

Engineering Mechanics: Statics in SI Units, 12e

5

Equilibrium of a Rigid Body

Chapter Objectives

- To develop the equations of equilibrium for a rigid body
- To introduce the concept of the free-body diagram for a rigid body
- To show how to solve rigid-body equilibrium problems using the equations of equilibrium

Chapter Outline

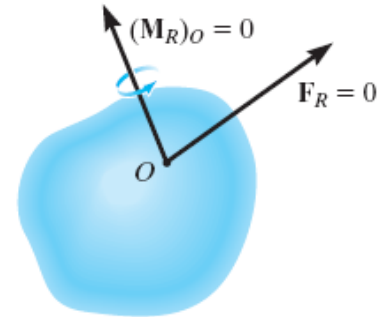
1. Conditions for Rigid Equilibrium
2. Support Reactions
3. Free-Body Diagrams
4. Equations of Equilibrium

5.1 Conditions for Rigid-Body Equilibrium

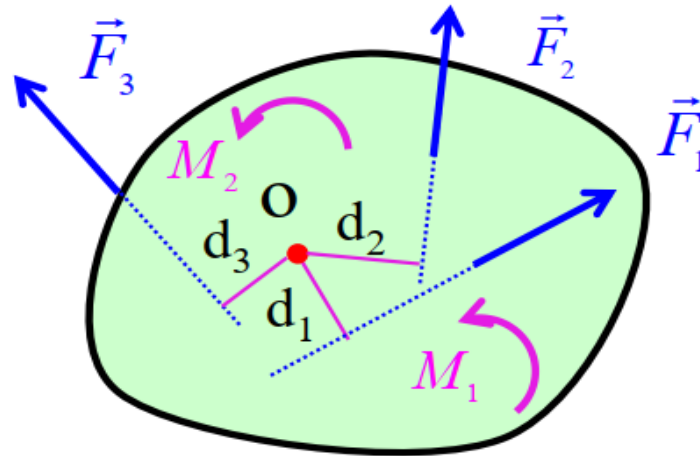
- When an object acted upon by a system of forces & moments is in equilibrium, the following conditions are satisfied:

- 1. The sum of the forces is zero:** $\sum \vec{F} = 0$

- 2. The sum of the moments about any point is zero:** $\sum \vec{M}_{any\ point} = 0$



