# **12** Vectors and the Geometry of Space



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12.4 The Cross Product

#### Context

- Cross Product of Two Vectors
- Properties of the Cross Product
- Triple Products
- Application

**Definition of the Cross Product If**  $a = \langle a_1, a_2, a_3 \rangle$  and  $b = \langle b_1, b_2, b_3 \rangle$ , then the cross product of a and b is the vector

$$\mathbf{a} \times \mathbf{b} = \langle a_2 b_3 - a_3 b_2, a_3 b_1 - a_1 b_3, a_1 b_2 - a_2 b_1 \rangle$$

Notice that the **cross product a** × **b** of two vectors **a** and **b** is a vector (whereas the dot product, product is a scalar). For this reason it is also called the **vector product**.

Note that **a** × **b** is defined only when **a** and **b** are *three-dimensional* vectors.

In order to make the Definition easier to remember, we use the notation of determinants.

A determinant of order 2 is defined by

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

For example,

$$\begin{vmatrix} 2 & 1 \\ -6 & 4 \end{vmatrix} = 2(4) - 1(-6) = 14$$

A determinant of order 3 can be defined in terms of second-order determinants

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

$$\begin{vmatrix} 1 & 2 & -1 \\ 3 & 0 & 1 \\ -5 & 4 & 2 \end{vmatrix} = 1 \begin{vmatrix} 0 & 1 \\ 4 & 2 \end{vmatrix} - 2 \begin{vmatrix} 3 & 1 \\ -5 & 2 \end{vmatrix} + (-1) \begin{vmatrix} 3 & 0 \\ -5 & 4 \end{vmatrix}$$
$$= 1(0-4) - 2(6+5) + (-1)(12-0)$$
$$= -38$$

If we now rewrite the Definition using second-order determinants and the standard basis vectors  $\mathbf{i}$ ,  $\mathbf{j}$ , and  $\mathbf{k}$ , we see that the cross product of the vectors  $\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$  and  $\mathbf{b} = b_1 \mathbf{i} + b_2 \mathbf{j} + b_3 \mathbf{k}$  is

$$\boldsymbol{a} \times \boldsymbol{b} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \boldsymbol{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \boldsymbol{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \boldsymbol{k}$$

MCQ: If  $\mathbf{a} = \langle 1, 3, 4 \rangle$  and  $\mathbf{b} = \langle 2, 7, -5 \rangle$ , then  $\mathbf{a} \times \mathbf{b} =$ 

- -43i+13**j**+**k**
- B -13i+43j+k
- -23i+13j+43k
- -43i+23j+13k

#### Example 1

If  $a = \langle 1, 3, 4 \rangle$  and  $b = \langle 2, 7, -5 \rangle$ , then

$$a \times b = \begin{vmatrix} 1 & j & k \\ 1 & 3 & 4 \\ 2 & 7 & -5 \end{vmatrix}$$

$$= \begin{vmatrix} 3 & 4 \\ 7 & -5 \end{vmatrix} i - \begin{vmatrix} 1 & 4 \\ 2 & -5 \end{vmatrix} j + \begin{vmatrix} 1 & 3 \\ 2 & 7 \end{vmatrix} k$$

$$= (-15 - 28)i - (-5 - 8)j + (7 - 6)k$$

$$= -43i + 13j + k$$

We constructed the cross product  $\mathbf{a} \times \mathbf{b}$  so that it would be perpendicular to both  $\mathbf{a}$  and  $\mathbf{b}$ . This is one of the most important properties of a cross product.

