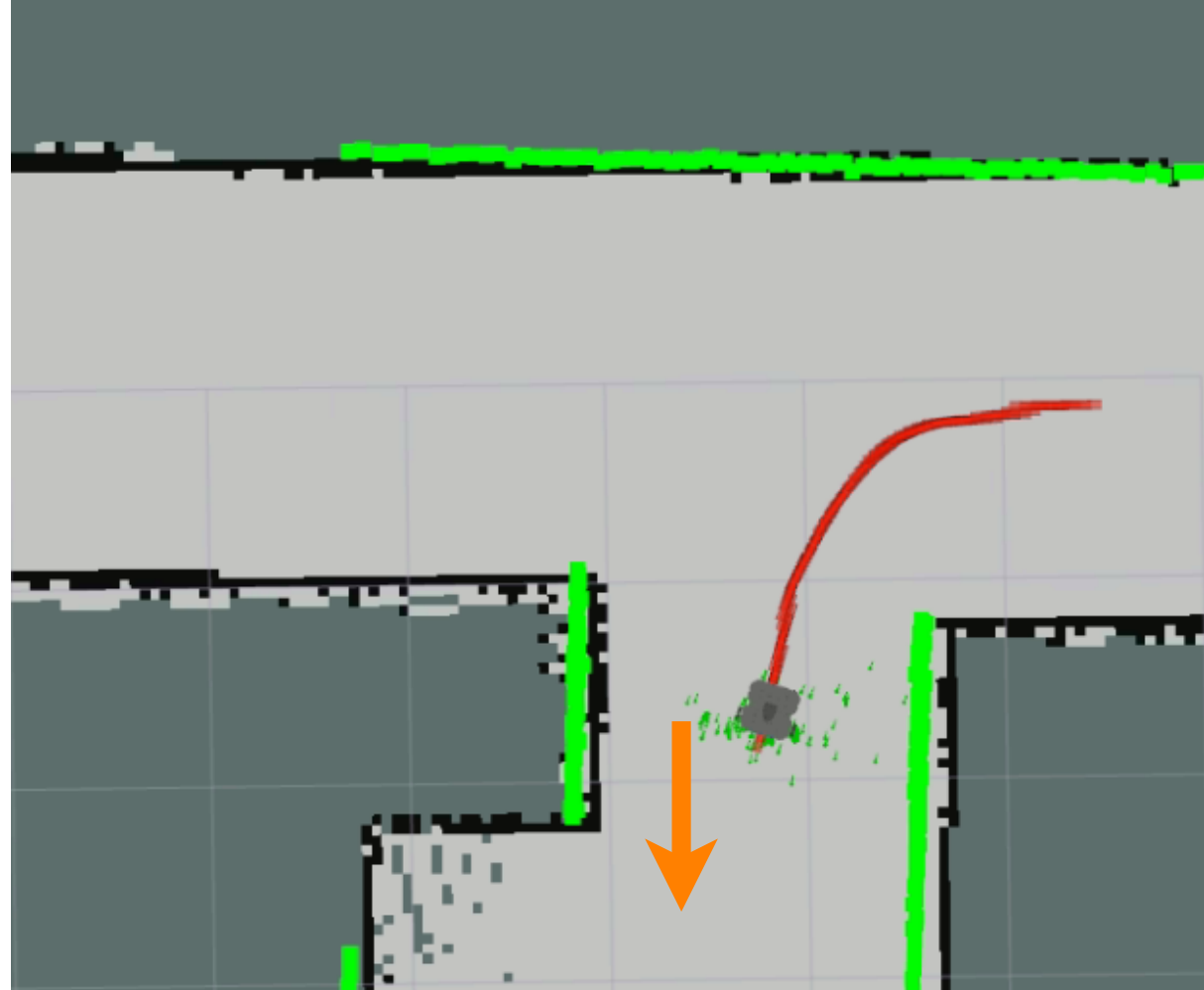




**Goal a1**



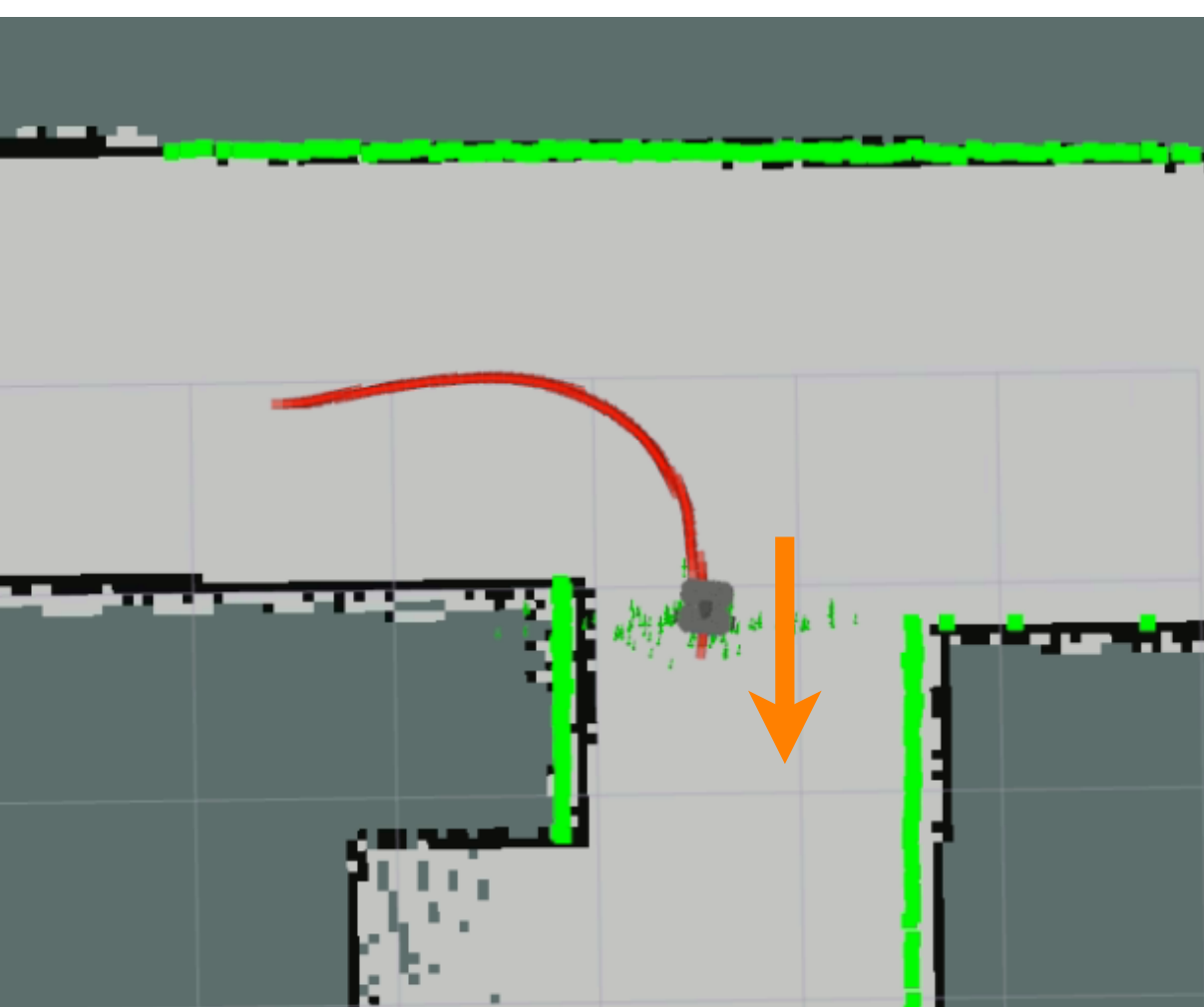
