



# Analysis of Algorithms

---



# Time for instructions on a computer that executes 1 billion instructions per second

$n$	$f(n) = n$	$f(n) = \log_2 n$	$f(n) = n \log_2 n$	$f(n) = n^2$	$f(n) = 2^n$
10	0.01 $\mu$ s	0.003 $\mu$ s	0.033 $\mu$ s	0.1 $\mu$ s	1 $\mu$ s
20	0.02 $\mu$ s	0.004 $\mu$ s	0.086 $\mu$ s	0.4 $\mu$ s	1 ms
30	0.03 $\mu$ s	0.005 $\mu$ s	0.147 $\mu$ s	0.9 $\mu$ s	1 s
40	0.04 $\mu$ s	0.005 $\mu$ s	0.213 $\mu$ s	1.6 $\mu$ s	18.3min
50	0.05 $\mu$ s	0.006 $\mu$ s	0.282 $\mu$ s	2.5 $\mu$ s	13 days
100	0.10 $\mu$ s	0.007 $\mu$ s	0.664 $\mu$ s	10 $\mu$ s	4 $\times 10^{13}$ years
1000	1.00 $\mu$ s	0.010 $\mu$ s	9.966 $\mu$ s	1 ms	
10,000	10 $\mu$ s	0.013 $\mu$ s	130 $\mu$ s	100ms	
100,000	0.10ms	0.017 $\mu$ s	1.67ms	10s	
1,000,000	1 ms	0.020 $\mu$ s	19.93ms	16.7m	
10,000,000	0.01s	0.023 $\mu$ s	0.23s	1.16 days	
100,000,000	0.10s	0.027 $\mu$ s	2.66s	115.7 days	



# Time and space

---

- **Analyzing an algorithm means:**
  - developing a formula for predicting *how fast* an algorithm is, based on the *size of the input* (**time complexity**), and/or
  - developing a formula for predicting *how much memory* an algorithm requires, based on the *size of the input* (**space complexity**)
- Usually **time** is our biggest concern
  - Most algorithms require a fixed amount of space



# What does “size of the input” mean?

- If we are searching an array, the “size” of the input could be the size of the array
- If we are merging two arrays, the “size” could be the sum of the two array sizes
- If we are computing the  $n^{\text{th}}$  Fibonacci number, or the  $n^{\text{th}}$  factorial, the “size” is  $n$
- We choose the “size” to be a parameter that determines the actual time (or space) required



# Exact values

---

- It is sometimes possible, *in assembly language*, to compute *exact* time and space requirements
  - We know exactly how many **bytes** and how many **cycles** each machine instruction takes
  - For a problem with a known sequence of steps (factorial, fibonacci), we can determine how many instructions of each type are required
- **However, often the exact sequence of steps cannot be known in advance**
  - The steps required to sort an array depend on the actual numbers in the array (which we do not know in advance)



# Higher-level languages

- In a higher-level language, we *do not know* how long each operation takes
  - Which is faster,  $x < 10$  or  $x \leq 9$  ?
  - We don't know exactly what the compiler does with this
  - The **compiler** almost certainly optimizes the test anyway (replacing the slower version with the faster one)
- In a higher-level language we *cannot* do an exact analysis
  - Our timing analyses will use *major* oversimplifications
  - Nevertheless, we can get some very useful results



# Average, best, and worst cases

- Usually we would like to find the *average* time to perform an algorithm
- However,
  - Sometimes the “average” isn’t well defined
    - **Example:** Sorting an “average” array
      - Time typically depends on how out of order the array is
      - How out of order is the “average” unsorted array?
  - Sometimes finding the average is too difficult
- Often we have to be satisfied with finding the *worst* (longest) time required
  - Sometimes this is even what we want (say, for time-critical operations)
- The *best* (fastest) case is seldom of interest



# Constant time

---

- *Constant time* means there is some constant **k** such that this operation always takes **k** nanoseconds
- A statement takes constant time if:
  - It does not include a loop
  - It does not include calling a method whose time is unknown or is not a constant
- If a statement involves a choice (**if** or **switch**) among operations, each of which takes constant time, we consider the statement to take constant time
  - This is consistent with *worst-case analysis*





# Example

Consider the following algorithm. (Assume that all variables are properly declared.)

	Line	# of operations
cout << "Enter two numbers";	1	1
cin >> num1 >> num2;	2	2
if (num1 >= num2)	3	1
max = num1;	4	1
else	5	
max = num2;	6	1
cout << "The maximum number is: " << max << endl;	7	3

Either Line 4 or Line 6 executes. Therefore, the total number of operations executed is  $1 + 2 + 1 + 1 + 3 = 8$ . In this algorithm, the number of operations executed is **fixed**.



