Numerical Integration

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- Not all functions have closed-form anti-derivatives. Thus not all integrals can be evaluated by the Fundamental Theorem of Calculus.
- For special functions, such as the error function

$$\frac{2}{\sqrt{\pi}}\int_0^x e^{-t^2}dt,$$

efforts can be taken to tabulate values once for all. But this practice is too limited.

- One better approach is to approximate the integral by quadratures.
 - Given a function f(t) defined on [a, b], a formula of the form

$$Q_n(f) := \sum_{i=1}^n \alpha_i f(x_i)$$
 (1)

with $\alpha_i \in R$ and $x_i \in [a, b]$ is called a quadrature rule for the integral $I(f) := \int_a^b f(t) dt$.

- The points x_i are called the quadrature points (abscissas)
- The values α_i are called the quadrature coefficients (weights).
- The quadrature error is defined to be $E_n(f) := I(f) Q_n(f)$.

- A quadrature rule is said to have degree of precision m if $E_n(x^k) = 0$ for k = 0, ..., m and $E_n(x^{m+1}) \neq 0$.
 - If a quadrature rule has degree of precision m, then $E_n(p_k) = 0$ for all polynomials $p_k(x)$ of degree $\leq m$.
- The trapezoidal rule,

$$Q_2(f) = \frac{b-a}{2}[f(a)+f(b)], \tag{2}$$

is a quadrature rule with degree of precision m = 1. (Try to prove this by graph.)

• Recall the linear interpolant of f(t) and the corresponding error:

$$f(t) = f(a) + \frac{f(b) - f(a)}{b - a}(t - a) + \frac{f''(\xi_t)}{2}(t - a)(t - b).$$

Integrate both side of the above, we obtain

$$I(f) \approx Q_2(f) = \frac{b-a}{2}[f(a)+f(b)]$$

and

$$E_2(t) = \int_a^b \frac{f''(\xi_t)}{2} (t-a)(t-b)dt.$$

• Recall the Mean Value Theorem for integrals: If f is continuous and g is nondecreasing in the interval [a, b], then there exists $\xi \in [a, b]$ such that

$$\int_a^b f dg = f(\xi) \int_a^b dg.$$

We may rewrite

$$E_2(t) = \frac{f''(\eta)}{2} \int_a^b (t-a)(t-b)dt = -\frac{f''(\eta)}{12}(b-a)^3.$$
 (3)

• If |f''(t)| is not too large and if b-a is small, the trapezoidal rule gives an approximation with errors around $O(h^3)$.

- Over a large interval, the trapezoidal rule should be applied by summing the results of many applications of the rule over smaller intervals. This is called composite trapezoidal rule.
 - Divide [a, b] into n equally spaced intervals with step size $h = \frac{b-a}{n}$ and nodes $x_i = a + ih$ for i = 0, 1, ..., n.
 - Use the trapezoidal rule to approximate

$$\int_{x_{i-1}}^{x_i} f(x) dx \approx \frac{h}{2} [f(x_{i-1}) + f(x_i)]$$

over each subinterval $[x_{i=1}, x_i]$.

• Sum these approximations together:

$$\int_{a}^{b} f(x)dx \approx h\left[\frac{f(x_{0})}{2} + f(x_{1}) + \ldots + f(x_{n-1}) + \frac{f(x_{n})}{2}\right]. \tag{4}$$

This is called the composite trapezoidal rule.

Lemma (Discrete Mean-Value Theorem)

Let $u \in C^0([a,b])$ and let x_j be k+1 points in [a,b] and a_j be k+1 constants, all having the same sign. Then there exists $\eta \in [a,b]$ such that

$$\sum_{j=0}^k a_j u(x_j) = u(\eta) \sum_{j=0}^k a_j.$$

Proof.

Without loss of generality, assume $a_j \ge 0$ for all j. Let $F(x) = \sum_{j=0}^k a_j u(x)$, $u(\bar{x}) = \min_{x \in [a,b]} u(x)$, and $u(\bar{x}) = \max_{x \in [a,b]} u(x)$. It follows that

$$F(\bar{x}) \leq \sum_{i=0}^k a_i u(x_i) \leq F(\bar{x}).$$

Since F is continuous on [a, b], there exists $\eta \in [a, b]$ such that

$$F(\eta) = \sum_{i=0}^{\kappa} a_i u(x_i).$$

Error formula for the composite trapezoidal rule :

$$E_n(f) = -\frac{h^3}{12} \sum_{i=1}^n f''(\eta_i) = -\frac{h^2}{12} \frac{b-a}{n} \sum_{i=1}^n f''(\eta_i) = -\frac{(b-a)h^2}{12} f''(\eta).$$

