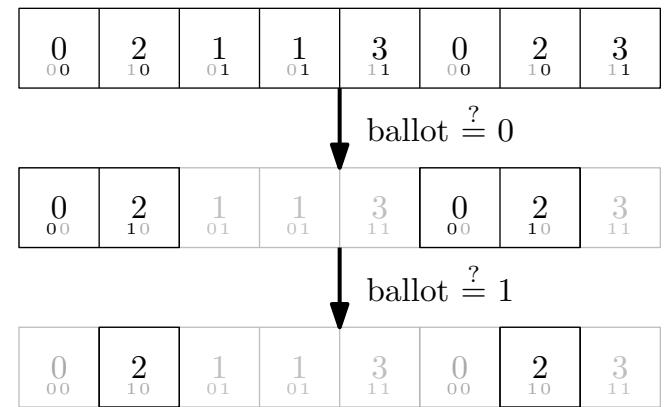


double precision



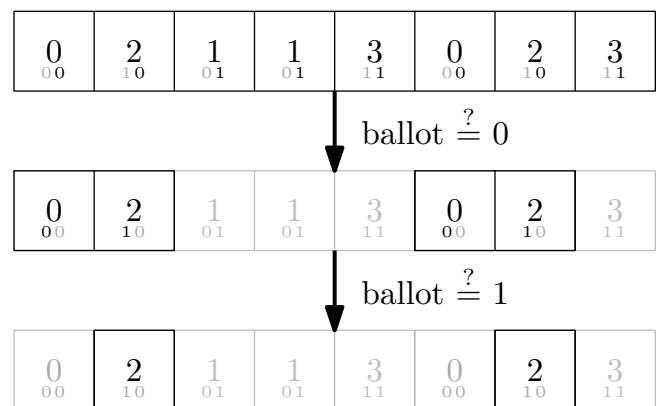
Kernel Optimization V: Element Repetition

Idea: use warp aggregations to mitigate the performance impact from atomic collisions.

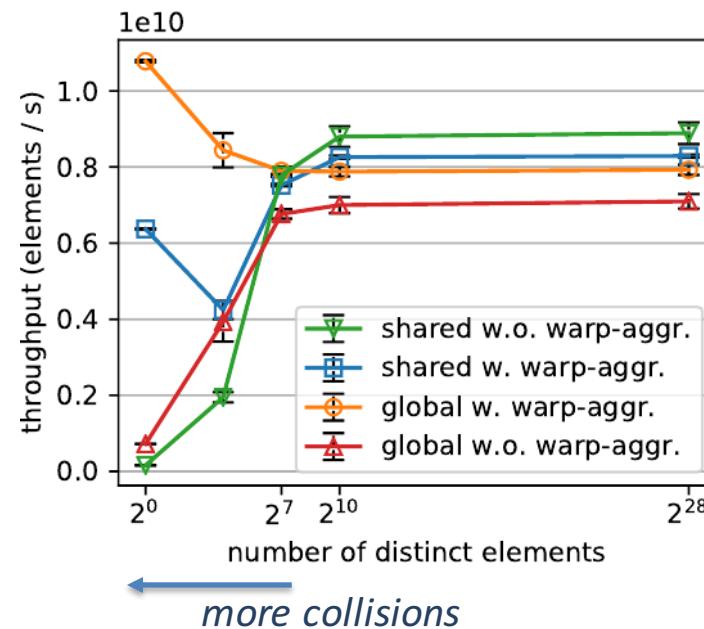


Kernel Optimization V: Element Repetition

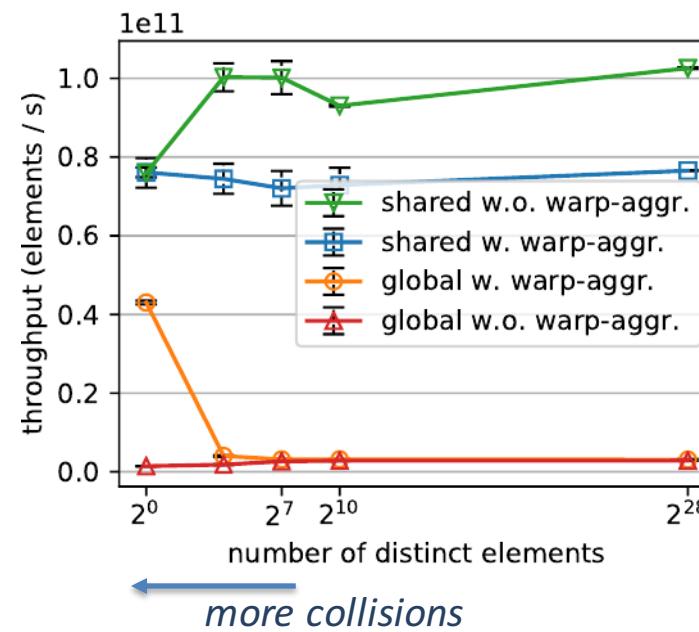
Idea: use warp aggregations to mitigate the performance impact from atomic collisions.