5.1 Conditions for Rigid-Body Equilibrium



$$\vec{R} = \Sigma \vec{F} = 0$$
$$\vec{M}_o = 0$$

or

$$\Sigma F_x = 0$$
$$\Sigma F_y = 0$$
$$\Sigma M_o = 0$$

Necessary



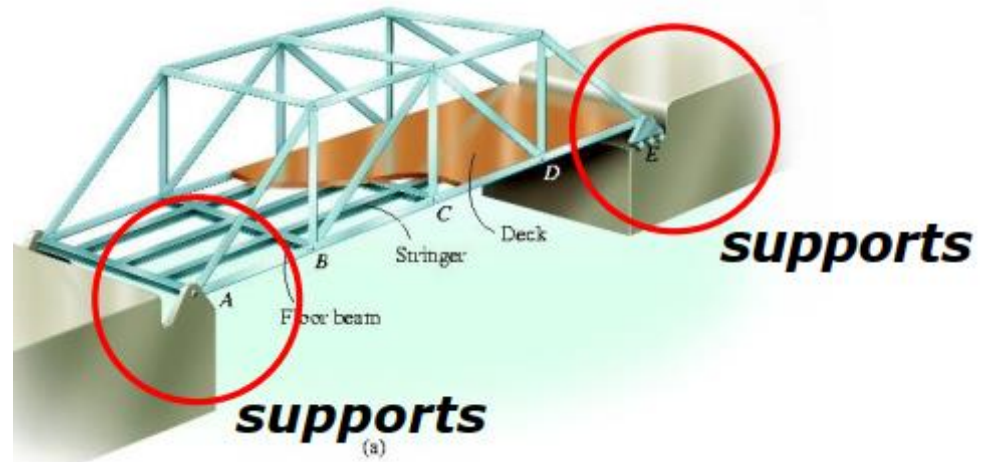
Sufficient

Body in Equilibrium

5.2 Support Reactions

Forces & couples exerted on an object by its supports are called reactions

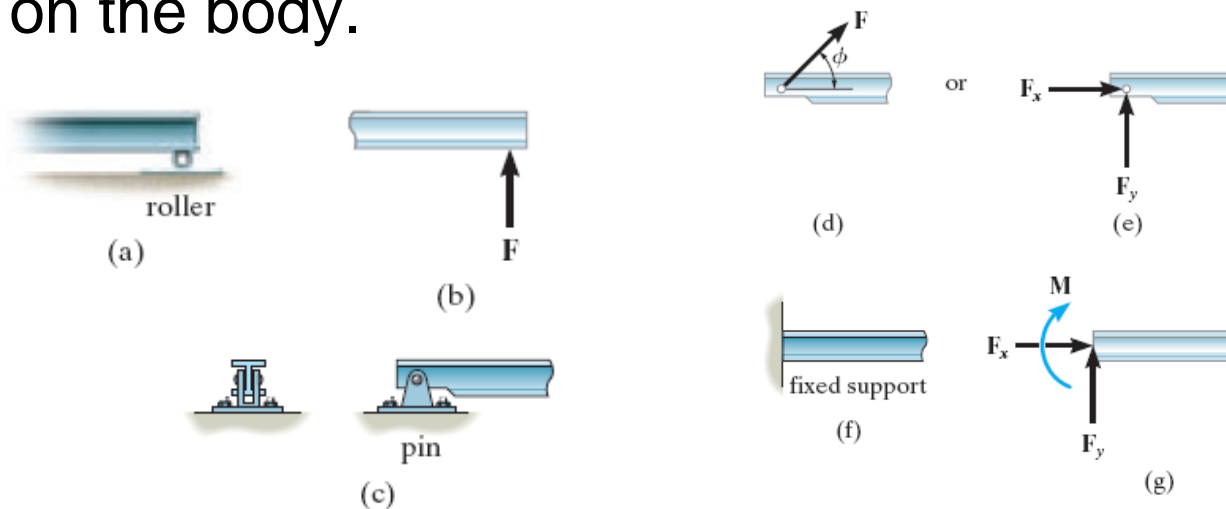
E.g. a bridge is held up by the reactions exerted by its supports.



5.2 Support Reactions

General Rules

- If a support prevents the translation of a body in a given direction, then a force is developed on the body in that direction.
- If rotation is prevented, a couple of moment is exerted on the body.



5.2 Support Reactions

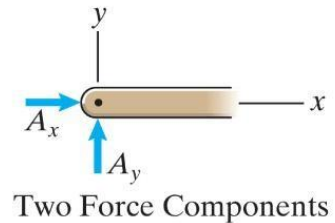
RESULTS Section 5.1 (Continued)

Supports

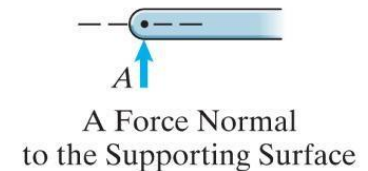
To draw the free-body diagram of an object, isolate it from its supports and show the *reactions*, the forces and moments that the supports may exert (Table 5.1).



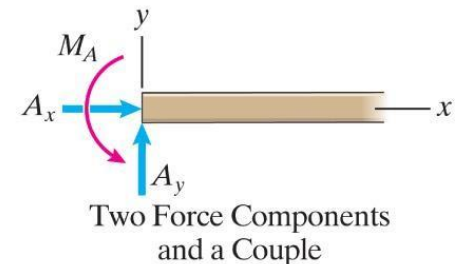
Pin Support



Roller Support



Fixed (Built-in) Support



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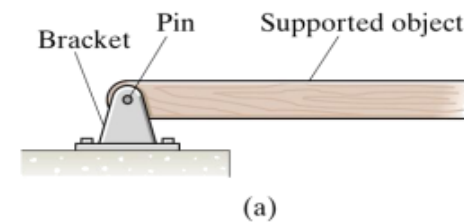
5.2 Support Reactions

- **The Pin Support:**

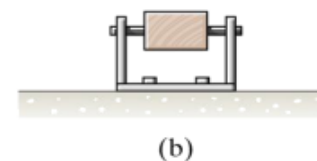
- Figure a: a pin support

- a bracket to which an object is attached by a smooth pin that passes through the bracket & the object

