

# Chapter 5

## Network Layer: Control Plane

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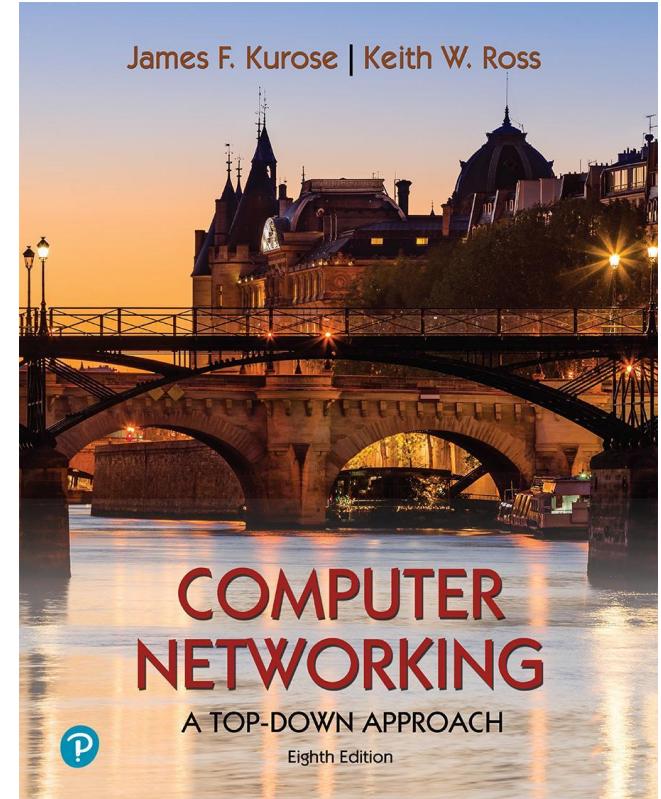
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*Computer Networking: A  
Top-Down Approach*  
8<sup>th</sup> edition  
Jim Kurose, Keith Ross  
Pearson, 2020

# Network layer control plane: our goals

- understand principles behind network control plane:
  - traditional routing algorithms
  - SDN controllers
  - network management, configuration
- instantiation, implementation in the Internet:
  - OSPF, BGP
  - OpenFlow, ODL and ONOS controllers
  - Internet Control Message Protocol: ICMP
  - SNMP, YANG/NETCONF

# Network layer: “control plane” roadmap

- introduction
- routing protocols
  - link state
  - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
  - SNMP
  - NETCONF/YANG

# Network-layer functions

- **forwarding:** move packets from router's input to appropriate router output
- **routing:** determine route taken by packets from source to destination

*data plane*

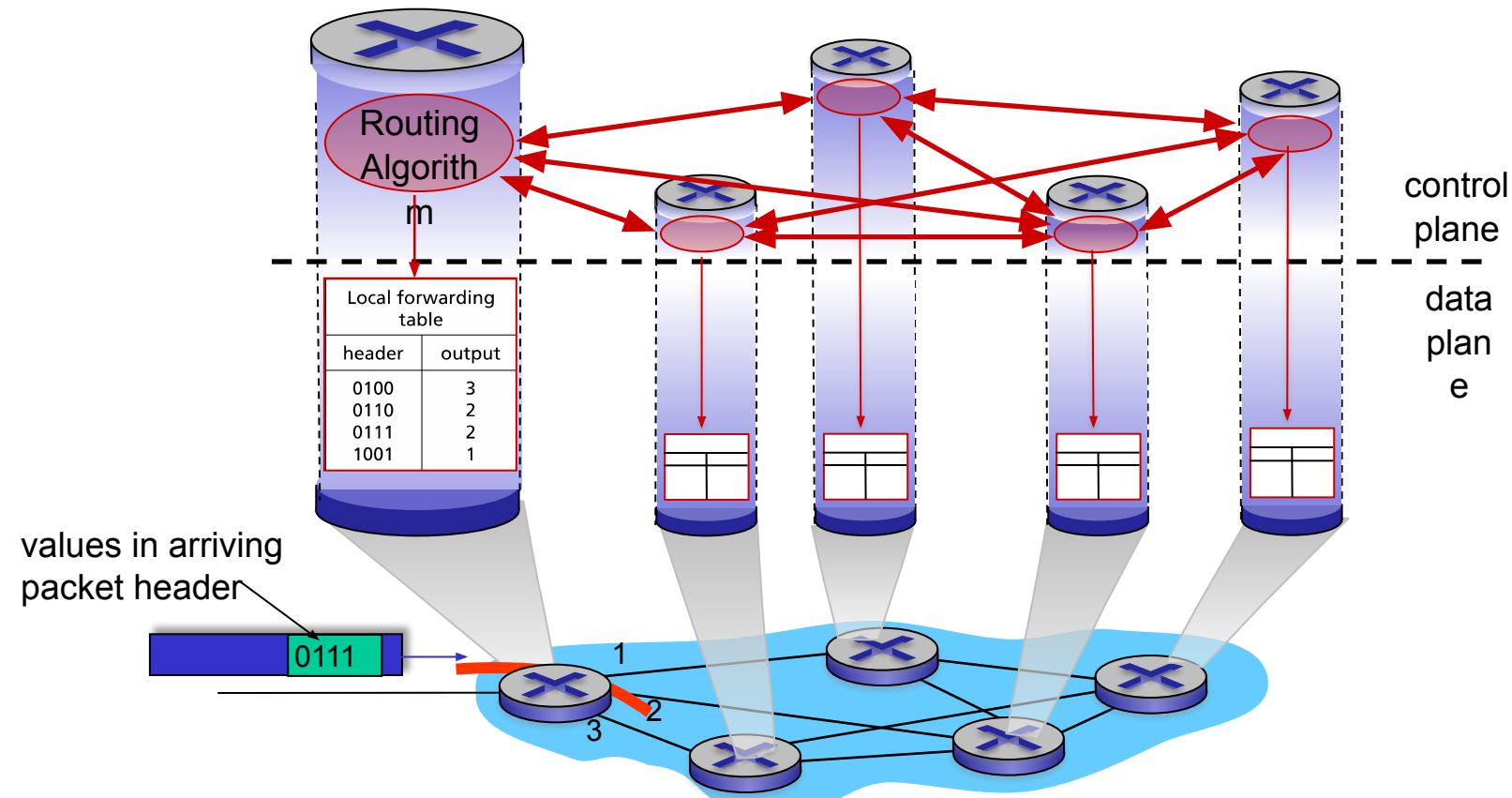
*control plane*

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

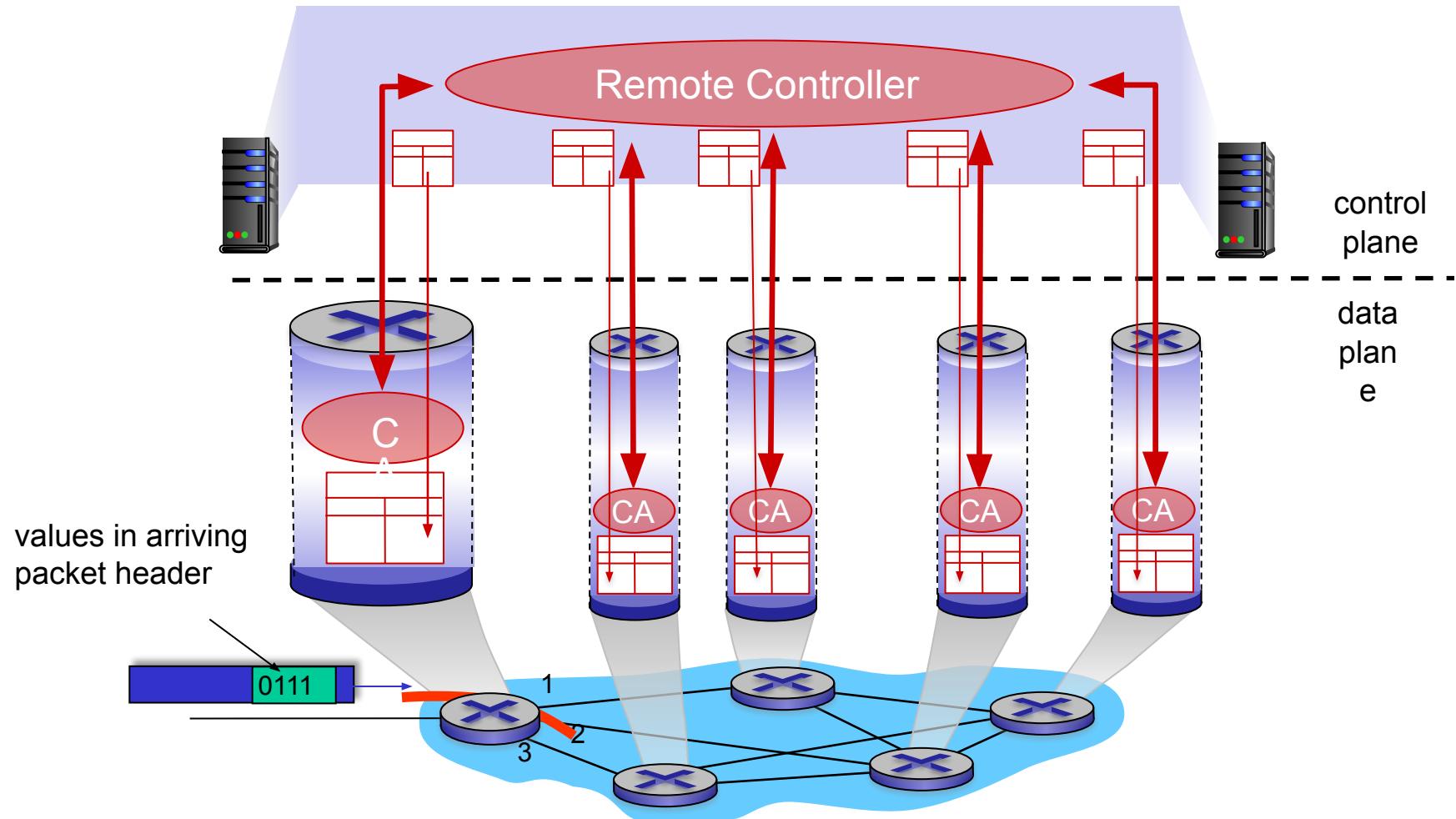
# Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane



# Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



# Network layer: “control plane” roadmap

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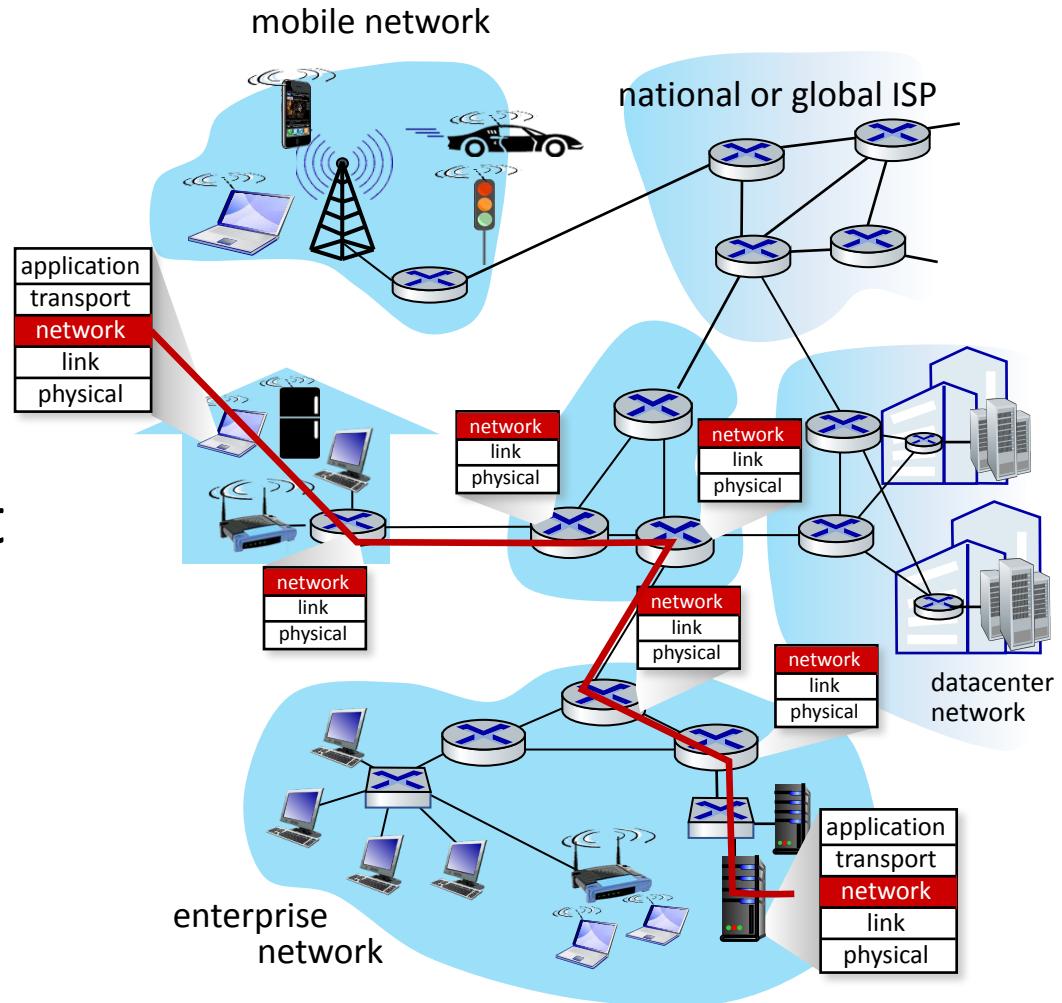


- network management, configuration
  - SNMP
  - NETCONF/YANG

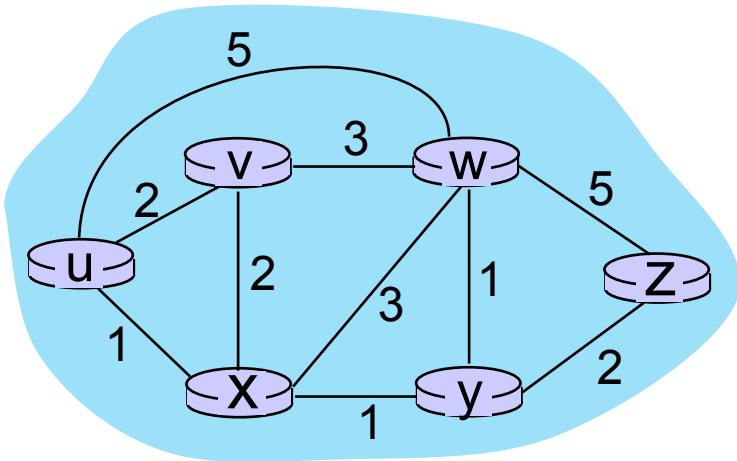
# Routing protocols

**Routing protocol goal:** determine “good” paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- **path:** sequence of routers packets traverse from given initial source host to final destination host
- **“good”:** least “cost”, “fastest”, “least congested”
- **routing:** a “top-10” networking challenge!



# Graph abstraction: link costs



graph:  $G = (N, E)$

$N$ : set of routers = {  $u, v, w, x, y, z$  }

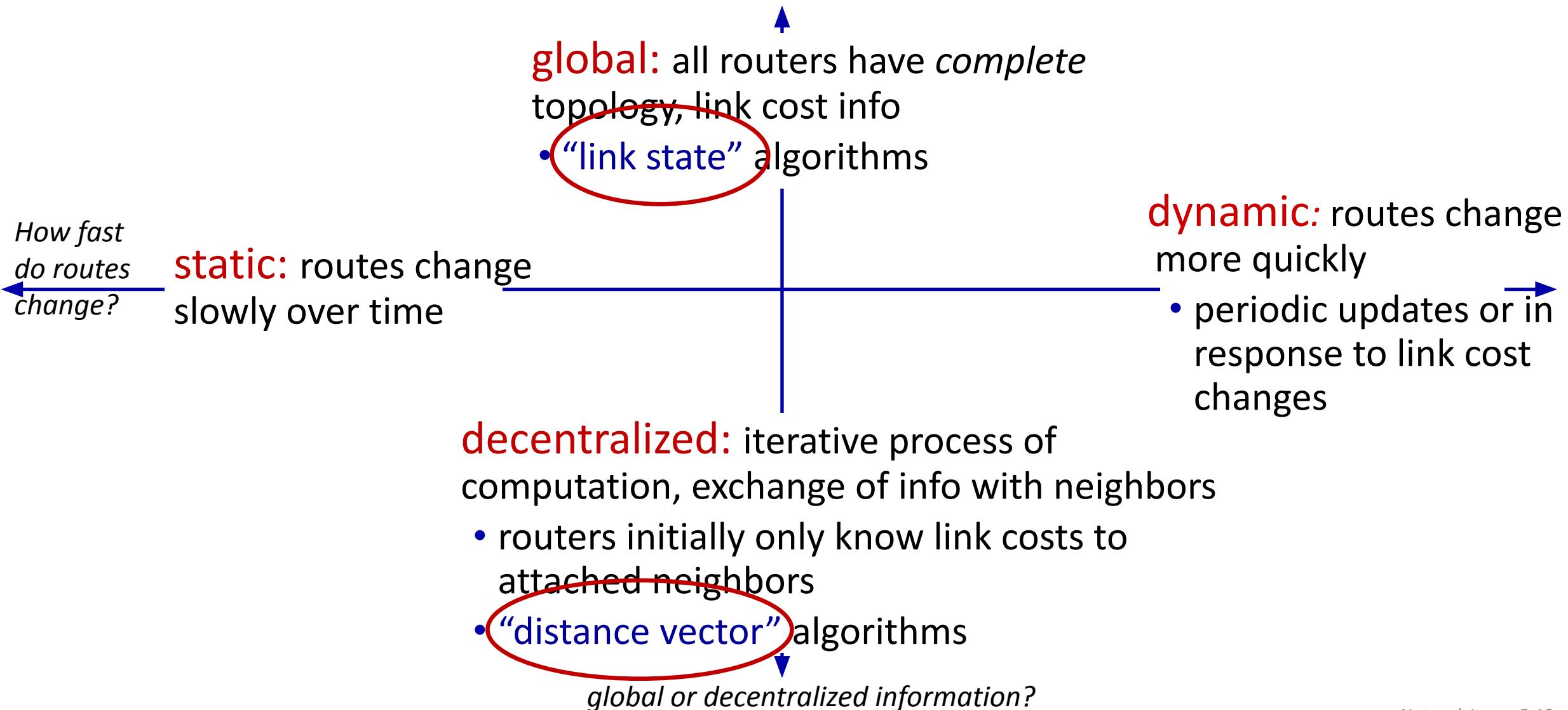
$E$ : set of links = {  $(u, v), (u, x), (v, x), (v, w), (x, w), (x, y), (w, y), (w, z), (y, z)$  }

$c_{a,b}$ : cost of *direct* link connecting  $a$  and  $b$

e.g.,  $c_{w,z} = 5, c_{u,z} = \infty$

cost defined by network operator:  
could always be 1, or inversely related  
to bandwidth, or inversely related to  
congestion

# Routing algorithm classification



# Network layer: “control plane” roadmap

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# Dijkstra's link-state routing algorithm

- **centralized:** network topology, link costs known to *all* nodes
  - accomplished via “link state broadcast”
  - all nodes have same info
- computes least cost paths from one node (“source”) to all other nodes
  - gives *forwarding table* for that node
- **iterative:** after  $k$  iterations, know least cost path to  $k$  destinations

## notation

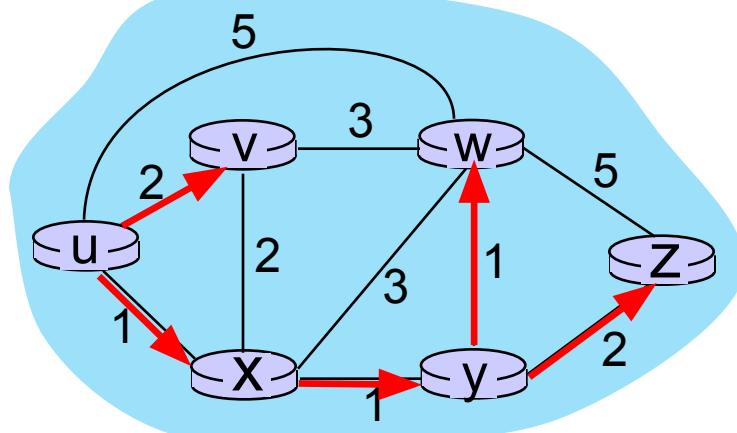
- $c_{x,y}$ : direct link cost from node  $x$  to  $y$ ;  $= \infty$  if not direct neighbors
- $D(v)$ : *current estimate* of cost of least-cost-path from source to destination  $v$
- $p(v)$ : predecessor node along path from source to  $v$
- $N'$ : set of nodes whose least-cost-path *definitively* known

# Dijkstra's link-state routing algorithm

```
1 Initialization:
2    $N' = \{u\}$                                 /* compute least cost path from u to all other nodes */
3   for all nodes  $v$ 
4     if  $v$  adjacent to  $u$                       /*  $u$  initially knows direct-path-cost only to direct neighbors */
5       then  $D(v) = c_{u,v}$                       /* but may not be minimum cost!
6     else  $D(v) = \infty$ 
7
8 Loop
9   find  $w$  not in  $N'$  such that  $D(w)$  is a minimum
10  add  $w$  to  $N'$ 
11  update  $D(v)$  for all  $v$  adjacent to  $w$  and not in  $N'$  :
12     $D(v) = \min(D(v), D(w) + c_{w,v})$ 
13  /* new least-path-cost to  $v$  is either old least-cost-path to  $v$  or known
14  least-cost-path to  $w$  plus direct-cost from  $w$  to  $v$  */
15 until all nodes in  $N'$ 
```

# Dijkstra's algorithm: an example

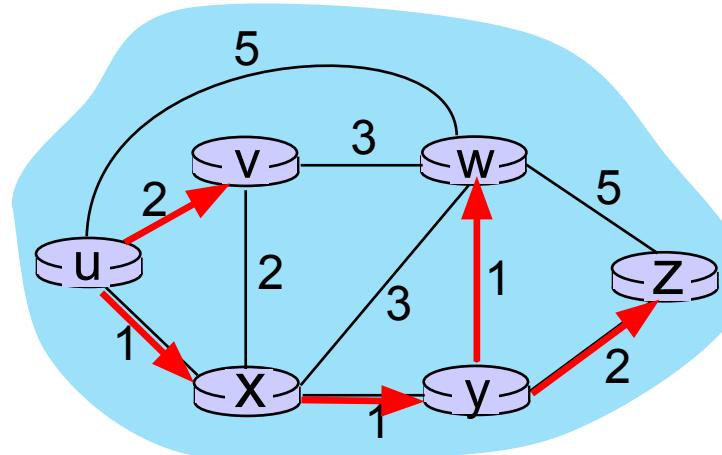
Step	$N'$	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	$\infty$	$\infty$
1	u, x	2, u	4, x	2, x	$\infty$	$\infty$
2	u, x, y	2, u	3, y		4, y	
3	u, x, y, v		3, y		4, y	
4	u, x, y, v, w					4, y
5	u, x, y, v, w, z					



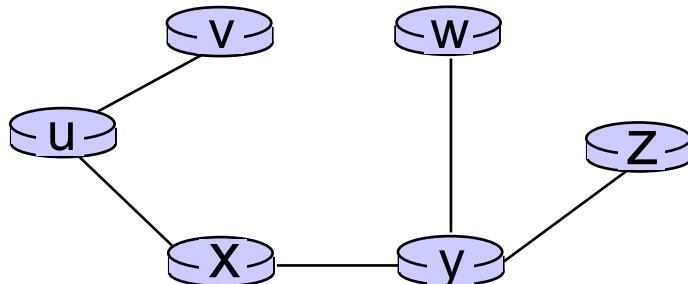
Initialization (step 0): For all  $a$ : if  $a$  adjacent to  $u$  then  $D(a) = c_{u,a}$

find  $a$  not in  $N'$  such that  $D(a)$  is a minimum  
add  $a$  to  $N'$   
update  $D(b)$  for all  $b$  adjacent to  $a$  and not in  $N'$ :  
$$D(b) = \min ( D(b), D(a) + c_{a,b} )$$

# Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



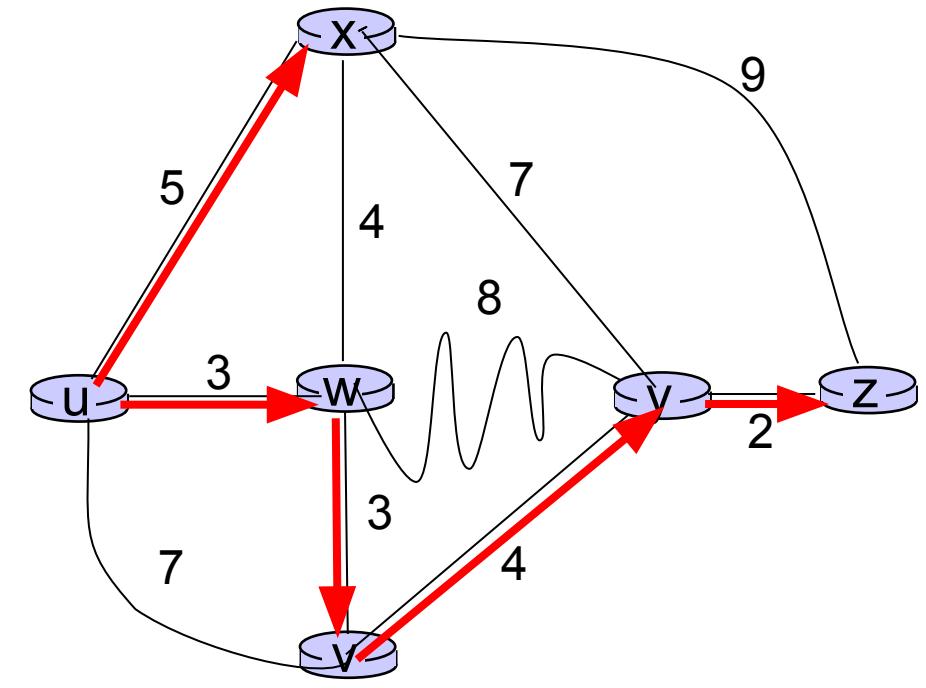
resulting forwarding table in u:

destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

route from  $u$  to  $v$  directly  
route from  $u$  to all other destinations via  $x$

