Harvard CS 121 and CSCI E-207 Lecture 18: Undecidability, Unprovability, Complexity

Harry Lewis

November 9, 2010

• Reading: Sipser §7.1, §7.2

Relation of Undecidability to Gödel's Incompleteness Theorem

- Axiom systems for mathematics, e.g.
 - ullet Peano arithmetic attempt to capture properties of ${\cal N}$
 - E.g. mathematical induction:

```
If P[0] and, for all n, P[n] \Rightarrow P[n+1], then for all n, P[n]
```

- Zermelo-Frankel-Choice set theory (ZFC) enough for all of modern mathematics
- Proofs of theorems from these axiom systems defined by (simple) rules of mathematical logic.

The Decision Problem (for Mathematics)

- Entscheidungsproblem is German for "Decision Problem"
- The Decision Problem is the problem of determining whether a mathematical statement is provable
- **Proposition:** Set of provable theorems is r.e.
- Is it decidable?
- A computation is a proof. A sequence of configurations
 - starting with an initial configuration
 - ending with a halting configuration
 - in which each configuration but the first is the successor of the previous under the TM's transition rules

is a proof that the machine halts.

Undecidability of mathematics

Theorem [Church, Turing]: Set of provable theorems is undecidable.

Proof sketch:

- Reduce from L_{ε} .
- $\langle M \rangle \mapsto$ mathematical statement $\phi_M = M$ halts on ε .
- M halts on $\varepsilon \Rightarrow \phi_M$ has a proof.
- M does not halt on $\varepsilon \Rightarrow \phi_M$ not true.

Incompleteness of Mathematics

Gödel's Incompleteness Theorem: Some true statement is not provable.

Proof sketch:

- For every statement ϕ , either ϕ or $\neg \phi$ is true.
- Suppose all true statements provable.
 - \Rightarrow For all statements ϕ , exactly one of ϕ and $\neg \phi$ is provable.
 - \Rightarrow Set of provable theorems r.e. and co-r.e.
 - ⇒ Set of provable theorems decidable.
- Contradiction.

See Sipser Chapter 6 for more on this & other advanced topics on computability theory.

Objective of Complexity Theory

- To move from a focus:
 - on what it is possible in principle to compute
 - to what is feasible to compute given "reasonable" resources
- For us the principle "resource" is time, though it could also be memory ("space") or hardware (switches)

What is the "speed" of an algorithm?

• **Def:** A TM M has running time $t: \mathcal{N} \to \mathcal{N}$ iff for all n, t(n) is the maximum number of steps taken by M over *all* inputs of length n.

- \rightarrow implies that M halts on every input
- → in particular, every decision procedure has a running time
- \rightarrow time used as a function of size n
- → worst-case analysis

Example running times

Running times are generally increasing functions of n

$$t(n) = 4n$$
.

$$t(n) = 2n \cdot \lceil \log n \rceil$$

 $\lceil x \rceil = \text{least integer} \ge x \text{ (running times must be integers)}$

$$t(n) = 17n^2 + 33.$$

$$t(n) = 2^n + n.$$

$$t(n) = 2^{2^n}.$$

"Table lookup" provides speedup for finitely many inputs

Claim: For every decidable language L and every constant k, there is a TM M that decides L with running time satisfying t(n) = n for all $n \le k$.

Proof:

 \Rightarrow study behavior only of Turing machines M deciding infinite languages, and only by analyzing the running time t(n) as $n \to \infty$.

Why bother measuring TM time, when TMs are so miserably inefficient?

- Answer: Within limits, multitape TMs are a reasonable model for measuring computational speed.
- The trick is to specify the right amount of "slop" when stating that two algorithms are "roughly equivalent".
- Even coarse distinctions can be very informative.

Complexity Classes

• **Def:** Let $t: \mathcal{N} \to \mathcal{R}^+$. Then TIME(t) is the class of languages L that can be decided by some multitape TM with running time $\leq t(n)$.

```
e.g. \mathsf{TIME}(10^{10} \cdot n), \mathsf{TIME}(n \cdot 2^n)
```

 \mathcal{R}^+ = positive real numbers

- **Q:** Is it true that with more time you can solve more problems? i.e., if g(n) < f(n) for all n, is $\mathsf{TIME}(g) \subsetneq \mathsf{TIME}(f)$?
- A: Not exactly . . .

Linear Speedup Theorem

Let $t: \mathcal{N} \to \mathcal{R}^+$ be any function s.t. $t(n) \ge n$ and $0 < \varepsilon < 1$, Then for every $L \in \mathsf{TIME}(t)$, we also have $L \in \mathsf{TIME}(\varepsilon \cdot t(n) + n)$

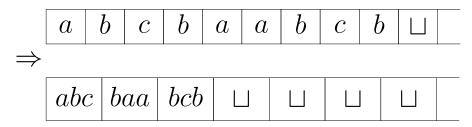
- n = time to read input
- Note implied quantification:

 $(\forall \mathsf{TM}\ M)(\forall \varepsilon > 0)(\exists \mathsf{TM}\ M')\ M'$ is equivalent to M but runs in fraction ε of the time.

 "Given any TM we can make it run, say, 1,000,000 times faster on all inputs."

