$\underset{\text{UCL}}{\text{MECH0007 Topic Notes}}$

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Contents

Chapter 1

Course Outline

1.1 Coursework and exam

- Metallography and Microstructure Lab week (week 26), held in Materials Lab Sub Basement Roberts.
- Manufacturing Case Study Friday afternoon consultancy slots (14:30 onwards), Materials Lab Sub Basement Roberts.
- One three hour exam, consistent of two sections: MCQ (sort of?) and conventional. Timetabled revision slots in summer term.

Add notes about the following topics:

- Cracking welding vs riveting, arrestment of cracks in a material.
- Casting and forging in context of manufacturing processes, perocity of a liquid vs a solid.
- Crystalline and amorphous solids materials which are one or the other, both or both in different capacities, look into molecular structure of each, crystallinity is a degree of structure which affects its properties.
- Plasticity and deformations in metals and other materials.

Structure - Property Relationship at the heart of all Material Science.

Manufacturing (Processing)	
Structure	Property

${\it MECH007}$ Topic Notes

Categories of materials - these all have different structures and hence properties.

- \bullet Metals
- Ceramics
- Polymers
- Composites a mix of the other three above (physical mix), provides an extra level of structure for scientists to work with.

Chapter 2

Properties of materials

2.1 Metals

2.1.1 General Properties

- High electrical conductivity "thermal".
- Heavy and plastically deformable.
 - Plastic permanent change in dimension.
- Shiny when polished.

All of these properties are a function of the atomic bonding ("metallic bond"). A metallic bond is traditionally thought to be a sea of delocalised electrons "orbiting" a regular array of ions. A regular array is known as a crystal. In this structure, we see repulsive and attractive forces from the atoms and subatomic particles. These are all balanced and thus in equilibrium. The interatomic distance can be defined as a_0 . The interatomic distance can be modelled as a spring. Initially a tensile (or a compressive) force will generate deformation and thus a_0 but will attempt to restore to its original shape; i.e. the deformation is recoverable. This is the definition of elastic behaviour.

Beyond a certain deflection/deformation, *permanent* deformation is achieved. When the deforming force is removed, only some of the deformation is recovered (the elastic portion) and the plastic deformation remains.

2.1.2 Mechanisms of plastic deformation in metals

Slip

this is where planes of atoms (ions) slip/slide past each other. Planes orientated at 45° to the tensile of compressive load will slip first. Slip (under tension) gener-

ates lengthening of the specimen. However, the *volume* of the specimen does not *change* i.e. the intermolecular distance stays the same. This means that under a tensile force, the specimen becomes *thinner*. Under compression, metals become *shorter/fatter*.

2.2 Polymers

2.2.1 Thermoplastics and Thermosets

General Properties

- Thermally and electrically poor conductors.
- Low density.
- Poor reflectors.
- Often flexible (low stiffness).
- Often deformable.
 - "Slip" is possible.
 - Behave plastically.

These properties (including the mechanical properties) are due to the *bonding* occurring in polymers. These bonds are *covalent* within a polymer molecule but the existence of secondary bonding (e.g. Van der Waals and H bonding) are very influential on the properties.

Polyethene (or PE) is a chain structure molecule made up of carbon and hydrogen atoms. This structure is thermoplastic or thermopolymer. Often these chains can be 100,000 carbon atoms long. The carbon-carbon bond is tetrahedral in reality. If such a polymer was to be stretched out linearly, its length would be approximately $20 \, \mu m$. Each molecule is stable i.e. all the covalent bonds are satisfied but there must be interaction between molecules; else PE would have no physical strength. Hence, intermolecular bonding must be present. There will be a degree of mechanical interaction with such "massive" molecules but secondary bonds (dipole interactions) dominate.

Not all polymers have this structure e.g. thermosets. Epoxy resin such as ure-aformaldehyde are thermosetting. The molecular structure of thermosets are similar to thermoplastics. However, there are real covalent bonds between the chains instead of secondary bonding. These are called crosslinks. Crosslinks are created through chemical reaction during the polymerisation process. This creates a new substance and have no chemical formula. Thermoplastics are polymerised at the factory. Thermosets are sold as two products (pre-polymers), which are to be reacted together to make the thermoset. As a consequence of the crosslinks, the properties differ to those of thermoplastics such as being stiffer, harder and they can also be stronger. They are also brittle (which can lead to weak behaviour).

