CART: Clarification & Regression Tree

CART, is a powerful tree based method which can be used for regression modelling and for classification tasks.

· CART is a non-parametric approach and does not require any distributional assumption.

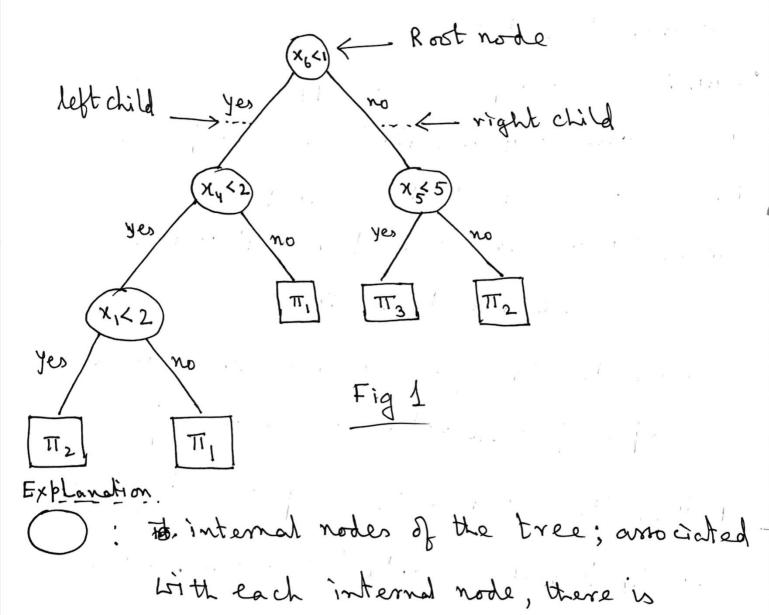
Before we talk about construction of such trees, let us first look at how it works.

Clarification Trees

clamfication tree (or a decision tree) is an example of a so multistage decision process.

Rather than wing the complete set of features i intly to make a output decision, different subsets of features are used at different

levels of the tree



: these are called terminal node or leaf: there is a class label armo ciated with Ihe top most internal node is the "rost" of the tree

a variable and a threshold

Remark: Construction of clarification tree would

revolve around

- (i) how to choose the variable arrociated with any internal node (including the rost node)
- (ii) how to find the thrushold arrowated with the variable at any internal node (iii) how to arrigh class label at the terminal nodes.
- (iv) When to declare a node atanterminal How to use the classification tree?

Suppose we have a feature vector

 $\chi = (5, 3, 6, 2, 1, 3)$ and

wish to use classification tree of Fig 1 to Classify the above feature vector.

S1: He begin with the nost mode; compare the value of ×6 (i.e. 3) with the threshold (which is 1) and find that threshold is exceeded and

hence take the right side path (called the text child of the node)

52: We arrive at the internal node (x5<5) We compare the value of the X5 variable in the feature (i.e. 1) with the threshold at that node (i.e. 5) and find that the thrushold is not exceeded; hence take the left side path (the left child)

53: We at the a terminal node with the last path direction. The terminal node that we have reached has a class label TT3 and hence the allot ment of the girenfeature Vector is TT3, i.e. Le arrign X = (5,3,6,2,1,3) to 113 The rule looks so simple!!

10n't 77)

Remark: The tree classifier in Fig I is an example of a binary decision tree.

Remark: Every internal node induces a partition of feature offace. These partitions induced are hyperplanes parallel to the Goodinate axes.

Remark: The classification partition is induced by the set of terminal nodes

Remark: For every internal node EET, there is a subspace $U(E) \in \mathcal{H}$. This U(E) is the union of then subspaces of the terminal nodes that are it's descendants (i.e. the terminal nodes below t in the tree structure).

Example: classification partitions

2-class problem: TI, LTI2

2-dimensional feature vector $X = (X_1, X_2)$

Clarification tree in given in Fig 2

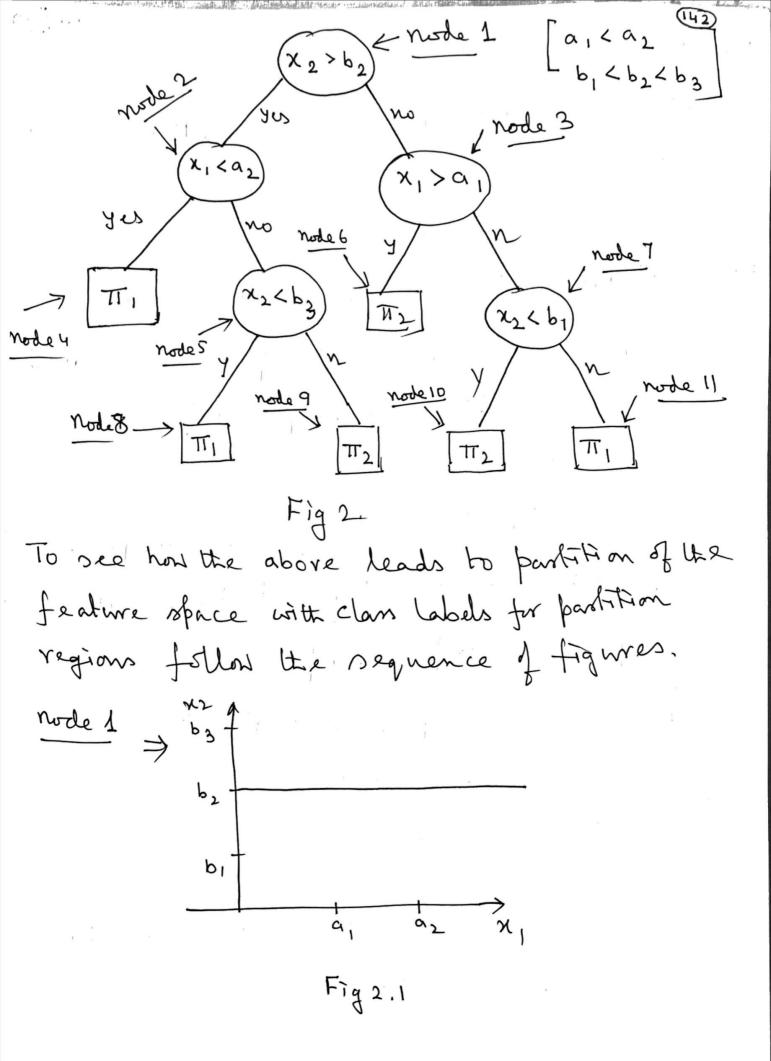
Remark: The tree classifier in Fig 1 is an example of a "binary decision tree". More generally, the ortione of a decision at any node can also be more than 2

