### Numerical Analysis & Scientific Computing II

# Module 2 Initial Value Problems

- 2.2 Stability
- 2.3 Euler's method
- 2.4 Implicit method



### Initial Value Problems: Implicit Methods

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  - Backward Euler method



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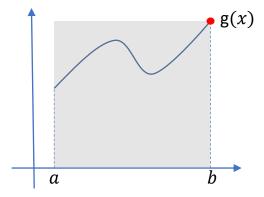
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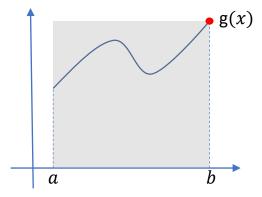
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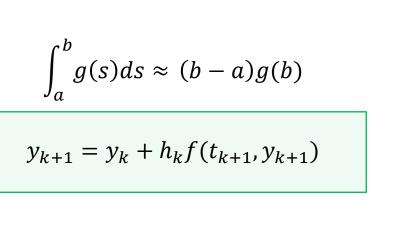
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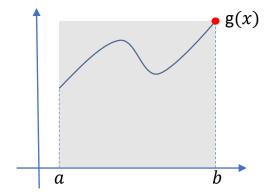
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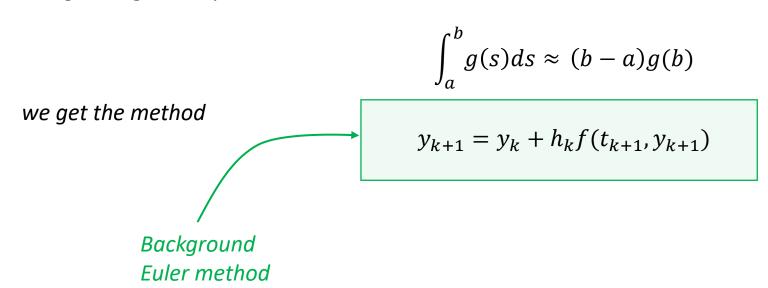
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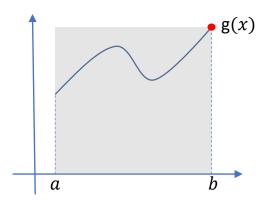
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When  $y_{k+1}$  appears on the righthand side of the method

$$y_{k+1} = \Phi(f, y_{k+1}, y_k, h_k)$$

then the method is called an implicit method.

### Initial Value Problems: Implicit Methods

#### **Example**

Let us solve  $y' = -y^3$ , y(0) = 1 using the backward Euler method taking the uniform step size  $h = h_k = t_{k+1} - t_k = 0.5$ .

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This is a nonlinear equation that can be solved using some of the techniques you learnt in the first course.

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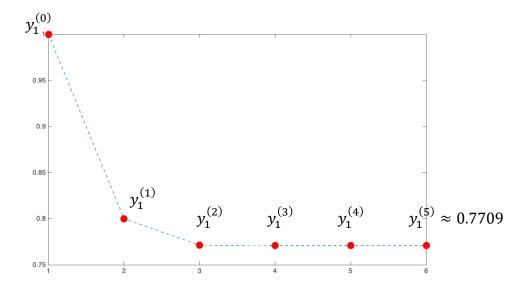
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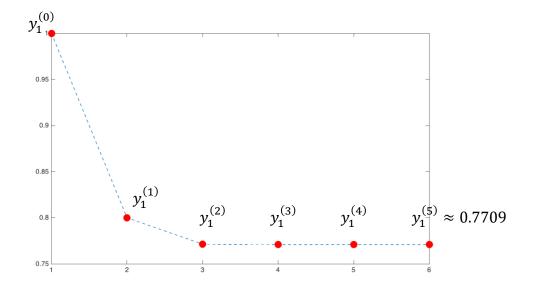


