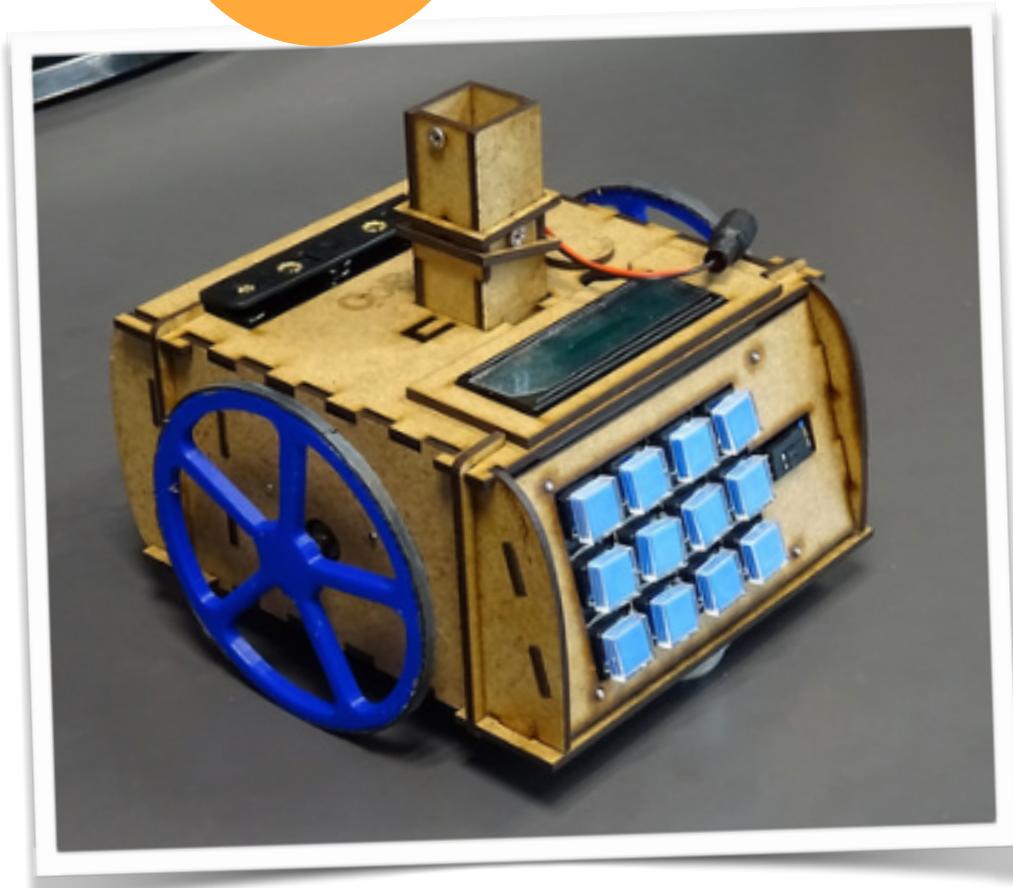
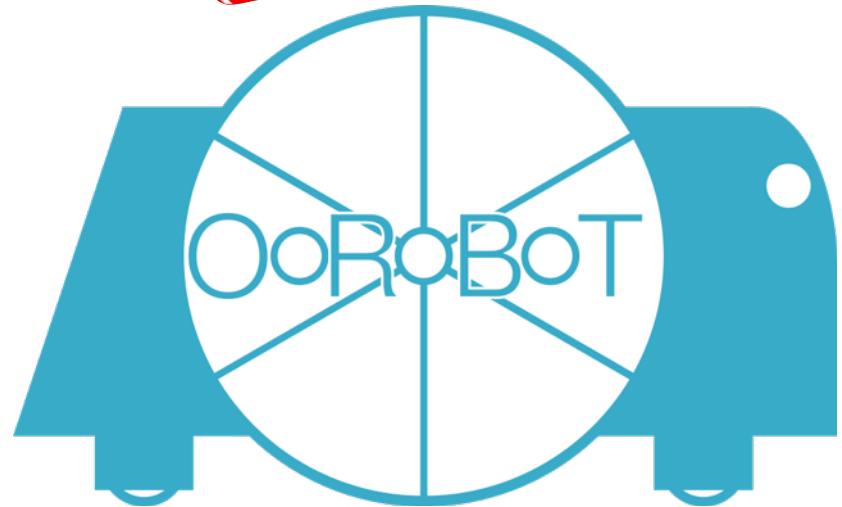


Notice de montage Oo-Robot pour

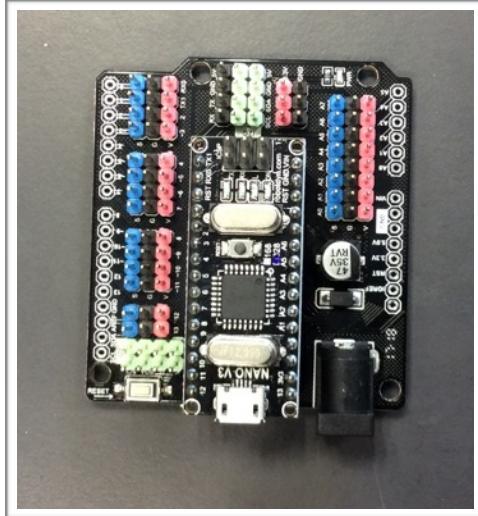
Cycle
3



d'après un projet développé par Matthieu Salvat
document élaboré par Jérôme Breheret et gilles tisseraud

I

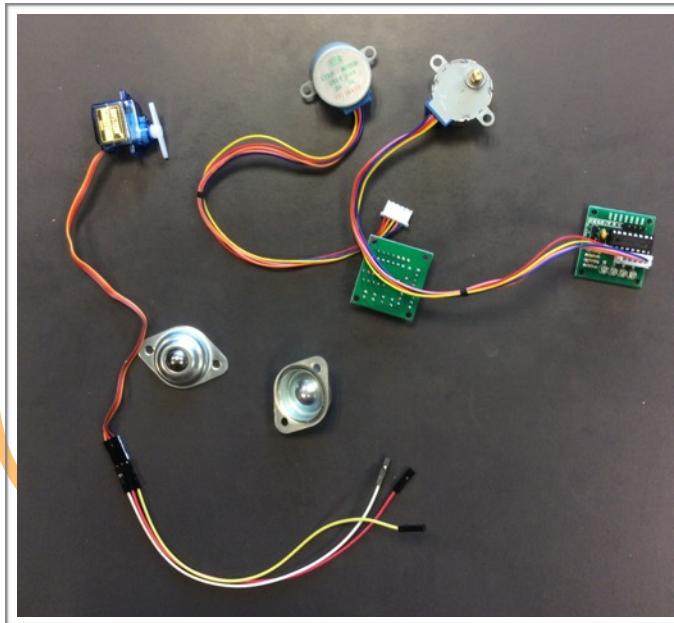
Je vérifie et j'organise mon matériel en les regroupant



les connecteurs et la visserie

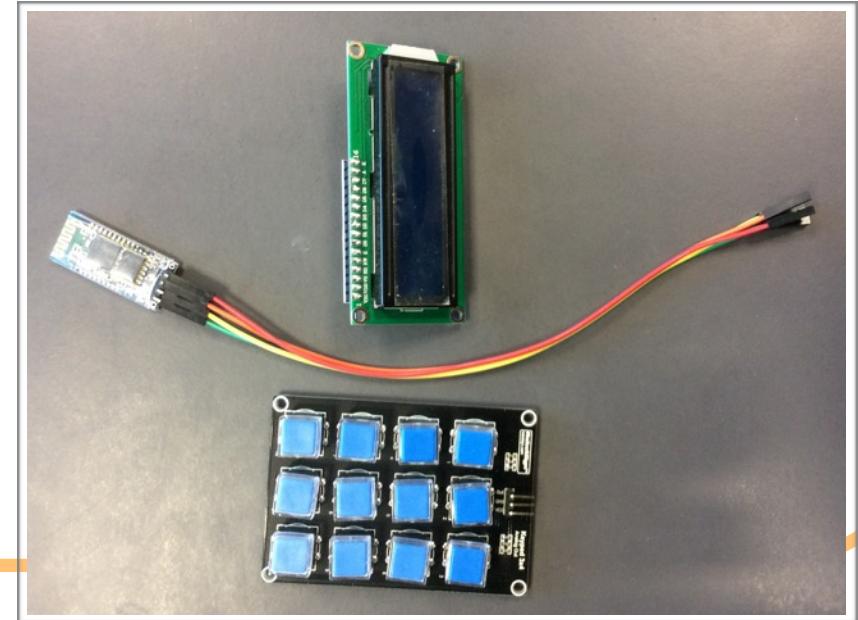


la carte mère
(centre de mon robot)