- Figure b: side view



SYMBOL USED IN NOTEBOOK



- The arrows indicate the directions of the reactions A_x and A_y



5.2 Support Reactions

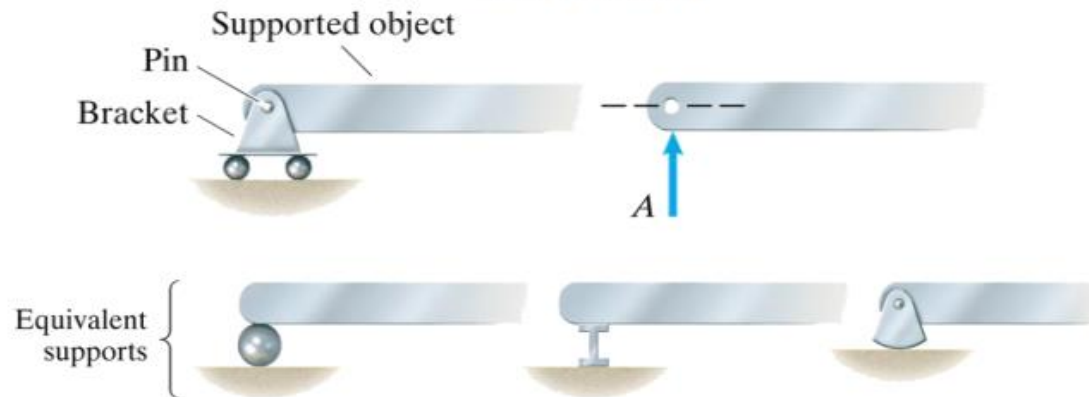
Examples of **Pin Support**
in real life



5.2 Support Reactions

The Roller Support

It can move freely in the direction parallel to the surface on which it rolls, it can't exert a force parallel to the surface but can exert a force normal (perpendicular) to this surface



- The arrow indicate the directions of the reaction **A**

SYMBOL USED IN NOTEBOOK



5.2 Support Reactions

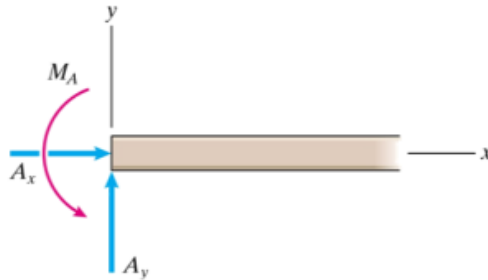
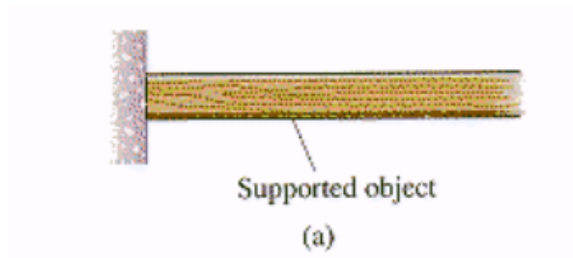
Examples of **Roller Support**
in real life



5.2 Support Reactions

• *The Fixed Support*

The fixed support shows the supported object literally built into a wall (built-in)



SYMBOL USED IN NOTEBOOK

A fixed support can exert

2 components of force

A_x

A_y

and a couple

M_A








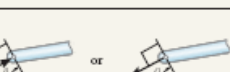





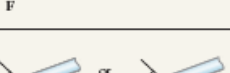
5.2 Support Reactions

Examples of **Fixed Support**
in real life


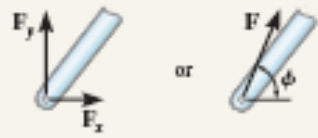






5.2 Support Reactions

TABLE 5-1 Supports for Rigid Bodies Subjected to Two-Dimensional Force Systems

Types of Connection	Reaction	Number of Unknowns
(1)  cable		One unknown. The reaction is a tension force which acts away from the member in the direction of the cable.
(2)  weightless link		One unknown. The reaction is a force which acts along the axis of the link.
(3)  roller		One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.
(4)  roller or pin in confined smooth slot		One unknown. The reaction is a force which acts perpendicular to the slot.
(5)  rocker		One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.
(6)  smooth contacting surface		One unknown. The reaction is a force which acts perpendicular to the surface at the point of contact.
(7)  member pin connected to collar on smooth rod		One unknown. The reaction is a force which acts perpendicular to the rod.

5.2 Support Reactions

TABLE 5-1 Continued		
Types of Connection	Reaction	Number of Unknowns
<p>(8)</p>  <p>smooth pin or hinge</p>		<p>Two unknowns. The reactions are two components of force, or the magnitude and direction ϕ of the resultant force. Note that ϕ and θ are not necessarily equal [usually not, unless the rod shown is a link as in (2)].</p>
<p>(9)</p>  <p>member fixed connected to collar on smooth rod</p>		<p>Two unknowns. The reactions are the couple moment and the force which acts perpendicular to the rod.</p>
<p>(10)</p>  <p>fixed support</p>		<p>Three unknowns. The reactions are the couple moment and the two force components, or the couple moment and the magnitude and direction ϕ of the resultant force.</p>

5.3 Free Body Diagrams

The Free-Body Diagram \equiv FBD

To apply equilibrium equations we must account for all known and unknown forces acting on the object.