- The way the trapezoidal rule is derived can be generalized to higher degree polynomial interpolants. Such a quadrature rule is called a Newton-Cotes formula.
- Let x_0, x_1, \dots, x_n be given nodes in [a, b]. Recall that the Lagrange interpolation of a function at these nodes is given by the polynomial

$$p(t) = \sum_{j=0}^{n} f(x_j) \ell_j(t)$$

where each $\ell_i(t)$ is the Lagrange polynomial

$$\ell_j(t) := \prod_{i=0, i\neq j}^n \frac{t-x_i}{x_j-x_i}, \ j=0,1,\ldots,n.$$

We therefore have

$$\int_{a}^{b} f(t)dt \approx \int_{a}^{b} \rho(t)dt = \sum_{j=0}^{n} \omega_{j} f(x_{j})$$

where the weight ω_i is determined by

$$\omega_j = \int_a^b \ell_j(t) dt. \tag{5}$$

• Note that if f(t) itself is a polynomial of degree $\leq n$, then

$$f(t) = \sum_{j=0}^{n} f(x_j) \ell_j(t). \text{ (Why?)}$$

In this case, the Newtow-Cotes quadrature rule evaluates $\int_a^b f(t)dt$ precisely.

• The Newton-Cotes quadrature rule has degree of precision at least n.

- It is nice to know how the weight ω_j should be calculated. However, there are some other concerns:
 - These weights are difficult to evaluate.
 - How high can the degree of precision be pushed?
- Suppose we approximate f(t) by a quadratic polynomial $p_2(t)$ that interpolates f(a), $f\left(\frac{a+b}{2}\right)$ and f(b).
 - It can be shown that

$$Q_3(f) = \frac{b-a}{6}[f(a) + 4f(\frac{a+b}{2}) + f(b)].$$
 (Do it now.)

• Compute
$$\ell_0(x) = \frac{(x - \frac{a+b}{2})(x-b)}{(a-b)^2/2}, \ \ell_1(x) = \dots, \ell_2(x) = \dots$$

- The error part is tricky!
 - Observe that the function (in variable s) from Newton's formula, $g(s) = p_2(s) + f[a, b, \frac{a+b}{2}, t](s-a)(s-b)(s-\frac{a+b}{2})$, interpolates f at $a, b, \frac{a+b}{2}$ and t.
 - $p_2(s)$: polynomial of degree 2.
 - Taking s as t and Thinking t as arbitrary, we should have

$$f(t) = p_2(t) + f[a, b, \frac{a+b}{2}, t](t-a)(t-b)(t-\frac{a+b}{2})$$

• The error $E_3(f)$ therefore is given by

$$E_3(f) = \int_a^b f[a, b, \frac{a+b}{2}, t] \omega(t) dt$$
 (6)

with
$$\omega(t) := (t - a)(t - b)(t - \frac{a+b}{2})$$
.

• We already know that the degree of precision is \geq 2. Can this be better?

- Here, we analyze $E_3(f)$ by the method of integration by parts.
 - Let $\Omega(x) := \int_a^x \omega(t) dt$. Then $\Omega'(x) = \omega(x)$.
 - By integration by parts, we have

$$E_3(f) = f[a, b, \frac{a+b}{2}, x]\Omega(x)|_a^b - \int_a^b f[a, b, \frac{a+b}{2}, x, x]\Omega(x)dx.$$

- $f[a, a+h] = \frac{f(a+h)-f(a)}{h}$.
- $f[a, a] = \lim_{h \to 0} \frac{f(a+h) f(a)}{h} = f'(a)$.

- Observe that $\Omega(a) = \Omega(b) = 0$. Observe also that $\Omega(x) > 0$ for all $x \in (a, b)$.
- We may apply the mean value theorem to conclude that

$$E_{3}(f) = -\int_{a}^{b} f[a, b, \frac{a+b}{2}, x, x] \Omega(x) dx$$

$$= -f[a, b, \frac{a+b}{2}, \xi, \xi] \int_{a}^{b} \Omega(x) dx$$

$$= -\frac{f^{(4)}(\eta)}{4!} \frac{4}{15} \left(\frac{b-a}{2}\right)^{5}$$

$$= -\frac{f^{(4)}(\eta)}{90} \left(\frac{b-a}{2}\right)^{5}.$$

• The degree of precision for Simpson's rule is 3 rather than 2.