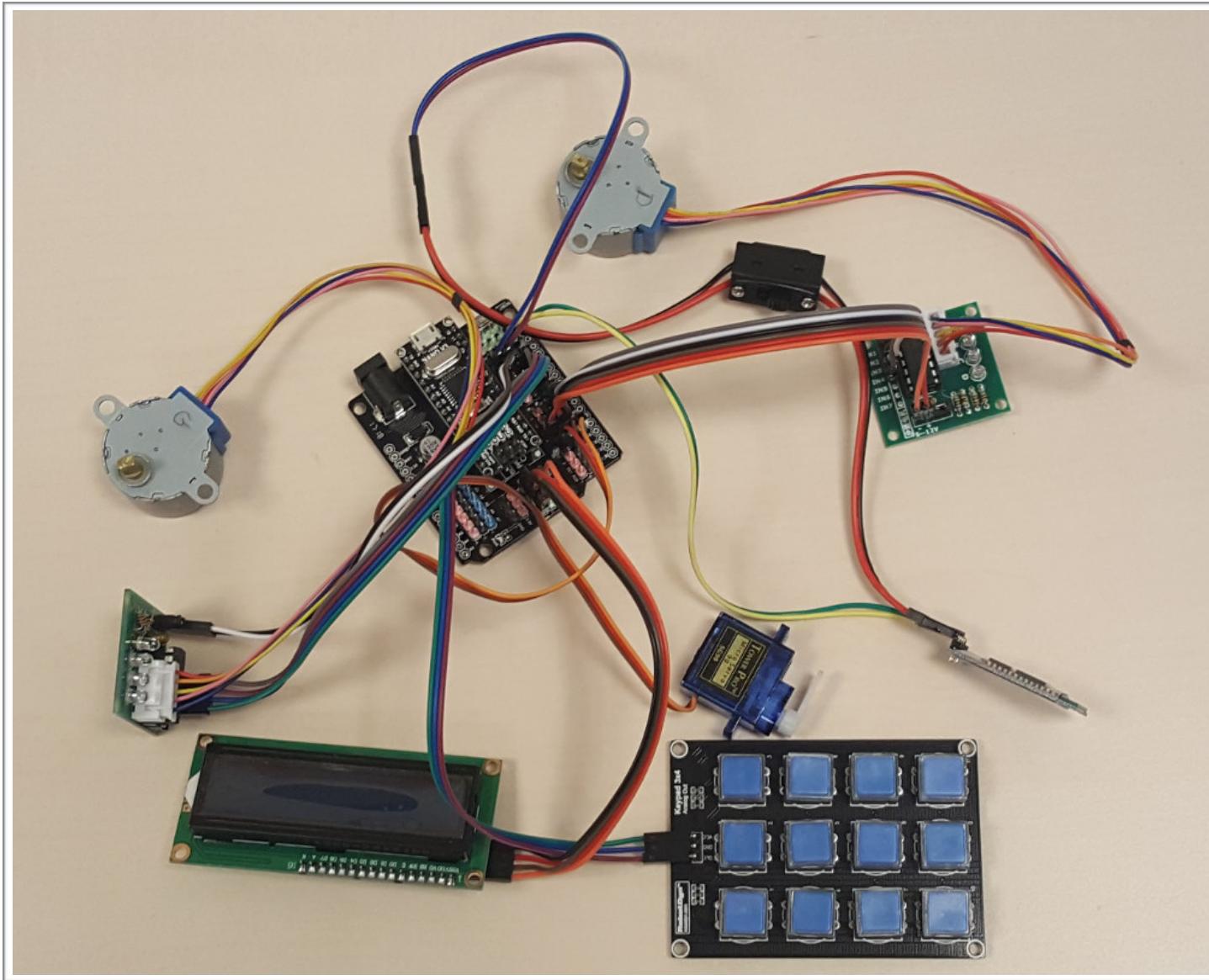
les moteurs

le panneau de
commandes



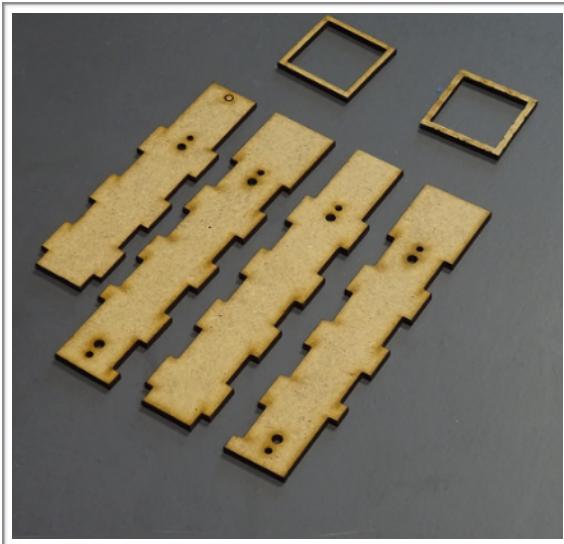
2

Aperçu du montage électronique final.



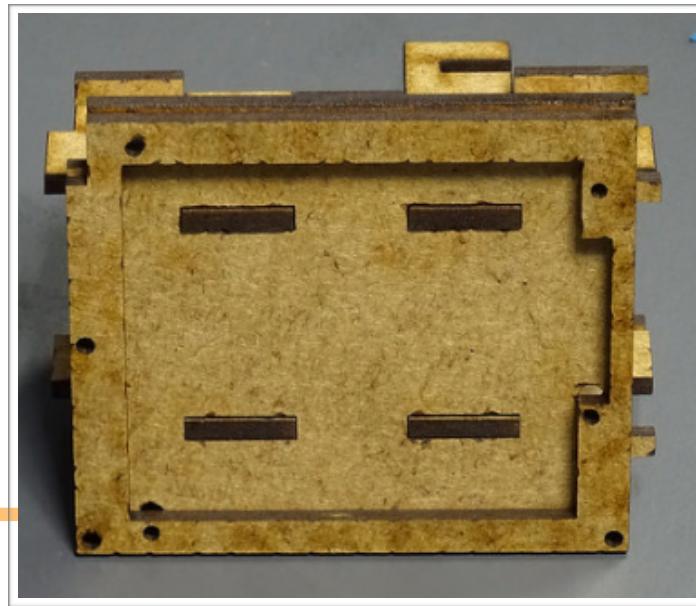
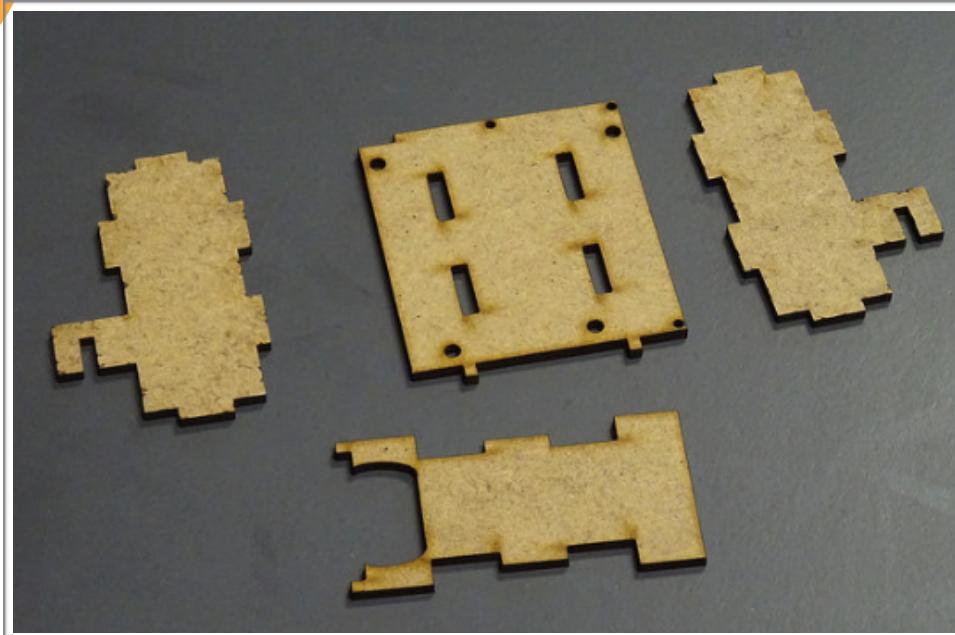
3