# Dijkstra's algorithm: another example

Step	$N'$	$v$	$w$	$x$	$y$	$z$
0	$u$	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
1	$uw$	$7, u$	$3, u$	$5, u$	$\infty$	$\infty$
2	$uwx$	$6, w$	$5, u$	$11, w$	$\infty$	
3	$uwxv$			$11, w$	$14, x$	
4	$uwxy$			$10, v$	$14, x$	
5	$uwxyz$				$12, y$	



notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

# Dijkstra's algorithm: discussion

## algorithm complexity: $n$ nodes

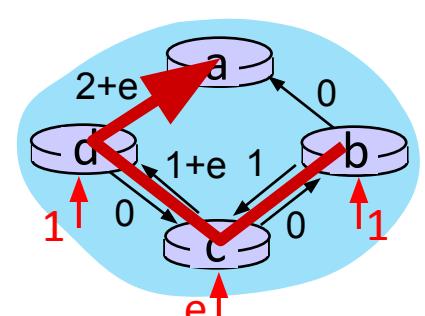
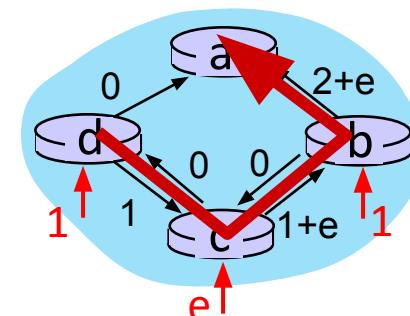
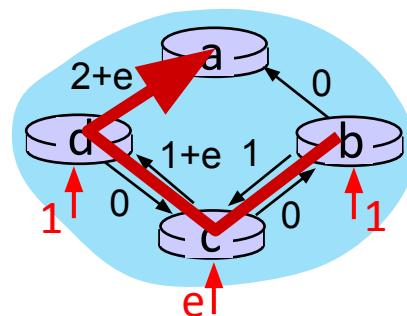
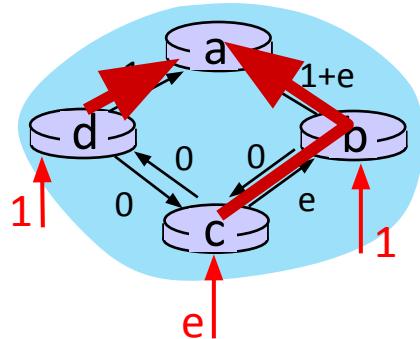
- each of  $n$  iteration: need to check all nodes,  $w$ , not in  $N$
- $n(n+1)/2$  comparisons:  $O(n^2)$  complexity
- more efficient implementations possible:  $O(n \log n)$

## message complexity:

- each router must *broadcast* its link state information to other  $n$  routers
- efficient (and interesting!) broadcast algorithms:  $O(n)$  link crossings to disseminate a broadcast message from one source
- each router's message crosses  $O(n)$  links: overall message complexity:  $O(n^2)$

# Dijkstra's algorithm: oscillations possible

- when link costs depend on traffic volume, **route oscillations** possible
- sample scenario:
  - routing to destination a, traffic entering at d, c, e with rates 1, e ( $<1$ ), 1
  - link costs are directional, and volume-dependent



# Network layer: “control plane” roadmap

- introduction
- routing protocols
  - link state
  - **distance vector**
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
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- network management, configuration
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# Distance vector algorithm

Based on *Bellman-Ford* (BF) equation (dynamic programming):

Bellman-Ford equation

Let  $D_x(y)$ : cost of least-cost path from  $x$  to  $y$ .

Then:

$$D_x(y) = \min_v \{ c_{x,v} + D_v(y) \}$$

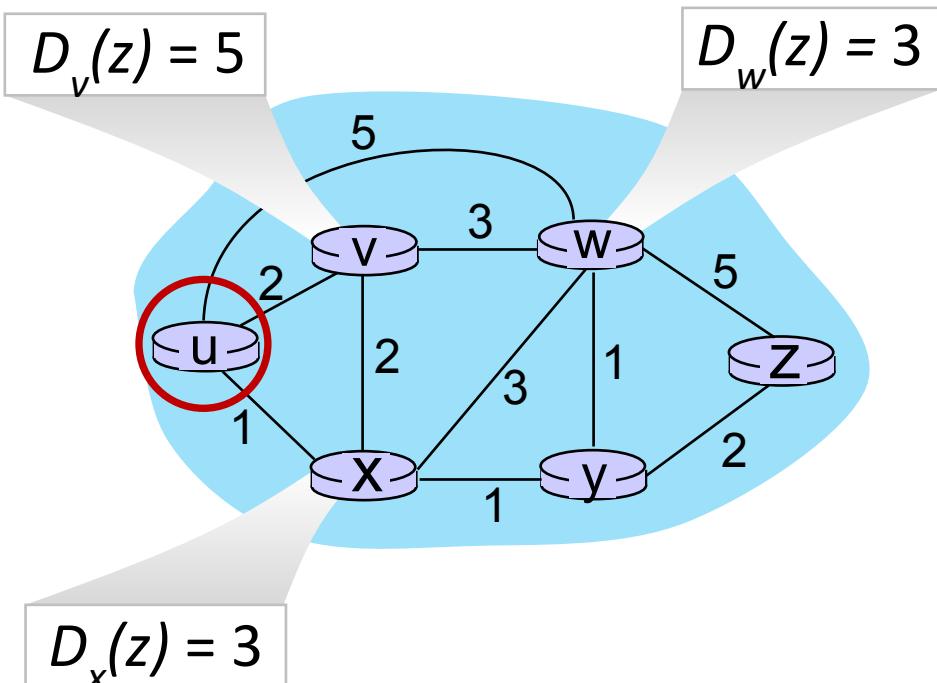
$\min$  taken over all neighbors  $v$  of  $x$

$v$ 's estimated least-cost-path cost to  $y$

direct cost of link from  $x$  to  $v$

# Bellman-Ford Example

Suppose that  $u$ 's neighboring nodes,  $x, v, w$ , know that for destination  $z$ :



Bellman-Ford equation says:

$$\begin{aligned} D_u(z) &= \min \{ c_{u,v} + D_v(z), \\ &\quad c_{u,x} + D_x(z), \\ &\quad c_{u,w} + D_w(z) \} \\ &= \min \{ 2 + 5, \\ &\quad 1 + 3, \\ &\quad 5 + 3 \} = 4 \end{aligned}$$

*node achieving minimum (x) is next hop on estimated least-cost path to destination (z)*

# Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when  $x$  receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v \{c_{x,v} + D_v(y)\} \text{ for each node } y \in N$$

- under minor, natural conditions, the estimate  $D_x(y)$  converge to the actual least cost  $d_x(y)$

# Distance vector algorithm:

each node:

*wait* for (change in local link cost or msg from neighbor)

*recompute* DV estimates using DV received from neighbor

if DV to any destination has changed, *notify* neighbors

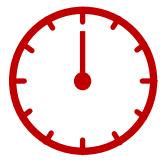
**iterative, asynchronous:** each local iteration caused by:

- local link cost change
- DV update message from neighbor

**distributed, self-stopping:** each node notifies neighbors *only* when its DV changes

- neighbors then notify their neighbors – *only if necessary*
- no notification received, no actions taken!

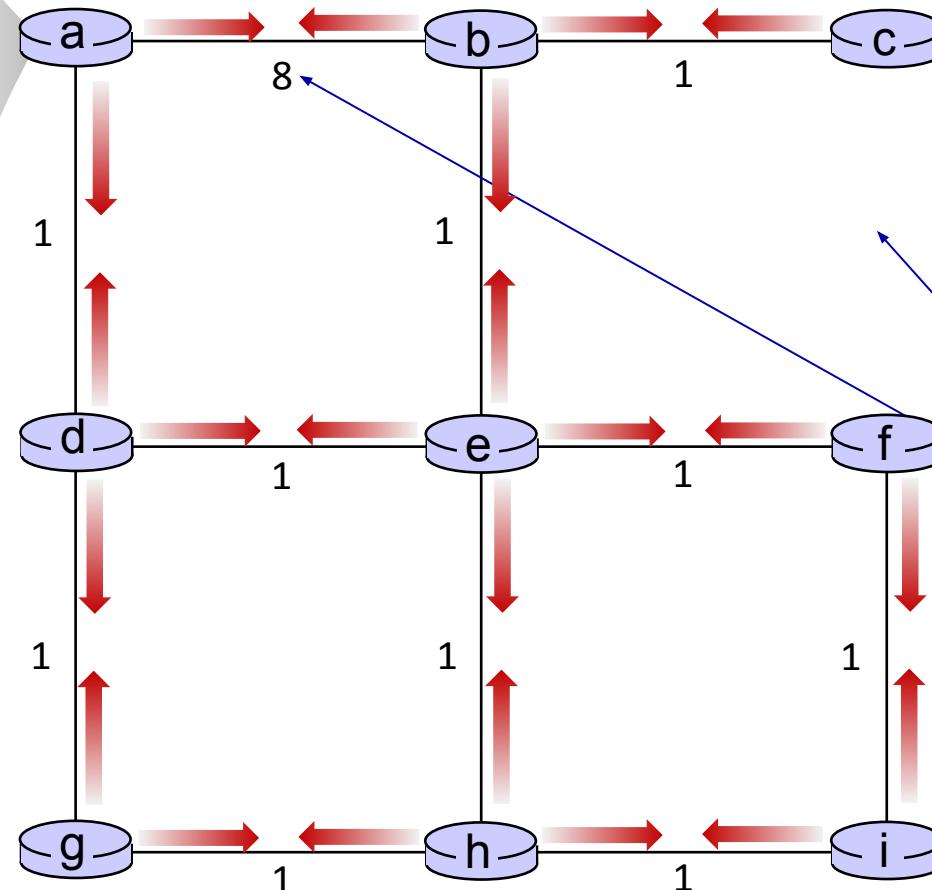
# Distance vector: example



$t=0$

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors

DV in a:
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$



- A few asymmetries:
- missing link
  - larger cost

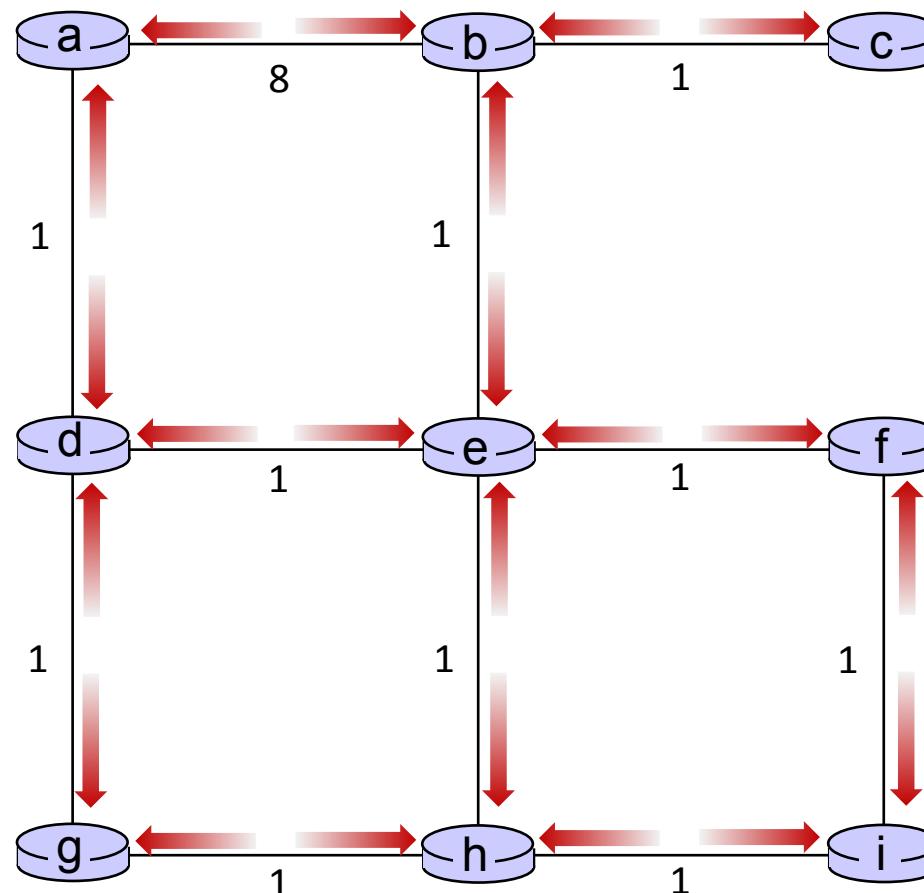
# Distance vector example: iteration



$t=1$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



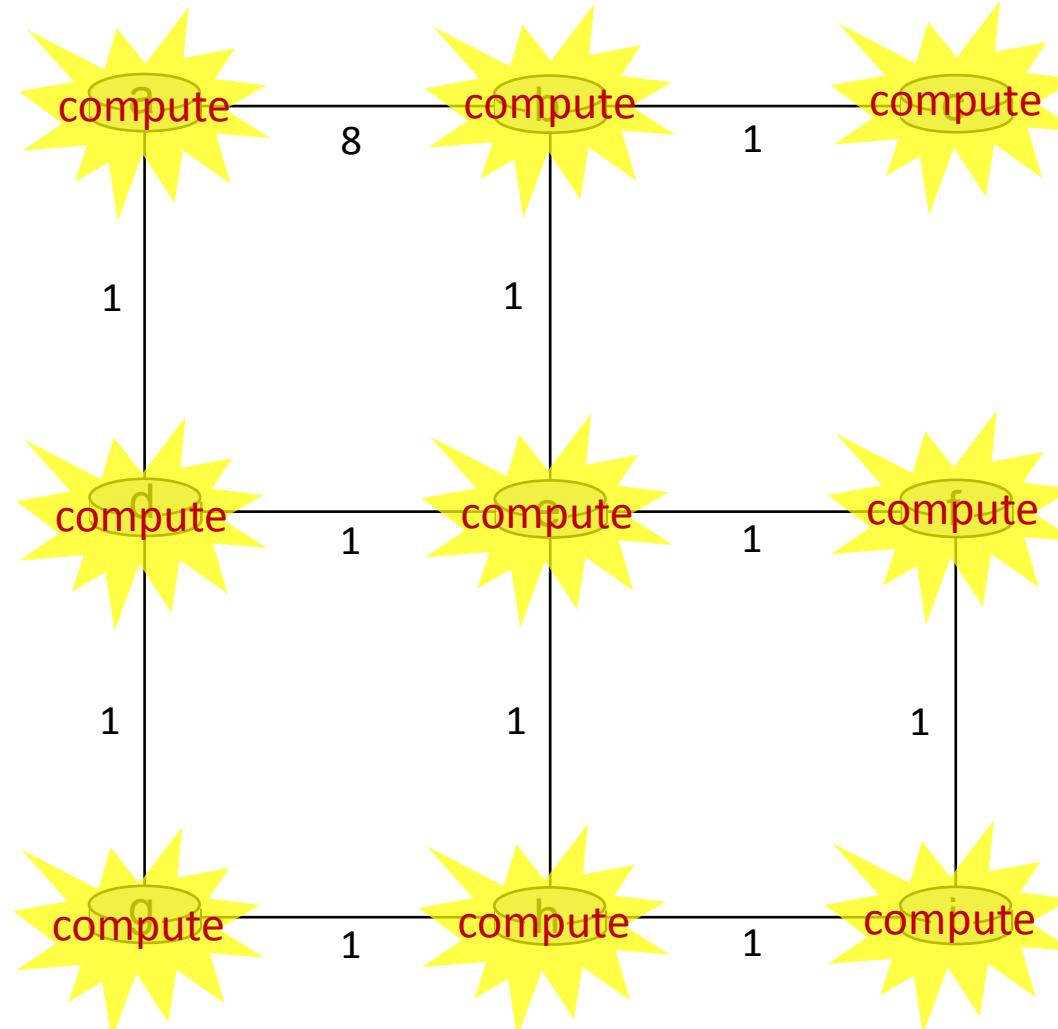
# Distance vector example: iteration



$t=1$

All nodes:

- receive distance vectors from neighbors
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- send their new local distance vector to neighbors