The best way to do this is to draw a free-body diagram FBD of the body.

This is a sketch that shows the rigid body “free” from its surroundings with all the forces acting on it.

Force Types

Active Forces : tend to set the body in motion.

Reactive Forces : result from constraints or supports and tend to prevent motion

5.3 Free Body Diagrams

Procedure for Drawing a FBD

1. Draw Outlined Shape

- Imagine body to be isolated or cut free from its constraints
- Draw outline shape

2. Show All Forces and Couple Moments

- Identify all external forces and couple moments that act on the body

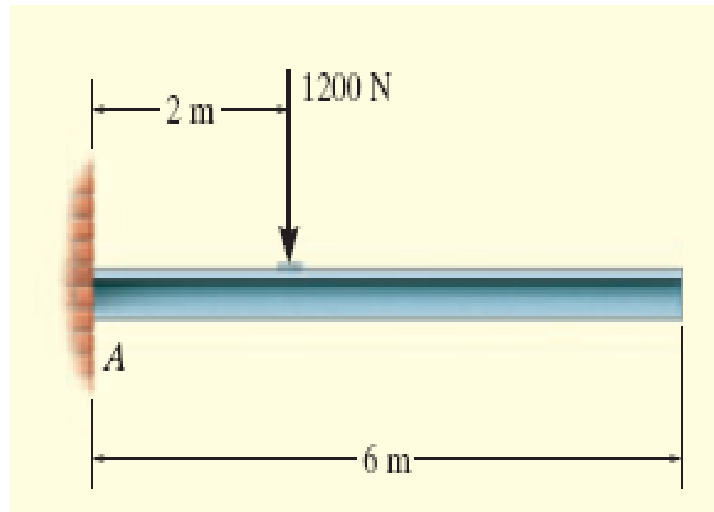
5.3 Free Body Diagrams

3. Identify Each Loading and Give Dimensions

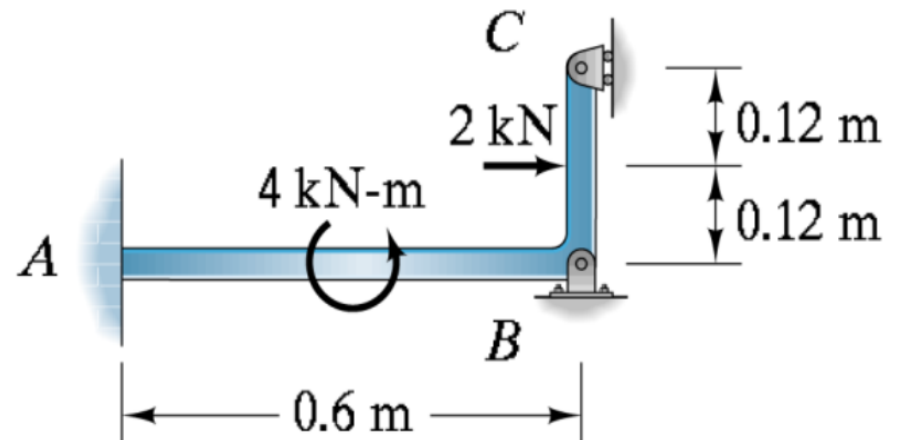
- Indicate dimensions for calculation of forces
- Known forces and couple moments should be properly labeled with their magnitudes and directions

Example 5.1

Draw the free-body diagram for shapes, a and b



a)



b)