C'est parti ! Tout d'abord, on assemble la 1ère partie du support à crayon



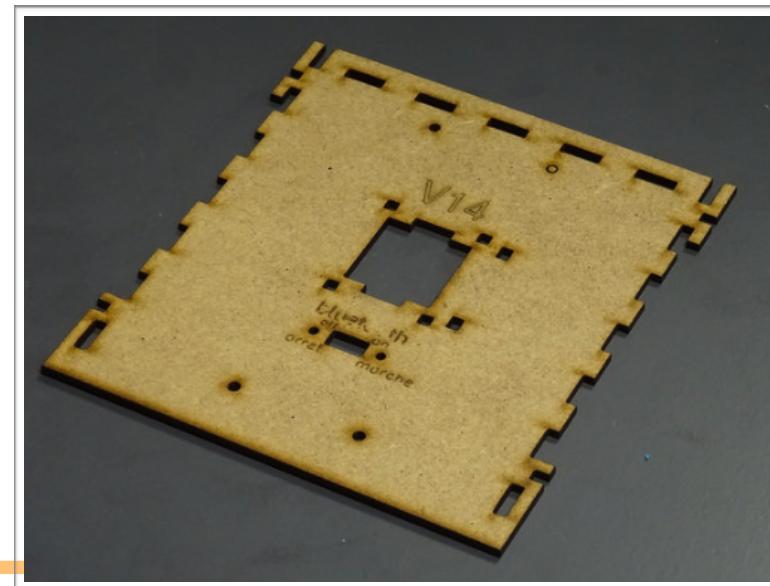
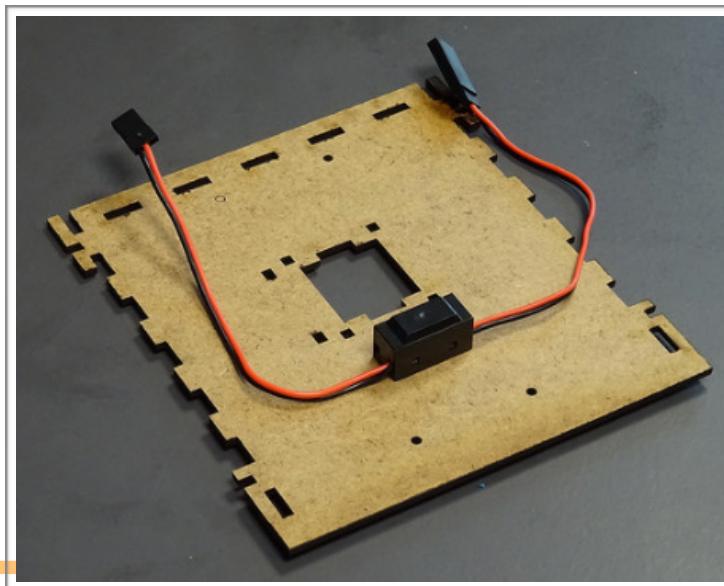
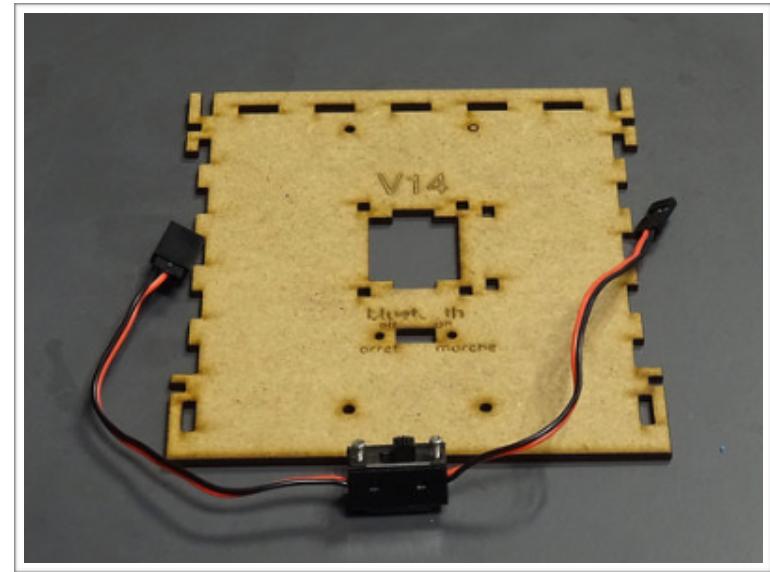
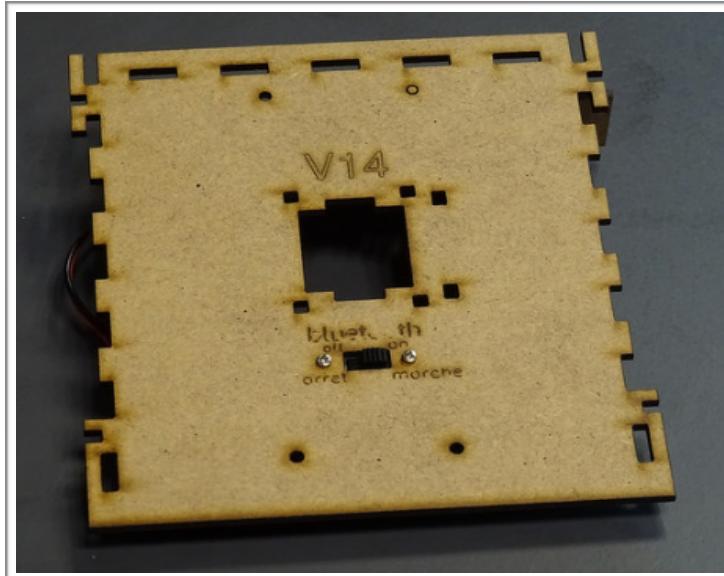
4