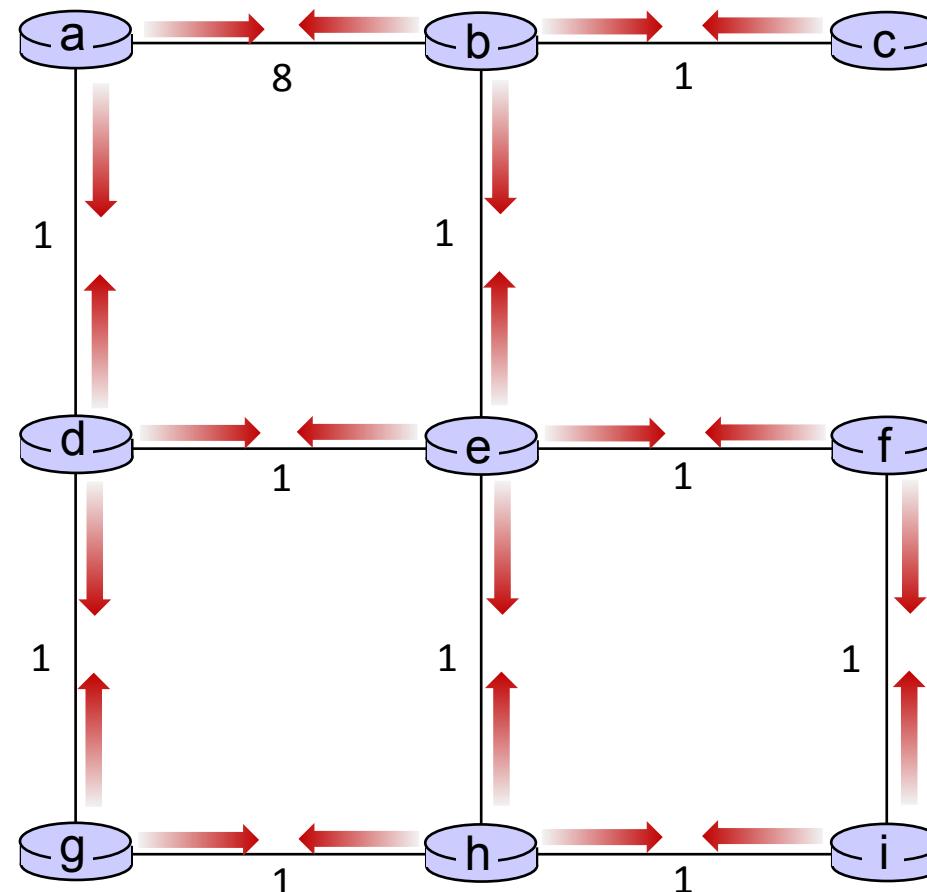
# Distance vector example: iteration



$t=1$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



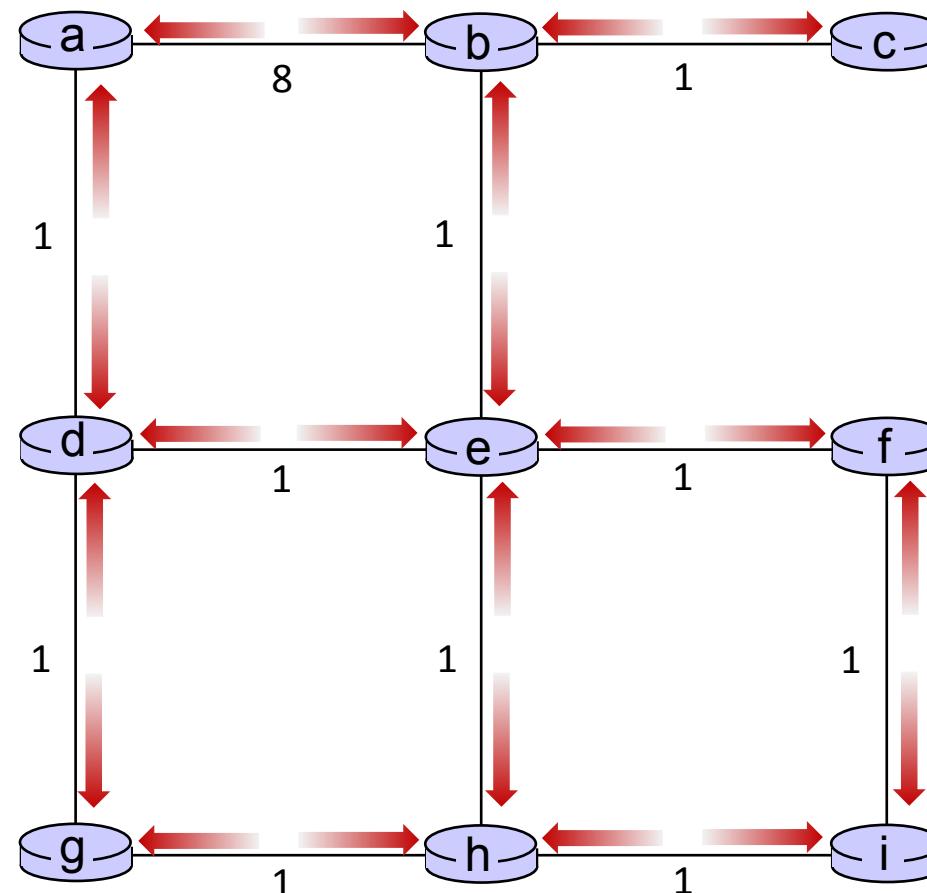
# Distance vector example: iteration



$t=2$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



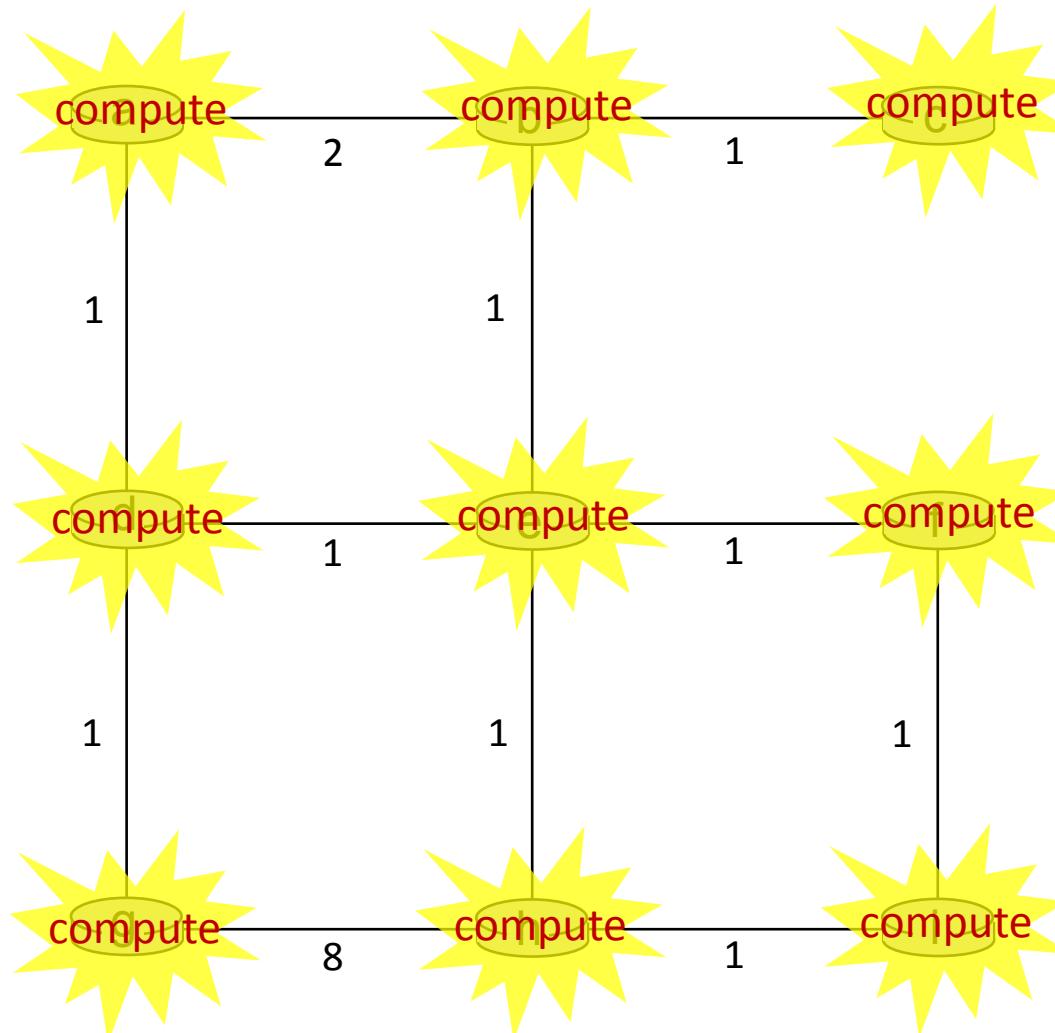
# Distance vector example: iteration



$t=2$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



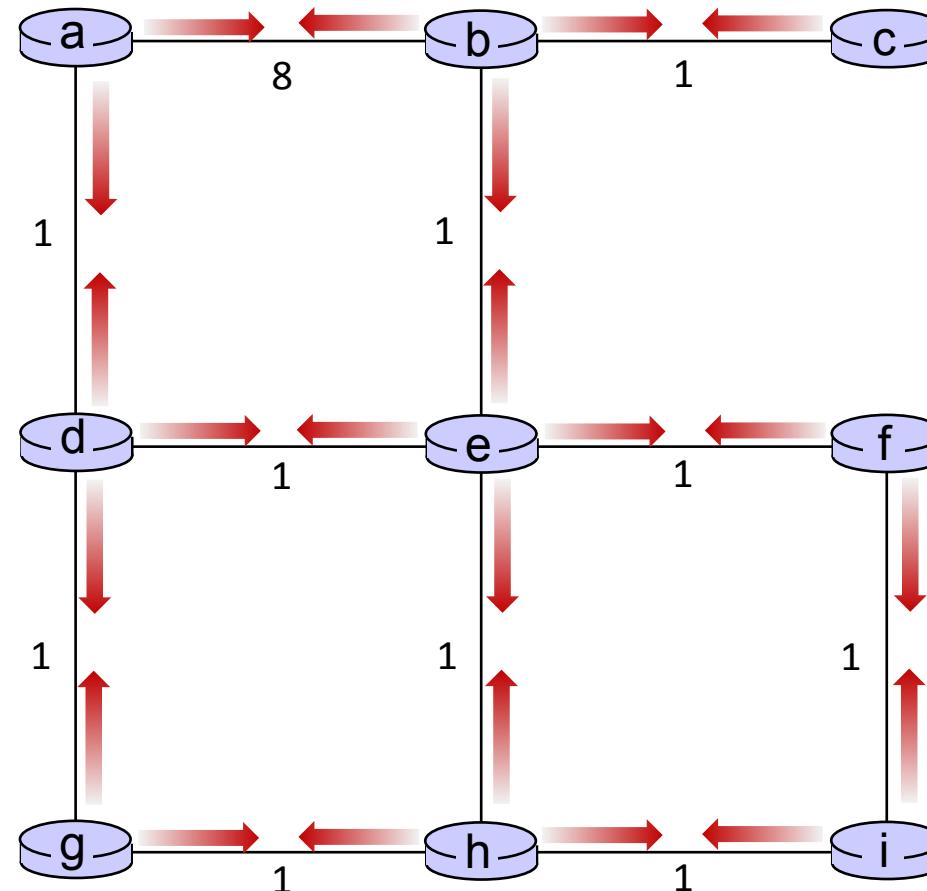
# Distance vector example: iteration



$t=2$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



# Distance vector example: iteration

.... and so on

Let's next take a look at the iterative *computations* at nodes

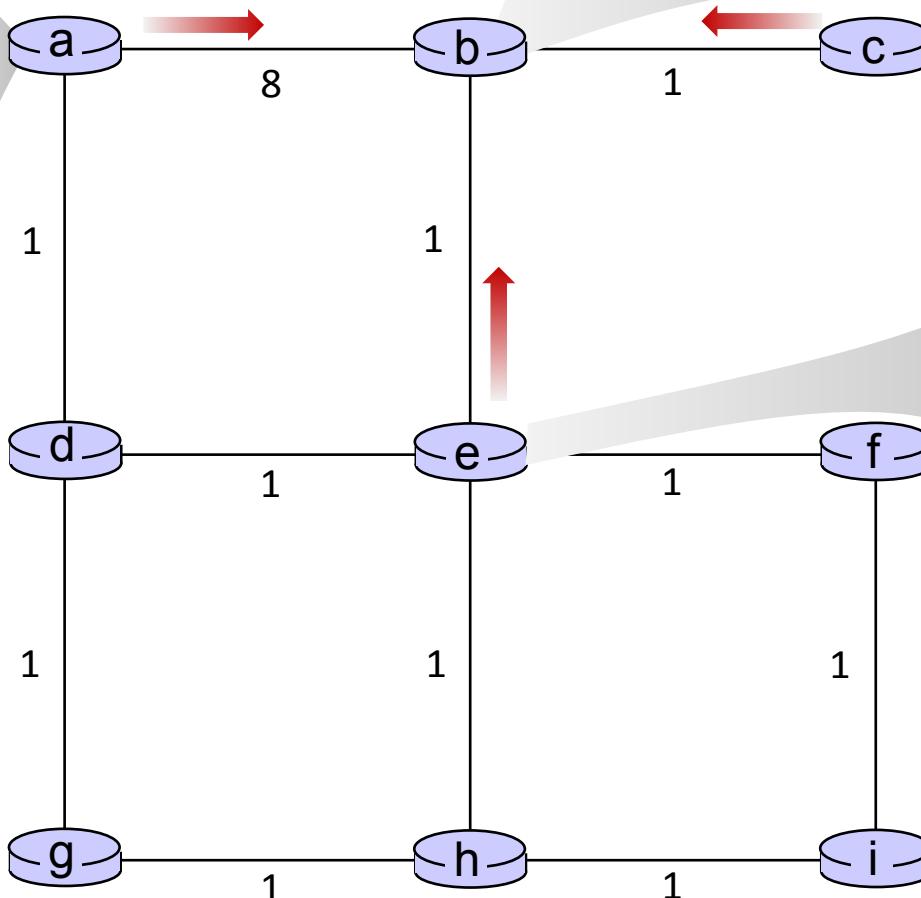
# Distance vector example



$t=1$

- b receives DVs from a, c, e

DV in a:
$D_a(a) = 0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$



DV in b:	
$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:
$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in e:
$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

# Distance vector example

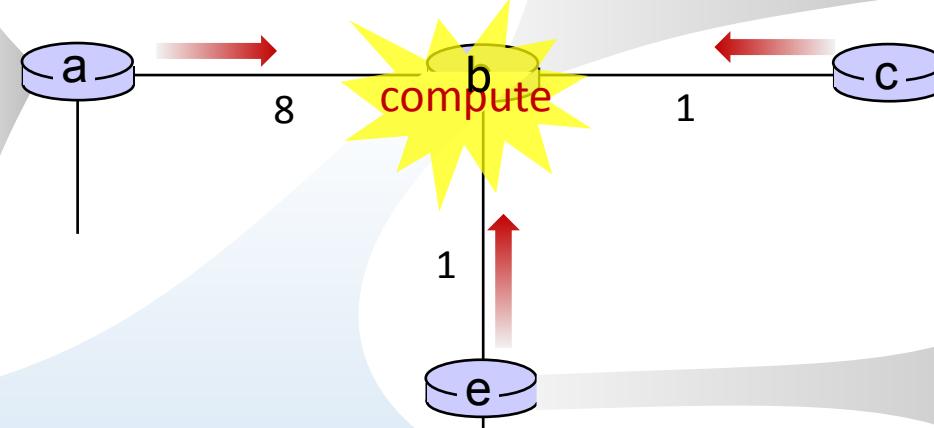


$t=1$

- b receives DVs from a, c, e, computes:

$$\begin{aligned}
 D_b(a) &= \min\{c_{b,a} + D_a(a), c_{b,c} + D_c(a), c_{b,e} + D_e(a)\} = \min\{8, \infty, \infty\} = 8 \\
 D_b(c) &= \min\{c_{b,a} + D_a(c), c_{b,c} + D_c(c), c_{b,e} + D_e(c)\} = \min\{\infty, 1, \infty\} = 1 \\
 D_b(d) &= \min\{c_{b,a} + D_a(d), c_{b,c} + D_c(d), c_{b,e} + D_e(d)\} = \min\{9, 2, \infty\} = 2 \\
 D_b(e) &= \min\{c_{b,a} + D_a(e), c_{b,c} + D_c(e), c_{b,e} + D_e(e)\} = \min\{\infty, \infty, 1\} = 1 \\
 D_b(f) &= \min\{c_{b,a} + D_a(f), c_{b,c} + D_c(f), c_{b,e} + D_e(f)\} = \min\{\infty, \infty, 2\} = 2 \\
 D_b(g) &= \min\{c_{b,a} + D_a(g), c_{b,c} + D_c(g), c_{b,e} + D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty \\
 D_b(h) &= \min\{c_{b,a} + D_a(h), c_{b,c} + D_c(h), c_{b,e} + D_e(h)\} = \min\{\infty, \infty, 2\} = 2 \\
 D_b(i) &= \min\{c_{b,a} + D_a(i), c_{b,c} + D_c(i), c_{b,e} + D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty
 \end{aligned}$$

DV in a:
$D_a(a)=0$
$D_a(b)=8$
$D_a(c)=\infty$
$D_a(d)=1$
$D_a(e)=\infty$
$D_a(f)=\infty$
$D_a(g)=\infty$
$D_a(h)=\infty$
$D_a(i)=\infty$



DV in b:	
$D_b(a)=8$	$D_b(f)=\infty$
$D_b(c)=1$	$D_b(g)=\infty$
$D_b(d)=\infty$	$D_b(h)=\infty$
$D_b(e)=1$	$D_b(i)=\infty$

DV in c:
$D_c(a)=\infty$
$D_c(b)=1$
$D_c(c)=0$
$D_c(d)=\infty$
$D_c(e)=\infty$
$D_c(f)=\infty$
$D_c(g)=\infty$
$D_c(h)=\infty$
$D_c(i)=\infty$

DV in b:	
$D_b(a)=8$	$D_b(f)=2$
$D_b(c)=1$	$D_b(g)=\infty$
$D_b(d)=2$	$D_b(h)=2$
$D_b(e)=1$	$D_b(i)=\infty$

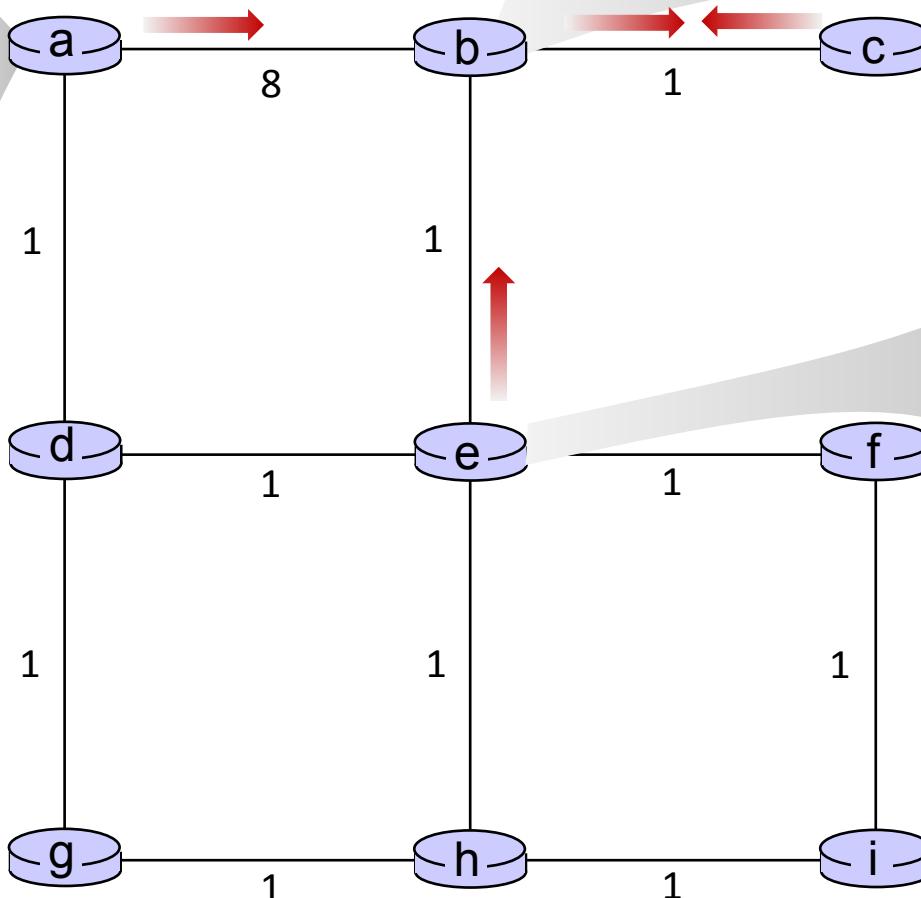
# Distance vector example



$t=1$

- c receives DVs from b

DV in a:	
$D_a(a) = 0$	
$D_a(b) = 8$	
$D_a(c) = \infty$	
$D_a(d) = 1$	
$D_a(e) = \infty$	
$D_a(f) = \infty$	
$D_a(g) = \infty$	
$D_a(h) = \infty$	
$D_a(i) = \infty$	



DV in b:	
$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:	
$D_c(a) = \infty$	
$D_c(b) = 1$	
$D_c(c) = 0$	
$D_c(d) = \infty$	
$D_c(e) = \infty$	
$D_c(f) = \infty$	
$D_c(g) = \infty$	
$D_c(h) = \infty$	
$D_c(i) = \infty$	

DV in e:	
$D_e(a) = \infty$	
$D_e(b) = 1$	
$D_e(c) = \infty$	
$D_e(d) = 1$	
$D_e(e) = 0$	
$D_e(f) = 1$	
$D_e(g) = \infty$	
$D_e(h) = 1$	
$D_e(i) = \infty$	

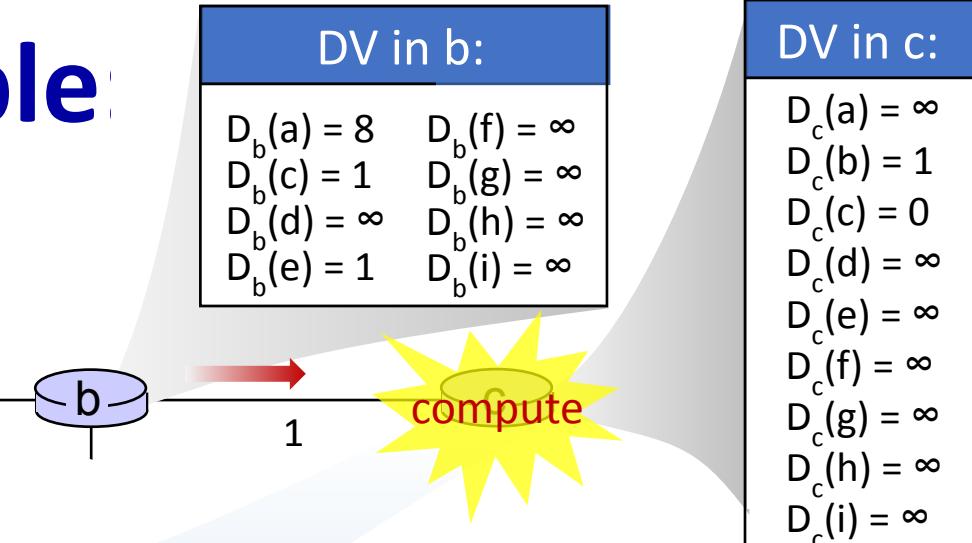
# Distance vector example



$t=1$

- c receives DVs from b computes:

$$\begin{aligned}D_c(a) &= \min\{c_{c,b} + D_b(a)\} = 1 + 8 = 9 \\D_c(b) &= \min\{c_{c,b} + D_b(b)\} = 1 + 0 = 1 \\D_c(d) &= \min\{c_{c,b} + D_b(d)\} = 1 + \infty = \infty \\D_c(e) &= \min\{c_{c,b} + D_b(e)\} = 1 + 1 = 2 \\D_c(f) &= \min\{c_{c,b} + D_b(f)\} = 1 + \infty = \infty \\D_c(g) &= \min\{c_{c,b} + D_b(g)\} = 1 + \infty = \infty \\D_c(h) &= \min\{c_{c,b} + D_b(h)\} = 1 + \infty = \infty \\D_c(i) &= \min\{c_{c,b} + D_b(i)\} = 1 + \infty = \infty\end{aligned}$$



DV in c:

$D_c(a) = 9$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = 2$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

\* Check out the online interactive exercises for more examples:  
[http://gaia.cs.umass.edu/kurose\\_ross/interactive/](http://gaia.cs.umass.edu/kurose_ross/interactive/)

# Distance vector example



**t=1**

- e receives DVs from b, d, f, h

DV in d:
$D_c(a) = 1$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = 0$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = \infty$
$D_c(i) = \infty$

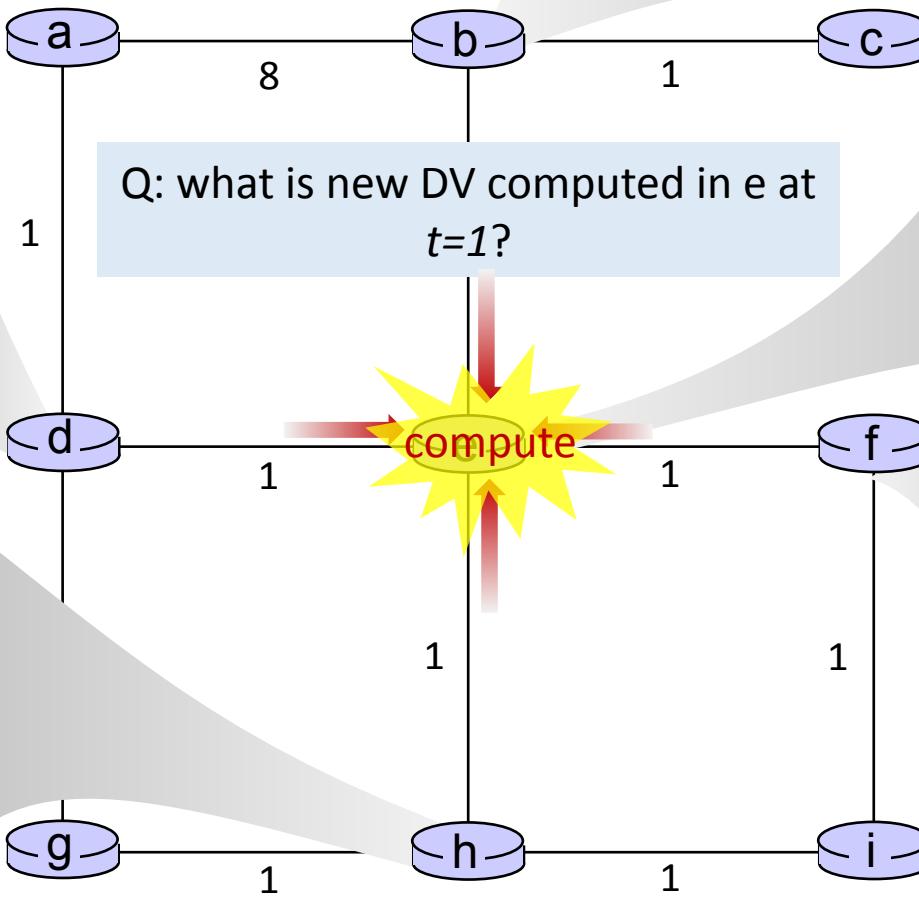
DV in h:
$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = 0$
$D_c(i) = 1$

DV in b:
$D_b(a) = 8$
$D_b(f) = \infty$
$D_b(c) = 1$
$D_b(g) = \infty$
$D_b(d) = \infty$
$D_b(h) = \infty$
$D_b(e) = 1$
$D_b(i) = \infty$

1

DV in e:
$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

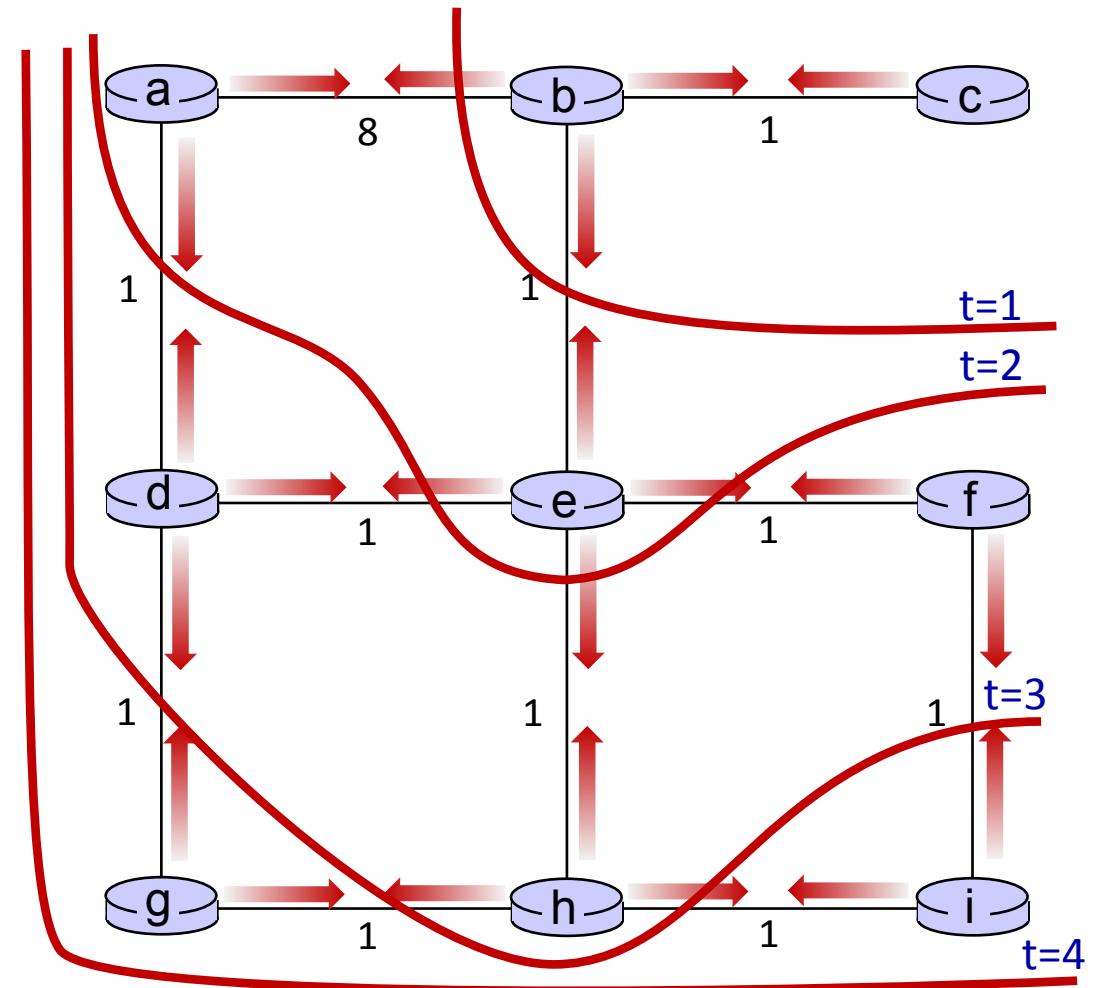
DV in f:
$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = 0$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = 1$



# Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

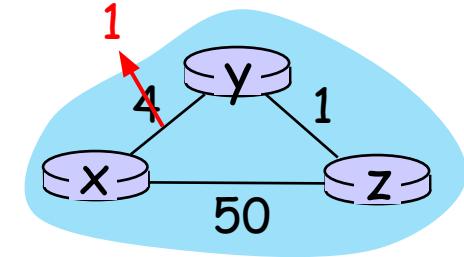
-  t=0 c's state at t=0 is at c only
-  t=1 c's state at t=0 has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b
-  t=2 c's state at t=0 may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well
-  t=3 c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at b,a,e and now at c,f,h as well
-  t=4 c's state at t=0 may influence distance vector computations up to **4** hops away, i.e., at b,a,e, c, f, h and now at g,i as well



# Distance vector: link cost changes

## link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors



$t_0$ : y detects link-cost change, updates its DV, informs its neighbors.

“good news travels fast”

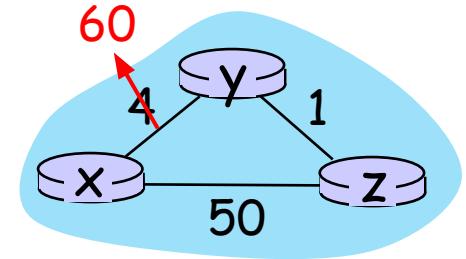
$t_1$ : z receives update from y, updates its table, computes new least cost to x , sends its neighbors its DV.

$t_2$ : y receives z's update, updates its distance table. y's least costs do *not* change, so y does *not* send a message to z.

