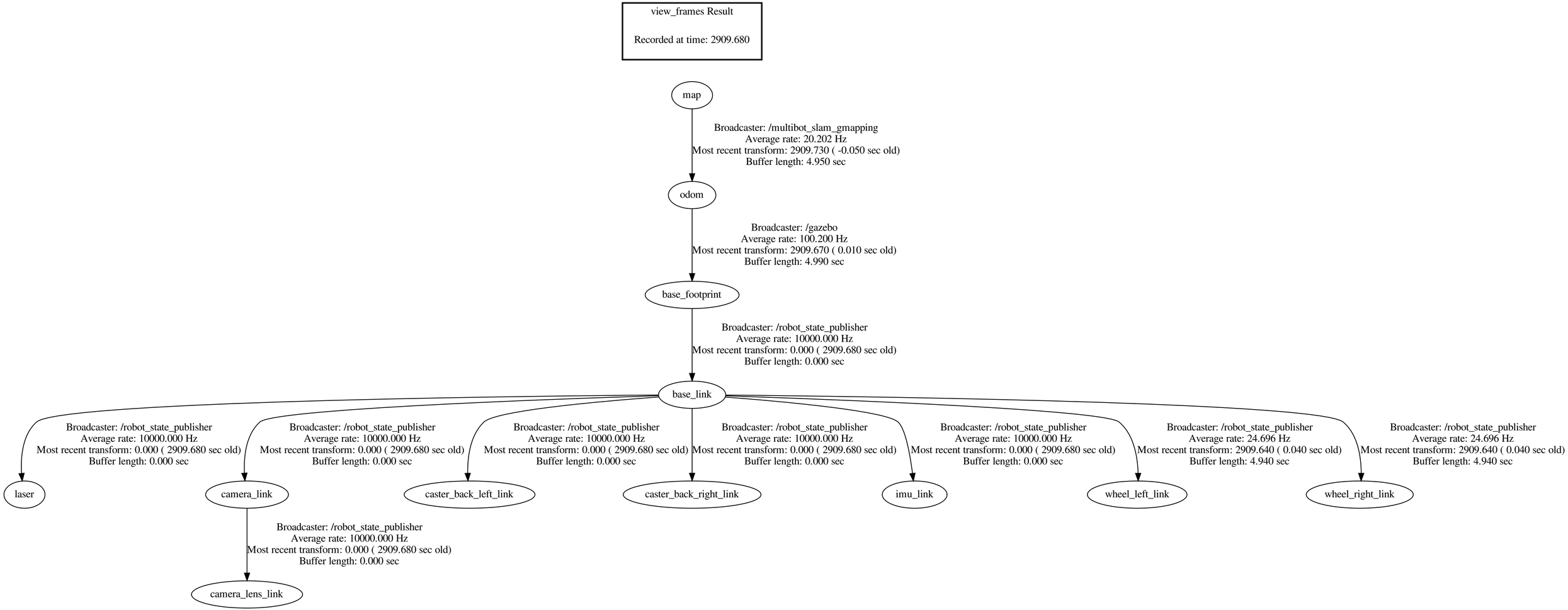
view_frames Result
Recorded at time: 2909.680
map
Broadcaster: /multibot_slam_gmapping
Average rate: 20.202 Hz
Most recent transform: 2909.730 (-0.050 sec old)
Buffer length: 4.950 sec
odom
Broadcaster: /gazebo
Average rate: 100.200 Hz
Most recent transform: 2909.670 (0.010 sec old)
Buffer length: 4.990 sec
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
laser
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
camera_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
camera_lens_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
caster_back_left_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
caster_back_right_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2909.680 sec old)
Buffer length: 0.000 sec
imu_link
Broadcaster: /robot_state_publisher
Average rate: 24.696 Hz
Most recent transform: 2909.640 (0.040 sec old)
Buffer length: 4.940 sec
wheel_left_link
Broadcaster: /robot_state_publisher
Average rate: 24.696 Hz
Most recent transform: 2909.640 (0.040 sec old)
Buffer length: 4.940 sec
wheel_right_link