

### **Anomaly Detection in Videos**

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#### Within:



Academic Year: 2021/2022

## **PLAN**

- 1. Introduction
- 2. General Framework of the Project
- 3. Problem Modeling
- 4. Exploring Experimental Results
- 5. Conclusion



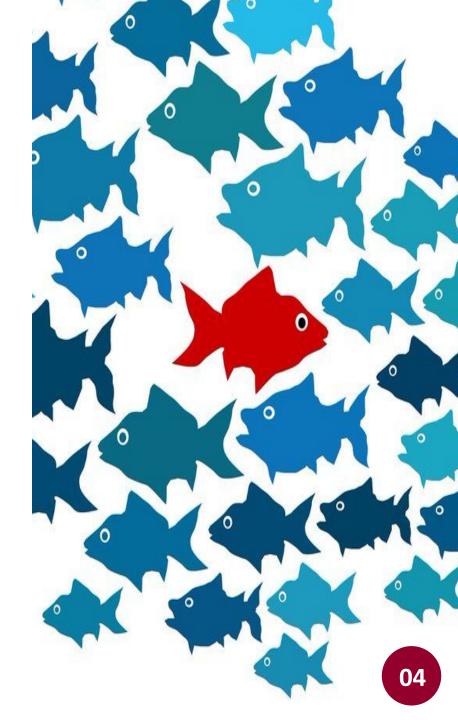
# INTRODUCTION



#### INTRODUCTION

Anomaly detection is the process of identifying unexpected items or events in data sets, which differ from the norm. And anomaly detection is often applied on unlabeled data which is known as unsupervised anomaly detection. Anomaly detection has two basic assumptions:

- Anomalies only occur very rarely in the data.
- Their features differ from the normal instances significantly.





# GENERAL FRAMEWORK OF THE PROJECT



#### HOSTING ORGANIZATION



- Merger of Loyola College and Sir George Williams University
- Gina Cody School of Engineering and Computer Science
- Concordia Institute for Information Systems Engineering
- Cybersecurity, Internet of Things, Artificial Intelligence, ...



# PROBLEM STATEMENT





# PROBLEM STATEMENT





#### **ANOMALY DETECTION IN VIDEOS**











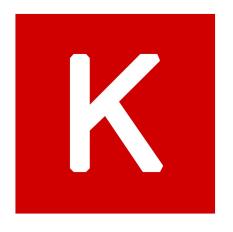


## PROBLEM MODELING



#### **PYTHON PACKAGES**











The UCSD pedestrian Dataset

The ShanghaiTech dataset

The CUHK Avenue dataset

#### The UCSD pedestrian

Dotocot







- A stationary video camera with a resolution of 238 X 158 pixels.
- Recorded at a frame rate of 26 frames per second.
- The Ped 1 dataset includes 34 train and 36 test video samples.



The UCSD pedestrian Dataset

The ShanghaiTech dataset

The CUHK Avenue dataset

#### The UCSD pedestrian

#### Detect







- A stationary video camera with a resolution of 238 X 158 pixels.
- Recorded at a frame rate of 26 frames per second.
- The Ped 2 dataset contains 16 train and 12 test video samples.



The UCSD pedestrian Dataset

The ShanghaiTech dataset

The CUHK Avenue dataset

#### The ShanghaiTech dataset







- It includes footage from 13 various cameras located throughout the ShanghaiTech University campus.
- It contains about 270, 000 training frames and 130 anomalous events.



The UCSD pedestrian Dataset

The ShanghaiTech dataset

The CUHK Avenue dataset

#### The CUHK Avenue dataset



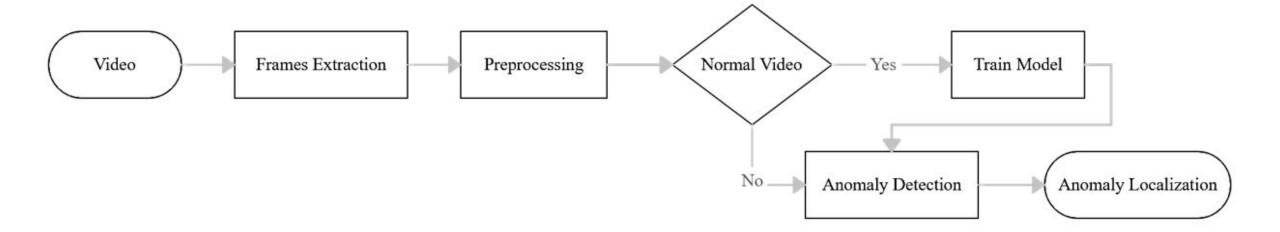




- created by filming street activities at the Chinese University of Hong Kong
- A stationary camera with a resolution of 640 X 360 pixels.
- Contains 16 train video examples and 21 test video samples.