# Distance vector: link cost changes

## link cost changes:

- node detects local link cost change
- “**bad news travels slow**” – count-to-infinity problem:
  - y sees direct link to x has new cost 60, but z has said it has a path at cost of 5. So y computes “my new cost to x will be 6, via z); notifies z of new cost of 6 to x.
  - z learns that path to x via y has new cost 6, so z computes “my new cost to x will be 7 via y), notifies y of new cost of 7 to x.
  - y learns that path to x via z has new cost 7, so y computes “my new cost to x will be 8 via y), notifies z of new cost of 8 to x.
  - z learns that path to x via y has new cost 8, so z computes “my new cost to x will be 9 via y), notifies y of new cost of 9 to x.
  - ...
- see text for solutions. *Distributed algorithms are tricky!*



# Comparison of LS and DV algorithms

## message complexity

LS:  $n$  routers,  $O(n^2)$  messages sent

DV: exchange between neighbors;  
convergence time varies

## speed of convergence

LS:  $O(n^2)$  algorithm,  $O(n^2)$  messages

- may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

**robustness:** what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect *link* cost
- each router computes only its *own* table

DV:

- DV router can advertise incorrect *path* cost (“I have a *really* low cost path to everywhere”): black-holing
- each router’s table used by others: error propagate thru network

# Network layer: “control plane” roadmap

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
  - SNMP
  - NETCONF/YANG

# Making routing scalable

our routing study thus far - idealized

- all routers identical
  - network “flat”
- ... not true in practice

**scale:** billions of destinations:

- can't store all destinations in routing tables!
- routing table exchange would swamp links!

**administrative autonomy:**

- Internet: a network of networks
- each network admin may want to control routing in its own network

# Internet approach to scalable routing

aggregate routers into regions known as “autonomous systems” (AS) (a.k.a. “domains”)

## intra-AS (aka “intra-domain”):

routing among *within same AS (“network”)*

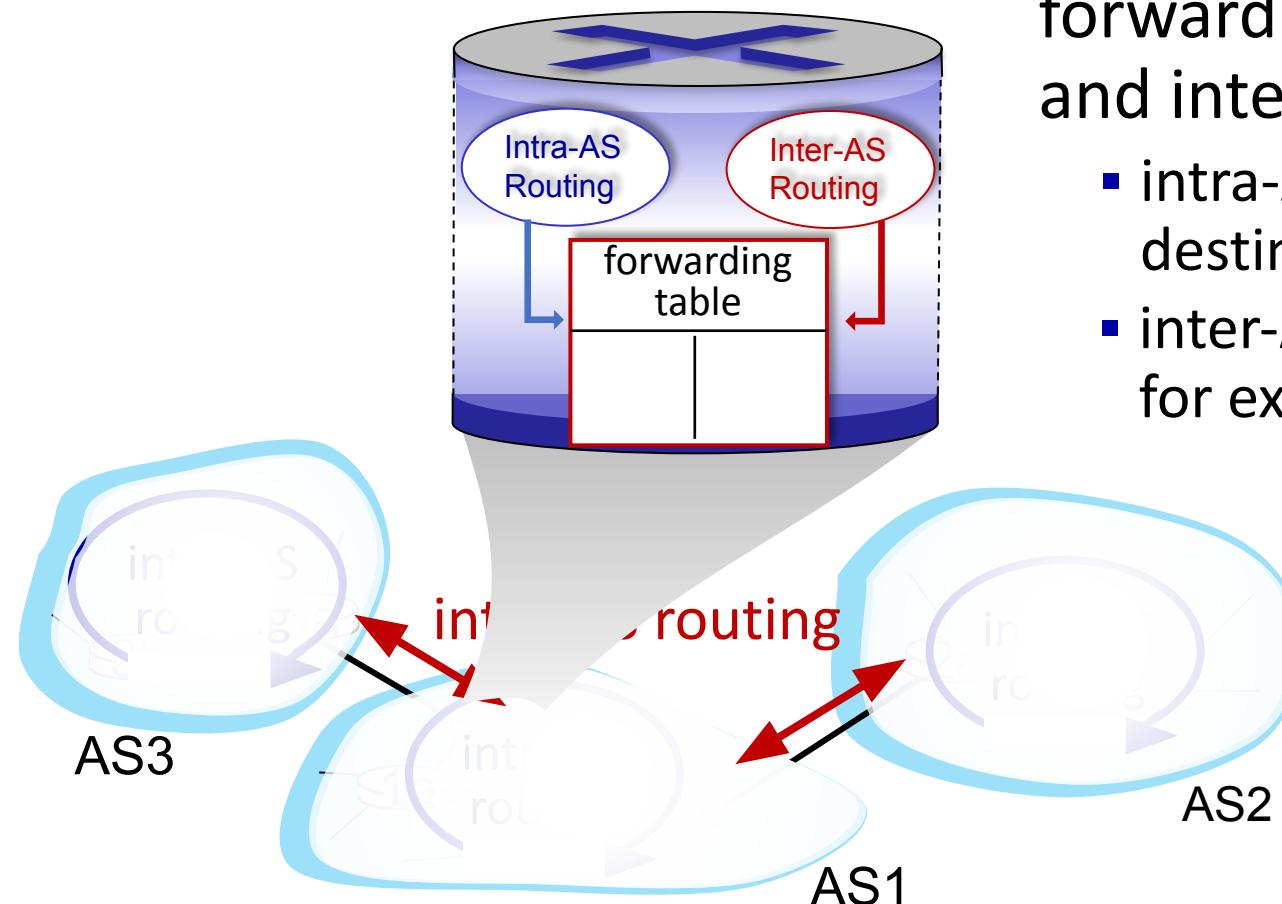
- all routers in AS must run same intra-domain protocol
- routers in different AS can run different intra-domain routing protocols
- **gateway router:** at “edge” of its own AS, has link(s) to router(s) in other AS'es

## inter-AS (aka “inter-domain”):

routing *among* AS'es

- gateways perform inter-domain routing (as well as intra-domain routing)

# Interconnected ASes



forwarding table configured by intra-  
and inter-AS routing algorithms

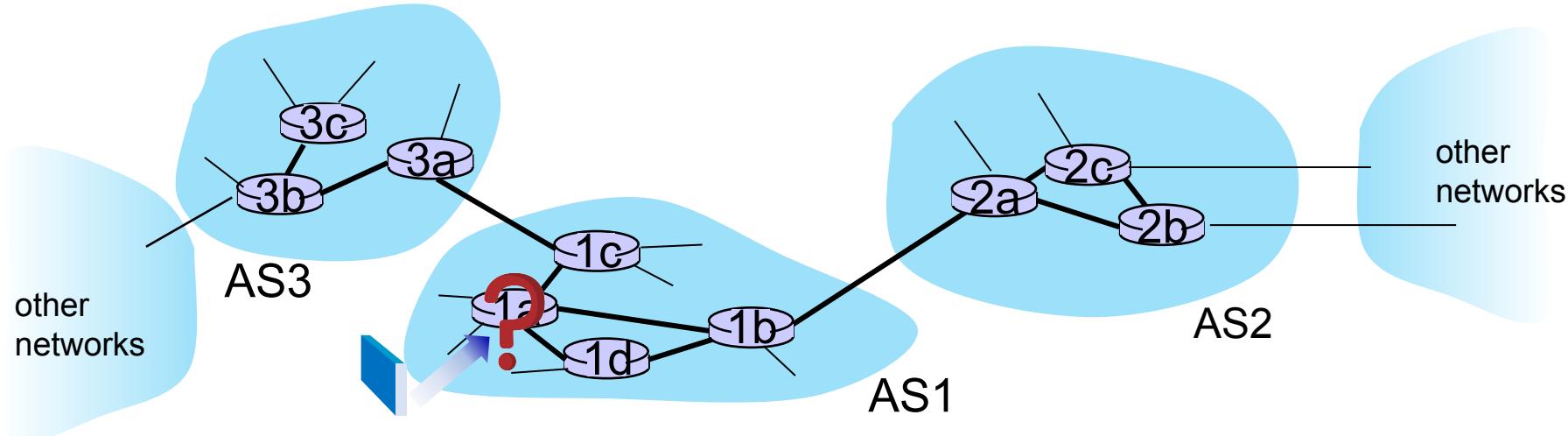
- intra-AS routing determine entries for destinations within AS
- inter-AS & intra-AS determine entries for external destinations

# Inter-AS routing: a role in intradomain forwarding

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router in AS1, but which one?

**AS1 inter-domain routing must:**

1. learn which destinations reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1



# Inter-AS routing: routing within an AS

most common intra-AS routing protocols:

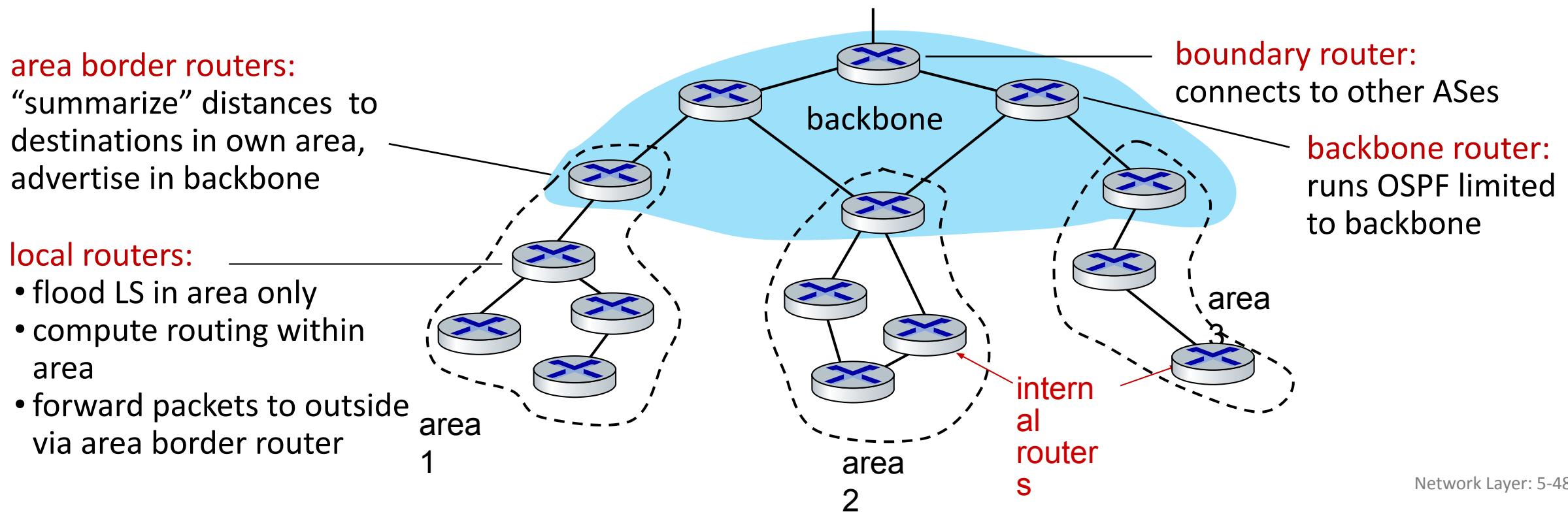
- **RIP: Routing Information Protocol [RFC 1723]**
  - classic DV: DVs exchanged every 30 secs
  - no longer widely used
- **EIGRP: Enhanced Interior Gateway Routing Protocol**
  - DV based
  - formerly Cisco-proprietary for decades (became open in 2013 [RFC 7868])
- **OSPF: Open Shortest Path First [RFC 2328]**
  - link-state routing
  - IS-IS protocol (ISO standard, not RFC standard) essentially same as OSPF

# OSPF (Open Shortest Path First) routing

- “open”: publicly available
- classic link-state
  - each router floods OSPF link-state advertisements (directly over IP rather than using TCP/UDP) to all other routers in entire AS
  - multiple link costs metrics possible: bandwidth, delay
  - each router has full topology, uses Dijkstra’s algorithm to compute forwarding table
- *security*: all OSPF messages authenticated (to prevent malicious intrusion)

# Hierarchical OSPF

- two-level hierarchy: local area, backbone.
  - link-state advertisements flooded only in area, or backbone
  - each node has detailed area topology; only knows direction to reach other destinations



# Network layer: “control plane” roadmap

- introduction
- routing protocols
- intra-ISP routing: OSPF
- **routing among ISPs: BGP**
- SDN control plane
- Internet Control Message Protocol

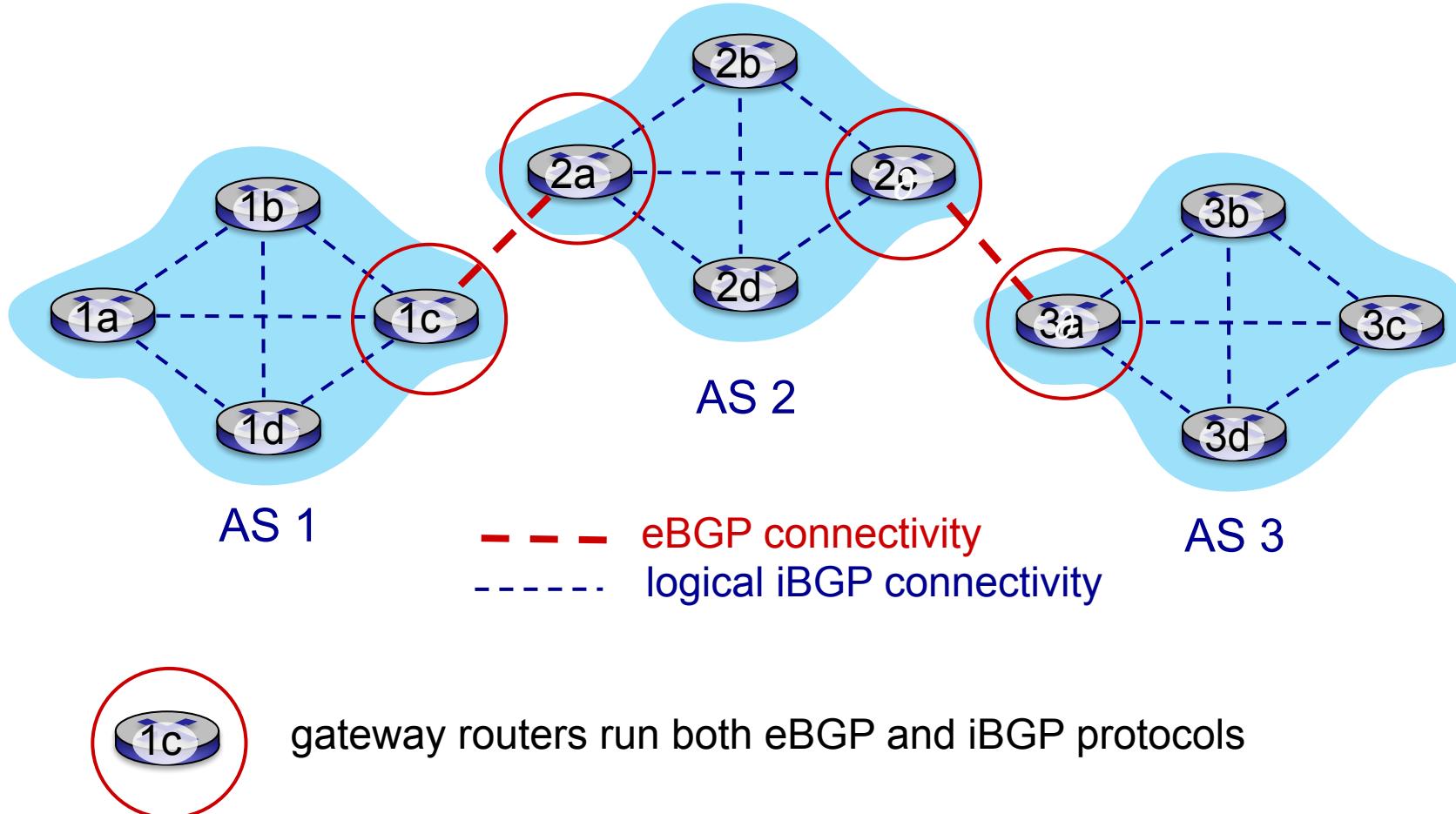


- network management, configuration
  - SNMP
  - NETCONF/YANG

# Internet inter-AS routing: BGP

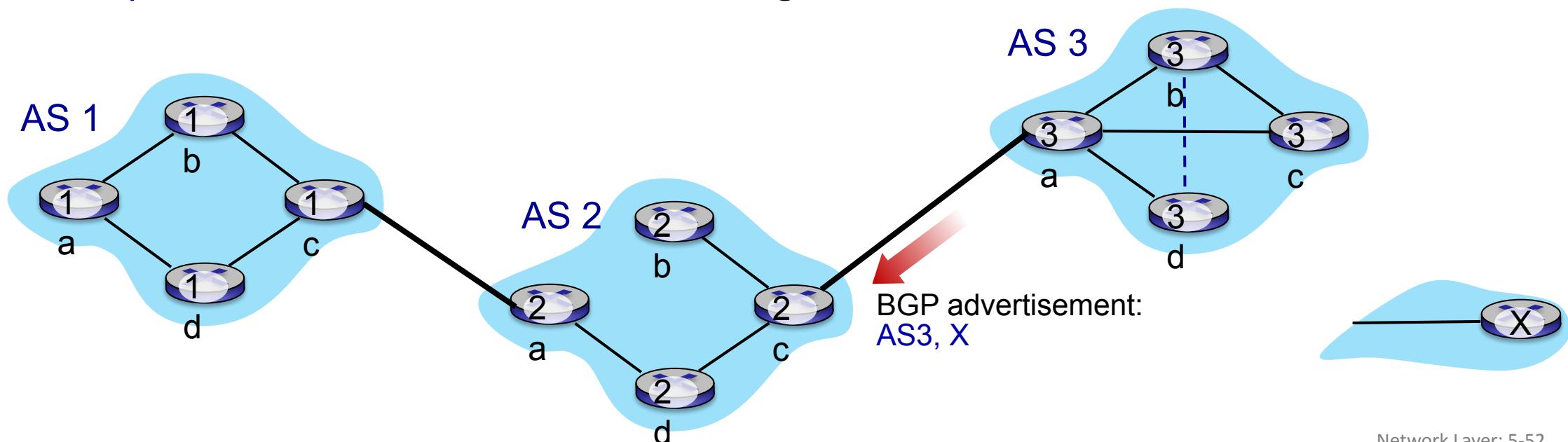
- BGP (Border Gateway Protocol): *the de facto* inter-domain routing protocol
  - “glue that holds the Internet together”
- allows subnet to advertise its existence, and the destinations it can reach, to rest of Internet: *“I am here, here is who I can reach, and how”*
- BGP provides each AS a means to:
  - eBGP: obtain subnet reachability information from neighboring ASes
  - iBGP: propagate reachability information to all AS-internal routers.
  - determine “good” routes to other networks based on reachability information and *policy*

# eBGP, iBGP connections



# BGP basics

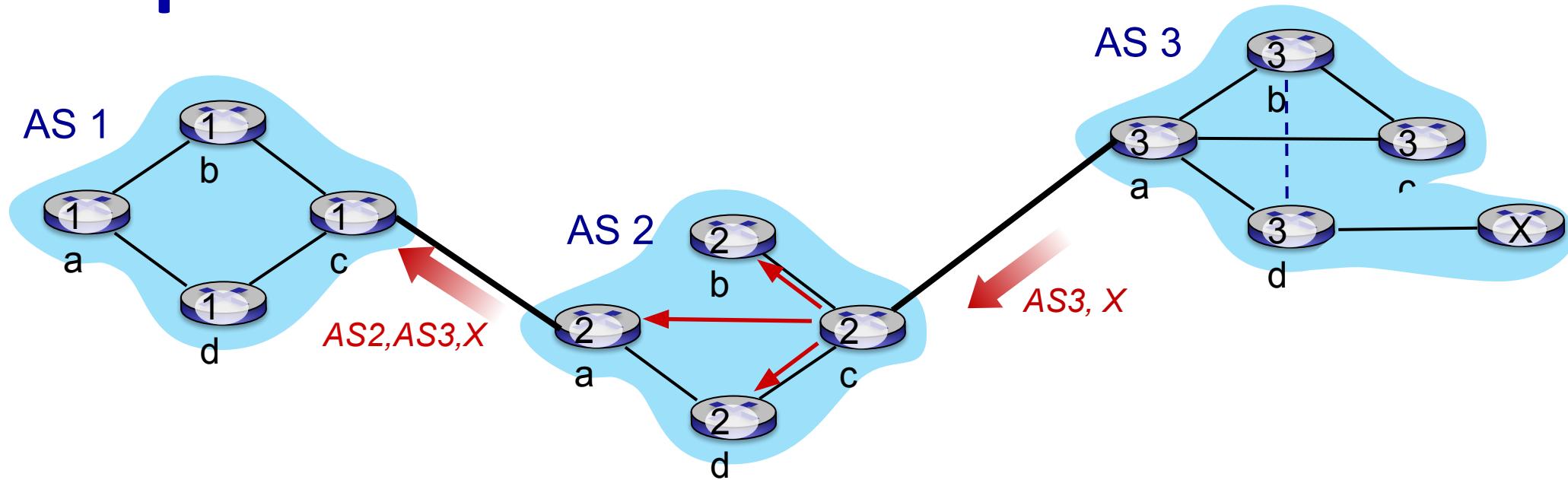
- **BGP session:** two BGP routers (“peers”) exchange BGP messages over semi-permanent TCP connection:
  - advertising *paths* to different destination network prefixes (BGP is a “path vector” protocol)
- when AS3 gateway 3a advertises **path AS3,X** to AS2 gateway 2c:
  - AS3 *promises* to AS2 it will forward datagrams towards X



# Path attributes and BGP routes

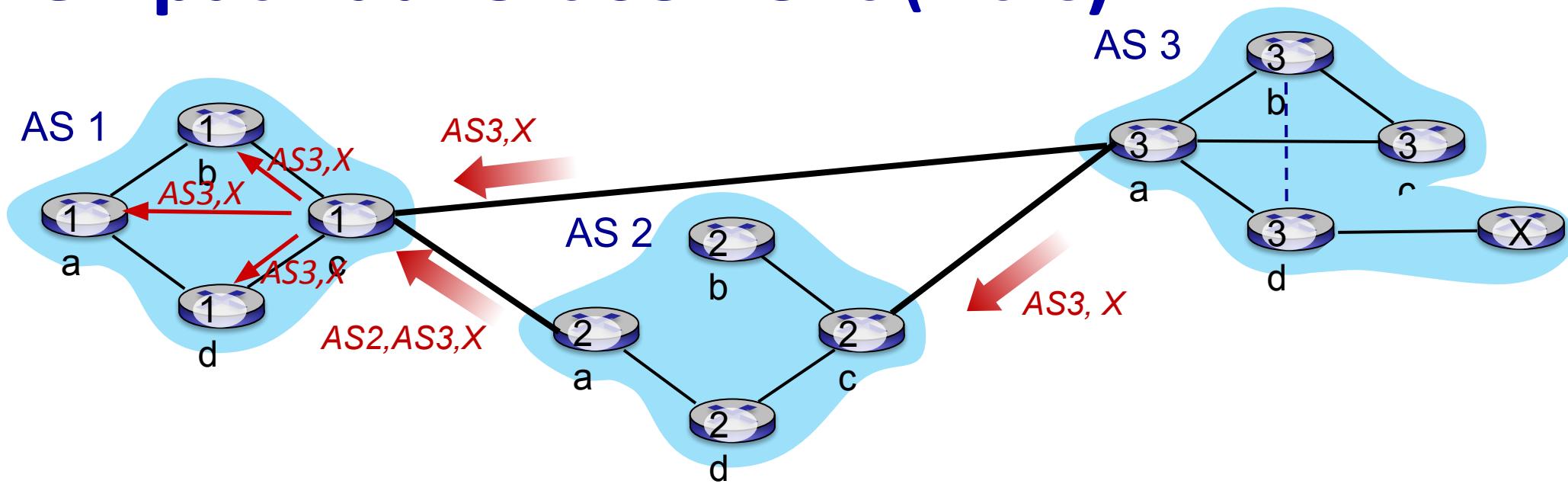
- BGP advertised route: prefix + attributes
  - prefix: destination being advertised
  - two important attributes:
    - AS-PATH: list of ASes through which prefix advertisement has passed
    - NEXT-HOP: indicates specific internal-AS router to next-hop AS
- policy-based routing:
  - gateway receiving route advertisement uses *import policy* to accept/decline path (e.g., never route through AS Y).
  - AS policy also determines whether to *advertise* path to other other neighboring ASes

# BGP path advertisement



- AS2 router 2c receives path advertisement **AS3,X** (via eBGP) from AS3 router 3a
- based on AS2 policy, AS2 router 2c accepts path AS3,X, propagates (via iBGP) to all AS2 routers
- based on AS2 policy, AS2 router 2a advertises (via eBGP) path **AS2, AS3, X** to AS1 router 1c