NVIDIA K40



NVIDIA V100



Approximate Selection

We do not descent to the lowest level of the recursion tree,
but limit to one single bucket selection.

- Accuracy depends on the number of splitters vs. dataset size
- Accuracy independent of value distribution (works on ranks, only)

Pick splitters

Sort splitters

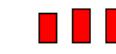
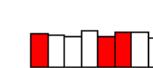
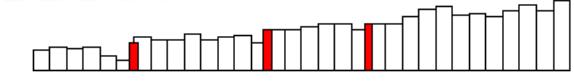
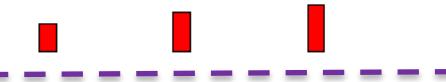
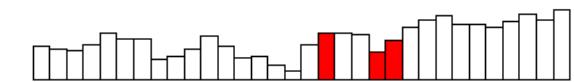
Select splitter
Group by bucket

Select bucket

Pick splitters

Sort splitters

Group by bucket



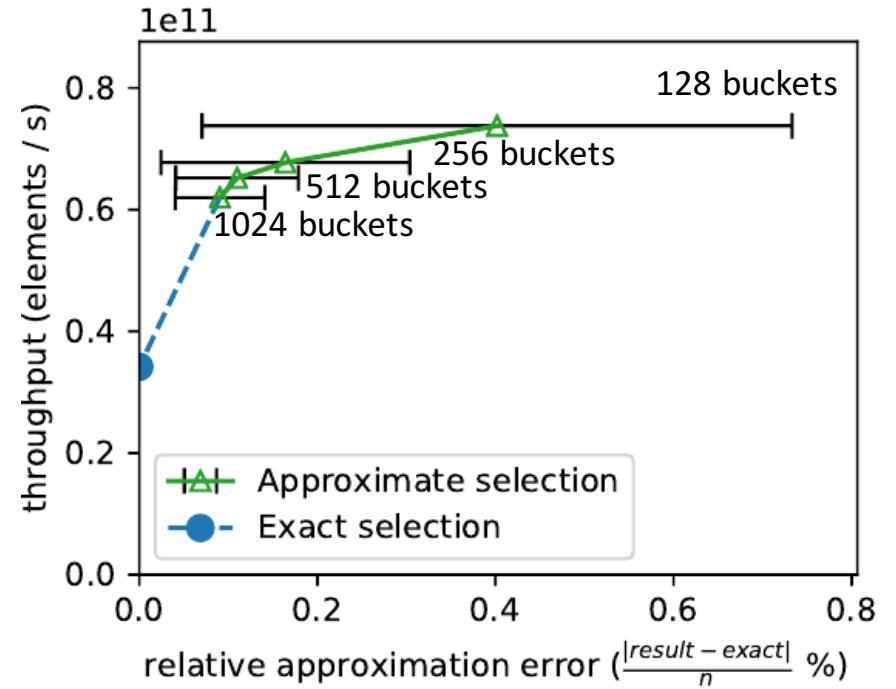
Approximate Selection

We do not descent to the lowest level of the recursion tree, but limit to one single bucket selection.

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- Accuracy independent of value distribution (works on ranks, only)

Test problem:

- 2^{28} uniformly distributed single precision values
- Approximate selection uses 1 level only
- We report statistics over 10 runs



Summary and Outlook

<http://bit.ly/SampleSelectGPU>

- SampleSelect kernel much faster than QuickSelect
- 36% (single) 48% (double) of experimental peak memory bandwidth on NVIDIA V100
- Approximate selection >2x faster than exact selection



Tobias Ribizel



Summary and Outlook

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What is approximate selection good for?

IPDPS Main Track, Tuesday 1:30
Session 6: GPU Computing:
ParILUT - A Parallel Threshold ILU for GPUs