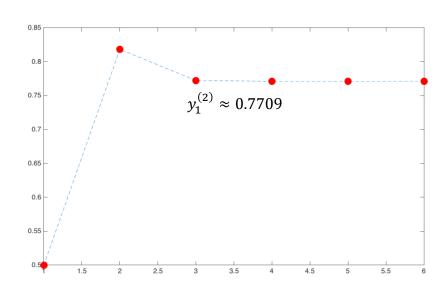
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#### Remark:

In the previous example, we could have used the fixed point iteration  $y_{k+1}^{(n+1)} = y_k + hf\left(t_{k+1}, y_{k+1}^{(n)}\right)$  in place of Newton's iterations

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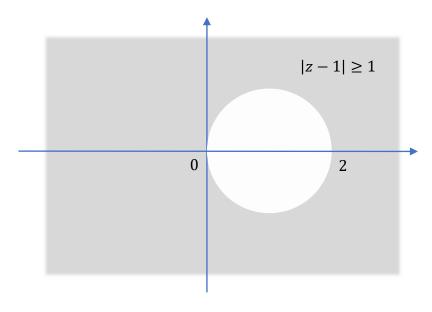
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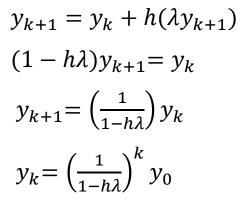
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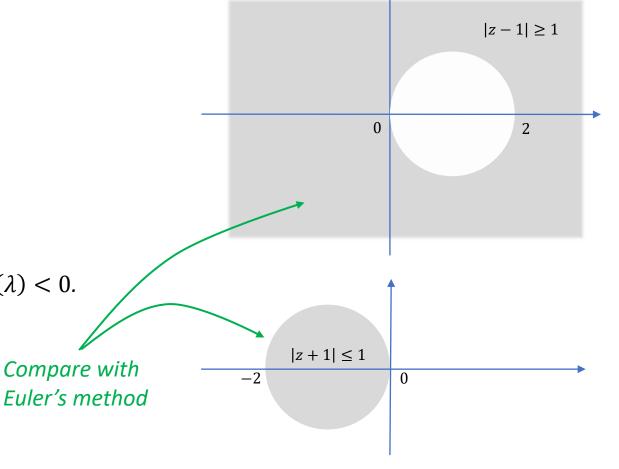
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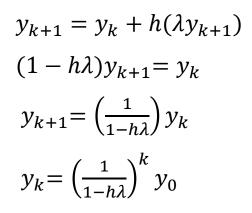
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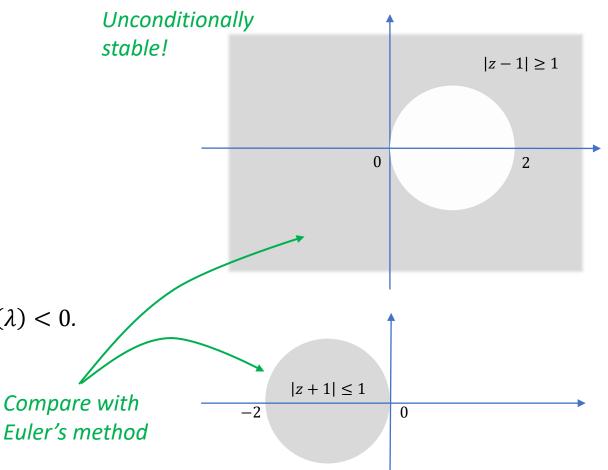
