Write a matlab code for linear convolution of two signals. Then

1. Generate the causal signals

```
x1[n] = \{3, 1, 4, 16, 2\}
\uparrow
x2[n] = \{3, -1, 3, -1\}
\uparrow
h[n] = \{2, -1, -4, 1, -3\}
```

Now, determine the output of the given systems

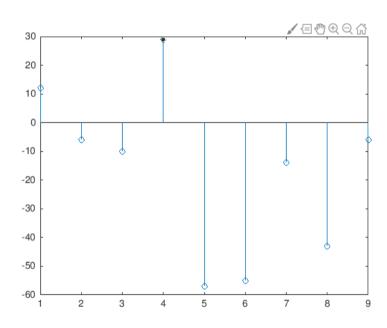
```
y1[n] = (x1[n] + x2[n]) * h[n]

y2[n] = x1[n] * h[n] + x2[n] * h[n]
```

- (a) Perform the calculations using your matlab code and verify the results using the inbuilt function conv and on-paper calculations.
- (b) Verify if the outputs y1[n] and y2[n] are identical or not.
- (c) Using the stem function, plot the signals x1[n], x2[n], h[n], y1[n] and y2[n].

1 solution)

```
x1 = [3 1 4 16 2];
x2 = [3 - 1 3 - 1];
h = [2 -1 -4 1 -3];
x = x1 + [x2,0];
M = length(x);
N = length(h);
L = M + N - 1;
xc = zeros(1,L);
hc = zeros(1,L);
xc(1:M) = x;
hc(1:N) = h;
for n = 1:L
       y1(n) = 0;
       for k = 1:n
              y1(n) = y1(n) + xc(k)*hc(n-k+1);
       end
end
stem(y1);
y1
```



output:-

```
x1 = [3 1 4 16 2];
h = [2 - 1 - 4 1 - 3];
                                                                                            但心田风公
                                                   30
M1 = length(x1);
N = length(h);
                                                    20
L1 = M1 + N - 1;
                                                    10
xe1 = zeros(1,L);
he1 = zeros(1,L);
                                                    0
xe1(1:M1) = x1;
                                                   -10
he1(1:N) = h;
for n = 1:L1
                                                   -20
      y1(n) = 0;
                                                   -30
       for k=1:n
                                                   -40
              y1(n) = y1(n) + xe1(k)*he1(n-
                                         k+1);
                                                   -50
       end
                                                   -60
end
x2 = [3 - 1 3 - 1];
M2 = length(x2);
L2 = M2 + N - 1;
xe2 = zeros(L2);
he2 = zeros(L2);
xe2(1:M2) = x2;
he2(1:N) = h;
for n = 1:L2
      y2(n) = 0;
       for k = 1:n
              y2(n) = y2(n) + xe2(n)*he2(n-k+1);
       end
end
y = y1 + [y2,0];
stem(y);
y
output:-
```

code for convulation the convulation using inbuilt functions

y = 12 -6 -10 29 -57 -55 -14 -43 -6

```
x1 = [3 1 4 16 2];
x2 = [3 -1 3 -1];
h = [2 -1 -4 1 -3];
y1 = conv(x1,h);
y2 = conv(x2,h);
y = y1 + [y2,0];
y
y1
```

output after verifying with convulation inbuilt function:-

```
x1 = [3 1 4 16 2];

x2 = [3 -1 3 -1];

h = [2 -1 -4 1 -3];

l=0:1:4;

subplot(311);

stem(l,x1);

m=0:1:3;

ylabel('x1(n)');

subplot(312);

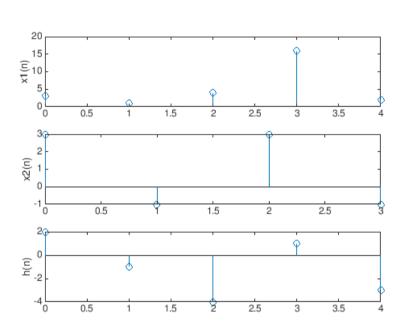
stem(m,x2);

ylabel('x2(n)');

subplot(313);

stem(l,h);

ylabel('h(n)');
```



2. Next, generate the signals

$$x[n] = \{-3, -2, 0, 1, 2, 3, \}$$

$$\uparrow$$

$$h[n] = \{3, 1, 1, 3, 1, 1\}$$

Now, determine the output of the given system

$$y[n] = x[n-3] * h[n]$$

- 1(a) Perform the calculations using your matlab code and verify the results using the inbuilt function conv and on-paper calculations.
- (b) Using the stem function, plot the signals x[n], h[n], and y[n].

