

Disparity Map

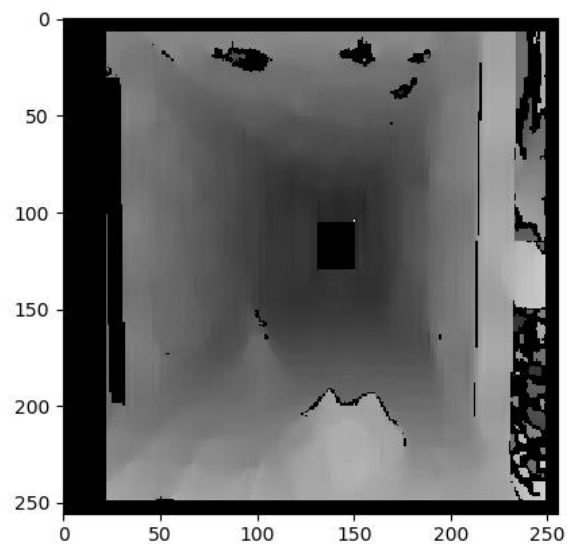
A **disparity map**, referred to as a depth map, is an image which contains depth information of every pixel stored in it. The term disparity in stereo vision refers to the apparent shift in pixel or motion in a pair of stereo images



Image_left



Image_right



Disparity Map