• Divide the interval into 2n equally space subintervals with $h=\frac{b-a}{2n}$ and $x_i=a+ih$ for $i=0,1,\ldots,2n$. Upon applying Simpson's rule over two consecutive subintervals $[x_{2j},x_{2j+2}]$ for $j=0,1,\ldots,n-1$ and summing up these integrals, we obtain the composite Simpson's rule:

$$\int_{a}^{b} f(t)dt \approx \frac{h}{3} \left\{ f_0 + 4f_1 + 2f_2 + 4f_3 + \ldots + 2f_{2n-2} + 4f_{2n-1} + f_{2n} \right\}. \quad (7)$$

 The error formula for the composite Simpson's rule can be obtained in the same way as we derived the error formula for the composite trapezoidal rule:

$$E_{3,cs} = \sum_{i=1}^{n} -\frac{f^{(4)}(\eta_i)}{90} h^5 = -\frac{(b-a)h^4}{180n} \sum_{i=1}^{n} f^{(4)}(\eta_i)$$
$$= -\frac{(b-a)h^4}{180} f^{(4)}(\eta).$$

- An improper integral such as $\int_0^1 \frac{1}{\sqrt{t}} dt$ does exist even though it is not defined at t = 0.
 - A Newton-Cotes quadrature must exclude the node t = 0. Even so, the results are not good. (Why?)
 - A better approach is to incorporate the singularity into the quadrature rule itself.
- The idea is to integrate a function f(t) with respect to a specified weight function w(x), i.e.,

$$I_{w}(f) := \int_{a}^{b} f(t)w(t)dt \tag{8}$$

where $w(t) \ge 0$ on [a, b]. In such a case, we consider a quadrature rule of the form

$$Q_{w}(f) := \sum_{i=1}^{n} \alpha_{i} f(x_{i}). \tag{9}$$

• Note that the weight function w(x) does not appear on the right hand side of (9).

• An example: Suppose $w(t)=t^{-1/2}$ and suppose the nodes selected are $x_1=\frac{1}{4}$ and $x_2=\frac{3}{4}$. We want to determined the coefficients α_1 and α_2 in the quadrature so that

$$\int_0^1 1t^{-1/2} dt = 2 = \alpha_1 + \alpha_2$$
$$\int_0^1 tt^{-1/2} dt = \frac{2}{3} = \frac{1}{4}\alpha_1 + \frac{3}{4}\alpha_2.$$

The newly weighted quadrature reads like

$$\int_0^1 f(t)t^{-1/2}dt \approx \frac{5}{3}f(\frac{1}{4}) + \frac{1}{3}f(\frac{3}{4}).$$

 The entire theory that works for Newton-Cotes or Gaussian quadratures can be generalized to the weighted integrals. The arguments will not be repeated in this course, but take note of this possibility.

- Newton-Cotes quadratures for the integral $I(f) = \int_a^b f(x) dx$ are based on the integration of the polynomial p(x) that interpolates f(x) at a set of pre-selected nodes in [a, b].
 - The weights of a Newton-Cotes are determined by $\omega_i = \int_a^b \ell_i(t) dt$.
 - It can be proved that (Theorem 9.2) the degree of precision for a Newton-Cotes formula of equally spaced nodes x_0, x_1, \dots, x_n is
 - n+1, if n is even (such as Simplson's rule). n, if n is odd (such as the trapezoidal rule).

• Gaussian quadratures adopt a different approach in which both the abscissas x_i and weights α_i are to be determined simultaneously so that the quadrature

$$Q_n(f) = \sum_{i=1}^n \alpha_i f(x_i)$$
 (10)

has a maximal degree of precision.

• Since there are 2n unknowns in (10), the requirements

$$E_n(x^k) = 0, k = 0, 1, \dots, 2n - 1$$
 (11)

supply 2n equations.

- It is expected that the maximal degree of precision is $\geq 2n 1$.
- To determine the Gaussian quadrature, one approach is through the orthogonal polynomials.

