robot.py

```python
def get_path(start, end):
    return make_plan(start, end)

def follow_path(robot, path):
    for point in path:
        robot.move_to(point)
```

Algorithm

```python
class Robot:
    def send_speed(self, v, w):
        serial.write(v)
        serial.write(w)
```

Interface with Hardware