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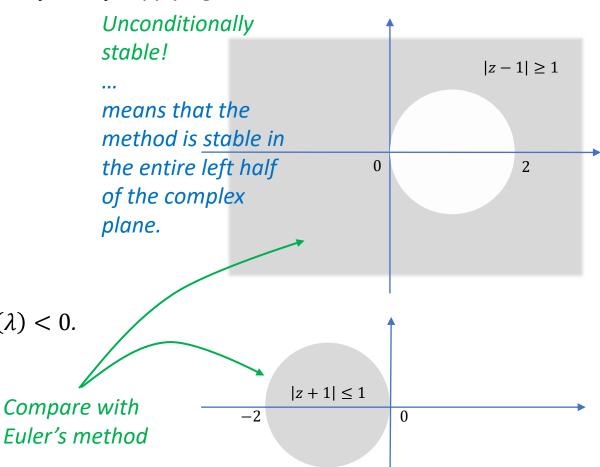
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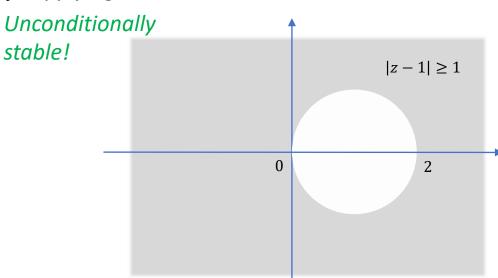
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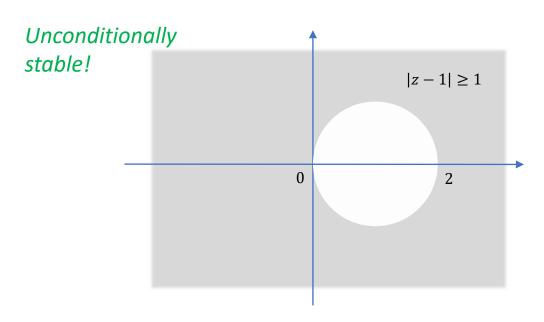
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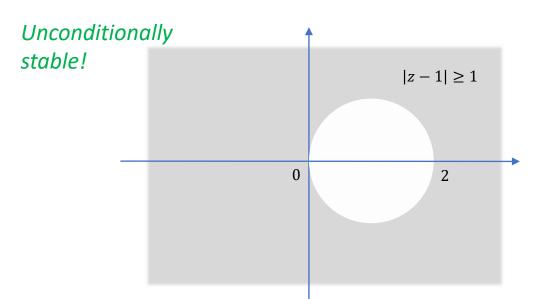
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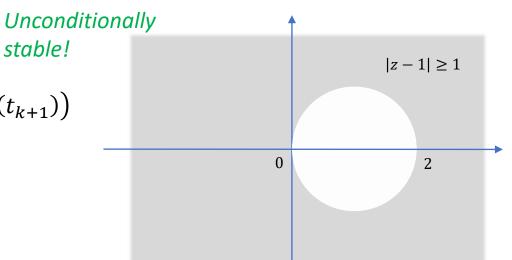
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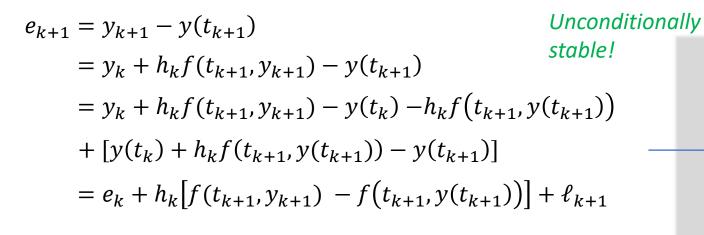
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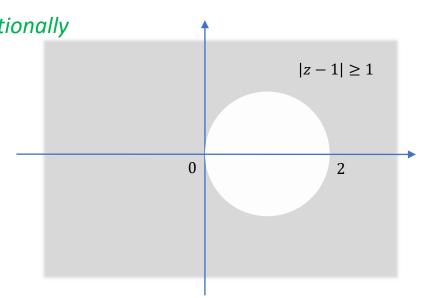
$$= y_k + h_k f(t_{k+1}, y_{k+1}) - y(t_k) - h_k f(t_{k+1}, y(t_{k+1}))$$

$$+ [y(t_k) + h_k f(t_{k+1}, y(t_{k+1})) - y(t_{k+1})]$$
Uncond stable!

