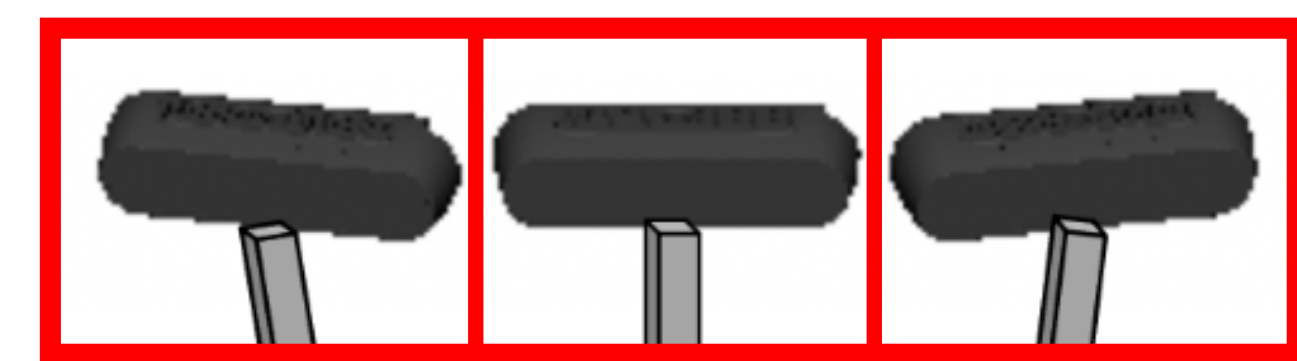


# Cameras

Right Center Left

RGB Image



Training

Deep Learning

2D LiDAR



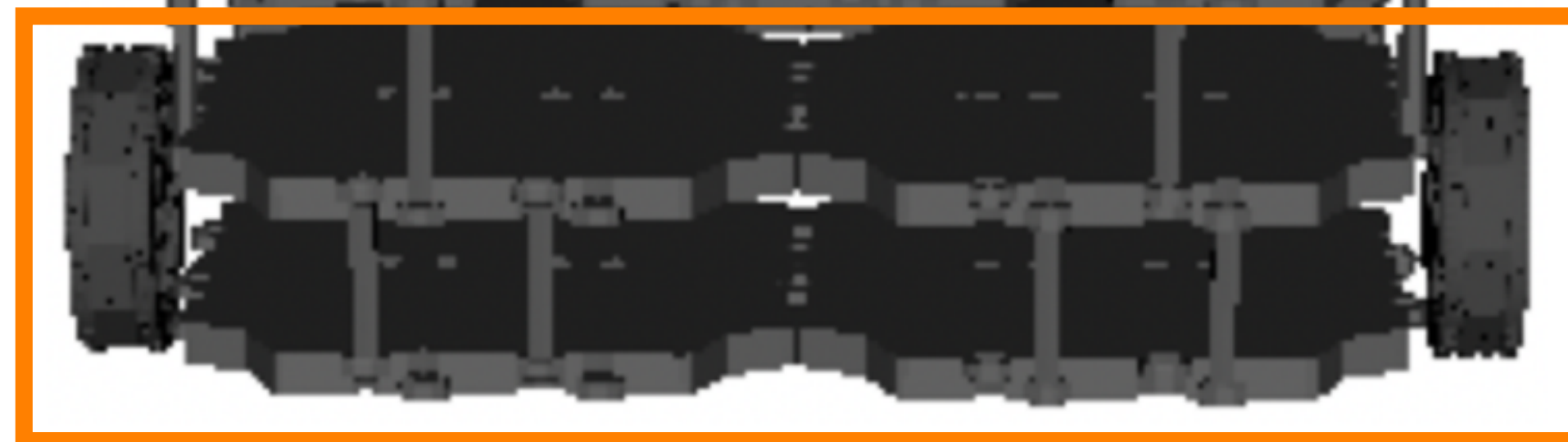
Scan

Target Direction

Map-Based Controller

Target Angular Velocity

Odometry



Wheel Encoder Motor