# BGP path advertisement (more)



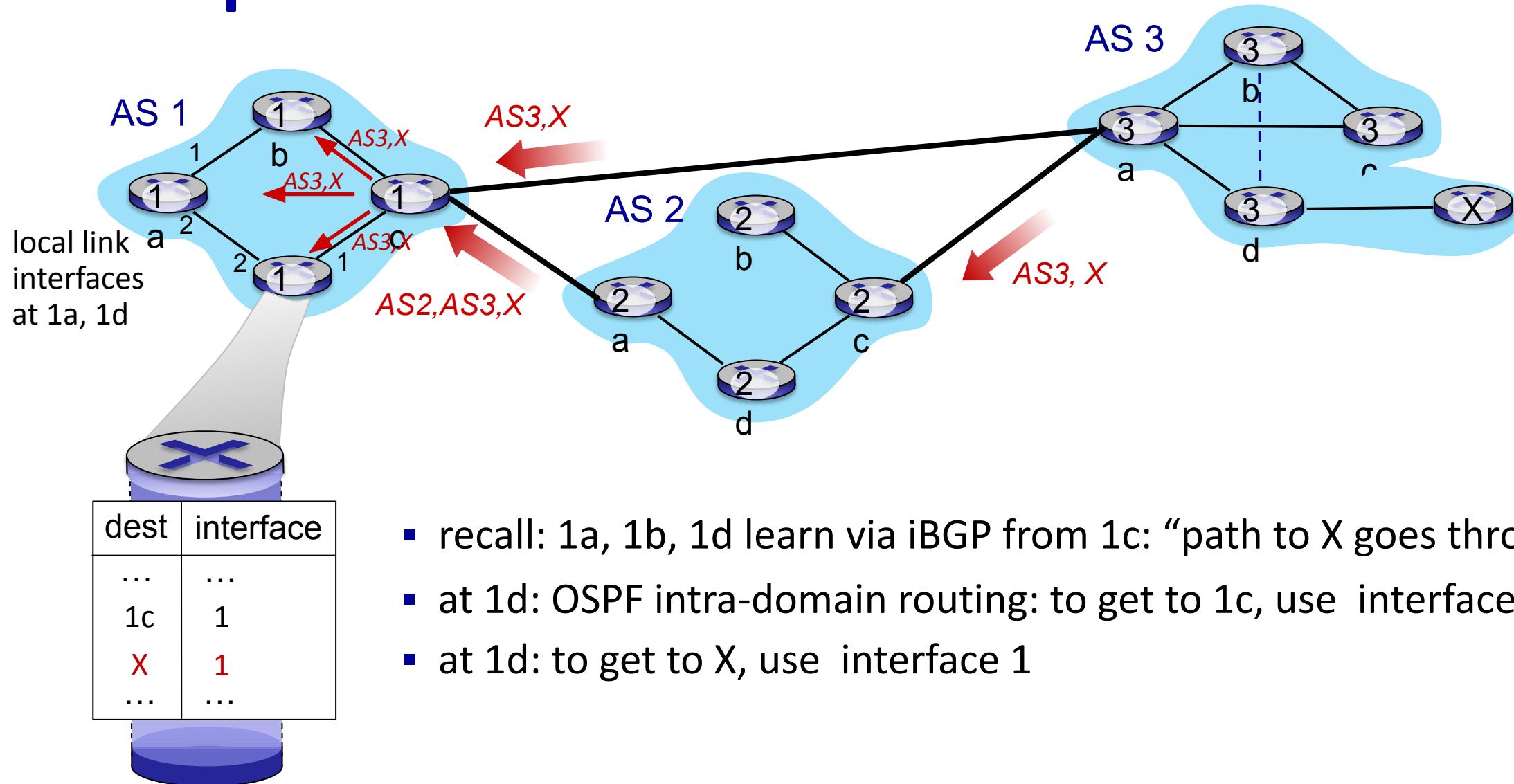
gateway router may learn about multiple paths to destination:

- AS1 gateway router 1c learns path **AS2,AS3,X** from 2a
- AS1 gateway router 1c learns path **AS3,X** from 3a
- based on *policy*, AS1 gateway router 1c chooses path **AS3,X** and advertises path within AS1 via iBGP

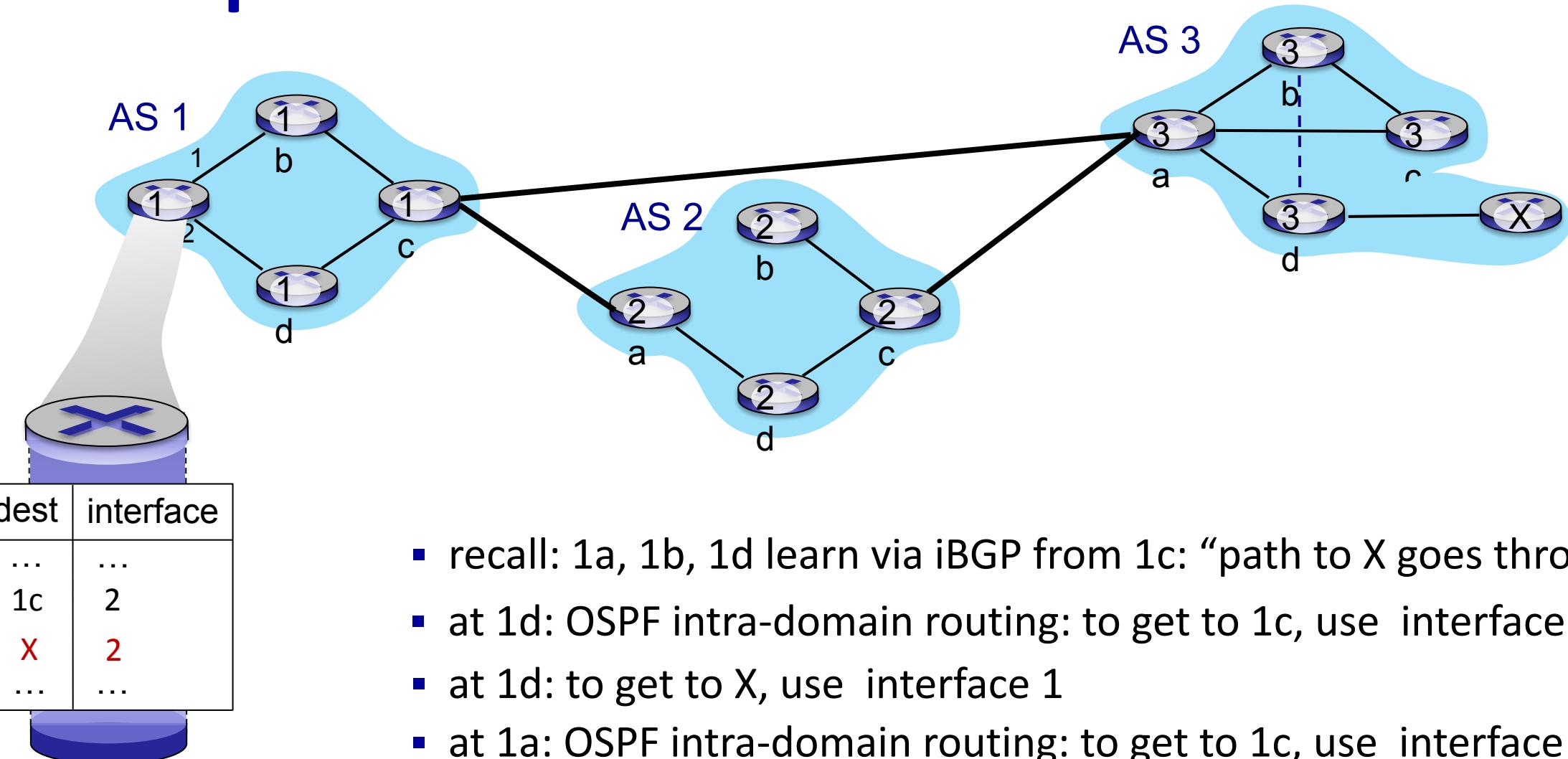
# BGP messages

- BGP messages exchanged between peers over TCP connection
- BGP messages:
  - **OPEN**: opens TCP connection to remote BGP peer and authenticates sending BGP peer
  - **UPDATE**: advertises new path (or withdraws old)
  - **KEEPALIVE**: keeps connection alive in absence of UPDATES; also ACKs OPEN request
  - **NOTIFICATION**: reports errors in previous msg; also used to close connection

# BGP path advertisement



# BGP path advertisement



- recall: 1a, 1b, 1d learn via iBGP from 1c: “path to X goes through 1c”
- at 1d: OSPF intra-domain routing: to get to 1c, use interface 1
- at 1d: to get to X, use interface 1
- at 1a: OSPF intra-domain routing: to get to 1c, use interface 2
- at 1a: to get to X, use interface 2

# Why different Intra-, Inter-AS routing ?

policy:

- inter-AS: admin wants control over how its traffic routed, who routes through its network
- intra-AS: single admin, so policy less of an issue

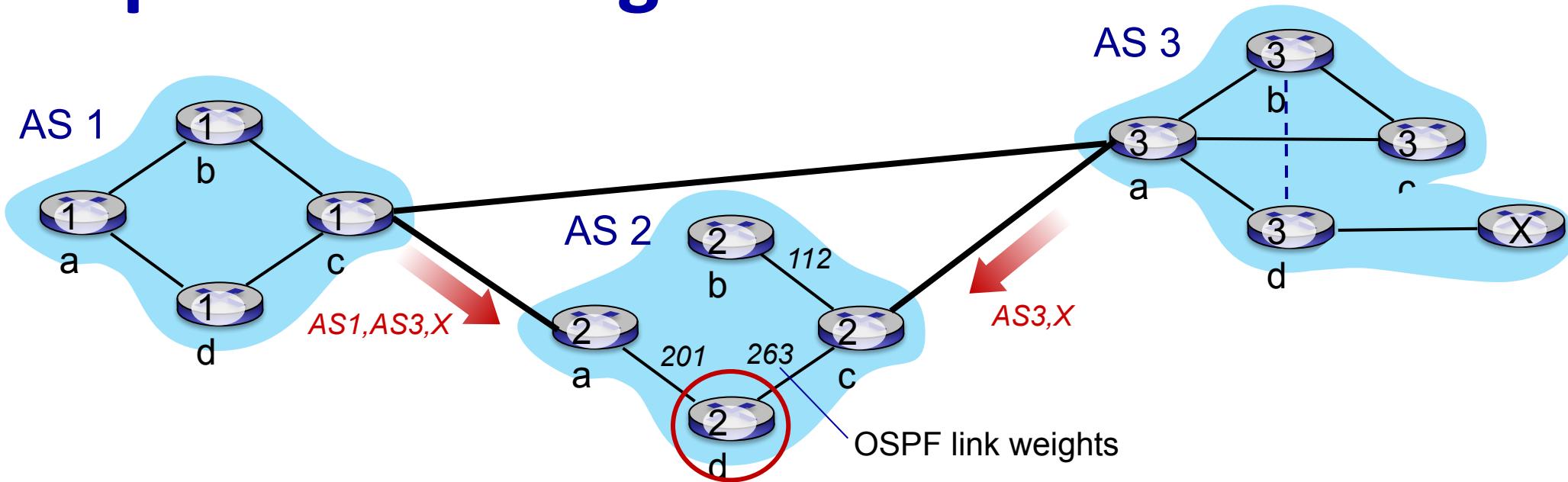
scale:

- hierarchical routing saves table size, reduced update traffic

performance:

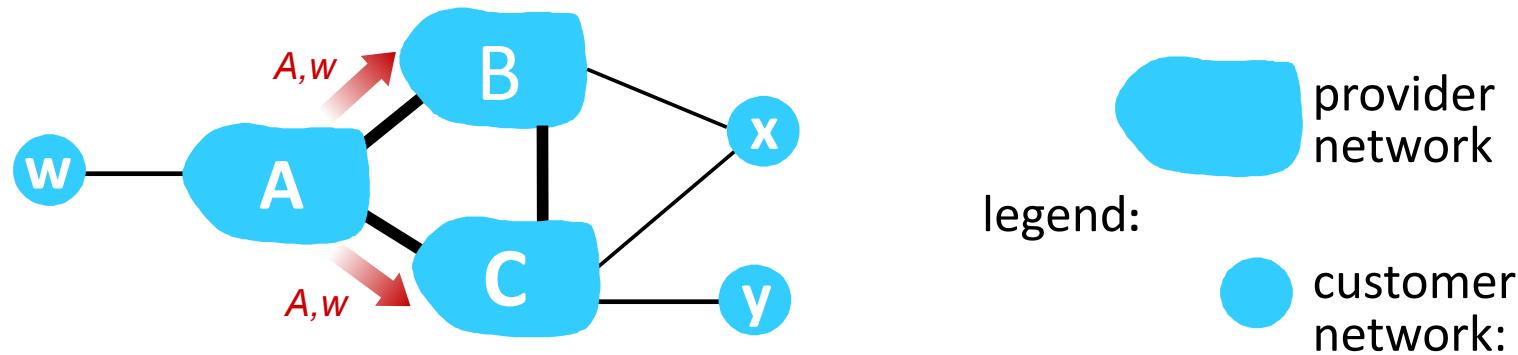
- intra-AS: can focus on performance
- inter-AS: policy dominates over performance

# Hot potato routing



- 2d learns (via iBGP) it can route to X via 2a or 2c
- **hot potato routing:** choose local gateway that has least *intra-domain* cost (e.g., 2d chooses 2a, even though more AS hops to X): don't worry about inter-domain cost!

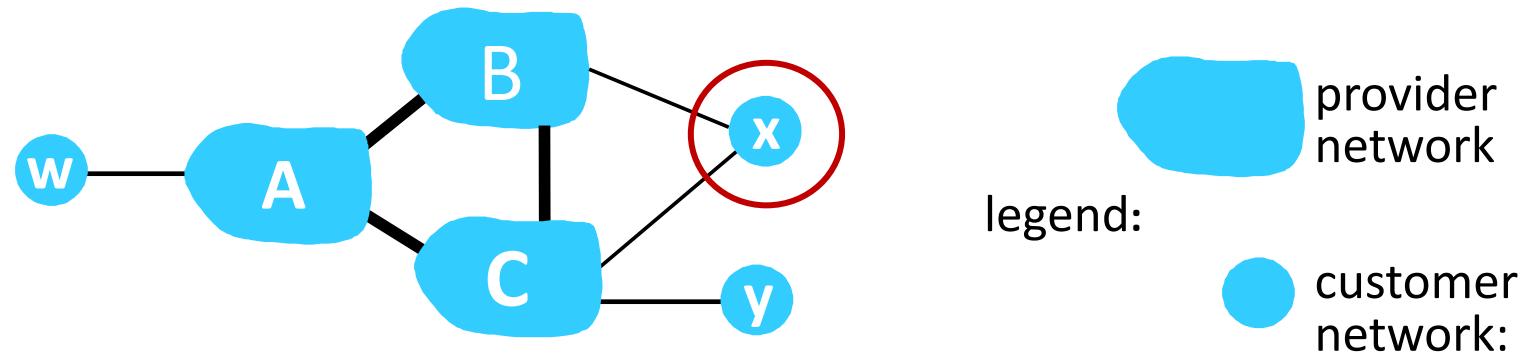
# BGP: achieving policy via advertisements



ISP only wants to route traffic to/from its customer networks (does not want to carry transit traffic between other ISPs – a typical “real world” policy)

- A advertises path Aw to B and to C
- B *chooses not to advertise* BAw to C!
  - B gets no “revenue” for routing CBAw, since none of C, A, w are B’s customers
  - C does *not* learn about CBAw path
- C will route CAw (not using B) to get to w

# BGP: achieving policy via advertisements (more)



ISP only wants to route traffic to/from its customer networks (does not want to carry transit traffic between other ISPs – a typical “real world” policy)

- A,B,C are **provider networks**
- x,w,y are **customer** (of provider networks)
- x is **dual-homed**: attached to two networks
- ***policy to enforce***: x does not want to route from B to C via x
  - .. so x will not advertise to B a route to C

# BGP route selection

- router may learn about more than one route to destination AS, selects route based on:
  1. local preference value attribute: policy decision
  2. shortest AS-PATH
  3. closest NEXT-HOP router: hot potato routing
  4. additional criteria

# Network layer: “control plane” roadmap

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- **SDN control plane**
- Internet Control Message Protocol



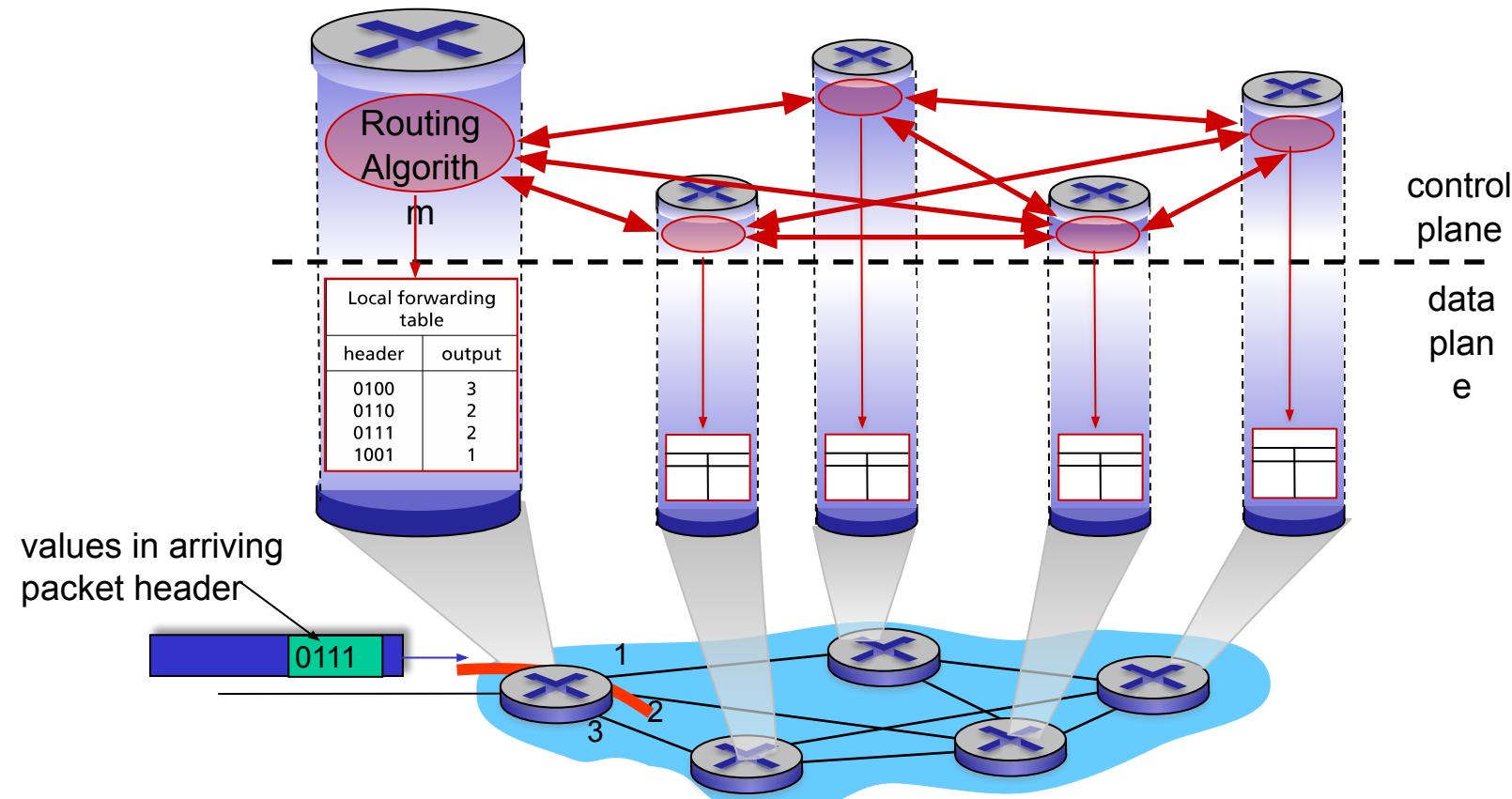
- network management, configuration
  - SNMP
  - NETCONF/YANG

# Software defined networking (SDN)

- Internet network layer: historically implemented via distributed, per-router control approach:
  - *monolithic* router contains switching hardware, runs proprietary implementation of Internet standard protocols (IP, RIP, IS-IS, OSPF, BGP) in proprietary router OS (e.g., Cisco IOS)
  - different “middleboxes” for different network layer functions: firewalls, load balancers, NAT boxes, ..
- ~2005: renewed interest in rethinking network control plane

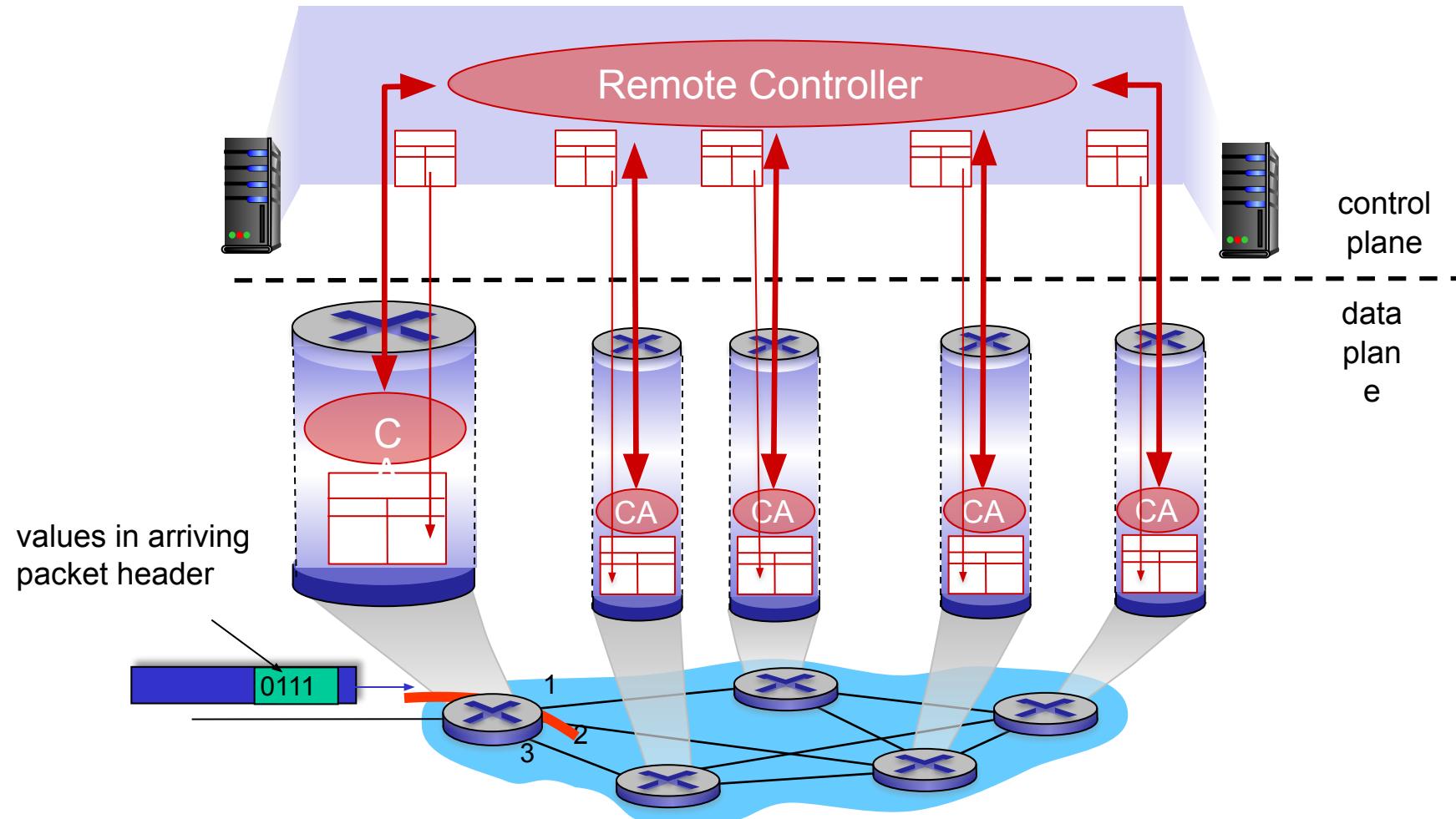
# Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane to computer forwarding tables



# Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



# Software defined networking (SDN)

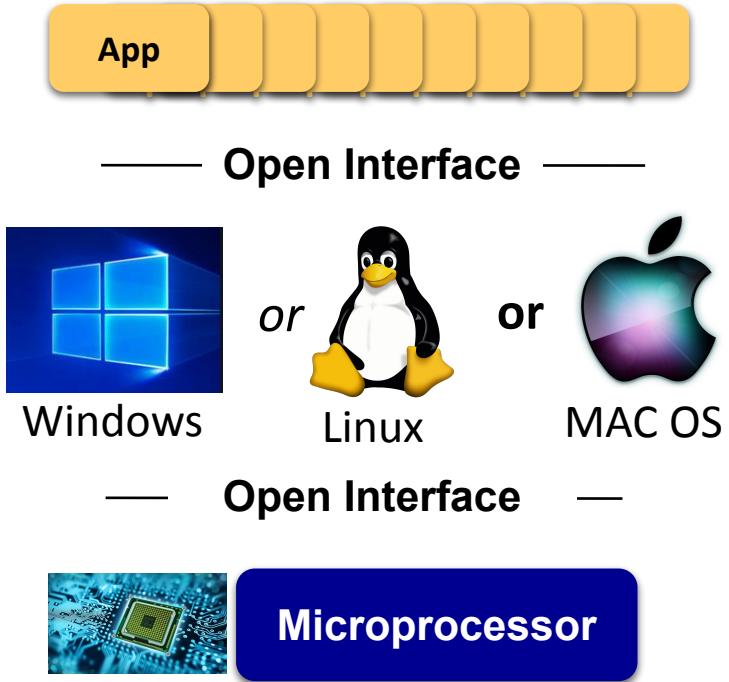
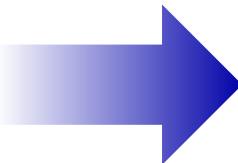
*Why a logically centralized* control plane?