Proof of Linear Speedup

- Let M be a TM deciding L in time T.
- A new, faster machine M':
- (1) Copies its input to a second tape, in compressed form.



- (Compression factor = 3 in this example—actual value TBD at end of proof)
- (2) Moves head to beginning of compressed input.
- (3) Simulates the operation of M treating all tapes as compressed versions of M's tapes.

Analysis of linear speedup

• Let the "compression factor" be $c\ (c=3\ \text{here})$, and let n be the length of the input.

- Running time of M':
- (1) n steps
- (2) $\lceil n/c \rceil$ steps.
 - $|\cdot|[x]| = \text{smallest integer} \ge x$
- (3) takes ?? steps.

How long does the simulation (3) take?

• M' remembers in its finite control which of the c "subcells" M is scanning.

- M' keeps simulating c steps of M by 8 steps of M':
- (1) Look at current cell on either side.

```
(4 steps to read 3c symbols)
```

- (2) Figure out the next c steps of M.
 - (can't depend on anything outside these 3c subcells)
- (3) Update these 3 cells and reposition the head.

```
(4 steps)
```

End of simulation analysis

- It must do this $\lceil t(n)/c \rceil$ times, for a total of $8 \cdot \lceil t(n)/c \rceil$ steps.
- Total of $\leq (10/c) \cdot t(n) + n$ steps of M' for sufficiently large n.
- If c is chosen so that $c \geq 10/\varepsilon$ then M' runs in time $\varepsilon \cdot t(n) + n$.

Implications/Rationalizations of Linear Speedup

- "Throwing hardware at a problem" can speed up any algorithm by any desired constant factor
- E.g. moving from 8 bit \rightarrow 16 bit \rightarrow 32 bit \rightarrow 64 bit parallelism
- Our theory does not "charge" for huge capital expenditures to build big machines, since they can be used for infinitely many problems of unbounded size
- This complexity theory is too weak to be sensitive to multiplicative constants — so we study growth rate

Growth Rates of Functions

- We need a way to compare functions according to how <u>fast</u> they increase not just how large their values are.
- •
- **Def:** For $f: \mathcal{N} \to \mathcal{R}^+$, $g: \mathcal{N} \to \mathcal{R}^+$, we write g = O(f) if there exist $c, n_0 \in \mathcal{N}$ such that $g(n) \leq c \cdot f(n)$ for all $n \geq n_0$.
 - Binary relation: we could write g = O(f) as $g \leq f$.
 - "If f is scaled up uniformly, it will be above g at all but finitely many points."
 - "g grows no faster than f."
 - Also write $f = \Omega(g)$.

Examples of Big-O notation

- If $f(n)=n^2$ and $g(n)=10^{10}\cdot n$ $g=O(f) \text{ since } g(n)\leq 10^{10}\cdot f(n) \text{ for all } n\geq 0$ where $c=10^{10}$ and $n_0=0$
- Usually we would write: " $10^{10} \cdot n = O(n^2)$ " i.e. use an expression to name a function
- By Linear Speedup Theorem, TIME(t) is the class of languages L that can be decided by some multitape TM with running time O(t(n)) (provided $t(n) \ge 1.01n$).

Examples

- $10^{10} \cdot n = O(n^2)$.
- 1764 = O(1).

1: The constant function 1(n) = 1 for all n.

- $n^3 \neq O(n^2)$.
- Time $O(n^k)$ for fixed k is considered "fast" ("polynomial time")
- Time $\Omega(k^n)$ is considered "slow" ("exponential time")
- Does this really make sense?

More Relations

- **Def:** We say that g = o(f) iff for every $\varepsilon > 0$, $\exists n_0$ such that $g(n) \le \varepsilon \cdot f(n)$ for all $n \ge n_0$.
 - Equivalently, $\lim_{n\to\infty} g(n)/f(n) = 0$.
 - "g grows more slowly than f."
 - Also write $f = \omega(g)$.
- **Def:** We say that $f = \Theta(g)$ iff f = O(g) and g = O(f).
 - "g grows at the same rate as f"
 - An equivalence relation between functions.
 - The equivalence classes are called growth rates.
 - Because of linear speed up, TIME(t) is really the union of all growth rate classes $\leq \Theta(t)$.

More Examples

• Polynomials (of degree *d*):

$$f(n) = a_d n^d + a_{d-1} n^{d-1} + \dots + a_1 n + a_0$$
, where $a_d > 0$.

- $f(n) = O(n^c)$ for $c \ge d$.
- $f(n) = \Theta(n^d)$
 - "If f is a polynomial, then lower order terms don't matter to the growth rate of f"
- $f(n) = o(n^c)$ for c > d.
- $f(n) = n^{O(1)}$.

More Examples

- Exponential Functions: $g(n) = 2^{n^{\Theta(1)}}$.
 - Then f = o(g) for any polynomial f.
 - $2^{n^{\alpha}} = o(2^{n^{\beta}})$ if $\alpha < \beta$.
- What about $n^{\lg n} = 2^{\lg^2 n}$?

Here
$$\lg x = \log_2 x$$

Logarithmic Functions:

$$\log_a x = \Theta(\log_b x)$$
 for any $a, b > 1$