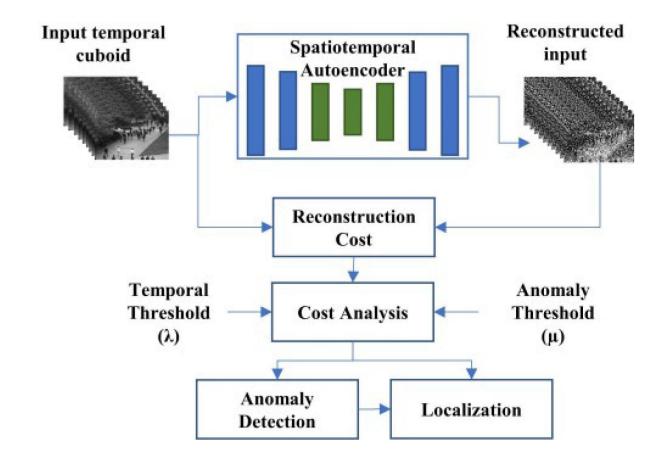


#### PROJECT'S PIPELINE



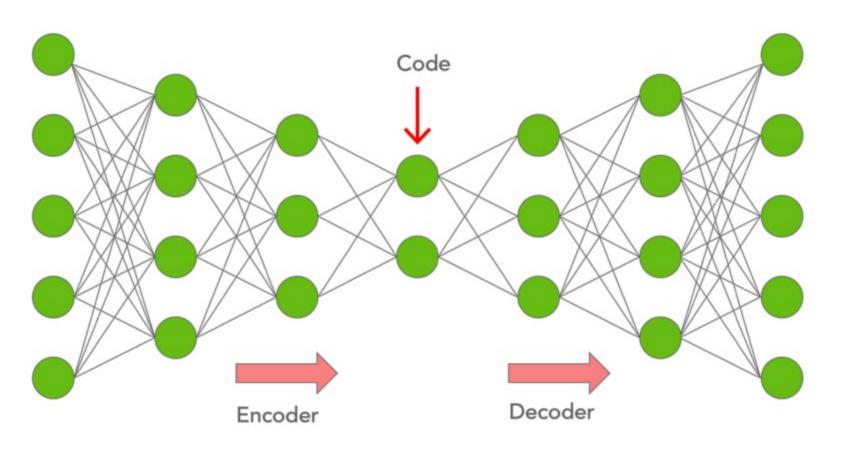


#### OUR SOLUTION





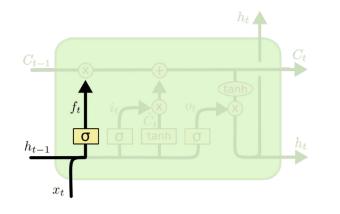
#### **AUTO-ENCODER**



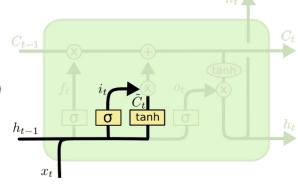


#### LONG AND SHORT TERM

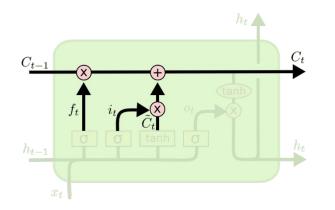
#### MEMORY



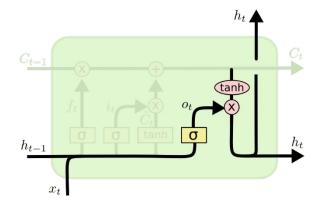
$$f_t = \sigma \left( W_f \cdot [h_{t-1}, x_t] + b_f \right)$$



$$i_t = \sigma (W_i \cdot [h_{t-1}, x_t] + b_i)$$
  
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$



$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$
$$h_t = o_t * \tanh (C_t)$$