 Two functions f and g defined on [a, b] are said to be orthogonal if and only if

$$\langle f,g\rangle := \int_a^b f(t)g(t)dt = 0.$$
 (12)

- The operation $\langle f, g \rangle$ may be regarded as an inner product of f and g.
- A sequence $\{p_i(t)\}_{i=0}^{\infty}$ of polynomials with $\deg(p_i) = i$ is called a sequence of orthogonal polynomials on [a, b] if

$$\int_a^b p_i(t)p_j(t)dt = 0, \text{ whenever } i \neq j.$$

- The orthogonality is not affected by scalar multiplication. We may assume that all $p_i(t)$ are monic, i.e., the leading coefficients of all $p_i(t)$ are one.
- Any n-th degree polynomial q(t) can uniquely be written as

$$q(t) = b_n p_n(t) + b_{n-1} p_{n-1}(t) + \ldots + b_0 p_0(t).$$

That is, the orthogonal polynomials of degree $\leq n$ span the entire space of polynomials of degree $\leq n$.

- The following process constructs orthogonal polynomials over an arbitrary [a, b]:
 - $p_0(t) = 1$.
 - $p_1(t) = t a_1$, but

$$0=\langle p_0,p_1\rangle \Longrightarrow a_1=\frac{b+a}{2}.$$

• Suppose $p_0(t), \dots p_n(t)$ has been constructed. We seek $p_{n+1}(t)$ in the form

$$p_{n+1}(t) = (t - a_{n+1})p_n(t) + b_{n+1}p_{n-1}(t) + c_{n+1}p_{n-2}(t) + \dots$$

a_{n+1} can be determined from

$$0 = \langle p_{n+1}, p_n \rangle \Longrightarrow a_{n+1} = \frac{\langle t, p_n^2 \rangle}{\langle p_n, p_n \rangle}.$$

• b_{n+1} can be determined from

$$0 = \langle p_{n+1}, p_{n-1} \rangle \Longrightarrow b_{n+1} = -\frac{\langle t, p_n p_{n-1} \rangle}{\langle p_{n-1}, p_{n-1} \rangle}.$$

• c_{n+1} can be determined from

$$0 = \langle p_{n+1}, p_{n-2}
angle \Longrightarrow c_{n+1} = -rac{\langle t, p_n p_{n-2}
angle}{\langle p_{n-2}, p_{n-2}
angle}.$$

But, surprisingly, the numerator $\langle t, p_n p_{n-2} \rangle = \langle p_{n-1}, p_n \rangle = 0$. (Why?)

• We therefore conclude that $p_{n+1}(t)$ can be generated by a three-term recurrence formula:

$$p_{n+1}(t) = (t - a_{n+1})p_n(t) + b_{n+1}p_{n-1}(t).$$
(13)

• If [a, b] = [-1, 1], such a sequence of orthogonal polynomials are called the Legendre polynomials.

We are interested in deriving quadratures with higher degrees of precision. Toward this end, observe the following two facts:

Theorem

A quadrature formula using n+1 distinct abscissas has degree of precision $\geq n$ if and only if it results from the integration of an interpolation polynomial.

Proof.

 (\longleftarrow)

• This follows from Theorem 8.3.1 of Chu's note for MA780.

 (\Longrightarrow)

- Suppose the quadrature rule is $Q_n(f) = \sum_{i=0}^n \alpha_i f(x_i)$.
- Following from the assumption, we have $\sum_{i=0}^{n} \alpha_i x_i^k = \frac{b^{k+1} a^{k+1}}{k+1}$ for $k = 0, \dots, n$.

We may rewrite this system of equations as

$$\begin{bmatrix} 1 & \dots & 1 \\ x_0 & \dots & x_n \\ \vdots & & & \\ x_0^n & \dots & x_n^n \end{bmatrix} \begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = \begin{bmatrix} b-a \\ \frac{b^2-a^2}{2} \\ \vdots \\ \frac{b^{n+1}-a^{n+1}}{n+1} \end{bmatrix}. \tag{14}$$

The coefficient matrix is the Vandermonde matrix. Thus the system (14) has a unique solution for α_i , i = 0, ..., n.

- On the other hand, we can construct an interpolating polynomial of degree n using the same nodes $\{x_i\}_{i=0}^n$.
- This polynomial results in a quadrature formula $\sum_{i=0}^{n} \beta_i f(x_i)$ which has degree of precision at least n. (Why?)
- By setting $E_n(x^k) = 0$ for k = 0, ..., n in the new quadrature, we end up with the same linear system (14).
- By uniqueness, it must be that $\alpha_i = \beta_i$.

Since the Gaussian quadrature is expected to have degree of precision higher than n, we conclude that

- It may be thought of as the integration of a certain polynomial that interpolates f(x) at a certain set of nodes x_0, \ldots, x_n .
- It must remain true that

$$E_{n+1}(f) = \int_{a}^{b} f[x_0, \dots, x_n, t] \prod_{i=0}^{n} (t - x_i) dt.$$
 (15)

• Not only $E_{n+1}(x^k) = 0$ for k = 0, ..., n, but we further would like to require $E_{n+1}(x^k) = 0$ for $k = n+1, ..., n+\nu$, and for ν as large as possible.