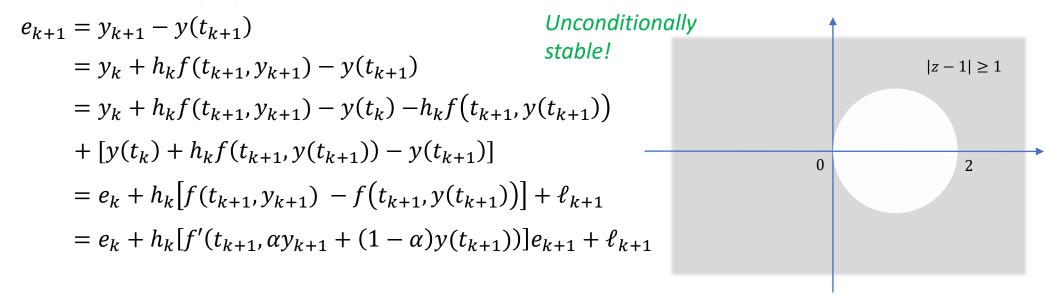


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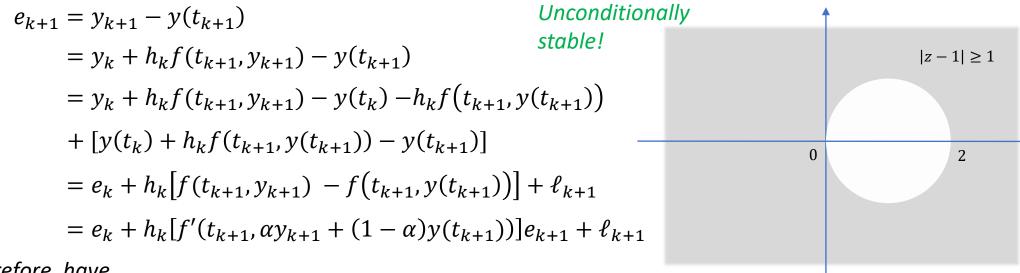


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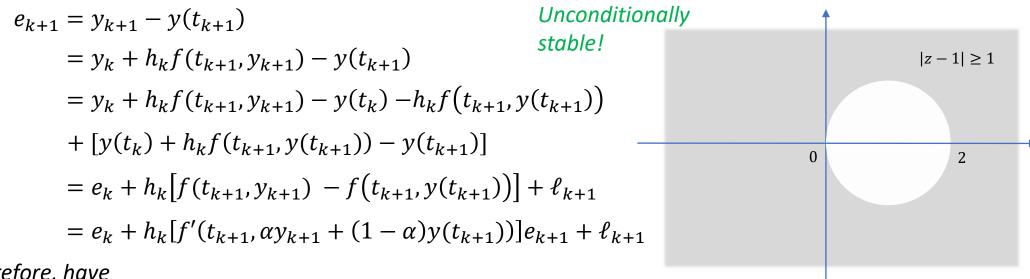


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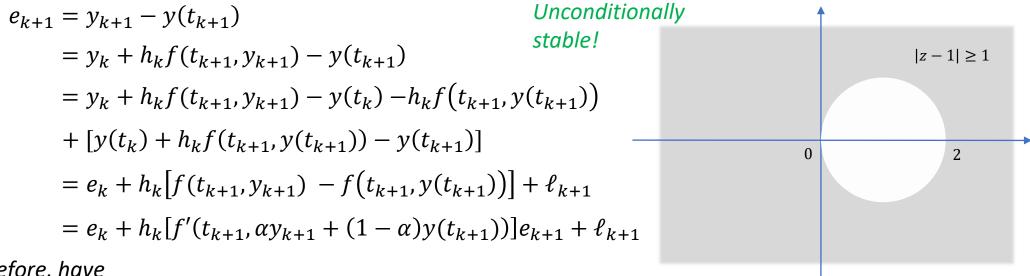