# Linear time

---

- We may not be able to predict to the nanosecond how long a program will take, but do know *some* things about timing:

```
for (i = 0, j = 1; i < n; i++) {  
    j = j * i;  
}
```

- This loop takes time  $k*n + c$ , for some constants  $k$  and  $c$

$k$  : How long it takes to go through the loop once  
(the time for  $j = j * i$ , plus loop overhead)

$n$  : The number of times through the loop  
(we can use this as the “size” of the problem)

$c$  : The time it takes to initialize the loop

- The total time  $k*n + c$  is *linear in*  $n$



# Example

	Lines	# of operations
sum = 0;	1	1
num = 10;	2	1
while (num != -1)	3	1
{	4	
sum = sum + num;	5	2
num = num -1;	6	2
}	7	
cout << sum;	8	1

If the while loop executes  $n$  times, the number of operations executed is:  $5n + 4$ .



# Cont.

---

n	$5n+4$
10	54
100	504
1000	5004
10000	50004

For very large values of  $n$ , the term  $5n$  becomes the dominating term and the term 4 become negligible.



# Constant time is (usually) better than linear time

- Suppose we have two algorithms to solve a task:
  - Algorithm A takes 5000 time units
  - Algorithm B takes  $100 \cdot n$  time units
- Which is better?
  - Clearly, algorithm B is better if our problem size is small, that is, if  $n < 50$
  - Algorithm A is better for larger problems, with  $n > 50$
  - So B is better on small problems that are quick anyway
  - But A is better for large problems, *where it matters more*
- We usually care most about very large problems
  - But not always!



# What about the constants?

---

- An added constant,  $f(n)+c$ , becomes less and less important as  $n$  gets larger
- A constant multiplier,  $k*f(n)$ , does *not* get less important, but...
  - Improving  $k$  gives a *linear* speedup (cutting  $k$  in half cuts the time required in half)
  - Improving  $k$  is usually accomplished by careful code optimization, not by better algorithms
  - We aren't that concerned with *only* linear speedups.
- Bottom line: ***Forget the constants!***



# Simplifying the formulae

---

- Throwing out the constants is one of *two* things we do in analysis of algorithms
  - By throwing out constants, we simplify  $12n^2 + 35$  to just  $n^2$
- Our timing formula is a polynomial, and may have terms of various orders (constant, linear, quadratic, cubic, etc.)
  - **We usually discard all but the *highest-order* term**
    - We simplify  $n^2 + 3n + 5$  to just  $n^2$



# Big O notation

---

- When we have a polynomial that describes the time requirements of an algorithm, we simplify it by:
  - Throwing out all but the highest-order term
  - Throwing out all the constants
- If an algorithm takes  $12n^3+4n^2+8n+35$  time, we simplify this formula to just  $n^3$
- We say the algorithm requires  $O(n^3)$  time
  - We call this **Big O** notation