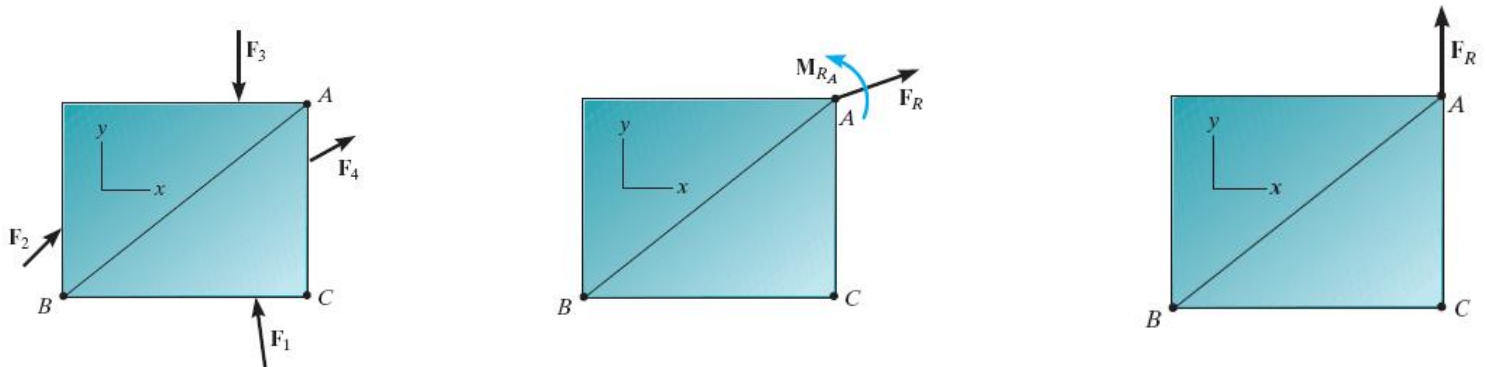
5.4 Equations of Equilibrium

- For equilibrium of a rigid body in 2D,
$$\sum F_x = 0; \sum F_y = 0; \sum M_O = 0$$
- $\sum F_x$ and $\sum F_y$ represent sums of x and y components of all the forces
- $\sum M_O$ represents the sum of the couple moments and moments of the force components

5.4 Equations of Equilibrium

Alternative Sets of Equilibrium Equations

- For coplanar equilibrium problems,
 $\sum F_x = 0$; $\sum F_y = 0$; $\sum M_O = 0$
- 2 alternative sets of 3 independent equilibrium equations,
 $\sum F_x = 0$; $\sum M_A = 0$; $\sum M_B = 0$



5.4 Equations of Equilibrium

Procedure for Analysis

Free-Body Diagram

- Force or couple moment having an unknown magnitude but known line of action can be assumed
- Indicate the dimensions of the body necessary for computing the moments of forces

5.4 Equations of Equilibrium

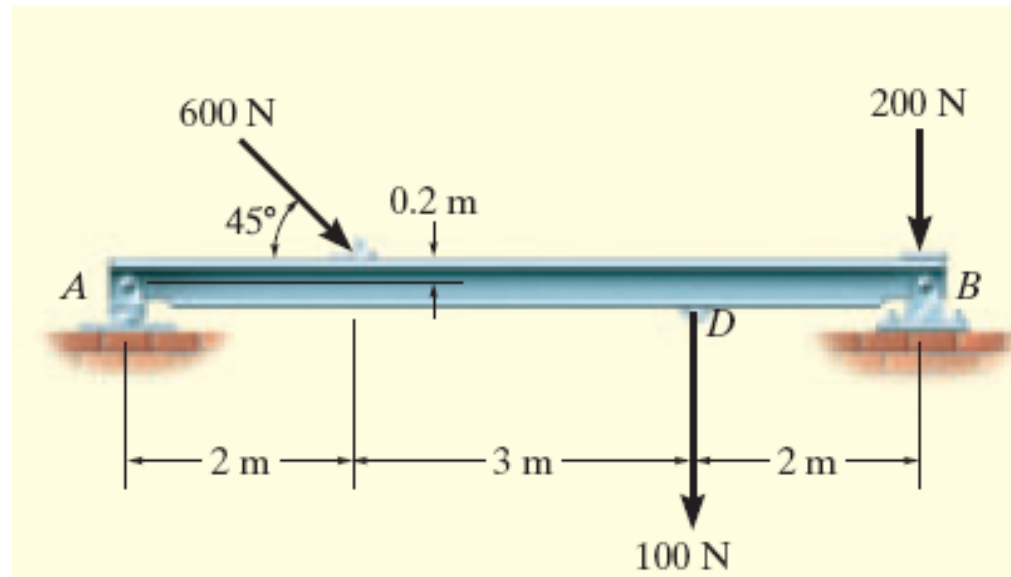
Procedure for Analysis

Equations of Equilibrium

- Apply $\sum M_O = 0$ about a point O
- Unknowns moments of forces are zero about O and a direct solution for the third unknowns can be determined
- Orient the x and y axes along the lines that will provide the simplest resolution of the forces into their x and y components
- Negative result scalar is opposite to that was assumed on the FBD