8 Theorem The vector **a** × **b** is orthogonal to both **a** and **b**.

Proof.

$$(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{a} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} a_1 - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} a_2 + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} a_3$$

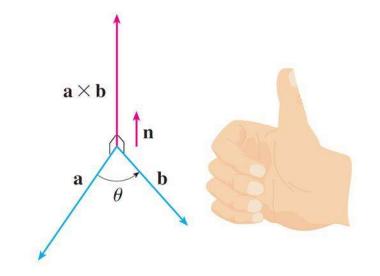
$$= a_1(a_2b_3 - a_3b_2) - a_2(a_1b_3 - a_3b_1) + a_3(a_1b_2 - a_2b_1)$$

$$= a_1a_2b_3 - a_1b_2a_3 - a_1a_2b_3 + b_1a_2a_3 + a_1b_2a_3 - b_1a_2a_3$$

$$= 0.$$

Similarly,  $(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{b} = 0$ .

If **a** and **b** are represented by directed line segments with the same initial point (as in Figure 1), then Theorem 8 says that the cross product **a** × **b** points in a direction perpendicular to the plane through **a** and **b**.



The right-hand rule gives the direction of  $\mathbf{a} \times \mathbf{b}$ .

Figure 1

It turns out that the direction of  $\mathbf{a} \times \mathbf{b}$  is given by the *right-hand rule*: If the fingers of your right hand curl in the direction of a rotation (through an angle less than 180°) from to  $\mathbf{a}$  to  $\mathbf{b}$ , then your thumb points in the direction of  $\mathbf{a} \times \mathbf{b}$ .

Now that we know the direction of the vector  $\mathbf{a} \times \mathbf{b}$ , the remaining thing we need to complete its geometric description is its length  $|\mathbf{a} \times \mathbf{b}|$  This is given by following theorem.

**9 Theorem** If  $\theta$  is the angle between **a** and **b** (so  $0 \le \theta \le \pi$ ), then the length of the cross product **a** × **b** is given by

$$|\boldsymbol{a} \times \boldsymbol{b}| = |\boldsymbol{a}||\boldsymbol{b}|\sin\theta$$

10 Corollary Two nonzero vectors a and b are parallel if and only if

$$\boldsymbol{a} \times \boldsymbol{b} = 0$$

Since a vector is completely determined by its magnitude and direction, we can now say that for nonparallel vectors **a** and **b**, **a** × **b** is the vector that is perpendicular to both **a** and **b**, whose orientation is determined by the right-hand rule, and whose length is  $|a||b|\sin\theta$ .

In fact, that is exactly how physicists define **a** × **b**.

The geometric interpretation of Theorem 9 can be seen by looking at Figure 2.

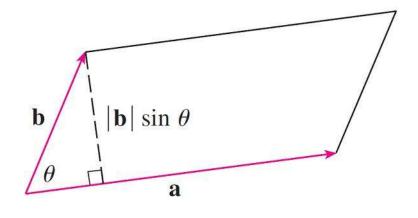


Figure 2

If **a** and **b** are represented by directed line segments with the same initial point, then they determine a parallelogram with base |a|, altitude  $|b| \sin \theta$ , and area

$$A = |\boldsymbol{a}|(|\boldsymbol{b}|\sin\theta) = |\boldsymbol{a}\times\boldsymbol{b}|$$

Thus we have the following way of interpreting the magnitude of a cross product.

The length of the cross product  $\mathbf{a} \times \mathbf{b}$  is equal to the area of the parallelogram determined by  $\mathbf{a}$  and  $\mathbf{b}$ .

MCQ: Find the area of the triangle with vertices P(1, 4, 6), Q(-2, 5, -1), and R(1, -1, 1).



$$5\sqrt{82}$$

$$5\sqrt{41}$$

$$\frac{5}{2}\sqrt{82}$$

$$\frac{5}{2}\sqrt{41}$$

#### Example

Find the area of the triangle with vertices P(1, 4, 6), Q(-2, 5, -1), and R(1, -1, 1).

#### Solution:

We computed that  $\overrightarrow{PQ} \times \overrightarrow{PR} = \langle -40, -15, 15 \rangle$ . The area of the parallelogram with adjacent sides PQ and PR is the length of this cross product:

$$|\overrightarrow{PQ} \times \overrightarrow{PR}| = \sqrt{(-40)^2 + (-15)^2 + 15^2}$$
$$= 5\sqrt{82}$$

The area A of the triangle PQR is half the area of this parallelogram, that is,  $\frac{5}{2}\sqrt{82}$ .

