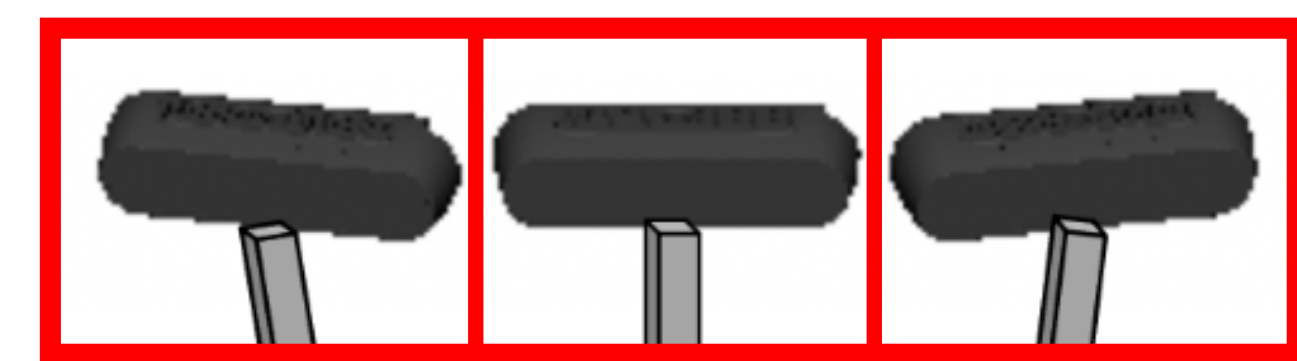


Cameras

Right Center Left

RGB Image



Training

Deep
Learning

2D LiDAR

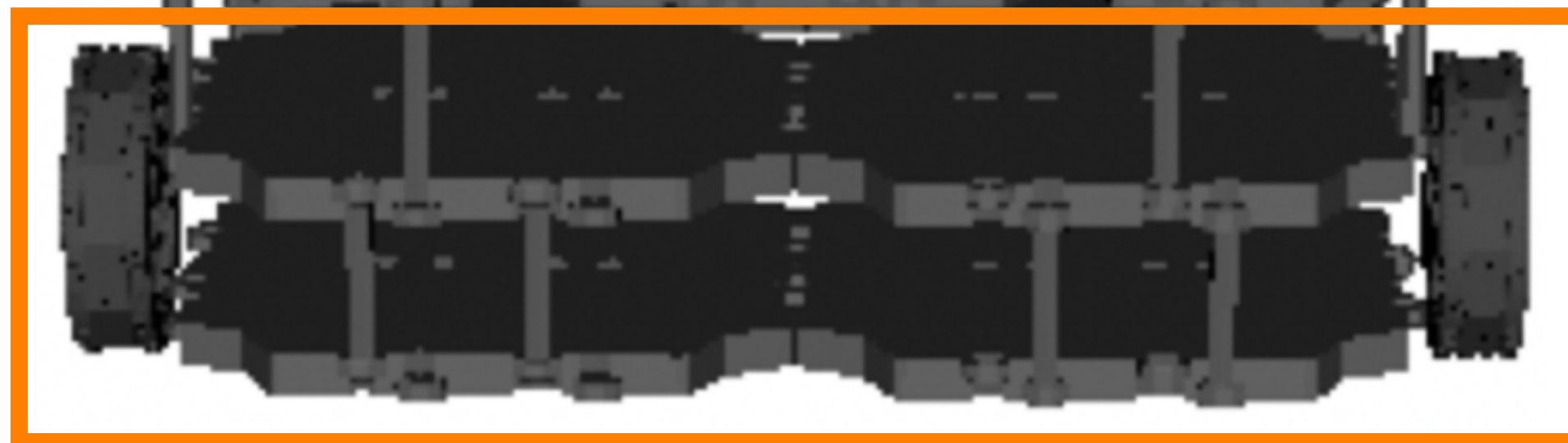
Scan



Odometry

Map-Based
Controller

Target Angular
Velocity



Wheel Encoder

Motor