Maintenant on assemble la partie externe du support à crayon



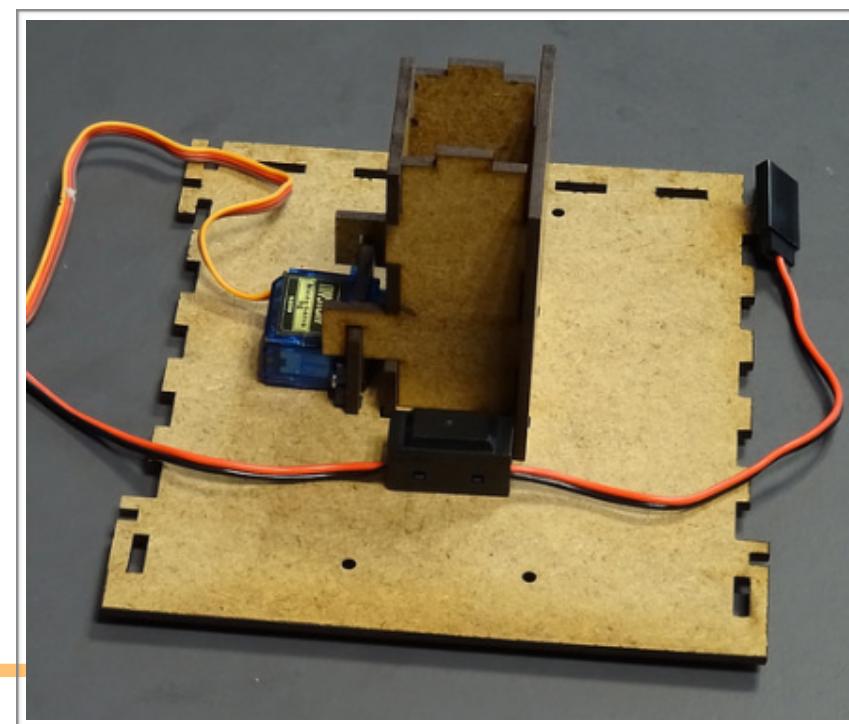
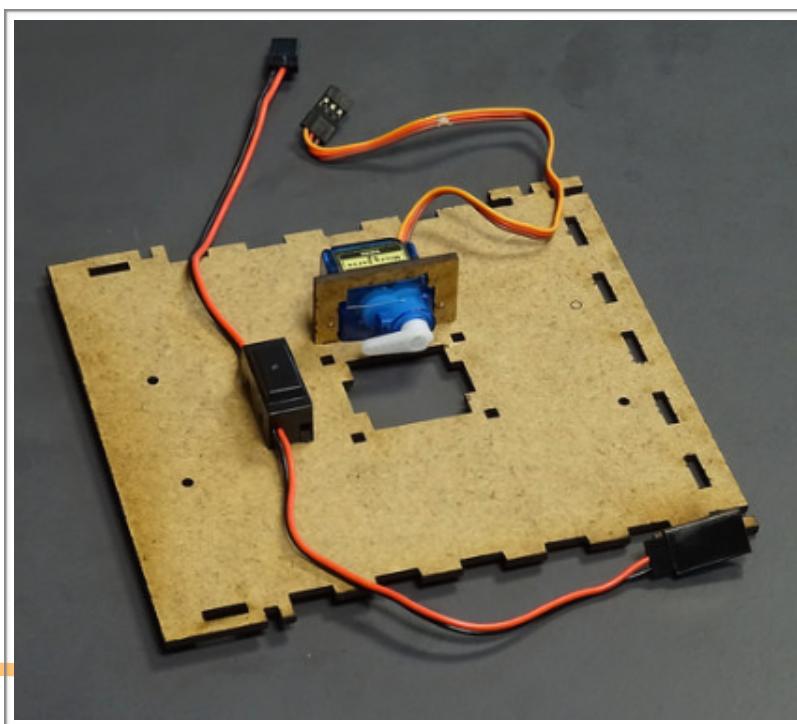
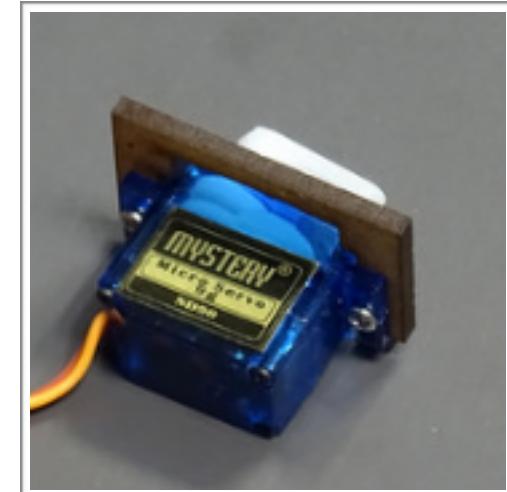
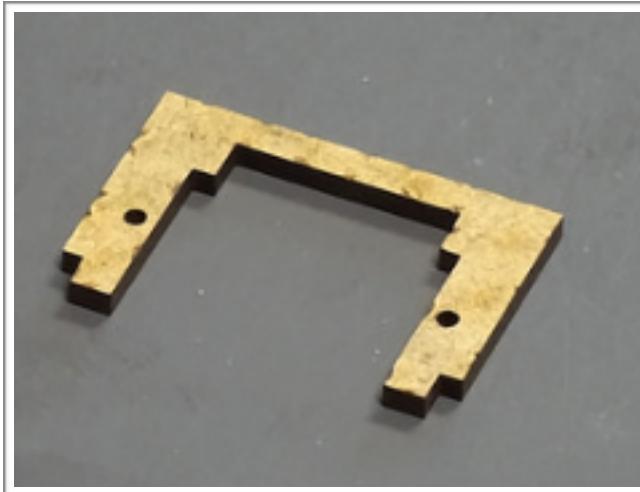
5

On attaque l'assemblage du corps en commençant par fixer l'interrupteur



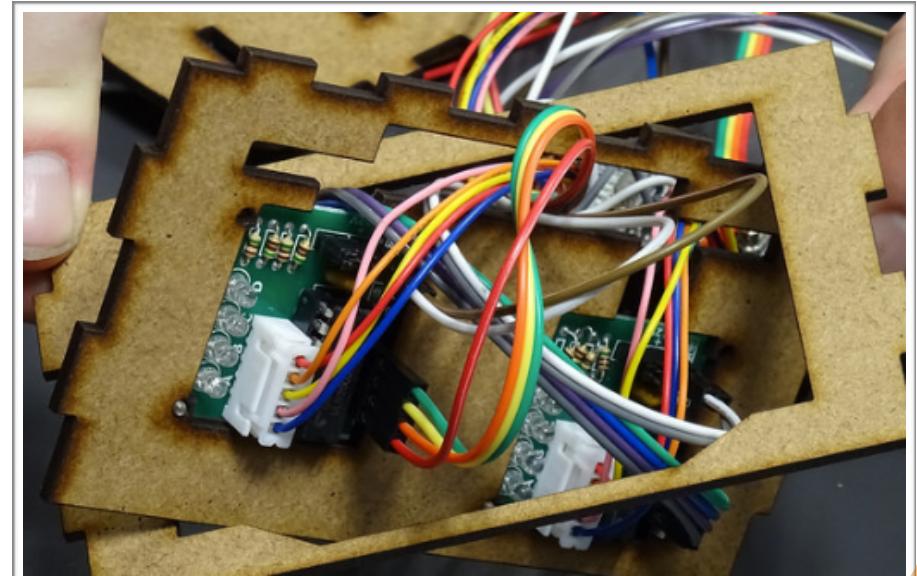
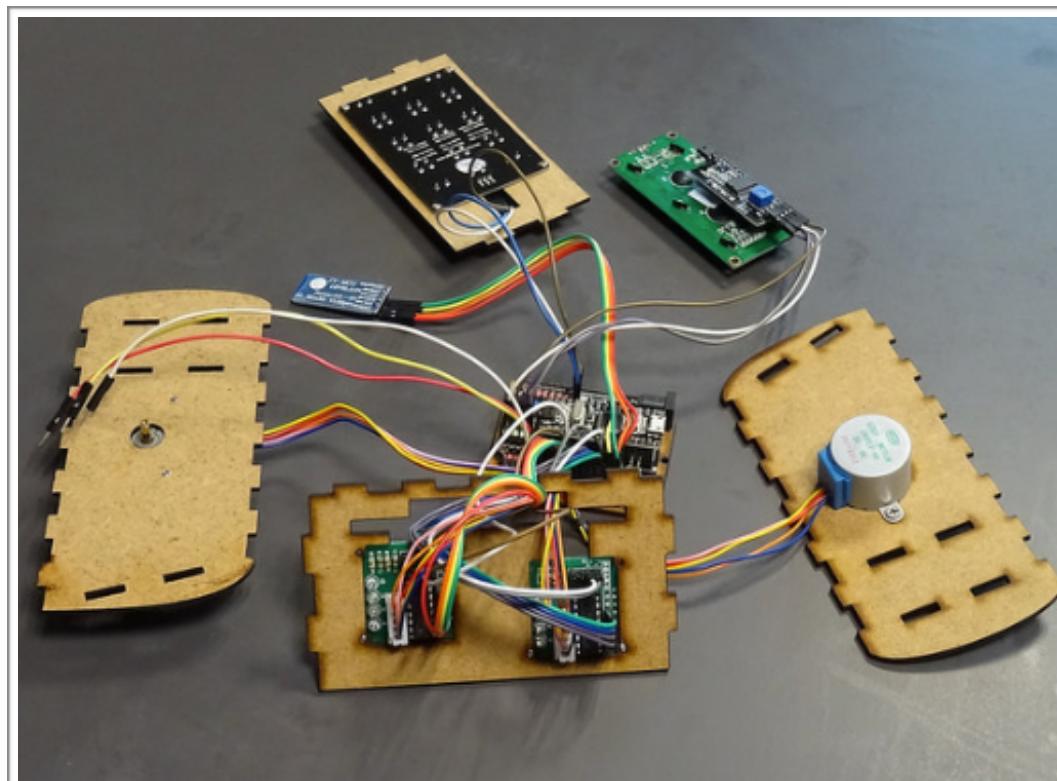
6

Et si on s'occupait des servo moteurs ?