2.2.2 Elastomers

General Properties

- Massive elastic deformation.
- No plastic deformation.
- Non recyclable (by melting).

Elastomers are effectively a subset of thermosets; they contain covalent crosslinks (not as many) and thus cannot be melted once formed. The crosslinks permit freedom of deformation (movement) of the carbon chains but ultimately restrict it and thereby stop plastic deformation. The degree of crosslinking strongly affects the stiffness of the elastomer. The stiffness increases with the number of crosslinks.

2.2.3 Ceramics

General Properties

• Inorganic compounds, usually between a metallic and non metallic element.

Alumina (Al_2O_3) , silica (Quartz) (SiO_2) and silicon carbide (SiC) (hard, abrasive) are all examples of ceramics.

2.3 Properties

2.3.1 Stress and strain

Stress a.k.a load, strain a.k.a deflection. Doubling the stress will double the deflection. Deflection will depend on the specimen size. In order to compare these properties, we need to normalise for differences in dimension e.g. $\delta L/L = \epsilon$ - strain. For stress, we divide the force by the area its being applied over i.e. $F/A = \sigma$. Strain is sometimes represented as percentage.

Note: stress is a variable. Strength is not, it is a fixed property of a material.

2.3.2 Hardness

Often quoted for metals as a design parameter as it is easy to measure and can be related to strength. Dimensions of indent can be related to the strength in compression, which can be measured in various ways. In the UK, Vickers hardness H_v (triangular indenter) is a test for the hardness of the material. Other systems, such

as Rockwell and Brinell hardness (circular indenter) exist. Scratching a specimen can also be used to test the hardness of a material e.g. Mohs scale, where diamond is at 10 and arbitrary hardness at the other end of the scale.

Indentation techniques are not suitable for brittle materials and is normally used for metals as they slip (plastically deform). They are also difficult to use on elastomers, where we use abrasion test or "bouncing ball" tests.

2.3.3 Stiffness

Also known as - Elastic Modulus, Modulus of Elasticity or the Young's Modulus (tension). May also be referred to as the opposite of floppiness. Refers to the flexibility of a material. Units are in Pascals Pa or N m⁻². The following equation gives us the Young's Modulus of a material.

$$E = \frac{\sigma}{\epsilon} \tag{2.1}$$

This equation relates the normalised load and its normalised deflection. It measures how far something deflects per unit load. These only apply in the elastic regime of a material's behaviour i.e. only for elastic strain.

2.3.4 Strength

Defined as the stress required to "break" a material (there are different types of break, hence different strengths definable).

Tensile strength

Defined as the stress required to fracture a material in tension into two bits. Symbol used is σ_{UTS} , where UTS stands for ultimate tensile strength. This has units Pa.

Compressive strength

In most cases, this is similar to σ_{UTS} , but its often difficult to measure. This is because materials such as metals don't break into two pieces under a compressive force - they just squash. Other materials such as ceramics will shatter or crush at a specific load. Hence, a compressive strength is definable for such materials.

Metals and polymers often "fail" at much lower stresses than σ_{UTS} e.g. they will suffer plastic deformation before fracture. This is always less than σ_{UTS} , if slip can occur, slip will occur first - this is a form of failure. The stress at which this happens is called the yield strength σ_y , defined as the stress required to induce plasticity in a material.

In a ceramic, there is no easy mechanism for slip and thus no noticeable plastic deformation. We define σ_f or fracture strength for such materials. As there is no plasticity, $\sigma_{UTS} = \sigma_y = \sigma_f$.

2.3.5 Ductility

Defined as the degree of plastic deformation achievable in a material before it breaks into two/fractures. It is a materials parameter and so a strain (plastic strain to fracture). It is often seen as a percentage of strain. Often 0.1% for most metals and up to even 2000% for some polymers. Ductility is very important if we want to create/shape materials through plastic deformation - extrusion, drawing, forging, bending. Ceramics have almost no observable ductility (no slip). These need to be sintered from powder.