# Can we justify Big O notation?

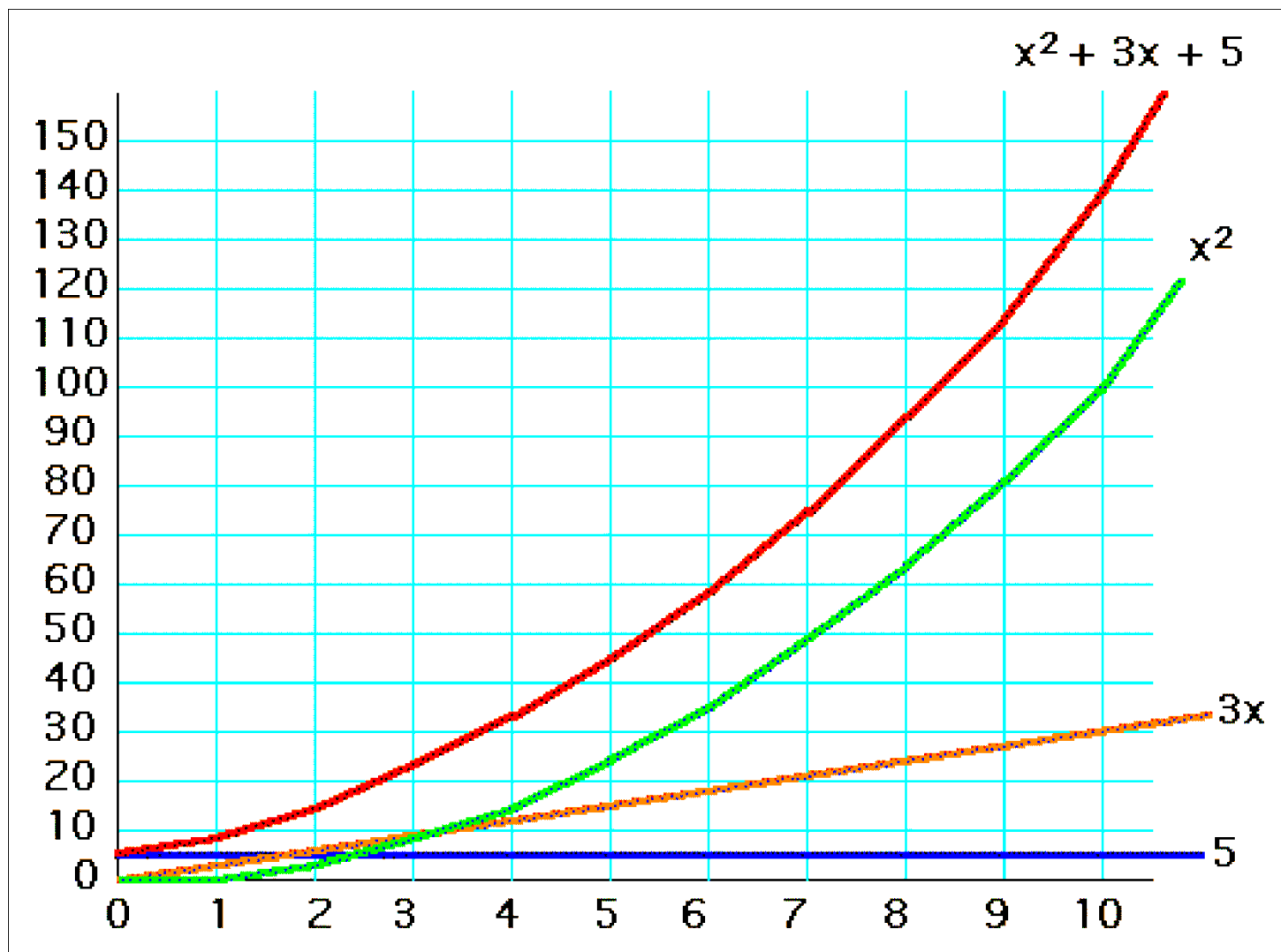
- Big O notation is a *huge* simplification; can we justify it?

- It only makes sense for *large* problem sizes
- **For sufficiently large problem sizes, the highest-order term swamps all the rest!**

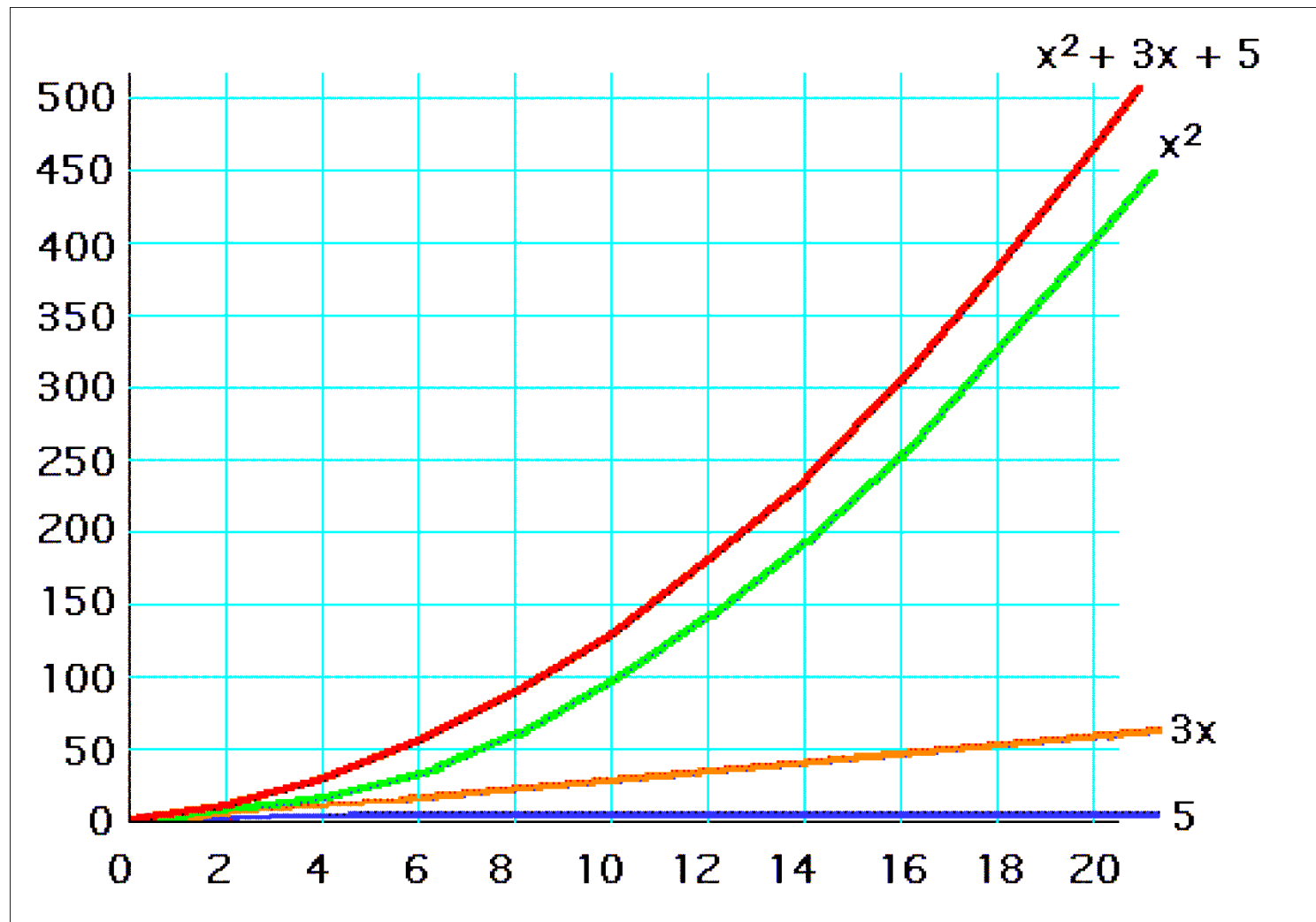
- Consider  $R = x^2 + 3x + 5$  as  $x$  varies:

$x = 0$	$x^2 = 0$	$3x = 0$	$5 = 5$	$R = 5$
$x = 10$	$x^2 = 100$	$3x = 30$	$5 = 5$	$R = 135$
$x = 100$	$x^2 = 10000$	$3x = 300$	$5 = 5$	$R = 10,305$
$x = 1000$	$x^2 = 1000000$	$3x = 3000$	$5 = 5$	$R = 1,003,005$
$x = 10,000$	$x^2 = 10^8$	$3x = 3 \cdot 10^4$	$5 = 5$	$R = 100,030,005$
$x = 100,000$	$x^2 = 10^{10}$	$3x = 3 \cdot 10^5$	$5 = 5$	$R = 10,000,300,005$


$$y = x^2 + 3x + 5, \text{ for } x=1..10$$




$$y = x^2 + 3x + 5, \text{ for } x=1..20$$





# Common time complexities

**BETTER**



**WORSE**

- $O(1)$  constant time
- $O(\log n)$  log time
- $O(n)$  linear time
- $O(n \log n)$  log linear time
- $O(n^2)$  quadratic time
- $O(n^3)$  cubic time
- $O(n^k)$  polynomial time
- $O(2^n)$  exponential time



# NP-complete problem

---

- Hard problem:
  - Most problems discussed are efficient (poly time)
  - An interesting set of hard problems: NP-complete.
- Why interesting:
  - Not known whether efficient algorithms exist for them.
  - If exist for one, then exist for all.
  - A small change may cause big change.
- Why important:
  - Arise surprisingly often in real world.
  - **Not waste time on trying to find an efficient algorithm to get best solution, instead find approximate or near-optimal solution.**
- **Example:** traveling-salesman problem. Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?



# Bjarne Stroustrup

---



- A Danish computer scientist, most notable for the creation and development of C++
- “I have always wished for my computer to be as easy to use as my telephone; my wish has come true because I can no longer figure out how to use my telephone”.





# Example 1

---

Find the running time, worst time, complexity, or Big-Oh analysis for the following code

```
for (i = 0; i < n; i++)  
    for (j = 0; j < n; j++)  
        cin >> A[i][j];
```

Number of times `cin >> A[i][j];` executed:  $n^2$

Complexity:  $O(n^2)$



## Example 2

---

```
for (i = 0; i <= n; i++)
```

```
    for (j = 0; j <= i; j++)
```

```
        A[i][j] = 0;
```

$O(n^2)$





## Example 3

---

```
for (i = 0; i < n; i++)  
{  
    for (j = 0; j < n; j++)  
        A[i][j] = j*2;  
    for (k = 0; k < 2* n; k++)  
        A[i][k] = k *3;  
}
```

$O(n^2)$



## Example 4

---

```
for (i = 0; i < n; i++)  
{  
    for (j = 0; j < n; j++)  
        A[i][j] = i * j;  
    for (k = 0; k < 2 * n; k++)  
        for (m = 0; m < 2 * n; m++)  
            sum = sum + 1;  
}
```

$O(n^3)$



## Example 5

---

```
void main()
{
    int i,j, tofind, A[100], n = 100;
    for (j = 0; j < n; j++)
        A[j] = j * 2;
    i = 0;
    cin >> tofind;
    while (A[i] != tofind) i++;
    if (i > n)
        cout << "not found";
    else
        cout << "found";
}
```

$O(n)$



# Summary

---

- <http://bigocheatsheet.com/>