Example 5.2

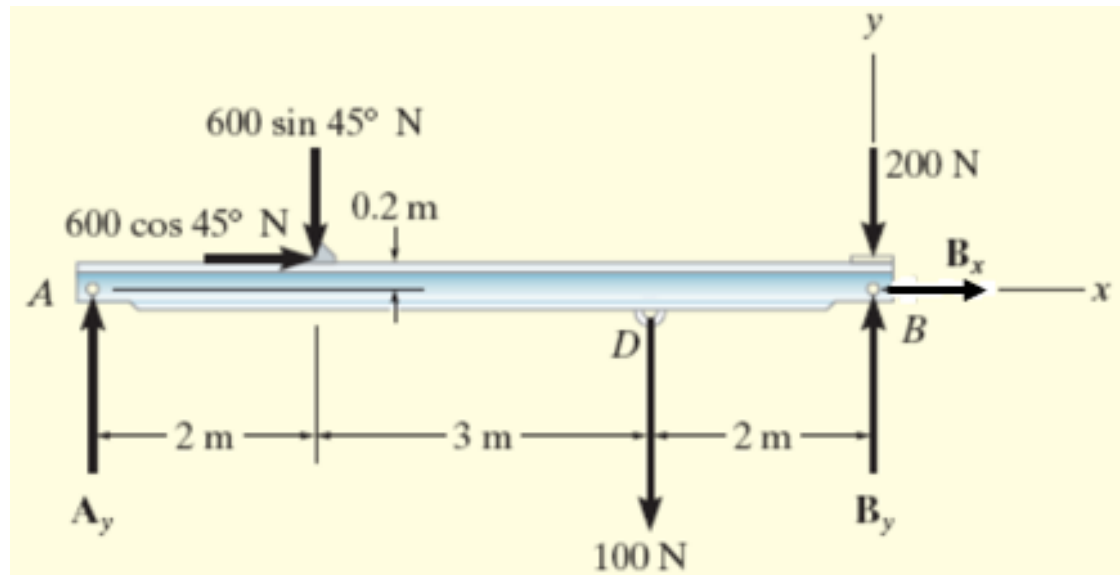
Determine the horizontal and vertical components of the reaction for support A (roller) and Support B (pin).



Solution

Free Body Diagrams

- 600N represented by x and y components
- 200N force acts on the beam at B



Solution

Equations of Equilibrium

$$+ \rightarrow \sum M_B = 0; \quad 600\cos 45^\circ N + B_x = 0 \Rightarrow B_x = -424 \text{ N}$$

$$\sum M_B = 0;$$

$$100N(2m) + (600\sin 45^\circ N)(5m) - (600\cos 45^\circ N)(0.2m) - A_y(7m) = 0$$