2 solution)

```
x = [-3 -2 0 1 2 3];
h = [3 1 1 3 1 1];
M = length(x);
N = length(h);
L = M + N - 1;
xe = zeros(1,L);
```

```
he = zeros(1,L);
xe(1:M) = x;
he(1:N) = h;
for n=1:L
y(n) = 0;
       for k = 1:n
              y(n) = y(n) + xe(k)*he(n - k + 1);
       end
end
                                            2
l=0:1:10;
                                         <u>څ</u> ٥
m=-3:1:2;
                                           -2
n=0:1:5;
subplot(311);
stem(m,x);
ylabel('x(n)');
                                          (L)
H 1
subplot(312);
stem(n,h);
ylabel('h(n)');
                                            0
                                                                               3
subplot(313);
stem(l,y);
                                           10 F
ylabel('y(n)');
                                            5
                                        y(n)
y
                                                                    φ
                                           -5
output:-
                                                                                           8
                                                                                                      10
y = -9 - 9 - 5 - 8 - 2 7 6 10 12 5 3
```

3. Next generate the causal signals

```
x[n] = \{1, 2, -3, 8, -9\}

\uparrow
h[n] = \{3, 2, 1, 2, 3\}
```

Now, compute the ouput of the given systems

```
y1[n] = x[n] * h[1 - n]

y2[n] = x[1 - n] * h[n]
```

- (a) Perform the calculations using your matlab code and verify the results using the inbuilt function conv and on-paper calculations.
- (b) Using the stem function, plot the signals x[n], h[n], y1[n] and y2[n].
- (c) Verify if the outputs y1[n] and y2[n] are identical or not.

```
x = [12 - 38 - 9];
                                               30
h = [3 \ 2 \ 1 \ 2 \ 3];
                                               20
hf = fliplr(h);
                                                10
xf = fliplr(x);
                                                0
nk = -3:5;
                                               -10
M1 = length(x);
                                               -20
M2 = length(xf);
                                               -30
                                                                                   2
                                                                                          3
                                                        -2
                                                                      0
                                                                                                 4
N1 = length(h);
N2 = length(hf);
                                               30
L1 = M1 + N2 - 1;
                                               20
L2 = M2 + N1 - 1;
                                                10
xc1 = zeros(1,L1);
                                                0
hc1 = zeros(1,L1);
                                               -10
xc1(1:M1) = x;
                                               -20
hc1(1:N2) = hf;
                                               -304
for n = 1:L1
                                                                                          3
       y1(n) = 0;
       for k = 1:n
              y1(n) = y1(n) + xc1(k)*hc1(n-k+1);
       end
end
xc2 = zeros(1,L2);
hc2 = zeros(1,L2);
xc2(1:M2) = xf;
hc2(1:N1) = h;
for n = 1:L2
       y2(n) = 0;
       for k = 1:n
              y2(n) = y2(n) + xc2(k)*hc2(n-k+1);
       end
end
subplot(211)
stem(nk,y1);
xlabel('n');
ylabel('y1[n]')
subplot(212)
stem(nk,y2);
xlabel('n');
ylabel('y2[n]')
y1
y2
output:-
```

y1 = 3 8 -4 22 -7 -10 -2 6 -27 y2 = -27 6 -2 -10 -7 22 -4 8 3

```
clc
                                             10
clear all
close all
%%
                                            -10 L
x = [12 - 38 - 9];
h = [3 \ 2 \ 1 \ 2 \ 3];
subplot(311);
                                            (i)
4
1
stem(x);
ylabel('x(n)');
                                             0 L
subplot(312);
stem(h);
ylabel('h(n)');
verifying using inbuilt conv function:
x = [12 - 38 - 9];
h = [3 \ 2 \ 1 \ 2 \ 3];
hf= fliplr(h);
```

3

2.5

2.5

1.5

1.5

3.5

3.5

4.5

4.5

output when using convulation inbuilt function:-

```
y = 3 8 -4 22 -7 -10 -2 6 -27
y1 = -27 6 -2 -10 -7 22 -4 8 3
```

xf= fliplr(x);
y = conv(x,hf);
y1 = conv(xf,h);

y y1

solution for all the questions (rough work)

1)
$$x_1[n] = \{3,1,4,16,2\}$$
 $x_2[n] = \{3,-1,3,-1\}$

$$h[n] = \{2,-1,-4,1,-3\}$$

$$x_1[n] * h[n] = \begin{cases} 2,-1,-4,1,-3 \\ 2 & 6 \end{cases}$$

$$x_2[n] * h[n] = \begin{cases} 3,1,4,16,2 \\ 2,-1,-3 \\ -1,-3 \\ -1,-4 \\ -16 \\ -61 \\ -8 \\ -1,-3 \\ -1,-4 \\ -18 \\ -8 \\ -8 \\ -1,-3 \\ -9 \\ -3 \\ -1,-3 \\ -1,-4 \\ -18 \\ -6 \\ -1,-4 \\ -18 \\ -6 \\ -1,-4 \\ -18 \\ -6 \\ -1,-4 \\ -18 \\ -6 \\ -1,-4 \\ -18 \\ -$$

TE (6,-1,-5,27,-36,-65,-4,-46,-6)

$$\begin{bmatrix}
 2 & 1 & 3 & -1 & 3 & -1 \\
 2 & 5 & -2 & 5 & -2 \\
 -1 & -3 & 4 & -12 & 4 \\
 -4 & -12 & 4 & -12 & 4 \\
 -3 & -9 & 3 & -9 & 3
 \end{bmatrix}$$

$$= \left\{ 6, -5, -5, 2, -21, 10, -10, 3 \right\}$$

= { 6,-5,-5,2,-21,10,-10,3}

z[n] = x,[n]+x2[n] = {6,0,7,15,2}

= x[n] * h[n]

here y, [n] + 4, [n]