**Goal b1**



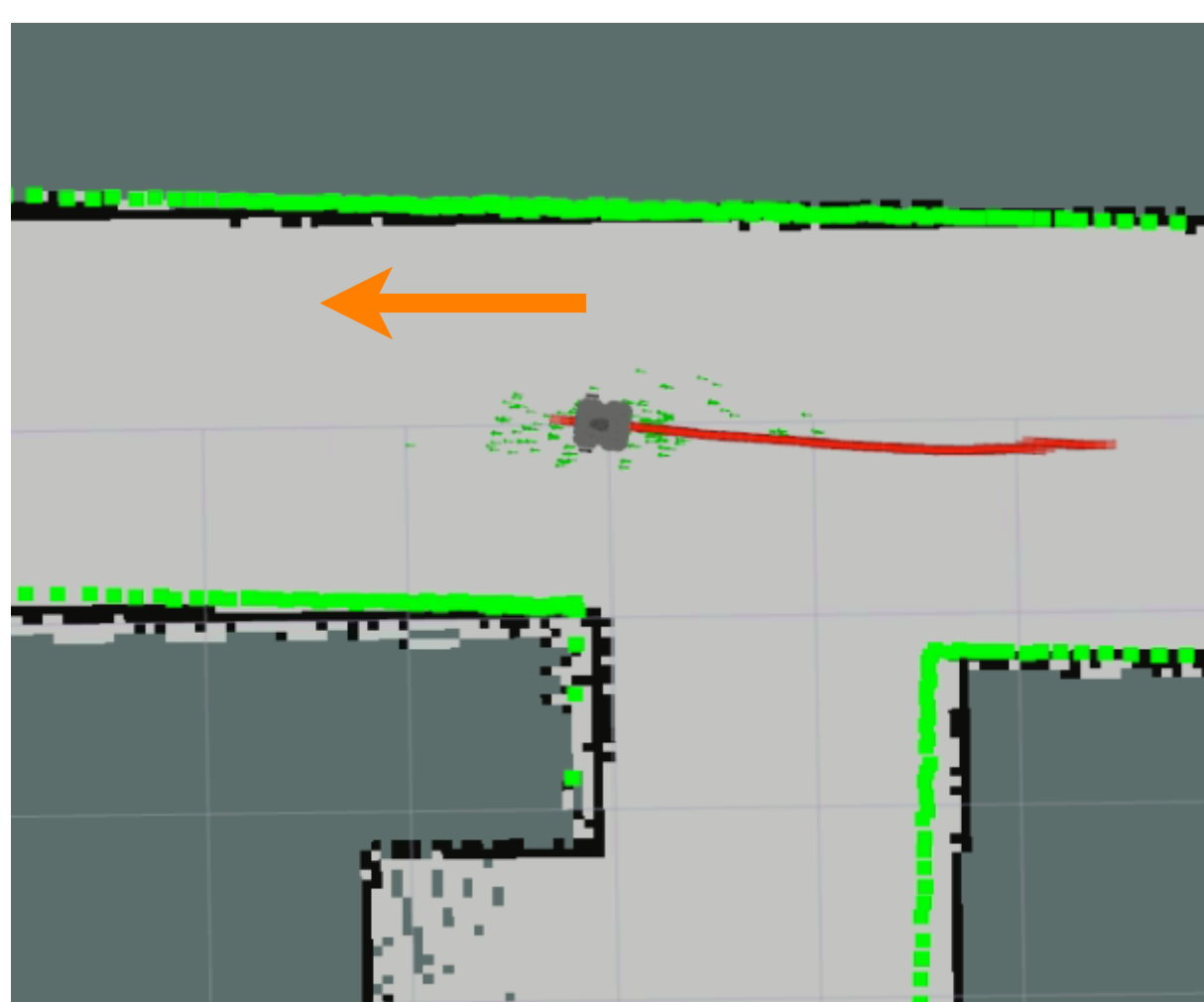
**Goal c1**





**Goal d1**



**Goal e1**



**Goal f1**

 :Direction of the robot's movement  
 :Trajectory of the robot