If we apply Theorems 8 and 9 to the standard basis vectors **i**, **j**, and **k** using  $\theta = \frac{\pi}{2}$ , we obtain

$$i \times j = k$$
  $j \times k = i$   $k \times i = j$   
 $j \times i = -k$   $k \times j = -i$   $i \times k = -j$ 

Observe that

$$i \times j \neq j \times i$$

Thus the cross product is not commutative. Also

$$i \times (i \times j) = i \times k = -j$$

whereas

$$(\mathbf{i} \times \mathbf{i}) \times \mathbf{j} = 0 \times \mathbf{j} = 0$$

So the associative law for multiplication does not usually hold; that is, in general,

$$(a \times b) \times c \neq a \times (b \times c)$$

However, some of the usual laws of algebra do hold for cross products.

The following theorem summarizes the properties of vector products.

11 Properties of the Cross Product If a, b, and c are vectors and c is a scalar, then

1. 
$$a \times b = -b \times a$$

**2.** 
$$(ca) \times b = c(a \times b) = a \times (cb)$$

3. 
$$a \times (b + c) = a \times b + a \times c$$

4. 
$$(a + b) \times c = a \times c + b \times c$$

5. 
$$a \cdot (b \times c) = (a \times b) \cdot c$$

6. 
$$\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$$

MAQ: Let  $a,b,c\neq 0$  while a+b+c=0

Which of the following statements are always true? (Multiple answers may be correct)

$$a \times b = b \times c = c \times a$$

$$(a \times b) \cdot c = 0$$

$$|a \times b| = |b \times c| = |c \times a|$$

$$(a \times b) \times c = a \times (b \times c)$$

#### Example

#### Solution:

$$a \times b = -(b+c) \times b = b \times c$$

And similarly, so option A and C will be ture

Because c = -a - b

The three vectors are **coplanar**. Thus the scalar triple product

$$(\boldsymbol{a} \times \boldsymbol{b}) \cdot \boldsymbol{c} = \boldsymbol{0}$$
 So option B will be ture.

The cross product is not associative in general, option D is false.

$$(a \times b) \times c \neq a \times (b \times c)$$

# **Triple Products**

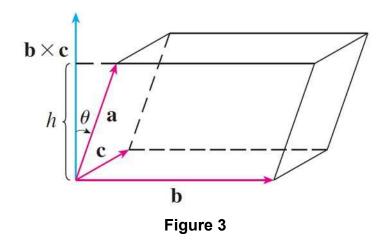
#### **Triple Products**

The product  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$  that occurs in Property 5 is called the **scalar triple product** of the vectors  $\mathbf{a}$ ,  $\mathbf{b}$ , and  $\mathbf{c}$ . Notice from Equation 12 that we can write the scalar triple product as a determinant:

13 
$$\boldsymbol{a} \cdot (\boldsymbol{b} \times \boldsymbol{c}) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

## Triple Products (2 of 5)

The geometric significance of the scalar triple product can be seen by considering the parallelepiped determined by the vectors **a**, **b**, and **c**.



The area of the base parallelogram is  $A = |\mathbf{b} \times \mathbf{c}|$ .

#### **Triple Products**

If  $\theta$  is the angle between **a** and **b** × **c**, then the height h of the parallelepiped is  $h = |a| |\cos \theta|$ . (We must use  $|\cos \theta|$  instead of  $\cos \theta$  in case  $\theta > \frac{\pi}{2}$ .) Therefore the volume of the parallelepiped is

$$V = Ah = |\mathbf{b} \times \mathbf{c}||\mathbf{a}||\cos\theta| = |\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})|$$

Thus we have proved the following formula.

