

Theorem

There is a unique solution to the discrete BVP

$$D_h^2 u_h(t_i) = f(t_i), \ t_i, i = 1, ..., n,$$

$$u_h(a) = \alpha, \qquad u_h(b) = \beta.$$

Proof:

It is sufficient to show that, if $D_h^2 u_h(t_i) = 0$ for t_i , i = 1, ..., n, and $u_h(a) = 0$, $u_h(b) = 0$, then $u_h \equiv 0$.



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satisfies

$$||u_h||_{\infty,h} \le \frac{(b-a)^2}{8} ||f||_{\infty,h} + \max\{|\alpha|, |\beta|\}.$$

Boundary Value Problems: Finite Difference Method

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Let
$$w(t) = \frac{1}{2} \left(t - \frac{a+b}{2} \right)^2$$
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Let
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therefore,

$$\max_{1 \leq i \leq n} u_h(t_i) \leq \max_{1 \leq i \leq n} (u_h(t_i) + w(t_i) \|f\|_{\infty,h}) \leq \max \{u_h(a) + w(a) \|f\|_{\infty,h}, (u_h(b) + w(b) \|f\|_{\infty,h}\}.$$



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A similar argument applies to $-u_h$ giving the theorem.

Boundary Value Problems: Finite Difference Method

Theorem

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Proof:

The error estimate follows from the previous theorem applied to the discrete problem

$$D_h^2(u_h - u)(t_i) = D_h^2 u_h(t_i) - D_h^2 u(t_i) = f(t_i) - D_h^2 u(t_i), \qquad i = 1, ..., n,$$

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Corollary

If $u \in C^2([a,b])$, then

$$\lim_{h\to 0} ||u_h - u||_{\infty,h} = 0.$$



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$$\lim_{h\to 0}||u_h-u||_{\infty,h}=0.$$

$$||u_h - u||_{\infty,h} \le \frac{h^2(b-a)^2}{96} ||u^{(4)}||_{\infty,[a,b]}.$$



Remark

The quantity $||f - D_h^2 u|| = ||u'' - D_h^2 u||$ is the consistency error of the discretization and the statement $\lim_{h\to 0} ||u'' - D_h^2 u|| = 0$ means that the discretization is consistent.



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An estimate of the form $||v|| \le C_h ||f||$ whenever $D_h^2 v(t_i) = f(t_i)$, i = 1, ..., n, and v(a) = 0, v(b) = 0, is a stability estimate and if it holds with C_h independent of h, we say that the discretization is stable.



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The previous result can be summarized as "consistency + stability implies convergence".



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The previous result can be summarized as "consistency + stability implies convergence".

As a final remark, the finite difference method helped us find the solution values at the mesh points, but the solution at non-mesh points are not readily available from the method. If needed, one can obtain the solution at non-mesh points through interpolation or try other approximation approaches ...

Numerical Analysis & Scientific Computing II

Lesson 3

Boundary Value Problems for ODEs

- 3.2 Shooting Method
- 3.3 Finite Difference Method
- 3.4 Variational Methods



Boundary Value Problems: Variational Methods

One way to rectify the non-availability of the solution at non-mesh points is to try to approximate the solution using functions coming from a finite dimensional space.

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We again consider a scalar two-point boundary value problem

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with boundary conditions

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We seek the solution of the form

$$u(t) \approx v(t, y) = \sum_{i=1}^{n} y_i \varphi_i(t),$$

where $\varphi_i(t)$ are basis functions defined on [a,b] and y is an n-vector of parameters to be determined.

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The residual r(t,y) := v''(t,y) - f(t,v(t,y),v'(t,y)) measures how well the approximation satisfies the ODE. For an exact approximation, that is, u(t) = v(t,y), we have r(t,y) = 0.