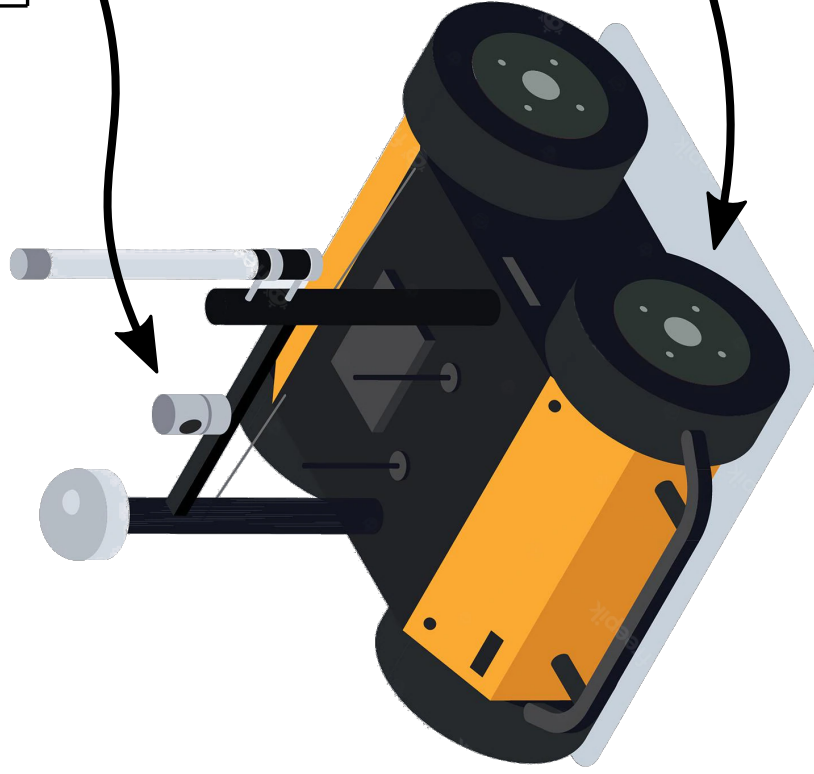


Map



Laser scanner

Search Algorithm

path following

Speed control