- easier network management: avoid router misconfigurations, greater flexibility of traffic flows
- table-based forwarding (recall OpenFlow API) allows “programming” routers
  - centralized “programming” easier: compute tables centrally and distribute
  - distributed “programming” more difficult: compute tables as result of distributed algorithm (protocol) implemented in each-and-every router
- open (non-proprietary) implementation of control plane
  - foster innovation: let 1000 flowers bloom

# SDN analogy: mainframe to PC revolution

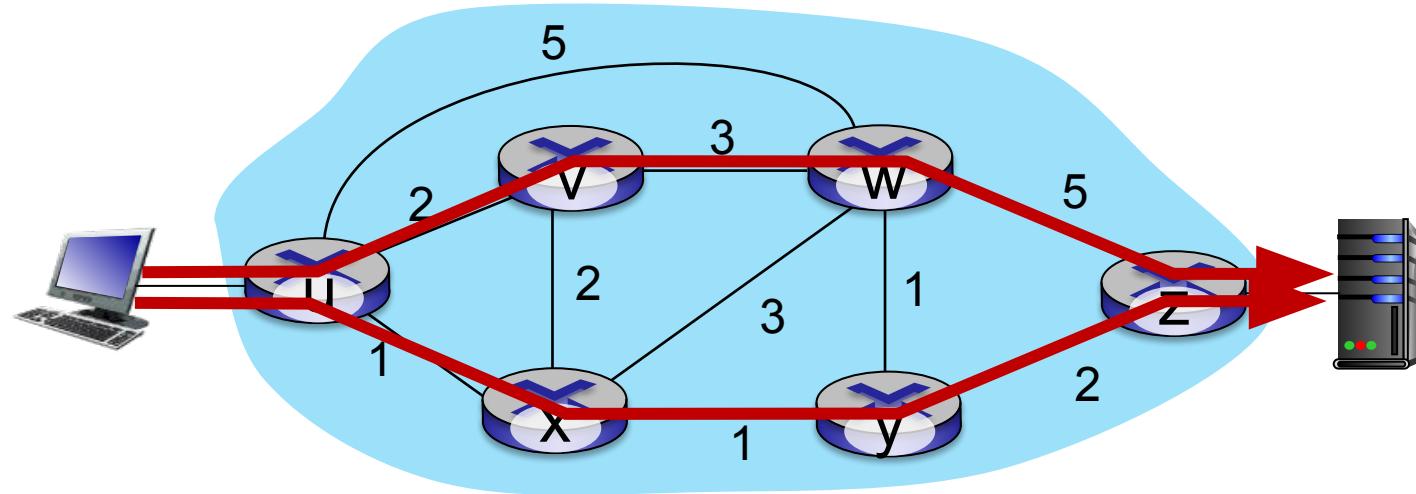


Vertically integrated  
Closed, proprietary  
Slow innovation  
Small industry



Horizontal  
Open interfaces  
Rapid innovation  
Huge industry

# Traffic engineering: difficult with traditional routing

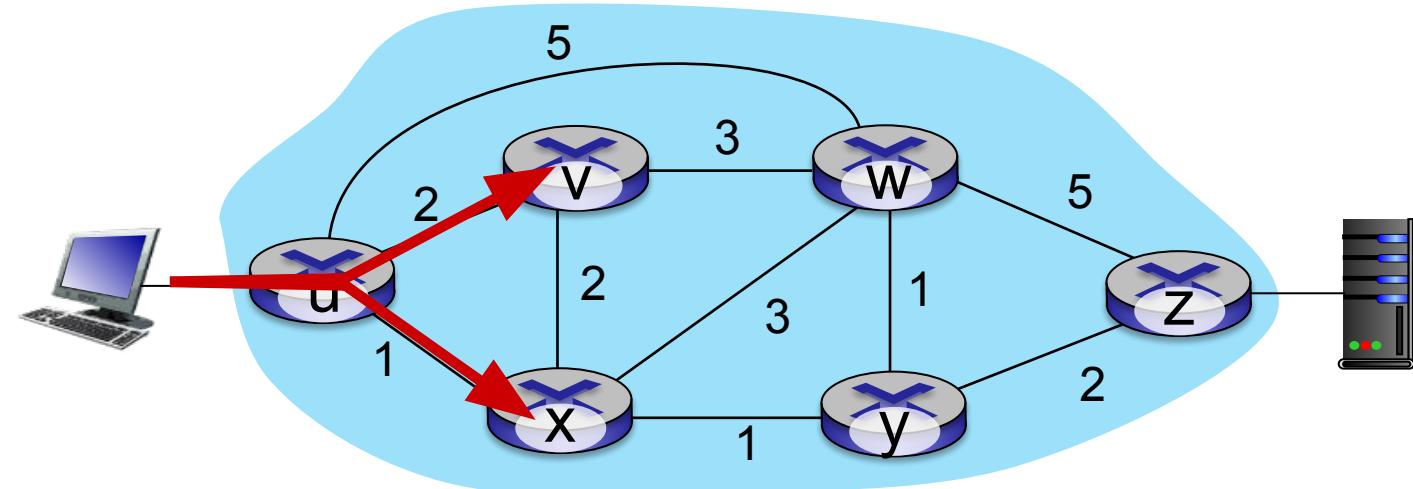


Q: what if network operator wants u-to-z traffic to flow along  $uvwz$ , rather than  $uxyz$ ?

A: need to re-define link weights so traffic routing algorithm computes routes accordingly (or need a new routing algorithm)!

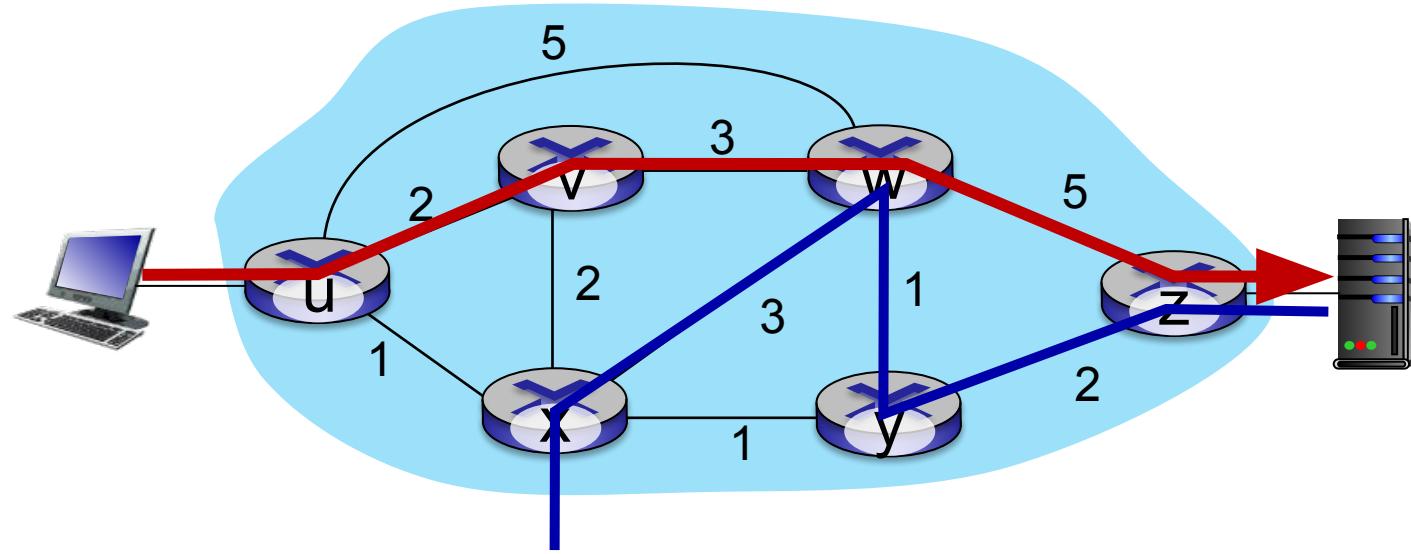
*link weights are only control “knobs”: not much control!*

# Traffic engineering: difficult with traditional routing



Q: what if network operator wants to split u-to-z traffic along uvwz *and* uxyz (load balancing)?  
A: can't do it (or need a new routing algorithm)

# Traffic engineering: difficult with traditional routing



Q: what if w wants to route blue and red traffic differently from w to z?

A: can't do it (with destination-based forwarding, and LS, DV routing)

We learned in Chapter 4 that generalized forwarding and SDN can be used to achieve *any* routing desired

# Software defined networking (SDN)

4. programmable  
control  
applications

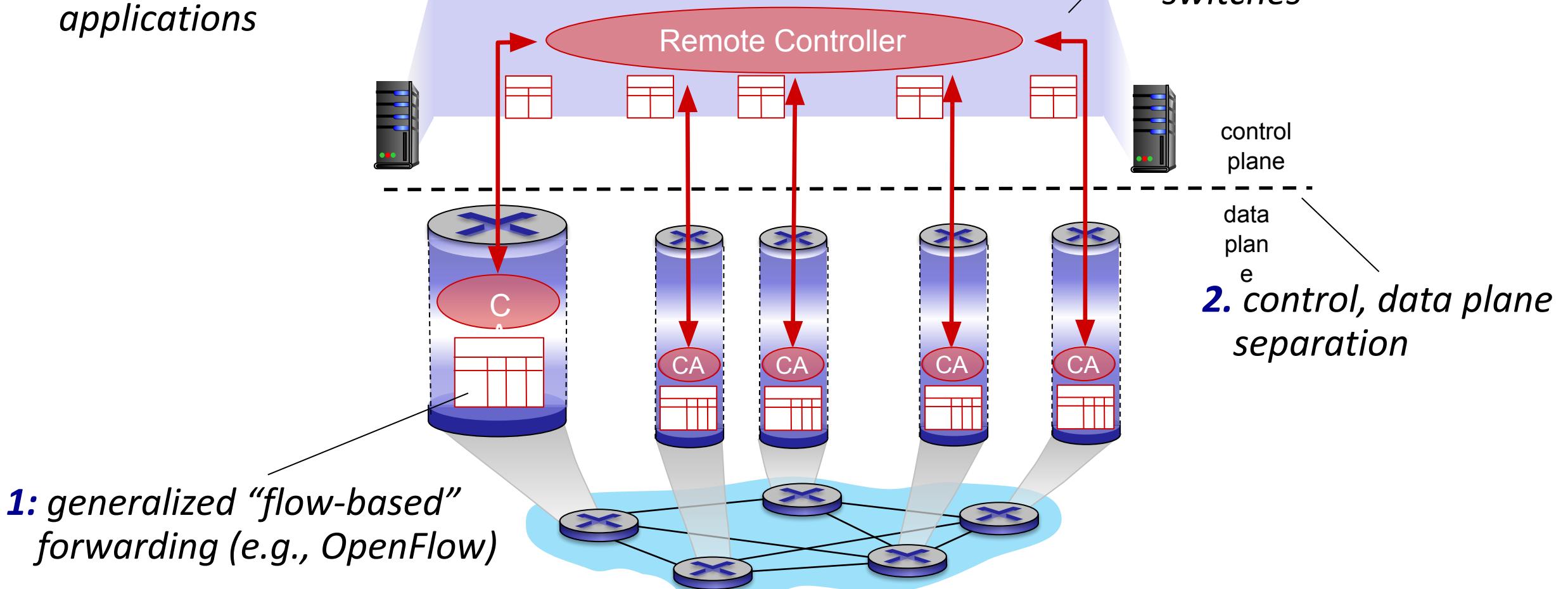
routing

access  
control

...

load  
balance

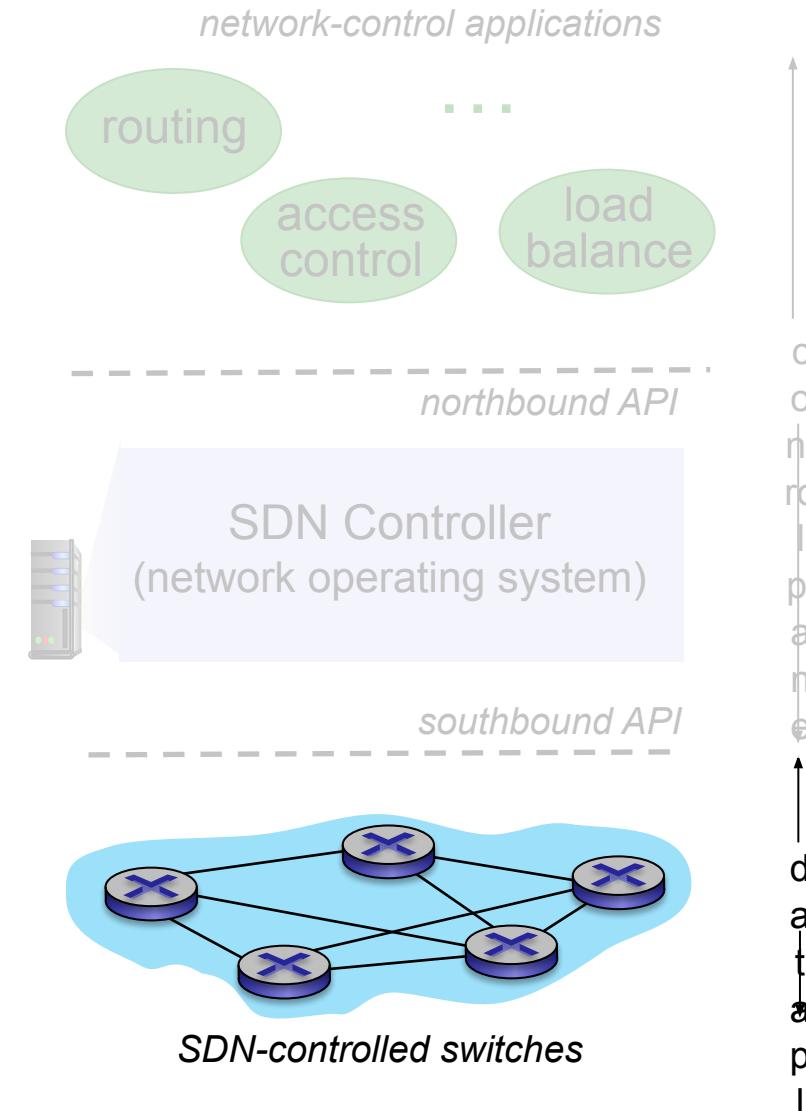
3. control plane functions  
external to data-plane  
switches



# Software defined networking (SDN)

## Data-plane switches:

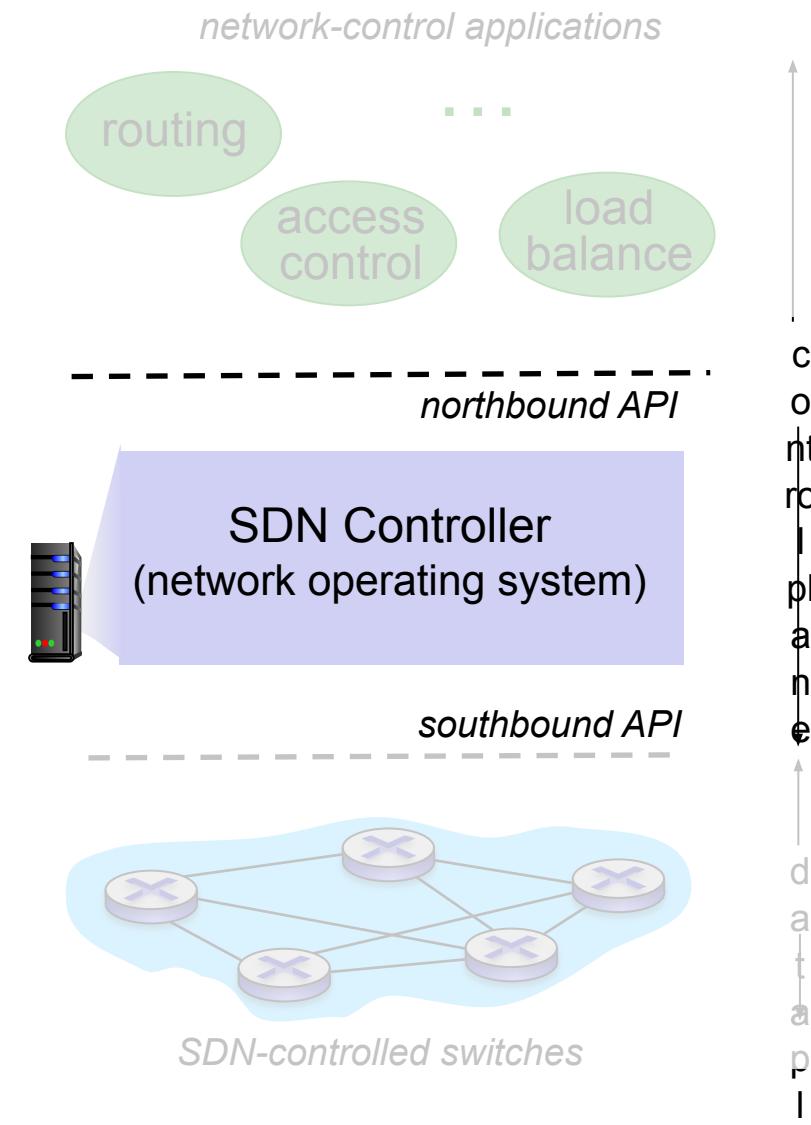
- fast, simple, commodity switches implementing generalized data-plane forwarding (Section 4.4) in hardware
- flow (forwarding) table computed, installed under controller supervision
- API for table-based switch control (e.g., OpenFlow)
  - defines what is controllable, what is not
- protocol for communicating with controller (e.g., OpenFlow)



# Software defined networking (SDN)

## SDN controller (network OS):

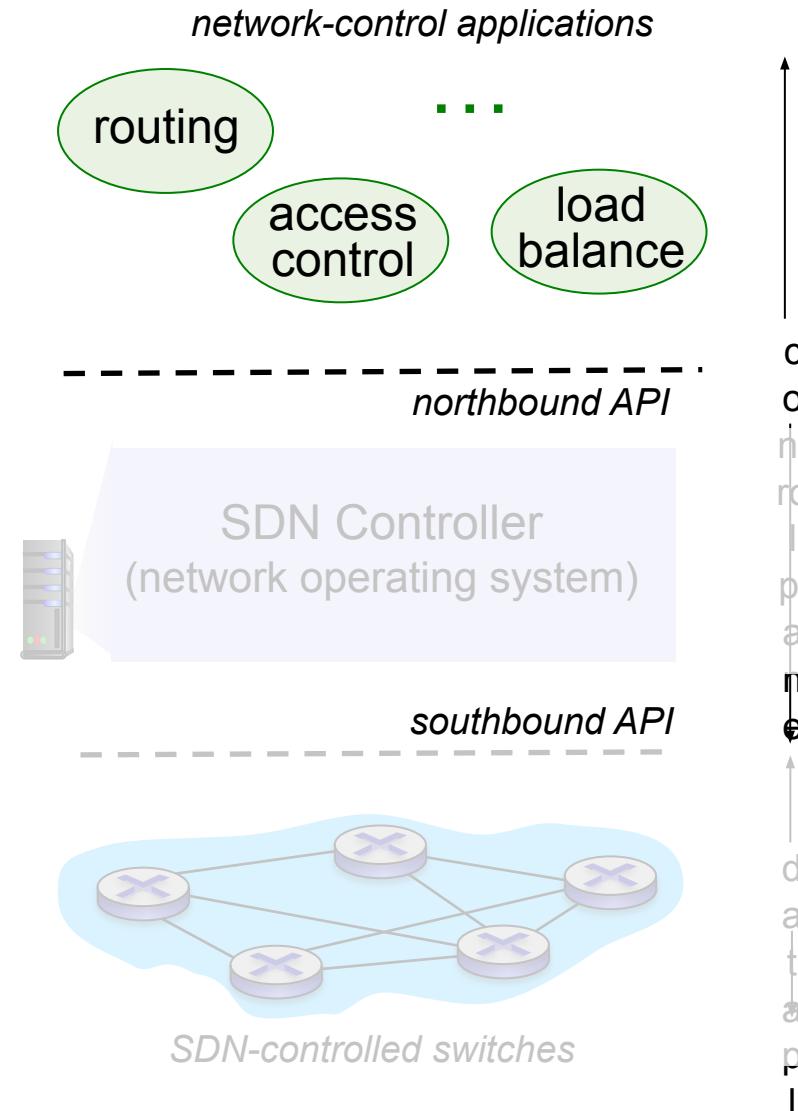
- maintain network state information
- interacts with network control applications “above” via northbound API
- interacts with network switches “below” via southbound API
- implemented as distributed system for performance, scalability, fault-tolerance, robustness



# Software defined networking (SDN)

## network-control apps:

- “brains” of control: implement control functions using lower-level services, API provided by SDN controller
- *unbundled*: can be provided by 3<sup>rd</sup> party: distinct from routing vendor, or SDN controller

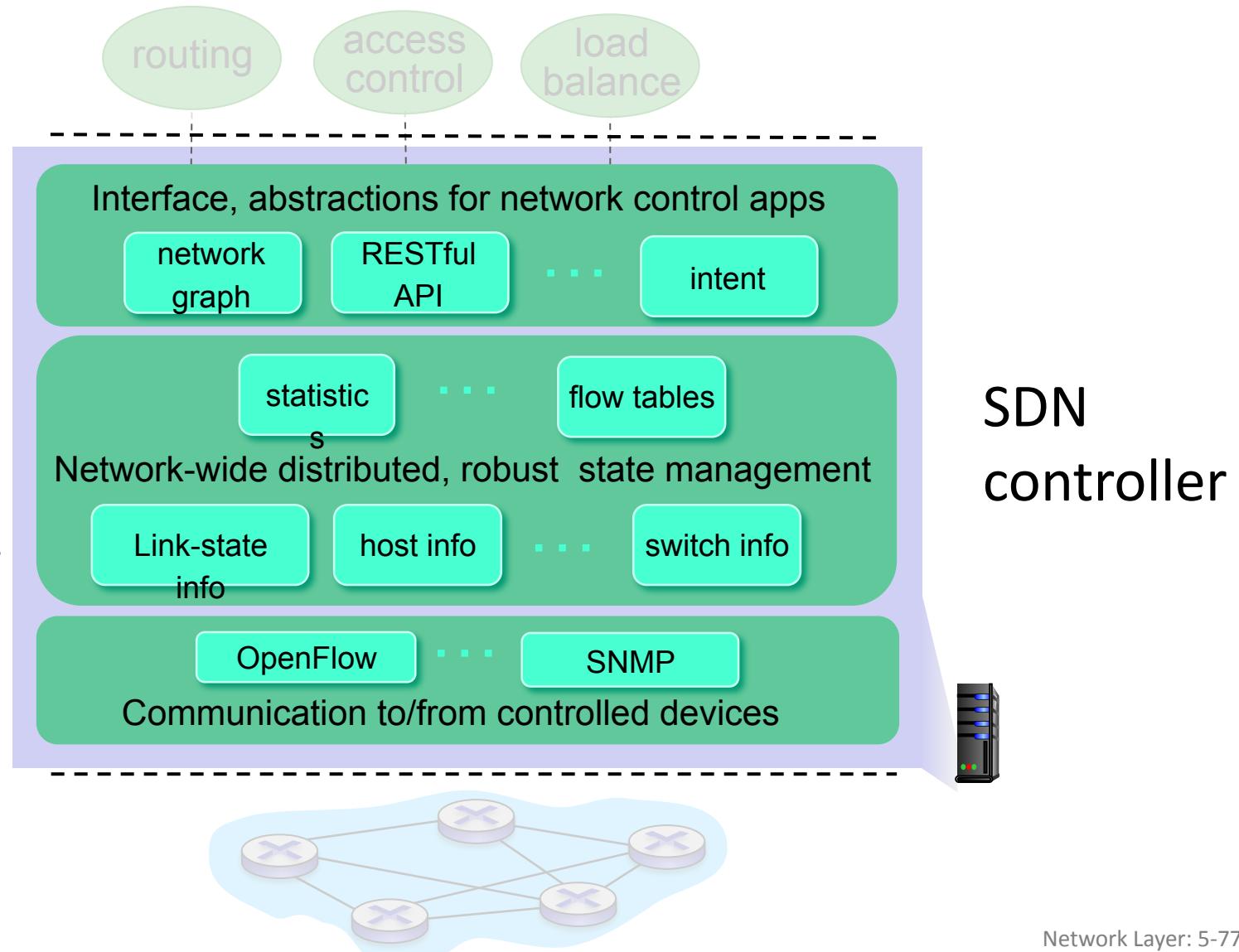


# Components of SDN controller

interface layer to network control apps: abstractions API

network-wide state management : state of networks links, switches, services: a *distributed database*

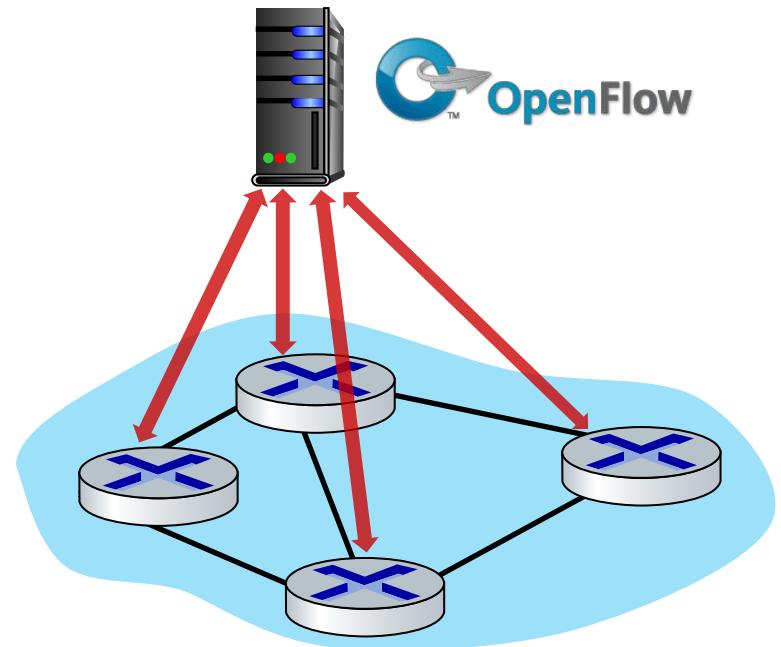
**communication**: communicate between SDN controller and controlled switches



