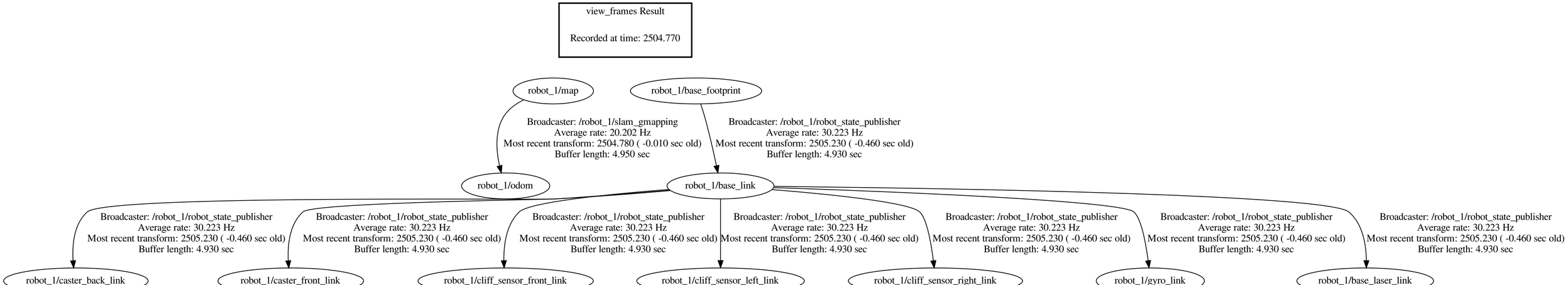
view_frames Result
Recorded at time: 2504.770
robot_1/map
robot_1/base_footprint
Broadcaster: /robot_1/slam_gmapping
Average rate: 20.202 Hz
Most recent transform: 2504.780 (-0.010 sec old)
Buffer length: 4.950 sec
Broadcaster: /robot_1/robot_state_publisher
Average rate: 30.223 Hz
Most recent transform: 2505.230 (-0.460 sec old)
Buffer length: 4.930 sec
robot_1/odom
robot_1/base_link
Broadcaster: /robot_1/robot_state_publisher
Average rate: 30.223 Hz
Most recent transform: 2505.230 (-0.460 sec old)
Buffer length: 4.930 sec
robot_1/caster_back_link
robot_1/caster_front_link
robot_1/cliff_sensor_front_link
robot_1/cliff_sensor_left_link
robot_1/cliff_sensor_right_link
robot_1/gyro_link
robot_1/base_laser_link