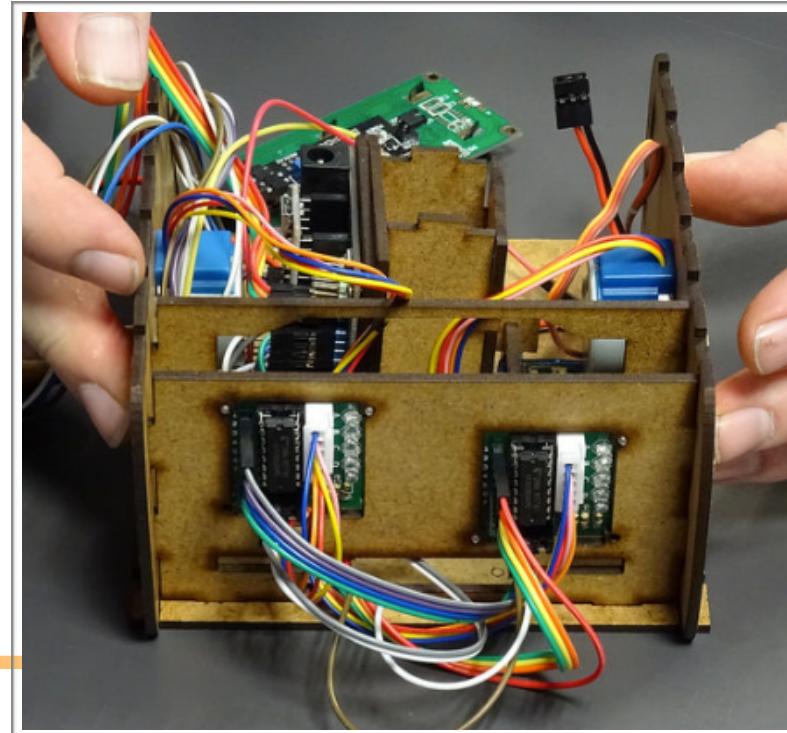
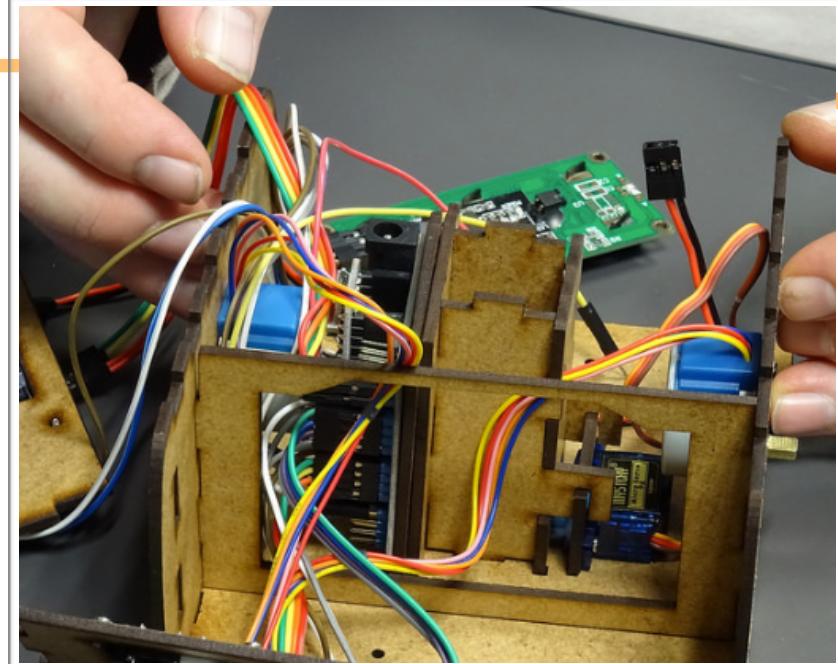
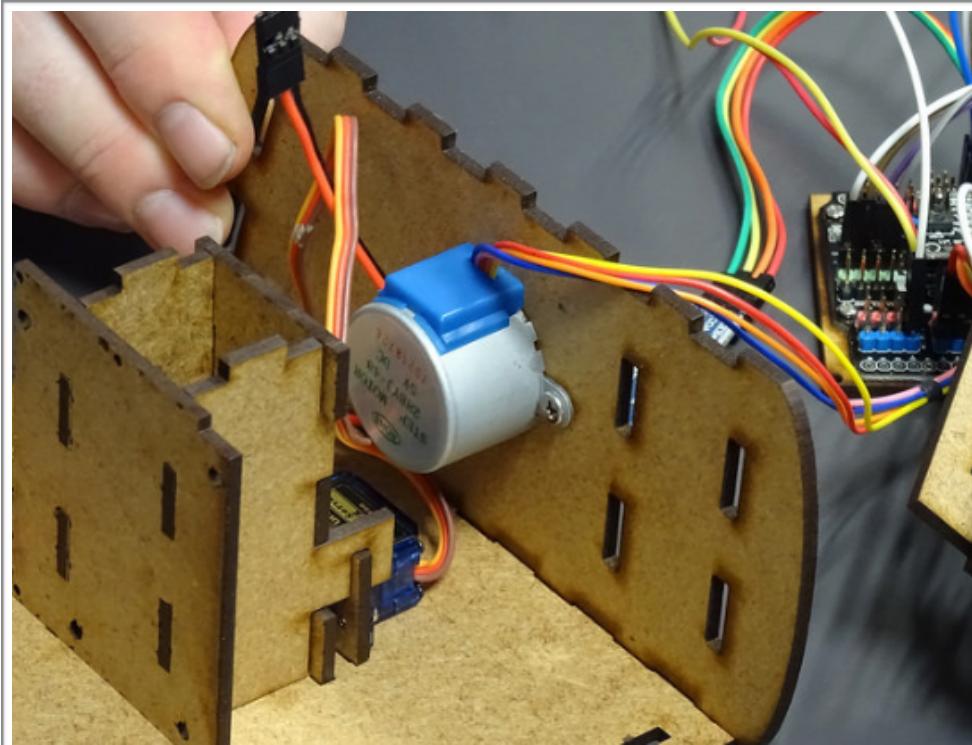
7

Attention pour cette étape, soyez particulièrement vigilants à l'assemblage et aux branchements.