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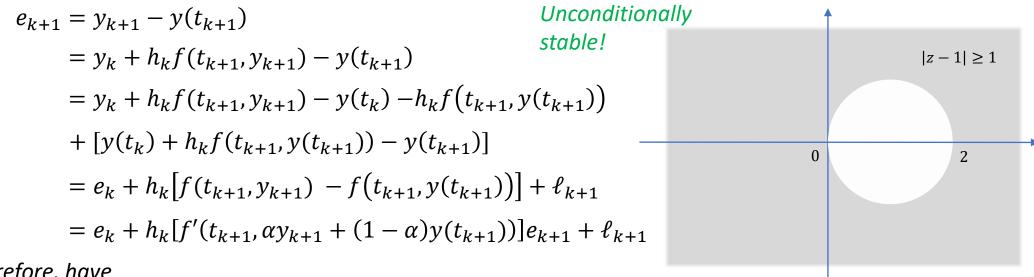
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$$(I - h_k f')e_{k+1} = e_k + \ell_{k+1}$$
 or  $e_{k+1} = (I - h_k f')^{-1}e_k + (I - h_k f')^{-1}\ell_{k+1}$ 

For stability, we need  $\rho(I - h_k f')^{-1} \le 1$ , i.e., eigenvalues of  $h_k f'$  must lie outside the unit circle centered at 1.