# OpenFlow protocol

- operates between controller, switch
- TCP used to exchange messages
  - optional encryption
- three classes of OpenFlow messages:
  - controller-to-switch
  - asynchronous (switch to controller)
  - symmetric (misc.)
- distinct from OpenFlow API
  - API used to specify generalized forwarding actions

OpenFlow Controller

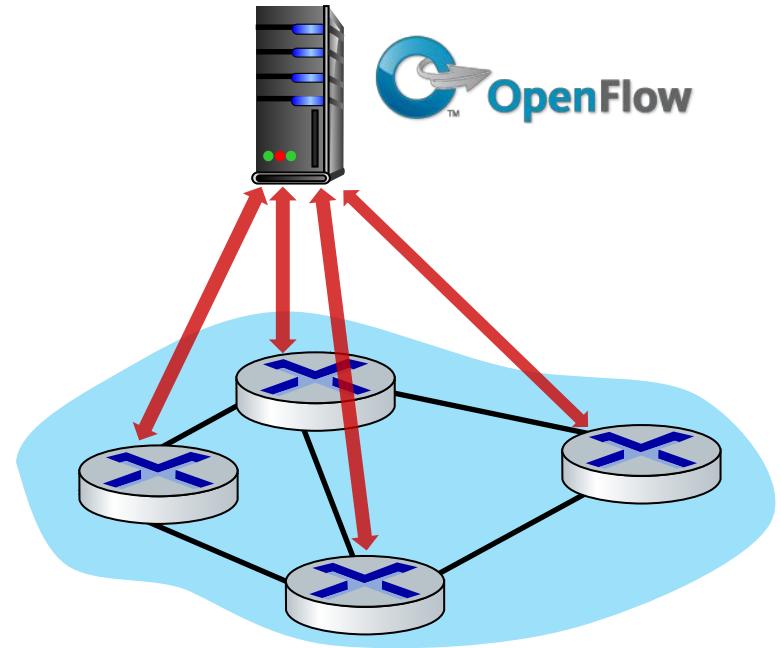


# OpenFlow: controller-to-switch messages

## Key controller-to-switch messages

- *features*: controller queries switch features, switch replies
- *configure*: controller queries/sets switch configuration parameters
- *modify-state*: add, delete, modify flow entries in the OpenFlow tables
- *packet-out*: controller can send this packet out of specific switch port

## OpenFlow Controller

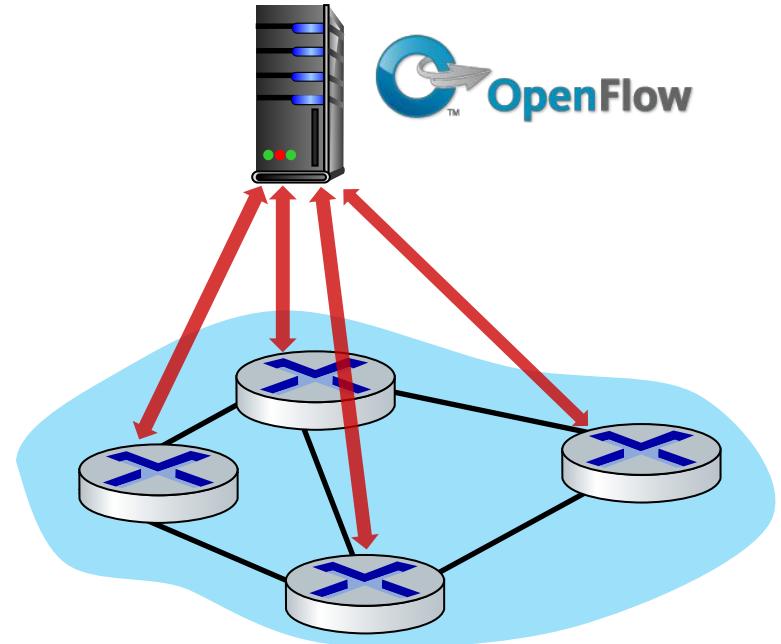


# OpenFlow: switch-to-controller messages

## Key switch-to-controller messages

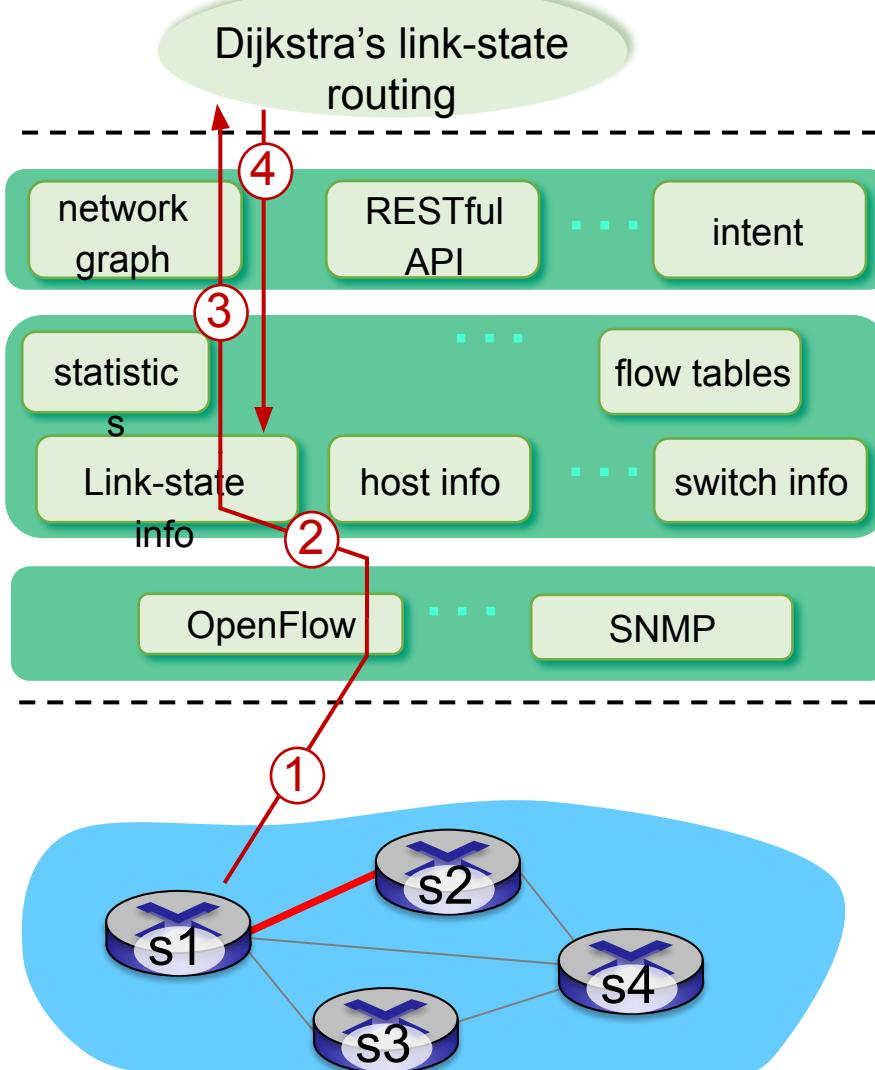
- *packet-in*: transfer packet (and its control) to controller. See packet-out message from controller
- *flow-removed*: flow table entry deleted at switch
- *port status*: inform controller of a change on a port.

## OpenFlow Controller



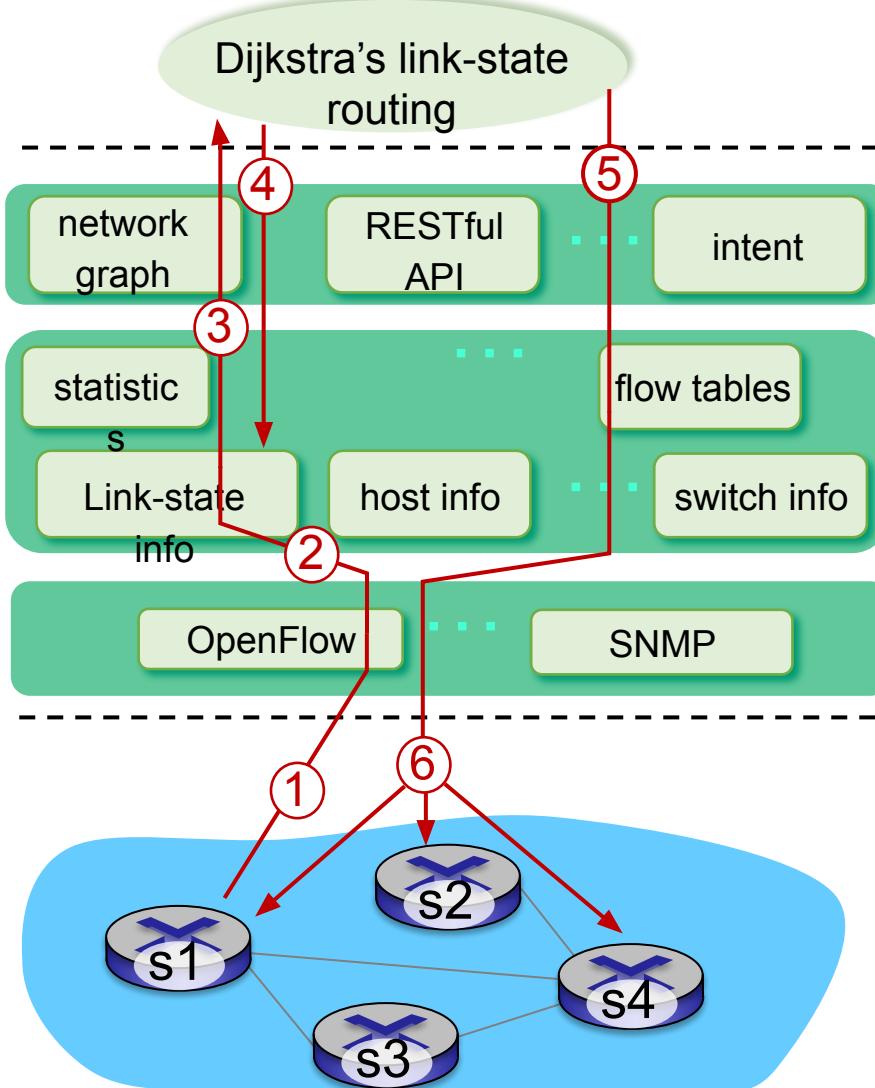
Fortunately, network operators don't "program" switches by creating/sending OpenFlow messages directly. Instead use higher-level abstraction at controller

# SDN: control/data plane interaction example



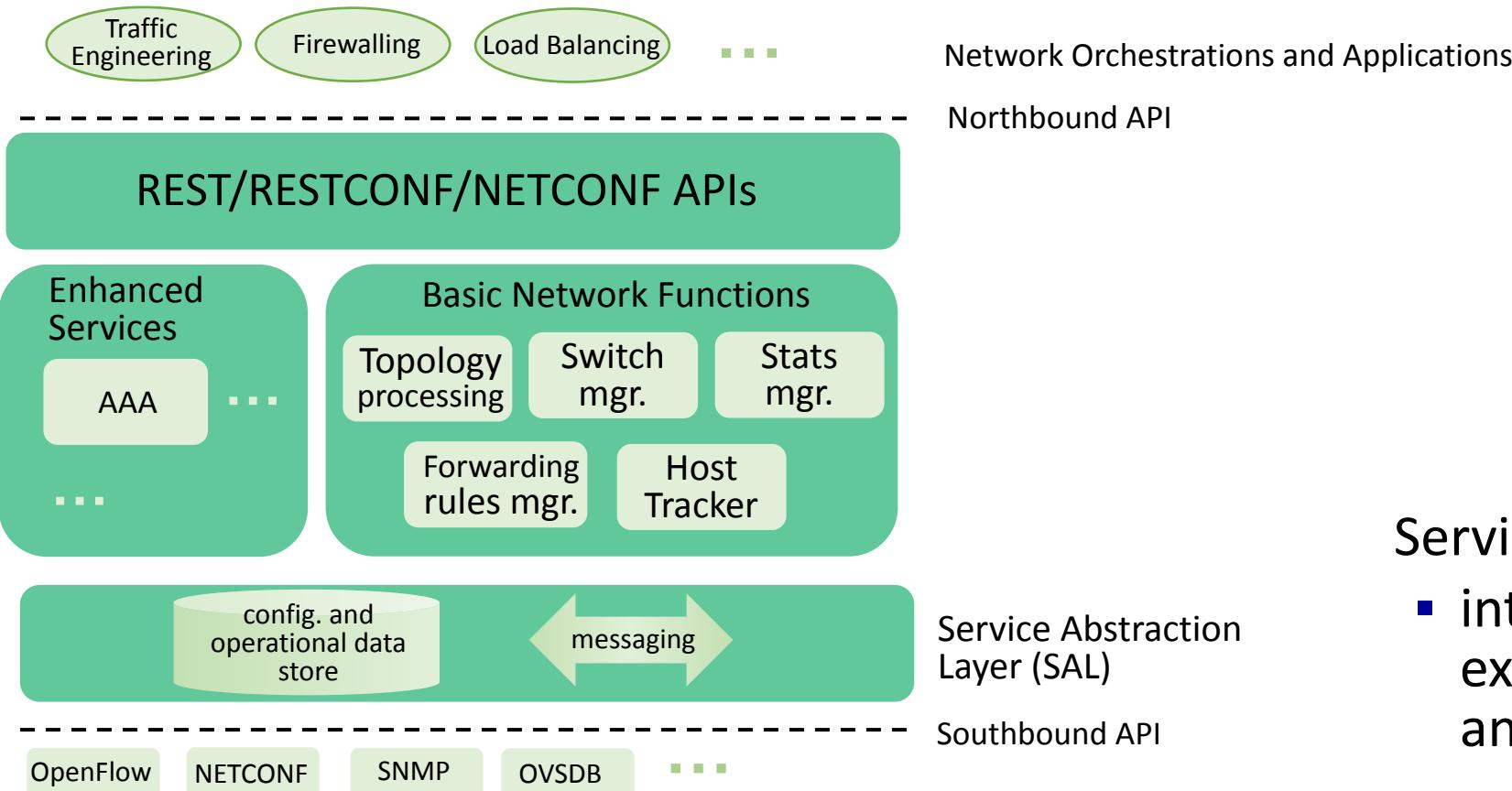
- ① S1, experiencing link failure uses OpenFlow port status message to notify controller
- ② SDN controller receives OpenFlow message, updates link status info
- ③ Dijkstra's routing algorithm application has previously registered to be called whenever link status changes. It is called.
- ④ Dijkstra's routing algorithm access network graph info, link state info in controller, computes new routes

# SDN: control/data plane interaction example



- ⑤ link state routing app interacts with flow-table-computation component in SDN controller, which computes new flow tables needed
- ⑥ controller uses OpenFlow to install new tables in switches that need updating

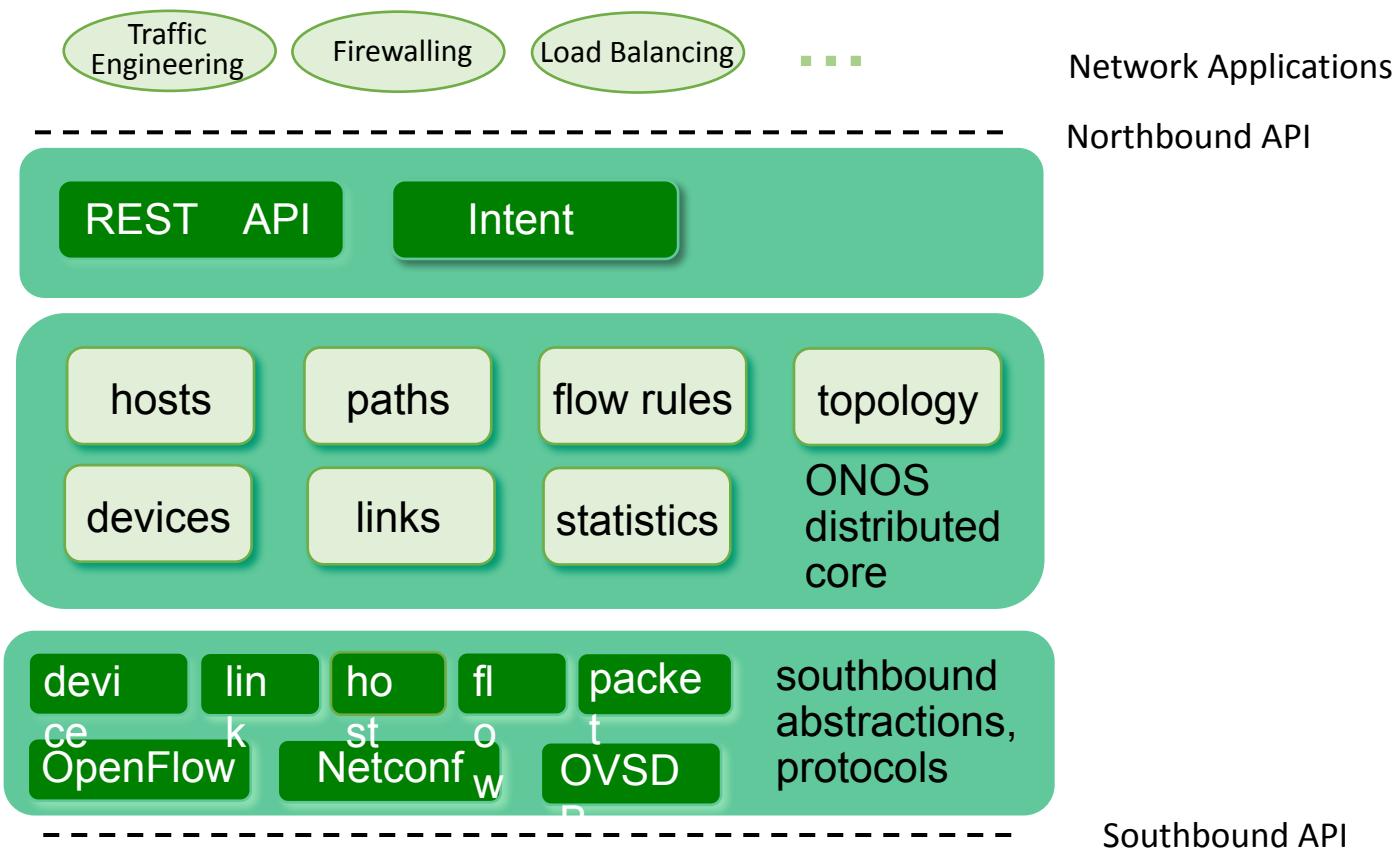
# OpenDaylight (ODL) controller



**Service Abstraction Layer:**

- interconnects internal, external applications and services

# ONOS controller



- control apps separate from controller
- intent framework: high-level specification of service: what rather than how
- considerable emphasis on distributed core: service reliability, replication performance scaling

# SDN: selected challenges

- hardening the control plane: dependable, reliable, performance-scalable, secure distributed system
  - robustness to failures: leverage strong theory of reliable distributed system for control plane
  - dependability, security: “baked in” from day one?
- networks, protocols meeting mission-specific requirements
  - e.g., real-time, ultra-reliable, ultra-secure
- Internet-scaling: beyond a single AS
- SDN critical in 5G cellular networks

# SDN and the future of traditional network protocols

- SDN-computed versus router-computer forwarding tables:
  - just one example of logically-centralized-computed versus protocol computed
- one could imagine SDN-computed congestion control:
  - controller sets sender rates based on router-reported (to controller) congestion levels



How will implementation of network functionality (SDN versus protocols) evolve?



# Network layer: “control plane” roadmap

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- **Internet Control Message Protocol**



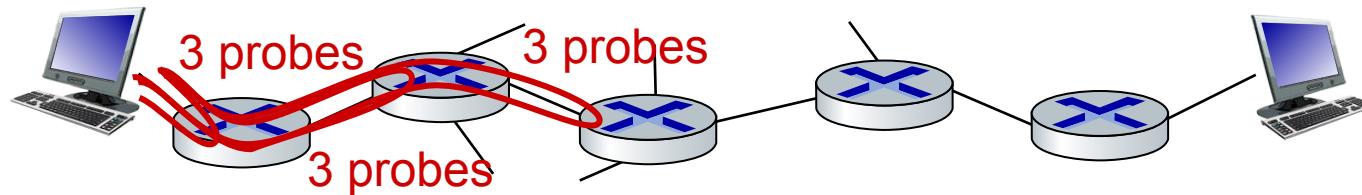
- network management, configuration
  - SNMP
  - NETCONF/YANG

# ICMP: internet control message protocol

- used by hosts and routers to communicate network-level information
  - error reporting: unreachable host, network, port, protocol
  - echo request/reply (used by ping)
- network-layer “above” IP:
  - ICMP messages carried in IP datagrams
- *ICMP message*: type, code plus first 8 bytes of IP datagram causing error

Type	Code	description
0	0	echo reply (ping)
3	0	dest. network unreachable
3	1	dest host unreachable
3	2	dest protocol unreachable
3	3	dest port unreachable
3	6	dest network unknown
3	7	dest host unknown
4	0	source quench (congestion control - not used)
8	0	echo request (ping)
9	0	route advertisement
10	0	router discovery
11	0	TTL expired
12	0	bad IP header

# Traceroute and ICMP



- source sends sets of UDP segments to destination
  - 1<sup>st</sup> set has TTL =1, 2<sup>nd</sup> set has TTL=2, etc.
- datagram in *n*th set arrives to *n*th router:
  - router discards datagram and sends source ICMP message (type 11, code 0)
  - ICMP message possibly includes name of router & IP address
- when ICMP message arrives at source: record RTTs

## stopping criteria:

- UDP segment eventually arrives at destination host
- destination returns ICMP “port unreachable” message (type 3, code 3)
- source stops

# Network layer: “control plane” roadmap

- introduction
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- network management, configuration
  - SNMP
  - NETCONF/YANG

# What is network management?

- autonomous systems (aka “network”): 1000s of interacting hardware/software components
- other complex systems requiring monitoring, configuration, control:
  - jet airplane, nuclear power plant, others?

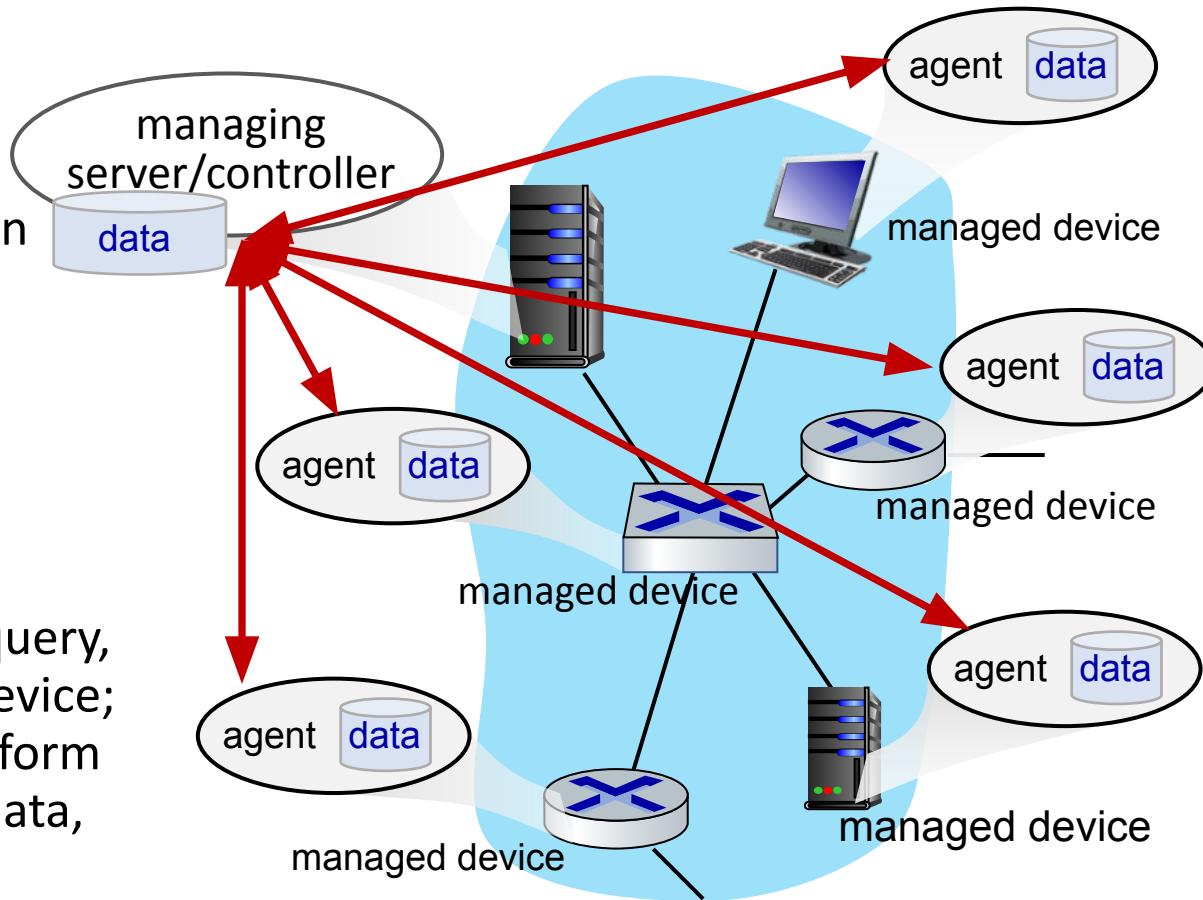


"Network management includes the deployment, integration and coordination of the hardware, software, and human elements to monitor, test, poll, configure, analyze, evaluate, and control the network and element resources to meet the real-time, operational performance, and Quality of Service requirements at a reasonable cost."