$$A_y = 319N$$

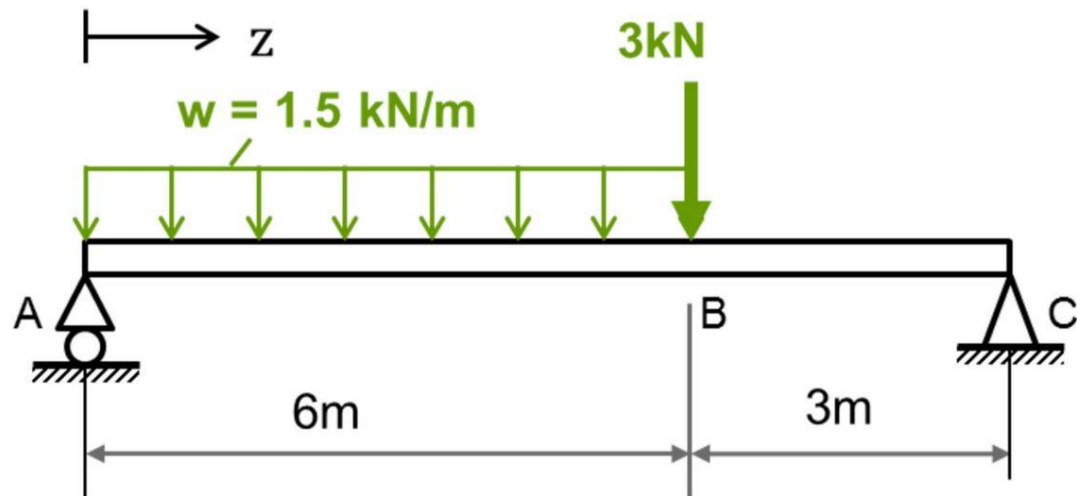
$$+ \uparrow \sum F_y = 0;$$

$$319N - 600\sin 45^\circ N - 100N - 200N + B_y = 0$$

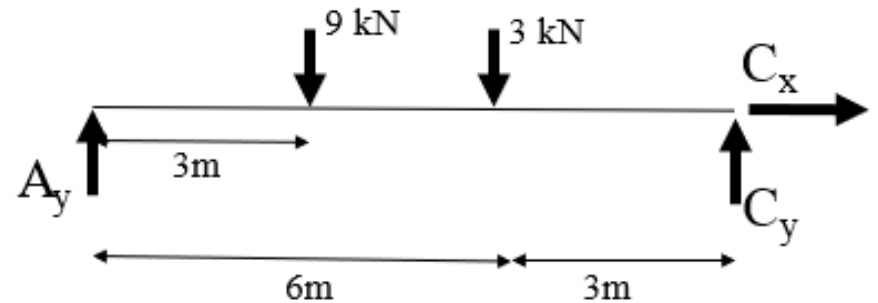
$$B_y = 405N$$

Example 5.3

Determine the Support Reactions at A and C



Solution



$$\sum F_x = 0 \quad A_x = 0$$

$$\sum F_y = 0 \quad A_y + C_y - 3 - (1.5)(6) = 0 \quad A_y + C_y = 12$$

$$\sum M_C = 0 \quad (-A_y)(9) + (9)(6) + (3)(3) = 0$$

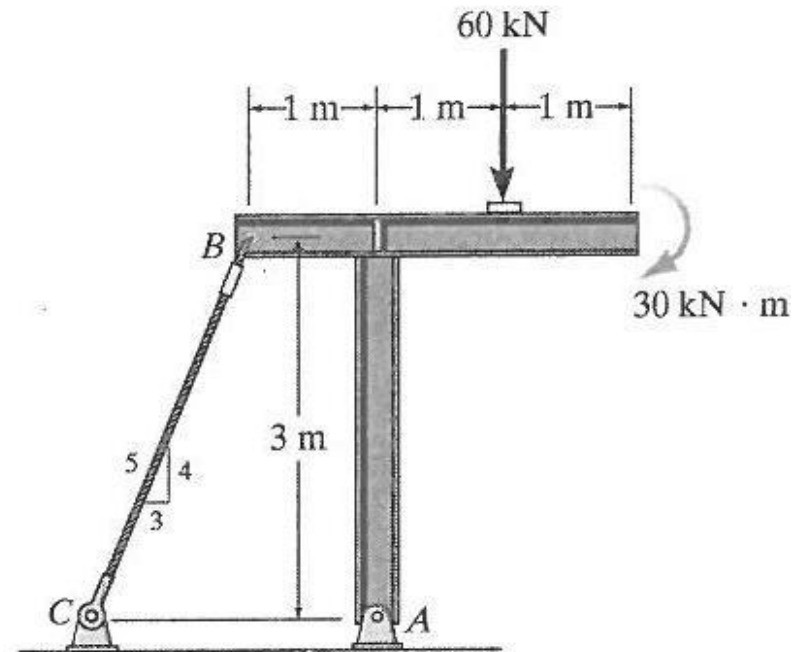
$$A_y = 7 \text{ kN}$$

$$C_y = 5 \text{ kN}$$

Example 5.4

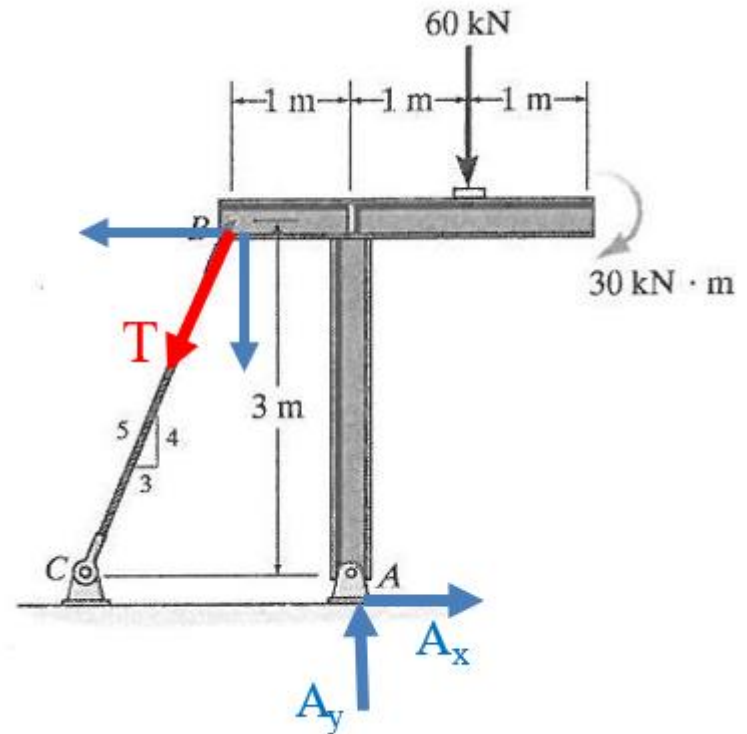
There is a Cable CB, determine:

