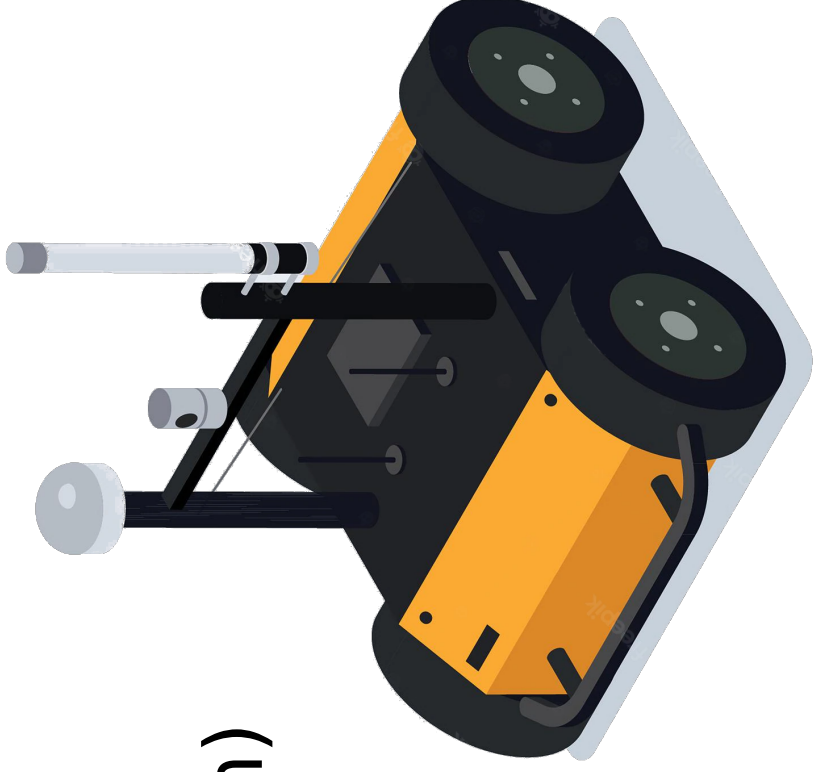


Mapping

Path Planning  
(search algorithm)



Localization

Path following

Robot interface