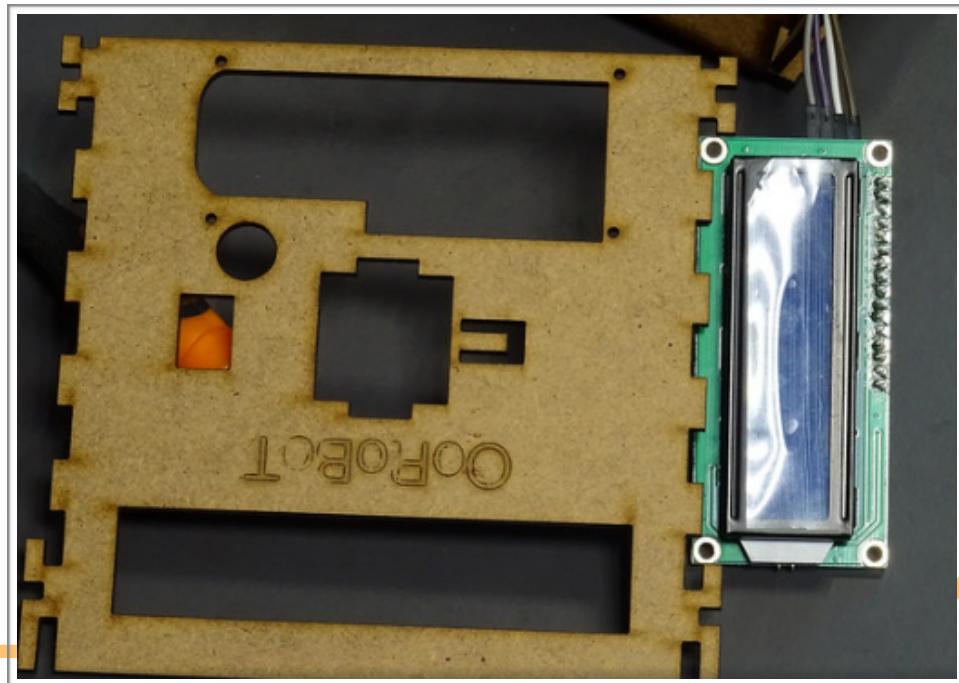
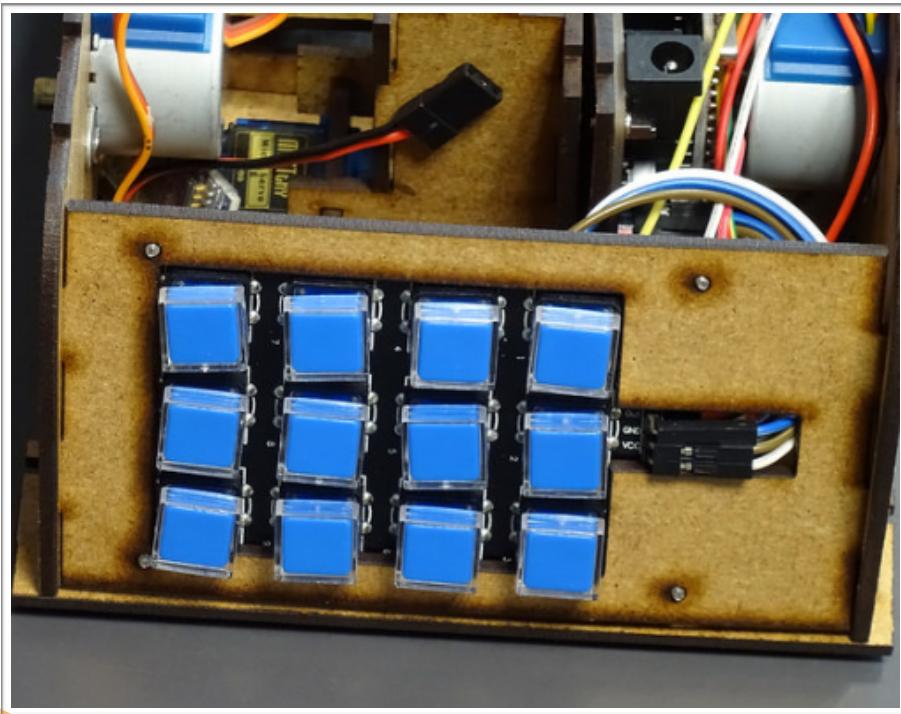
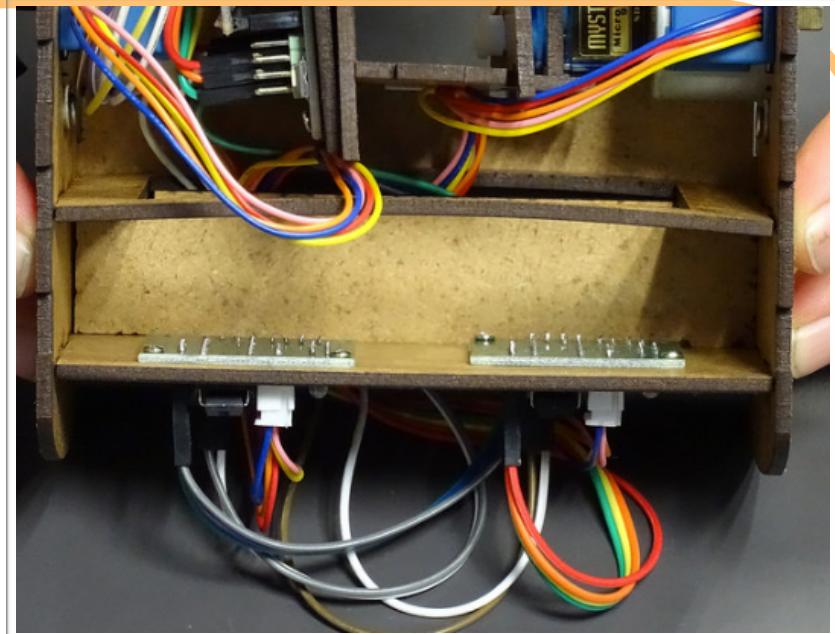
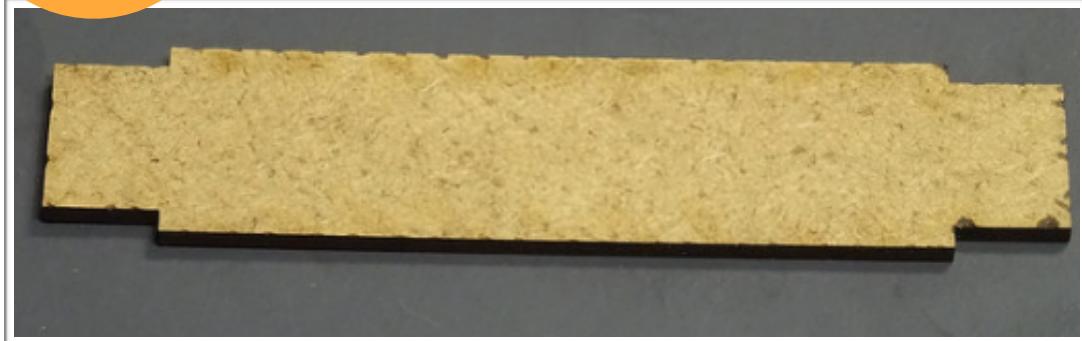
8

Suite de l'étape....



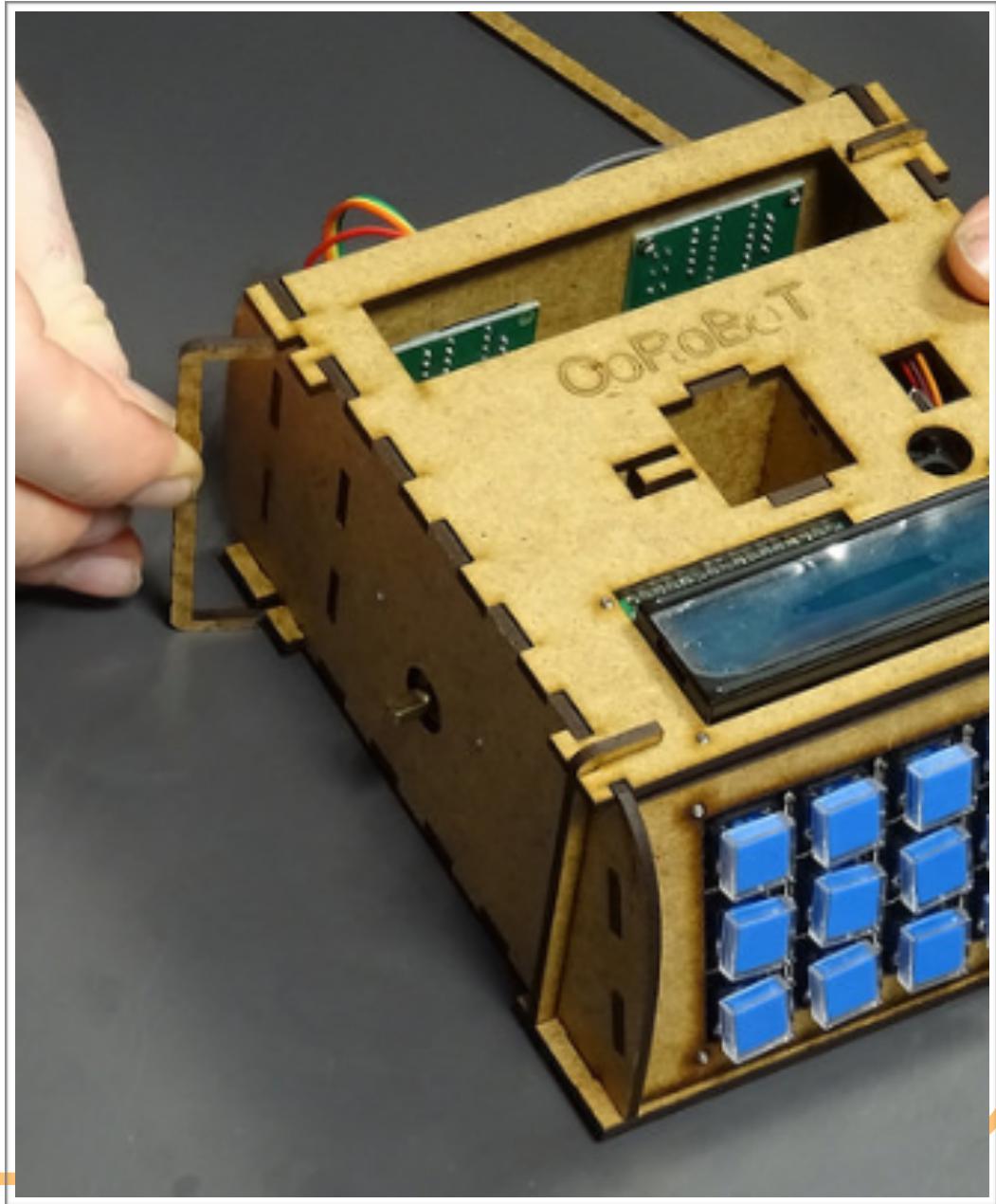
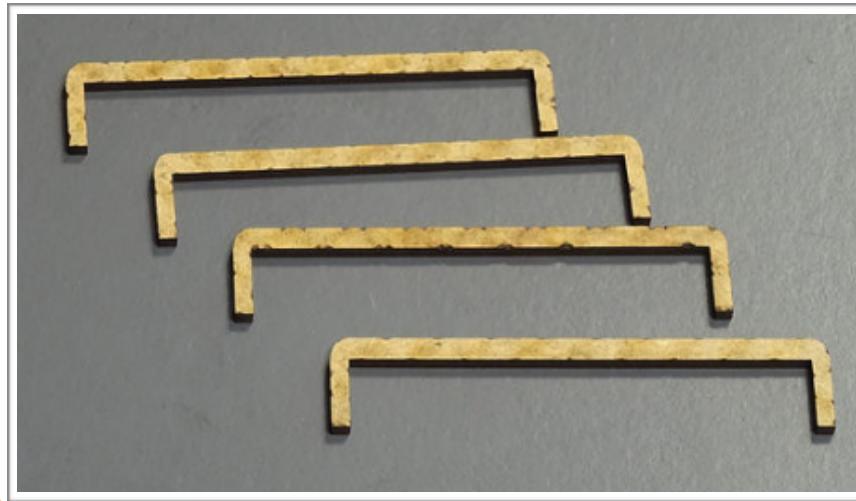
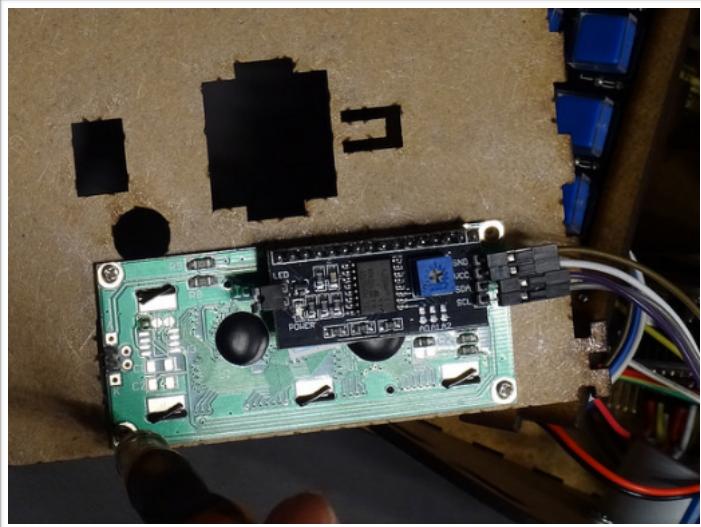
9