#### MODEL ARCHITECTURE

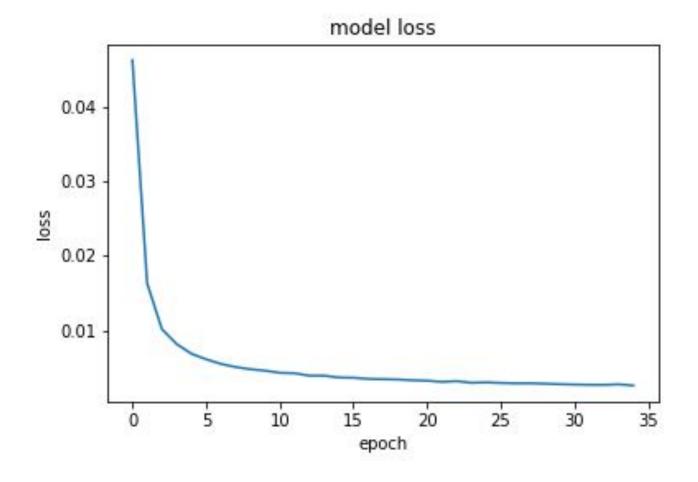
Type of layer	Output Shape	Weights (N)	Weights (%)
Input	(8, 224, 224, 1)		
TimeDistributed	(8, 56, 56, 128)	93440	1.1%
LayerNormalization	(8, 56, 56, 128)	256	0.0%
TimeDistributed	(8, 28, 28, 64)	1384512	15.6%
LayerNormalization	(8, 28, 28, 64)	128	0.0%
ConvLSTM2D	(8, 28, 28, 64)	295168	3.3%
LayerNormalization	(8, 28, 28, 64)	128	0.0%
ConvLSTM2D	(8, 28, 28, 32)	110720	1.2%
LayerNormalization	(8, 28, 28, 32)	64	0.0%
ConvLSTM2D	(8, 28, 28, 64)	221440	2.5%
LayerNormalization	(8, 28, 28, 64)	64	0.0%
TimeDistributed	(8, 56, 56, 64)	692288	7.8%
LayerNormalization	(8, 56, 56, 64)	128	0.0%
TimeDistributed	(8, 224, 224, 128)	5972096	67.4%
LayerNormalization	(8, 224, 224, 128)	256	0.0%
TimeDistributed	(8, 224, 224, 1)	93313	1.1%



# EXPLORING EXPERIMENTAL RESULTS



#### MODEL TRAINING

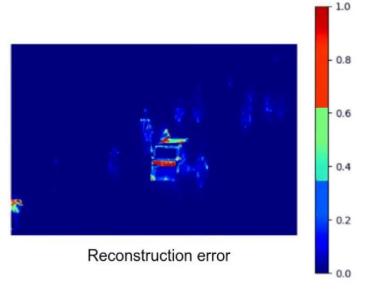




#### **TEST OUR MODEL**



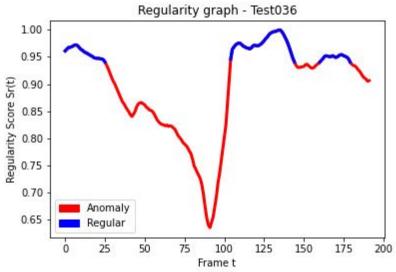
Input





#### TEST OUR MODEL









#### COMPARISON

Model	Ped 1	Ped 2	Avenue
Conv-AE	81.0	90.0	70.2
S-RBM	70.3	86.4	78.8
Unmasking	68.4	82.2	80.6
ISTL	75.2	91.1	76.8
Our algorithm	70.4	84.2	74.6

Comparison of AUC



# CONCLUSION



#### CONCLUSION

- Our model is based on the spatiotemporal auto-encoder.
- Our model does not only detect anomalies but also can localize them in the spatial reference.
- Despite the low available computational resources, our model achieved good results.



#### **PERSPECTIVES**

- Minimize the prediction serving latency
- Enhance quality of results
- Use of active learning techniques
- Real-time anomaly detection



# THANK YOU