Theorem

If $f(t) = t^{(n+1)+\nu}$, $\nu \ge 0$, then the (n+1)-th divided difference $f[x_0, \dots, x_n, t]$ is a polynomial of degree at most ν .

Proof.

- When n=0, we find $f[x_0,t]=\frac{f(x_0)-f(t)}{x_0-t}=\frac{x_0^{1+\nu}-t^{1+\nu}}{x_0-t}$ is obviously a polynomial of degree ν .
- Suppose the assertion is true for n = k. Consider $f(t) = t^{[(k+1)+1]+\nu}$. (We are preparing to use the Induction Principle on n.)
- Regard $f(t) = t^{(k+1)+(1+\nu)}$. Then, by induction hypothesis, the difference quotient $f[x_1, \ldots, x_{k+1}, t]$ is a polynomial of degree at most $\nu + 1$.
- Observe that

$$f[x_0,\ldots,x_{k+1},t]=\frac{f[x_0,\ldots,x_{k+1}]-f[x_1,\ldots,x_{k+1},t]}{x_0-t}.$$

Note that the numerator has a zero at $t = x_0$. After cancelation, $f[x_0, \ldots, x_{k+1}, t]$ is a polynomial of degree of most ν .

The assertion now follows from the induction.

- Recall that
 - The Gaussian quadrature is a special type of Newton-Cotes quadrature.
 - The error in the quadrature is given by

$$E_{n+1}(f) = \int_a^b f[x_0, \ldots, x_n, t] \prod_{i=0}^n (t - x_i) dt.$$

- The divided difference $f[x_0, \ldots, x_n, t]$ is a polynomial of degree at most ν if $f(t) = t^{(n+1)+\nu}$.
- If we can choose the nodes x_i so that $\omega(t) = \prod_{i=0}^n (t-x_i)$ is the (n+1)-th orthogonal polynomials, then the error $E(t^{(n+1)+\nu}) = 0$ for all $\nu = 0, 1, \dots, n$.

- Need to make sure all roots of the n-th orthogonal polynomial are real-valued, distinct, and contained in (a, b).
 - Let $x_0 \ldots, x_m \in (a, b)$ denote all the distinct, real zeros of $\omega_n(x)$ with odd multiplicity.
 - Assume m < n. We want to prove by contradiction.
 - Consider the integral $\int_a^b (x-x_0) \dots (x-x_m) \omega_n(x) dx$. Note that the integrand does not change sign over [a,b] and is not identically zero. Thus the integral is positive.
 - But $(x x_0) \dots (x x_m)$ is a polynomial of degree m < n.
 - By orthogonality of $\omega_n(x)$, the integral should be zero. This is a contradiction.
 - It must be that m = n, and the multiplicity is 1.

• Gaussian abscissas and weights over the interval [-1, 1].

n	Abscissas x _j	Weights α_j
1	$\pm 1/\sqrt{3}$	1
2	$\pm\sqrt{0.6}$	5/9
	0	8/9
3	±0.8611363116	0.3478548451
	± 0.3399810436	0.6521451549
4	±0.9061798459	0.2369268850
	± 0.5384693101	0.4786286705
	0	0.5688888889
5	±0.9324695142	0.1713244924
	±0.6612093865	0.3607615730
	± 0.2386191861	0.4679139346

- To integrate f(x) over an arbitrary interval [a, b],
 - Change of variables:

$$x = a + \frac{b-a}{2}(\xi+1), dx = \frac{b-a}{2}d\xi.$$

Substitution:

$$\int_{a}^{b} f(x)dx = \int_{-1}^{1} f(a + \frac{b - a}{2}(\xi + 1)) \frac{b - a}{2} d\xi$$

$$= \frac{b - a}{2} \int_{-1}^{1} f(a + \frac{b - a}{2}(\xi + 1)) d\xi$$

$$\approx \frac{b - a}{2} \sum_{i=1}^{n} \alpha_{i} f(x_{i})$$

- α_j are the tabulated Gaussian weights associated with the tabulated Gaussian abscissa ξ_j in [-1, 1].
- x_j is obtained from ξ_j through $x_j = a + \frac{b-a}{2}(\xi_j + 1), \ j = 0, \dots, n$.