2.3.6 Toughness

Related to the work/energy required to fracture a material, the amount of "damage" a material can take before fracturing. Very different to strength - which is the force required to fracture. Strength and toughness are not absolutely related from an atomic viewpoint. The opposite of tough is brittle, where very little energy is required to fracture.

Fractured surfaces tend to be "clean" and fit back together again. Brittle is often confused with being 'weak' i.e. a low force to break. It is true that brittle materials often appear to be weak in practice but not necessarily intrinsically weak. They behave 'weakly' due to the presence of defects - some can be visible (scratches, cracks) while others can be minute (micro-cracking at the atomic level, porosity). Defects determine the failure load (stress) of brittle materials. These act as stress concentrators, raising the globally applied load to much higher values on a local level, so much so that local bonds are broken i.e. the intrinsic strength is exceeded. so failure occurs at an apparently lower stress. Manufacturing has a huge role to play in determining the presence and severity of defects. However, if there are mechanisms for plastic deformation e.g. slip, then as the stress rises at the defect, slip will begin to occur locally.

Note: "bad" stress concentrators are sharp and long e.g. cracks and holes (which are still stress concentrators, just not to the same degree). [...] the σ can quickly build up to that necessary to break the bonds at a crack tip (i.e. exceed theoretical strength). Long, deep cracks are more severe than shallower ones and sharp cracks are worse than rounded or blunt ones. Thus, on breaking A-B bond, the crack gets longer, σ 's concentration increases and the crack propagates uncontrollably (i.e. a brittle material).

In a 'tough' material, local stress concentrators exist, so σ_{global} rises ahead of the crack to reach the point at which *plastic* deformation occurs, such that yield will occur (slip (in metals) absorbs energy because work is consumed).

Slip can slow down a crack or stop it. This work is demanded from an external load in order for the crack to propagate. It can change the shape of σ 's concentration i.e. smooth it out. Slippage and sliding can open up a defect and extra surface area is generated (blunting). Thus, in a plastically deformable material, existing defects are tolerated (no longer critical to strength). These materials are described as tough.

2.3.7 Fatigue strength

The ability to resist failure under a cyclical load. Fatigue occurs at loads well below σ_{UTS} and can initiate and then propagate defects (principally cracks) to a point where they cause failure by fracture. Steels typically have a lifetime of $10^6 - 10^8$ cycles for typical loads. All materials 'suffer' fatigue failure, even though the internal mechanisms vary from category to category. The amplitude of the alternating stress is a factor. Low amplitudes favour many cycles before failure - 'long lifetime' but lifetime is stress dependent.

2.3.8 Other properties

- Cost
 - Dependent on the availability (rarity) of a material.
 - Manufacturing note: polymers are expensive in but but component cost is reduced due to ease of manufacturing.
- Corrosion resistance.
 - Rate of reaction with an environment. Most applicable to metals but polymers and ceramics also suffer from corrosion (to a degree).
- Abrasion resistance
 - The ability to avoid wear in components that are in sliding contact (bearings).
 - Usually, materials with high hardness is best for reducing wear but we must also consider frictional coefficients.
- Environmental 'credentials'
 - Recyclability and re-use. Rubber is a good example of something which is very hard to recycle.
 - Toxicity/waste.

2.3.9 Stress/strain responses

Many mechanical properties can either be measured, inferred or illustrated from a stress-strain response. We plot σ vs ϵ in tension. Doing such a test we are measuring force and deflection and using the dimensions of the specimen we can calculate σ/ϵ . Extension is measured using an extensometer (laser based or contact based). The

extensometer is placed across the gauge length (distance between the two necks of a dog bone shaped specimen). It measures $L + \Delta L$. The distance between the grips is also an alternative but this is inaccurate.

Deviation from linearity normally due to extending σ_y because metals are linearly elastic, caused by slip. Drop in σ required just before failure due to 'necking'. Local failure point, material will decrease in cross section. Necking is a random instability in the material; if at some point it gets longer faster than elsewhere. Due to the volume being conserved, specimen gets thinner. This raises the global stress applied such that further extension is focussed in this region. This is known as a positive feedback mechanism and the neck is the ultimate failure location. You can plot 'true stress' (and strain) which takes into account the decrease in cross section area.