. Documentation

Release

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EUROBOT PACKAGE

1.1 Subpackages

1.1.1 Eurobot.gui package

Submodules

Eurobot.gui.communication module

```
class Eurobot.gui.communication.CanTableControl
    Bases: PyQt4.QtGui.QWidget
    add_data (msg_frame)
    change_typ_filter()
    run_button_clicked()
class Eurobot.gui.communication.EditHost
    Bases: PyQt4.QtGui.QWidget
class Eurobot.gui.communication.SendCan
    Bases: PyQt4.QtGui.QWidget
    selection_changed()
class Eurobot.gui.communication.Table(header)
    Bases: PyQt4.QtGui.QTableWidget
    add_row (data, color, autoscroll, visible)
    filter_types (types)
class Eurobot.gui.communication.TcpConnection(host, port)
    Bases: PyQt4.QtCore.QThread
    run()
Eurobot.gui.field module
```

```
class Eurobot.gui.field.GameField
    Bases: PyQt4.QtGui.QWidget
    draw_robot (painter, robot, scale)
    paintEvent (event)
```

```
setpoint (msg_frame)
```

Module contents

1.1.2 Eurobot.tests package

Submodules

```
Eurobot.tests.can_traffic module
```

```
Eurobot.tests.can_traffic.main()
```

Eurobot.tests.test_can module

```
class Eurobot.tests.test_can.TestCanPacker (methodName='runTest')
    Bases: unittest.case.TestCase
    test_decode_booleans()
    test_encode_booleans()
    test_pack()
    test_unpack()
```

Module contents

1.2 Submodules

1.3 Eurobot.can module

```
class Eurobot.can.Can (interface, sender)
    Bases: builtins.object
    build_can_frame (can_id, data)
    dissect_can_frame (frame)
    recv_can()
    recv_connection()
    send (msg_frame)
    send_can (can_id, can_msg)
    send_connection()

class Eurobot.can.MsgSender
    Bases: enum.Enum

class Eurobot.can.MsgTypes
    Bases: enum.Enum
Eurobot.can.decode_booleans (intval, bits)
    decodes one int value to a list of booleans
```

Parameters

- intval (int) int value
- bits (int) number of bits to decode

Returns list of booleans

Return type bool[]

Eurobot.can.encode_booleans (bool_lst) encodes a list of bool variables to one number

Parameters bool_lst (bool[]) – list of booleans to encode

Returns result

Return type int

Eurobot.can.pack (msg_frame, sender)

Eurobot.can.unpack(can_id, can_msg)

1.4 Eurobot.ethernet module

```
class Eurobot.ethernet.Client (host, port)
    Bases: Eurobot.ethernet._TcpConnection
    connection(s)

class Eurobot.ethernet.Server
    Bases: Eurobot.ethernet._TcpConnection
    connection(s)

wait_connections(s)
```

1.5 Eurobot.gui module

1.6 Eurobot.kern module

```
Eurobot.kern.main()
```

1.7 Eurobot.speak module

Eurobot.speak.speak(text)

1.8 Module contents

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