**14** The volume of the parallelepiped determined by the vectors **a**, **b**, and **c** is the magnitude of their scalar triple product:

$$V = |\boldsymbol{a} \cdot (\boldsymbol{b} \times \boldsymbol{c})|$$

 $= |a \cdot (b \times c)|$  If we use the formula and discover that the volume of the parallelepiped determined by **a**, **b**, and **c** is 0, then the vectors must lie in the same plane; that is, they are coplanar.

#### Example

Use the scalar triple product to show that the vectors  $\mathbf{a} = \langle 1, 4, -7 \rangle$ ,  $\mathbf{b} = \langle 2, -1, 4 \rangle$ , and  $\mathbf{c} = \langle 0, -9, 18 \rangle$ , are coplanar.

#### Solution:

We use Equation 13 to compute their scalar triple product:

$$a \cdot (\mathbf{b} \times \mathbf{c}) = \begin{vmatrix} 1 & 4 & -7 \\ 2 & -1 & 4 \\ 0 & -9 & 18 \end{vmatrix}$$
$$= 1 \begin{vmatrix} -1 & 4 \\ -9 & 18 \end{vmatrix} - 4 \begin{vmatrix} 2 & 4 \\ 0 & 18 \end{vmatrix} - 7 \begin{vmatrix} 2 & -1 \\ 0 & -9 \end{vmatrix}$$
$$= 1(18) - 4(36) - 7(-18)$$
$$= 0$$

This means that **a**, **b**, and **c** are coplanar.

# Application: Torque

## Application: Torque (1 of 3)

The idea of a cross product occurs often in physics. In particular, we consider a force **F** acting on a rigid body at a point given by a position vector **r**. (For instance, if we tighten a bolt by applying a force to a wrench as in Figure 4, we produce a turning effect.)

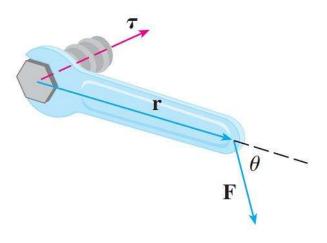


Figure 4

### Application: Torque (2 of 3)

The **torque**  $\tau$  (relative to the origin) is defined to be the cross product of the position and force vectors

$$\tau = r \times F$$

and measures the tendency of the body to rotate about the origin. The direction of the torque vector indicates the axis of rotation.

### Application: Torque (3 of 3)

According to Theorem 9, the magnitude of the torque vector is

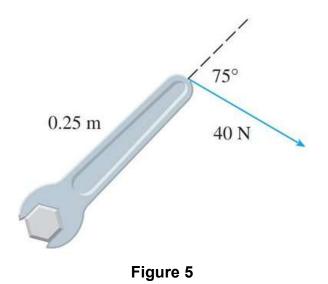
$$|\tau| = |r \times F| = |r||F| \sin \theta$$

where  $\theta$  is the angle between the position and force vectors. Observe that the only component of **F** that can cause a rotation is the one perpendicular to **r**, that is,  $|F| \sin \theta$ .

The magnitude of the torque is equal to the area of the parallelogram determined by **r** and **F**.

#### Example 6

A bolt is tightened by applying a 40-N force to a 0.25-m wrench as shown in Figure 5.



Find the magnitude of the torque about the center of the bolt.

#### Example 6 – Solution

The magnitude of the torque vector is

$$|\tau| = |r \times F| = |r||F| \sin 75^{\circ}$$
  
=  $(0.25)(40) \sin 75^{\circ}$   
=  $10 \sin 75^{\circ} \approx 9.66 \text{ N} \cdot \text{m}$ 

If the bolt is right-threaded, then the torque vector itself is

$$\tau = |\tau| n \approx 9.66 n$$

where **n** is a unit vector directed down into the page (by the right-hand rule).

#### Recap

- Cross Product of Two Vectors
- Properties of the Cross Product
- Triple Products
- Application