Allez, courage, on continue
l'assemblage !



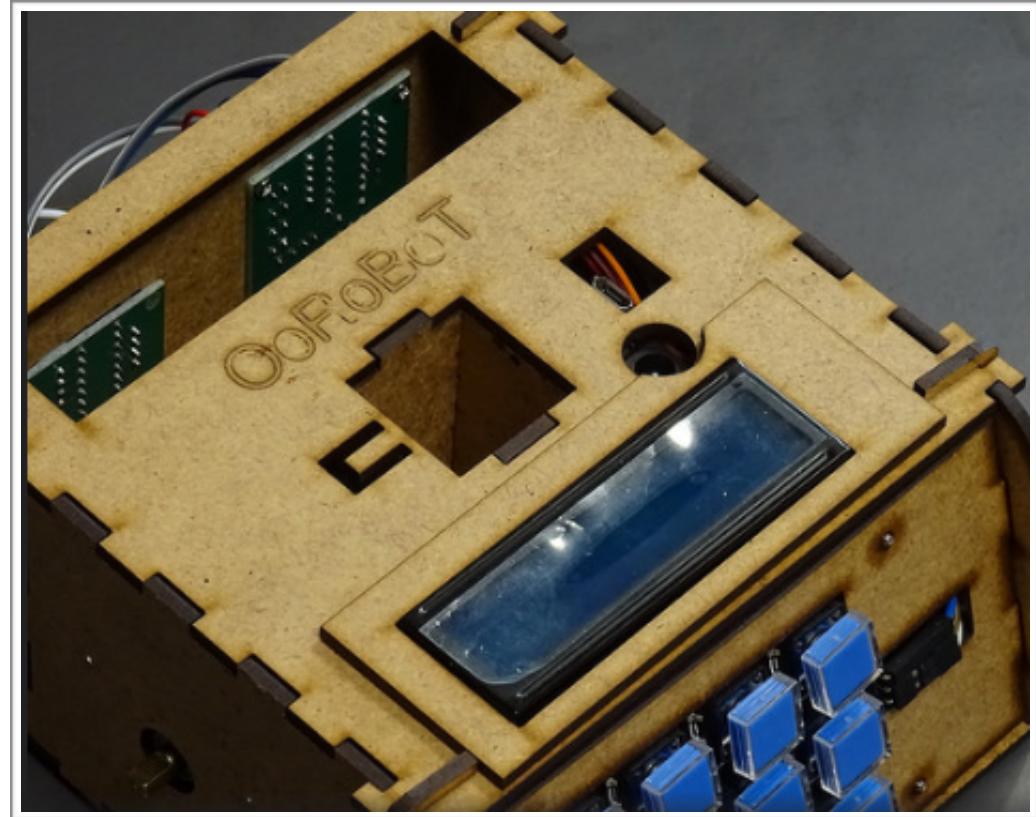
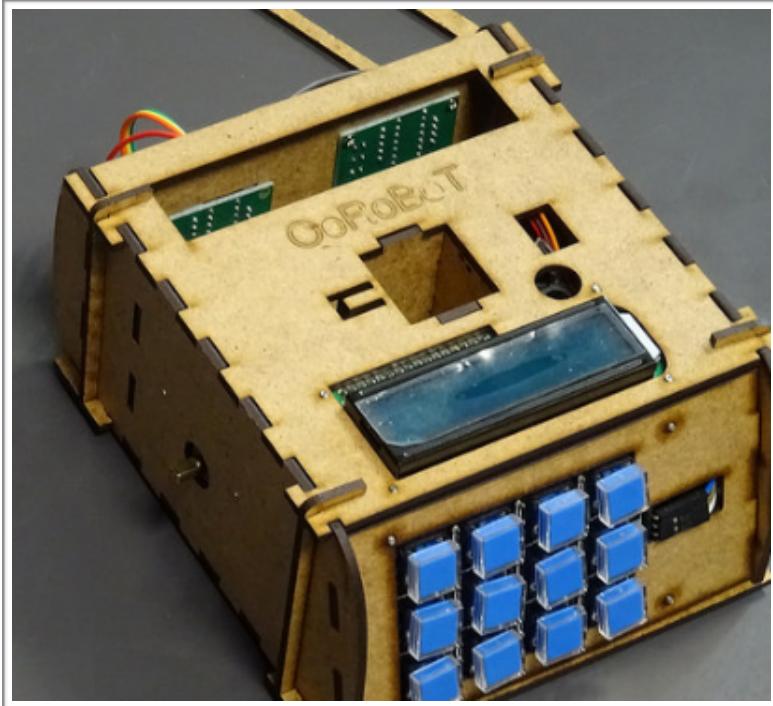
10

Fixation des ergots en « U »