# Components of network management

**Managing server:**  
application, typically  
with network  
managers (humans) in  
the loop

**Network  
management  
protocol:** used by  
managing server to query,  
configure, manage device;  
used by devices to inform  
managing server of data,  
events.



**Managed device:**  
equipment with manageable,  
configurable hardware,  
software components

**Data:** device “state”  
configuration data,  
operational data,  
device statistics

# Network operator approaches to management

## CLI (Command Line Interface)

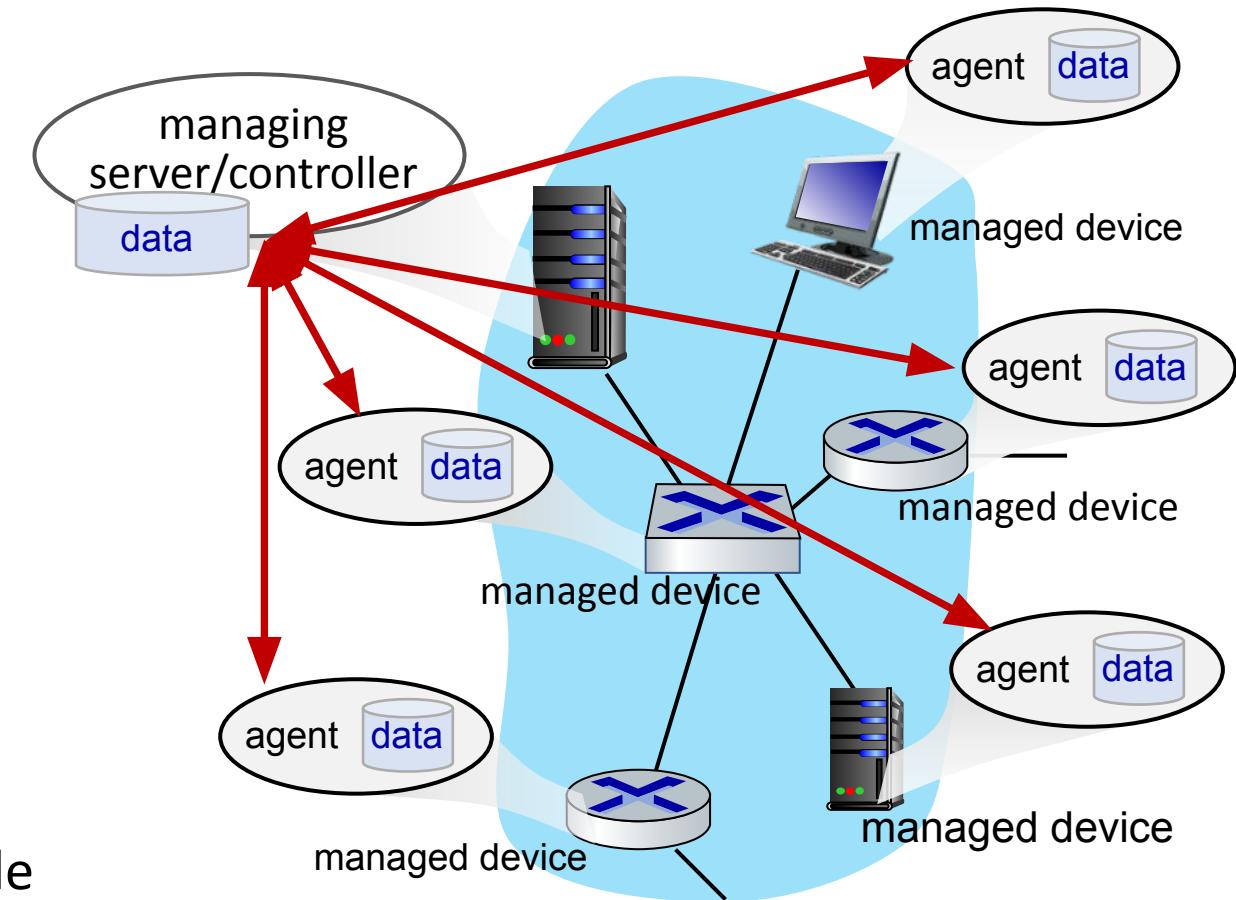
- operator issues (types, scripts) direct to individual devices (e.g., via ssh)

## SNMP/MIB

- operator queries/sets devices data (MIB) using Simple Network Management Protocol (SNMP)

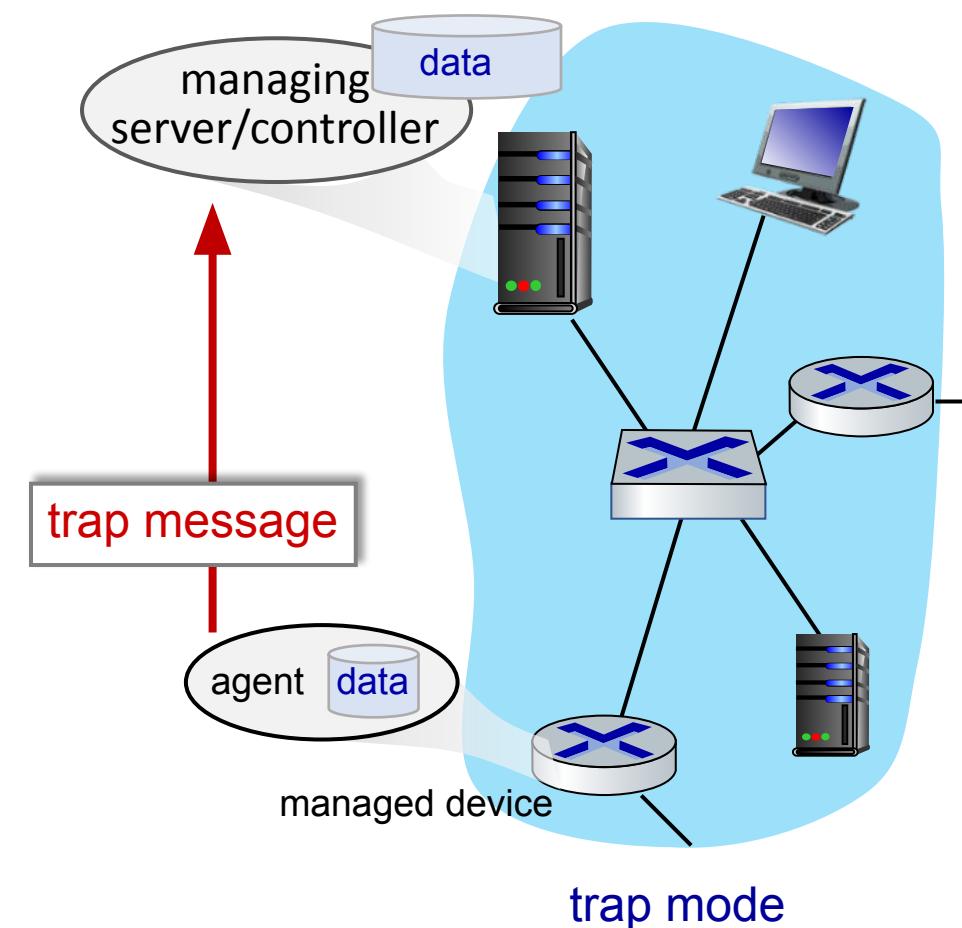
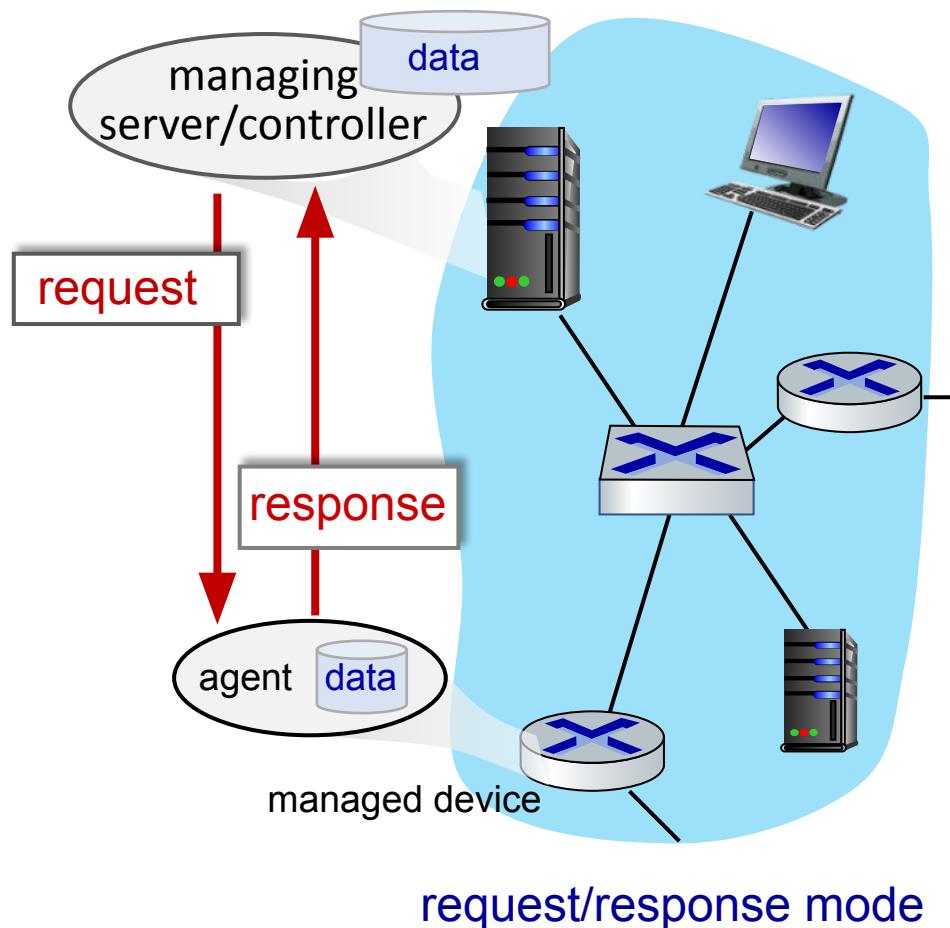
## NETCONF/YANG

- more abstract, network-wide, holistic
- emphasis on multi-device configuration management.
- YANG: data modeling language
- NETCONF: communicate YANG-compatible actions/data to/from/among remote devices



# SNMP protocol

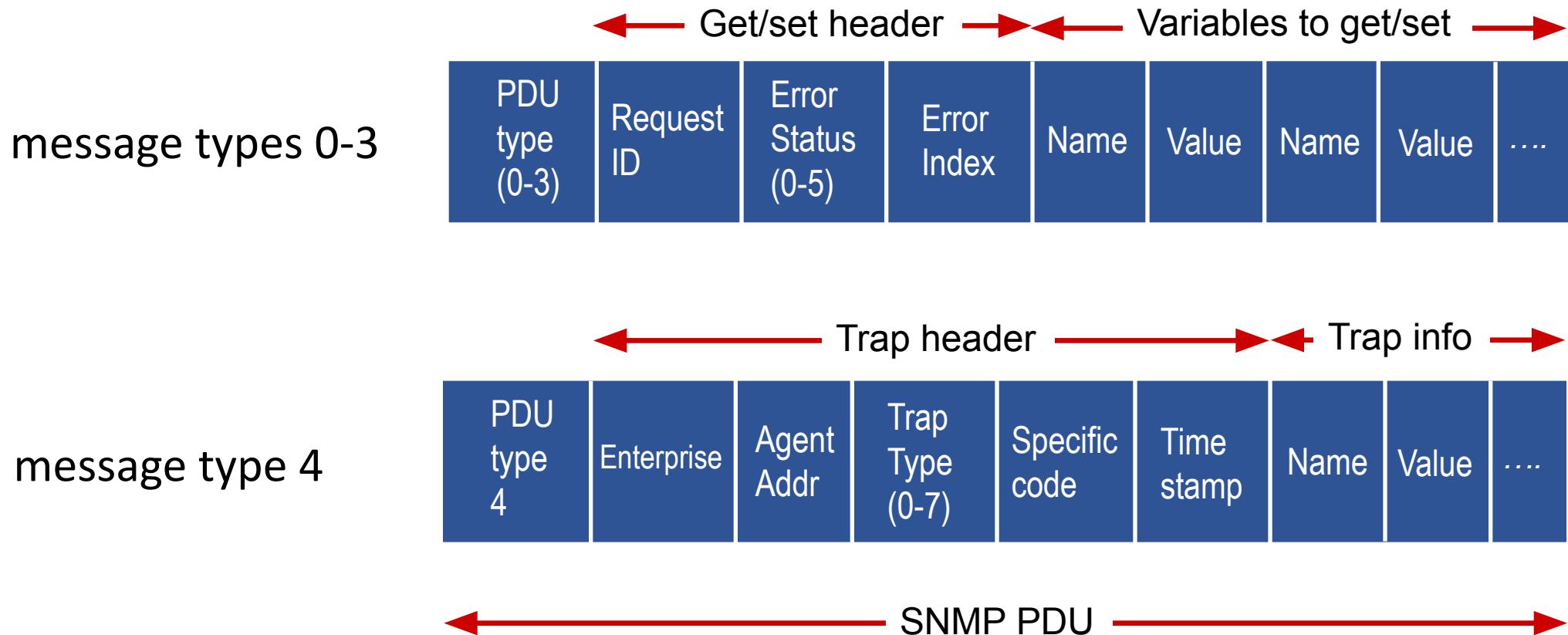
Two ways to convey MIB info, commands:



# SNMP protocol: message types

Message type	Function
GetRequest GetNextRequest GetBulkRequest	manager-to-agent: “get me data” (data instance, next data in list, block of data).
SetRequest	manager-to-agent: set MIB value
Response	Agent-to-manager: value, response to Request
Trap	Agent-to-manager: inform manager of exceptional event

# SNMP protocol: message formats



# SNMP: Management Information Base (MIB)

- managed device's operational (and some configuration) data
- gathered into device **MIB module**
  - 400 MIB modules defined in RFC's; many more vendor-specific MIBs
- **Structure of Management Information (SMI):** data definition language
- example MIB variables for UDP protocol:

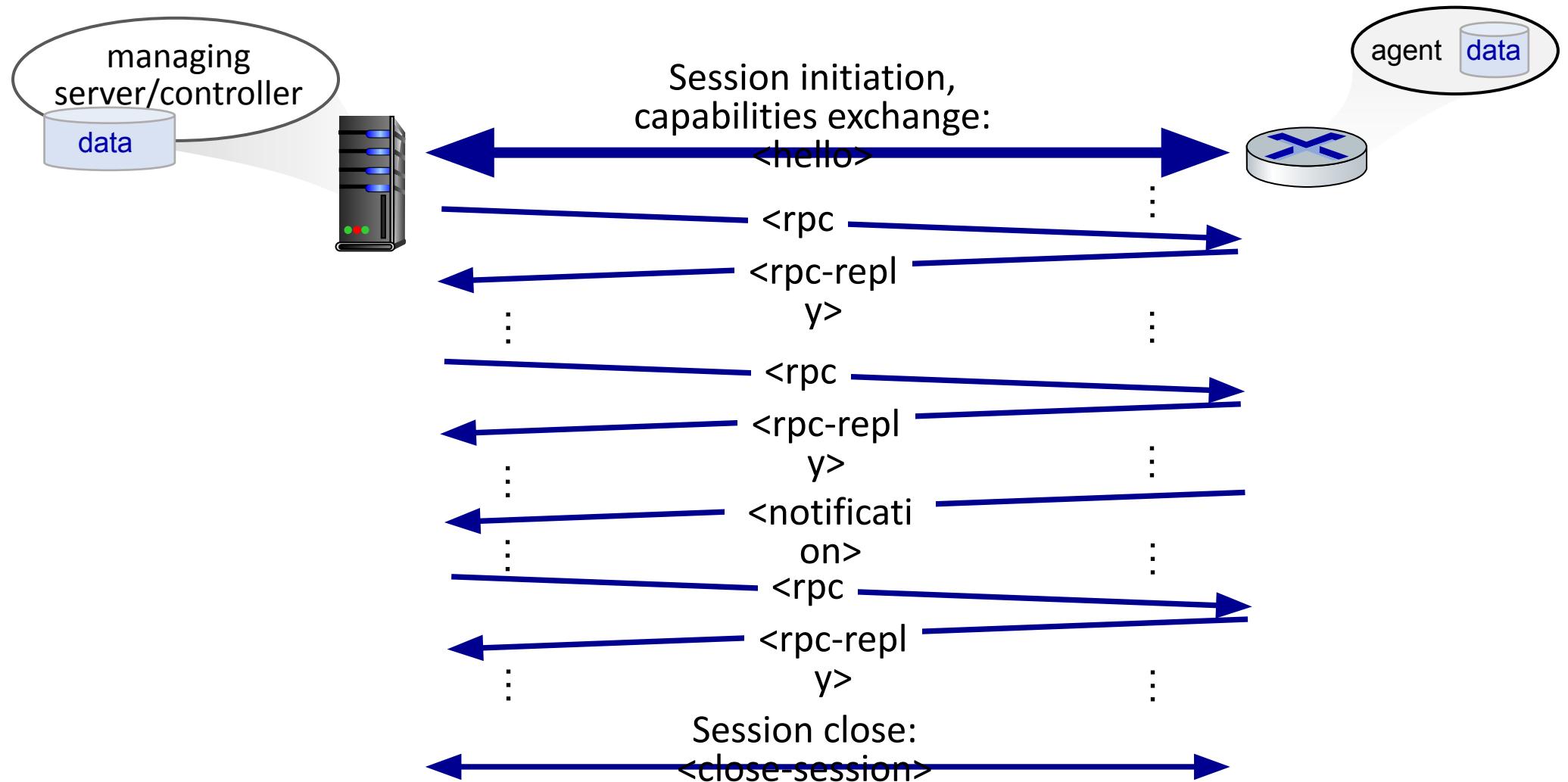


Object ID	Name	Type	Comments
1.3.6.1.2.1.7.1	UDPIInDatagrams	32-bit counter	total # datagrams delivered
1.3.6.1.2.1.7.2	UDPNoPorts	32-bit counter	# undeliverable datagrams (no application at port)
1.3.6.1.2.1.7.3	UDInErrors	32-bit counter	# undeliverable datagrams (all other reasons)
1.3.6.1.2.1.7.4	UDPOutDatagrams	32-bit counter	total # datagrams sent
1.3.6.1.2.1.7.5	udpTable	SEQUENCE	one entry for each port currently in use

# NETCONF overview

- **goal:** actively manage/configure devices network-wide
- operates between managing server and managed network devices
  - actions: retrieve, set, modify, activate configurations
  - **atomic-commit** actions over multiple devices
  - query operational data and statistics
  - subscribe to notifications from devices
- remote procedure call (RPC) paradigm
  - NETCONF protocol messages encoded in XML
  - exchanged over secure, reliable transport (e.g., TLS) protocol

# NETCONF initialization, exchange, close



# Selected NETCONF Operations

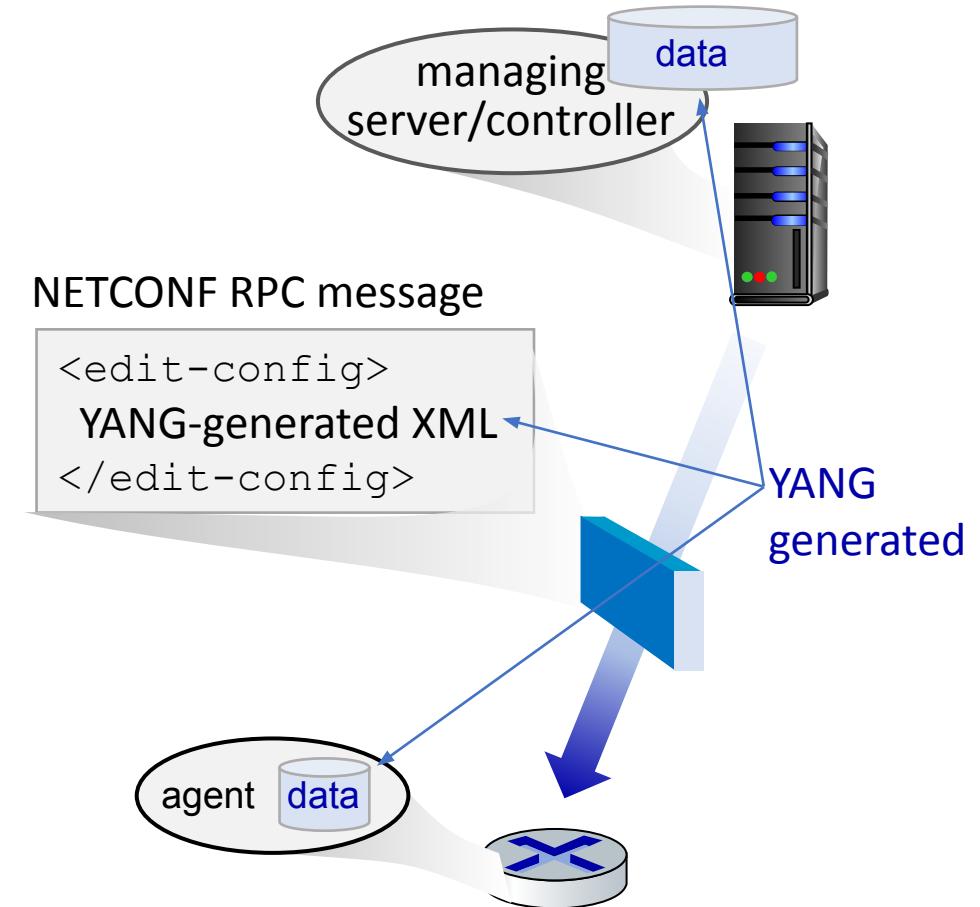
NETCONF	Operation Description
<get-config>	Retrieve all or part of a given configuration. A device may have multiple configurations.
<get>	Retrieve all or part of both configuration state and operational state data.
<edit-config>	Change specified (possibly running) configuration at managed device. Managed device <rpc-reply> contains <ok> or <rpcerror> with rollback.
<lock>, <unlock>	Lock (unlock) configuration datastore at managed device (to lock out NETCONF, SNMP, or CLIs commands from other sources).
<create-subscription>, <notification>	Enable event notification subscription from managed device

# Sample NETCONF RPC message

```
01 <?xml version="1.0" encoding="UTF-8"?>
02 <rpc message-id="101" note message id
03   xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
04     <edit-config>    change a configuration
05       <target>
06         <running/>  change the running configuration
07       </target>
08     <config>
09       <top xmlns="http://example.com/schema/
10         1.2/config">
11           <interface>
12             <name>Ethernet0/0</name>  change MTU of Ethernet 0/0 interface to 1500
13             <mtu>1500</mtu>
14           </interface>
15         </top>
16       </config>
17     </edit-config>
18   </rpc>
```

# YANG

- data modeling language used to specify structure, syntax, semantics of NETCONF network management data
  - built-in data types, like SMI
- XML document describing device, capabilities can be generated from YANG description
- can express constraints among data that must be satisfied by a valid NETCONF configuration
  - ensure NETCONF configurations satisfy correctness, consistency constraints



# Network layer: Summary

we've learned a lot!

- approaches to network control plane
  - per-router control (traditional)
  - logically centralized control (software defined networking)
- traditional routing algorithms
  - implementation in Internet: OSPF , BGP
- SDN controllers
  - implementation in practice: ODL, ONOS
- Internet Control Message Protocol
- network management

*next stop: link layer!*

# Network layer, control plane: Done!

- introduction
- routing protocols
  - link state
  - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
  - SNMP
  - NETCONF/YANG

# **Additional Chapter 5 slides**

# Distance vector: another example

	cost to		
	x	y	z
from	0	2	7
x	∞	∞	∞
y	∞	∞	∞
z	∞	∞	∞

	cost to		
	x	y	z
from	0	2	3
x	2	0	1
y	7	1	0
z			

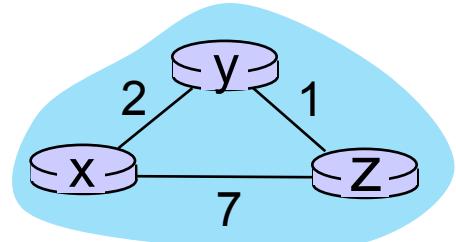
	cost to		
	x	y	z
from	∞	∞	∞
x	2	0	1
y	∞	∞	∞
z	∞	∞	∞

	cost to		
	x	y	z
from	∞	∞	∞
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

$$\begin{aligned}
 D_x(z) &= \min\{c_{x,y} + D_y(z), c_{x,z} + D_z(z)\} \\
 &= \min\{2+1, 7+0\} = 3
 \end{aligned}$$

$$\begin{aligned}
 D_x(y) &= \min\{c_{x,y} + D_y(y), c_{x,z} + D_z(y)\} \\
 &= \min\{2+0, 7+1\} = 2
 \end{aligned}$$

► time



# Distance vector: another example