For the general ODE y' = f(t, y), we have

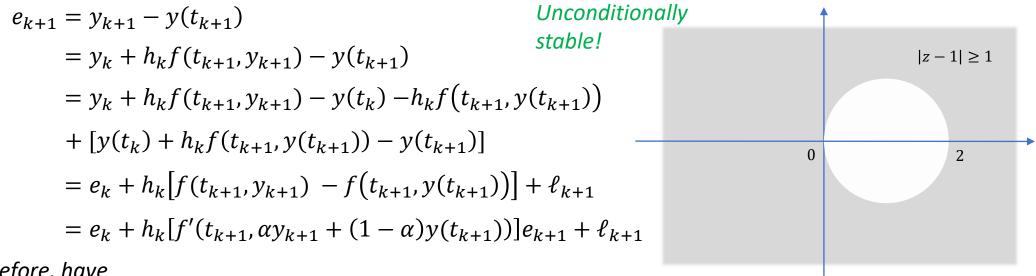


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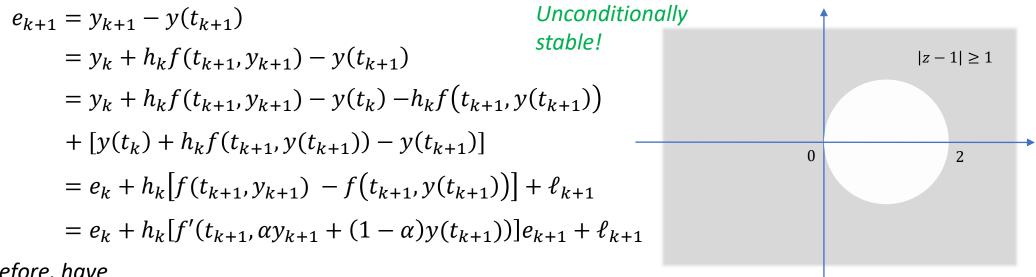
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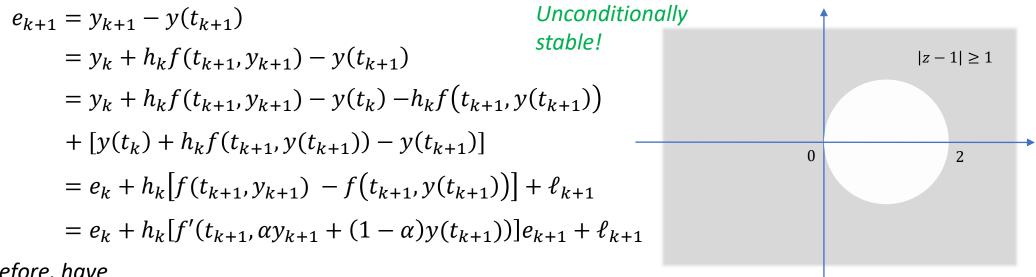
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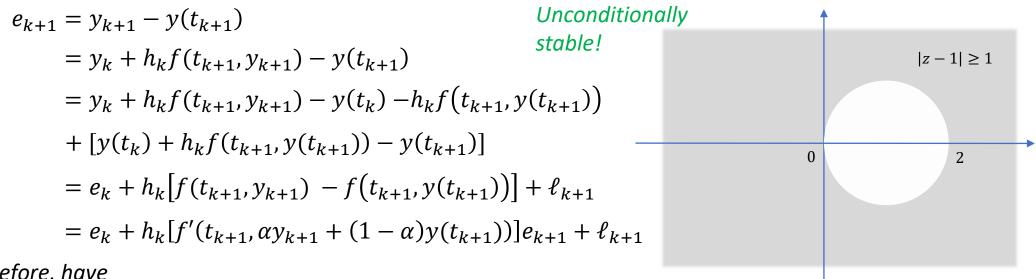
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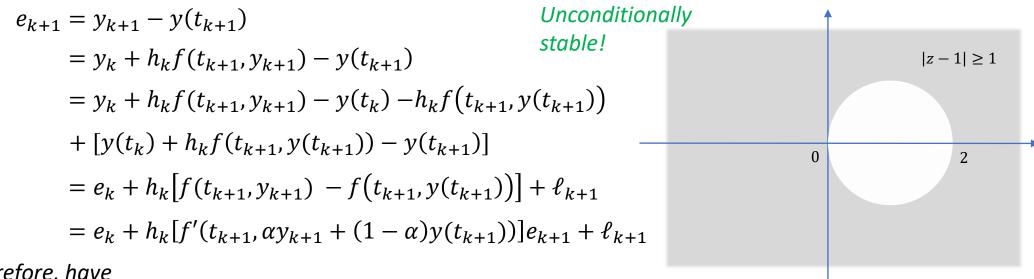
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$$\begin{split} \ell_{k+1} &= y(t_k) + h_k f(t_{k+1}, y(t_{k+1})) - y(t_{k+1}) = h_k f(t_{k+1}, y(t_{k+1})) + [y(t_k) - y(t_{k+1})] \\ &= h_k f(t_{k+1}, y(t_{k+1})) + [(t_k - t_{k+1})y'(t_{k+1}) + O((t_k - t_{k+1})^2)] \\ &= h_k f(t_{k+1}, y(t_{k+1})) + \left[ -h_k f(t_{k+1}, y(t_{k+1})) + O(h_k^2) \right] \end{split}$$



For the general ODE y' = f(t, y), we have



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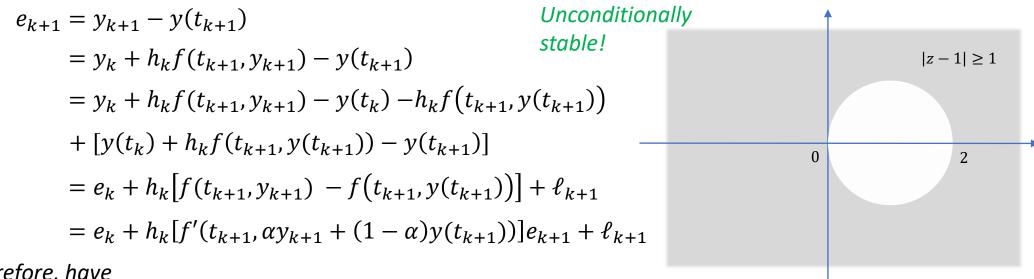
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first-order accurate!