- a) The tension force at CB
- b) the support reaction at A (pin)



Solution

Free-body Diagram



Solution

$$\zeta + \sum M_A = 0;$$

$$(T) (3/5) (1) + (T) (4/5) (3) - (60) (1) - 30 = 0$$

$$\mathbf{T = 30 \text{ kN}}$$

$$\rightarrow \sum F_x = 0;$$

$$A_x - (30) (3/5) = 0$$

$$\mathbf{A_x = 18 \text{ kN}}$$

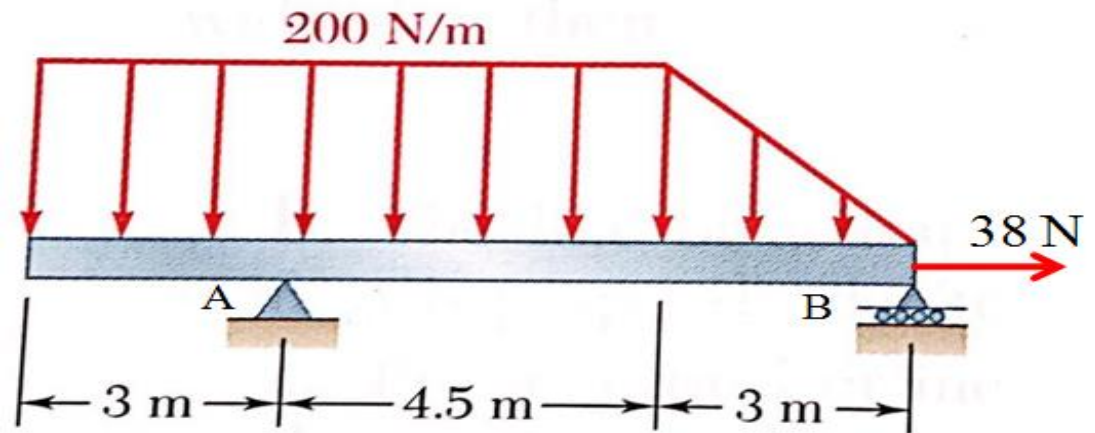
$$+\uparrow \sum F_y = 0;$$

$$A_y - (30) (4/5) - 60 = 0$$

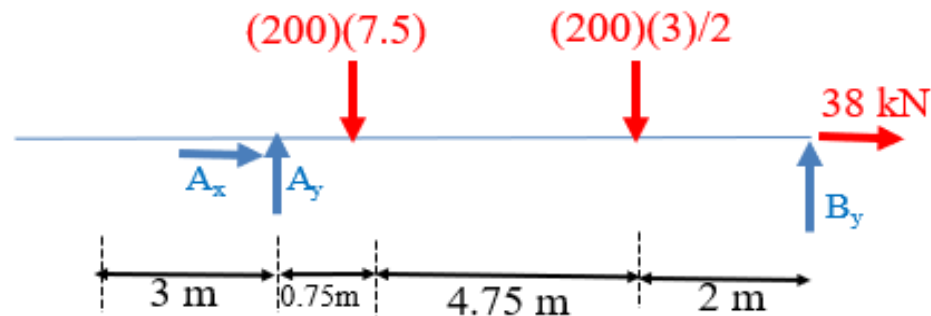
$$\mathbf{A_y = 84 \text{ kN}}$$

Example 5.5

determine the reactions at pin support **A** and roller support **B**



Solution



$$\rightarrow \sum F_x = 0;$$

$$A_x + 38 = 0$$

$$A_x = -38 \text{ N}$$

$$\zeta + \sum M_B = 0;$$

$$-(A_y)(7.5) + (1500)(6.75) + (300)(2) = 0$$

$$A_y = 1430 \text{ N}$$

$$+\uparrow \sum F_y = 0;$$

$$B_y + 1430 - 1500 - 300 = 0$$

$$B_y = 370 \text{ N}$$