# Haseeb Shaikh

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#### EDUCATION

### McMaster University

Hamilton, ON

B.Eng, Computer Engineering (ECE)

Expected Graduation: April 2027

- Deans' Honour List Scholar | GPA: 3.79/4.0
- Relevant Coursework: Data Structures and Algorithms, Principles of Programming, Logic Design, Microprocessor and Embedded Systems Design, Circuits and Waves, Electronic Devices and Circuits

### EXPERIENCE

Sales Associate

August 2023 – Present

Columbia Sportswear Company

Halton Hills, ON

- $\bullet$  Assisted 100+ customers per shift and accurately processed up to 300 transactions daily.
- Consistently exceeded sales targets, personally generating \$2,000+ in single shifts.
- Managed inventory flow, restocking 100+ SKUs per day using store systems.
- Received **positive customer reviews** and **employee appreciation cards** from store managers.

Team Member

Jan. 2025 – Present

McMaster Robo Sub

Remote

- Researched **pressurization systems** for underwater enclosures in AUVs.
- Assisted in evaluating material trade-offs in mechanical design.
- Contributed to integration discussions with **embedded systems**.

#### Projects

 $\textbf{CampConnect} \mid \textit{Node.js}, \textit{Express.js}, \textit{MongoDB}, \textit{Mongoose}, \textit{Cloudinary}, \textit{MapTiler}, \textit{Passport.js}, \textit{Render}, \textit{Bootstrap}$ 

- Built a CRUD-based web platform enabling users to browse, create, and manage campground listings.
- Implemented secure user login and role-based authorization to protect user-generated content.
- Integrated MongoDB Atlas for scalable cloud data storage and Cloudinary for image upload and delivery.
- Designed **dynamic routes** and templated views for a seamless, user-friendly experience.

Embedded Spatial Mapping Project | C, Python, Assembly, Microcontroller Systems

- Developed a microcontroller-based system for 360° spatial scanning using stepper motor and ToF sensor.
- Programmed data acquisition and control logic in C with I2C/UART protocols for real-time measurements.
- Utilized Python to generate **3D models** from raw sensor measurements, enabling detailed spatial visualization.
- Optimized system performance, improving scan accuracy and speed by over 50% through testing and calibration.

**Snake Game** | Visual Studio, C++, Object-Oriented Programming (OOP)

- Developed a C++ version of the classic Snake Game by fully utilizing OOP principles.
- Implemented advanced gameplay features, including dynamic speed control, to enhance interactivity and provide a more engaging user experience.
- Designed and optimized the **user interface** to improve usability, enhancing responsiveness and interactivity through **iterative testing and development**.
- Applied advanced debugging and memory management, ensuring zero memory leaks.

Revenge of the Recycling System | PyCharm, Python, Rasberry Pi, Autodesk Inventor, PrusaSlicer

- Designed an **automated sorting system** for the **Quanser Q-arm robotic platform** by developing Python code, achieving a **40% increase in sorting speed** and a **20% reduction in error rates**.
- Designed and simulated hopper-lifting mechanism in Autodesk Inventor, then prototyped with 3D printing.
- Tested robotic workflows in a digital environment using PyCharm for code development.

## TECHNICAL SKILLS

Programming Languages: Python, Java, C/C++, HTML, CSS, JavaScript, Assembly, HDL (Verilog), Matlab Programming Environments: Visual Studio, IDLE, NetBeans, Quartus, Keil uVision5

Developer Tools: Git, GitHub, AutoDesk Inventor, AutoCAD, Solid Works, PrusaSlicer (3D Printing), Ansys Granta Edu, PSpice, WaveForms - Digilent Reference, React.js, Express.js, Bootstrap, Bulma, Node.js, MongoDB, Mongoose, EJS, Passport.js, Helmet, Cloudinary, Render, MS Office

Lab Equipment: MSP432E401Y Microcontroller, Oscilloscopes, Multimeters, Function Generators, etc...