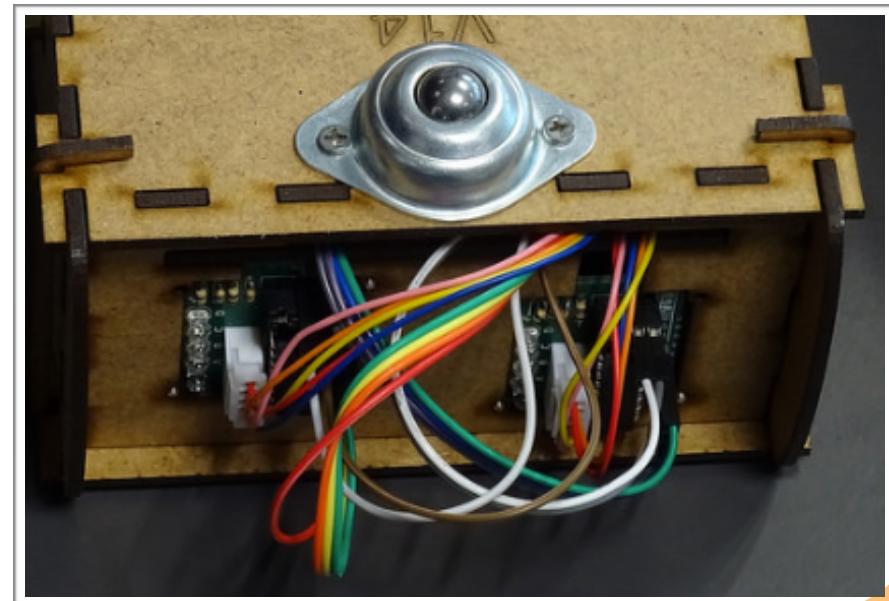
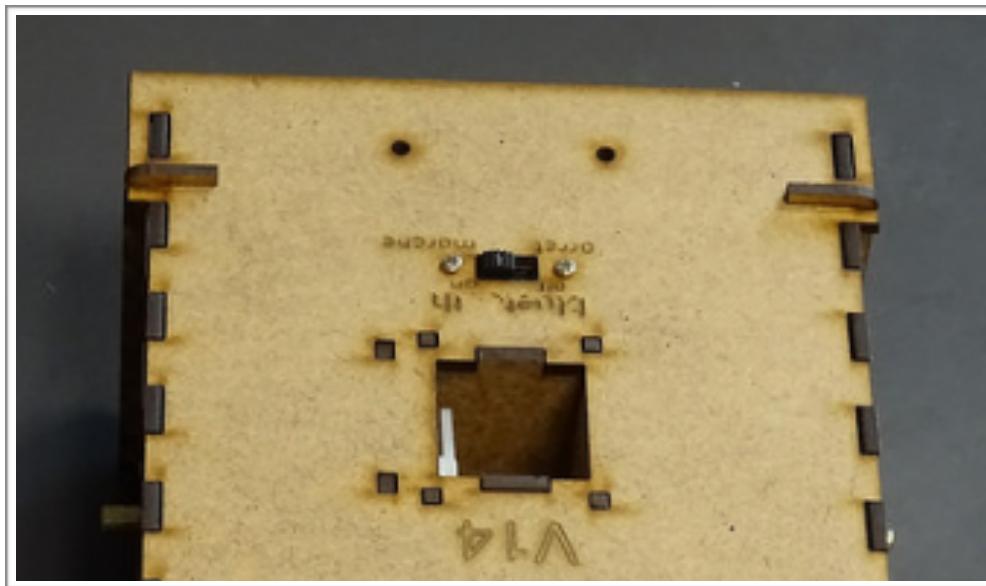
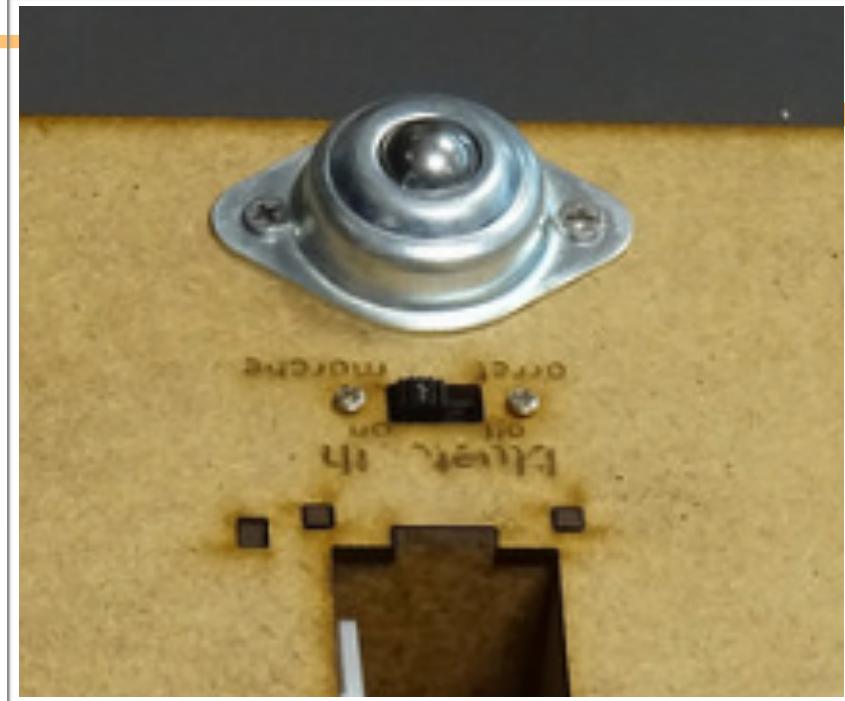
II

il est temps de coller le cache écran à
cristaux liquides



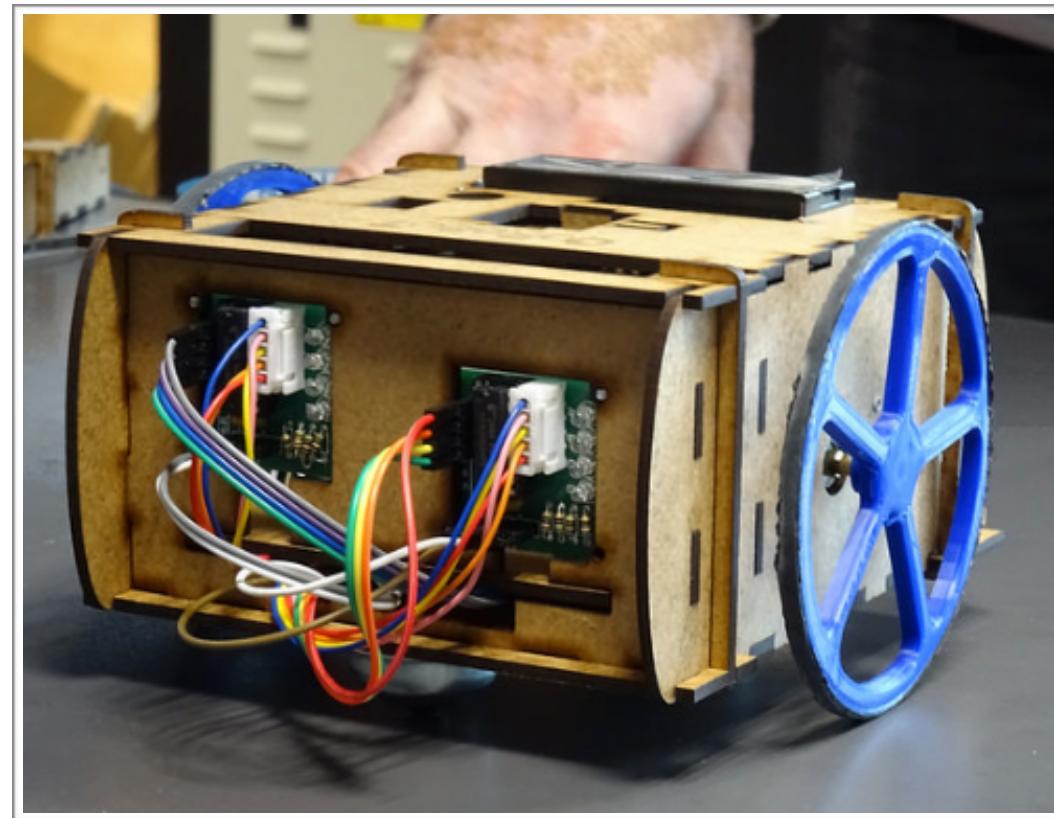
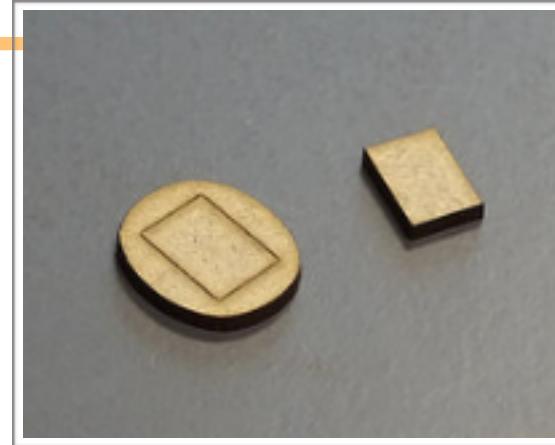
12

On place la roue pivot sous le robot



13

La dernière étape...



14

Et voilà, le robot est maintenant
achevé ! Bravo !