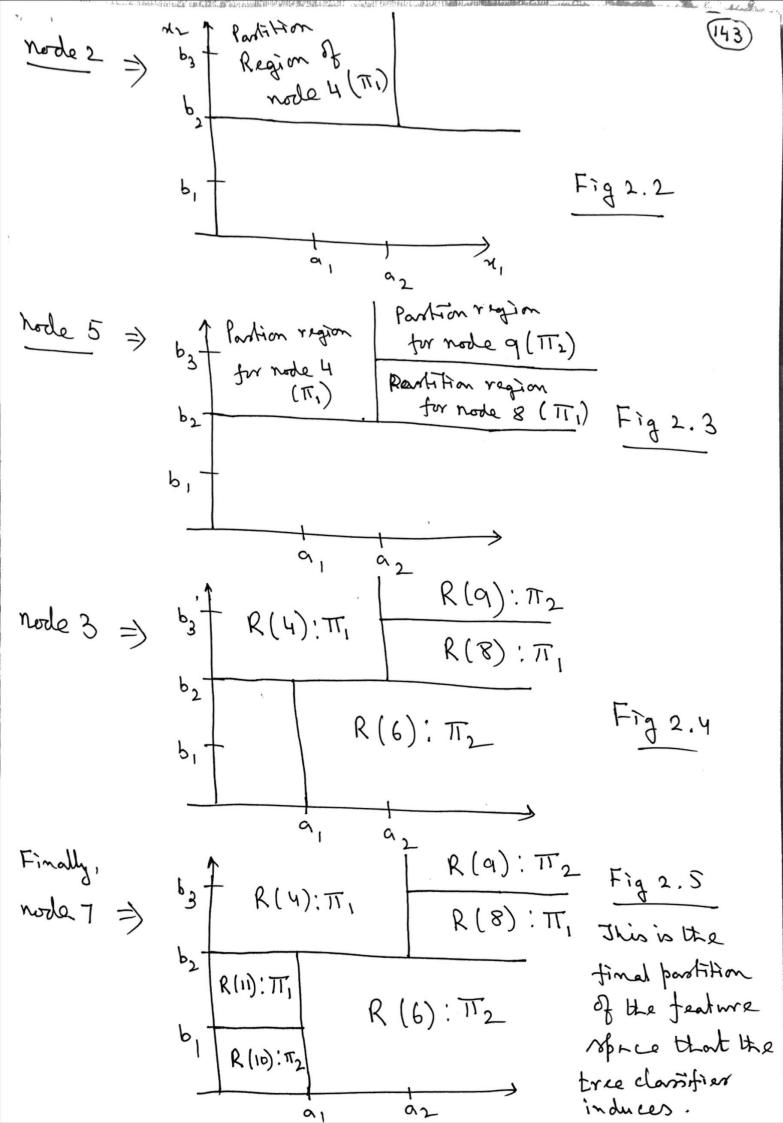
Remark: Binary trees partition the feature Space into 2 parts. The partitions induced (as in Fig 1) are hyperplaner parallel to It e coordinate axes.

> het me try to illustrate the concept of partitions induced by such trees with help of a simple example

Example: 2-clan problem: Ti, & TI 2-dimensional feature vector $\chi = (\chi_1, \chi_2)'$

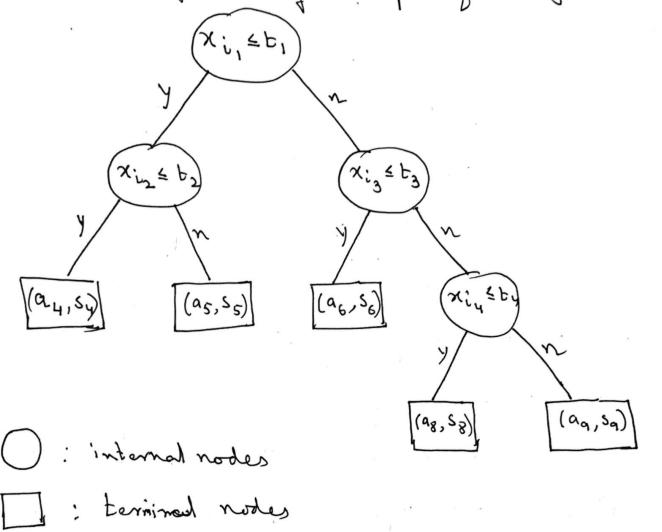
> Let the constructed clamfication tree be given by Fig 2





Regression Trees

Consider the following example of a regression tree



ij : it split van able

tj: split point value

: avg of all the response values of putterns ind

reaching terminal node i.

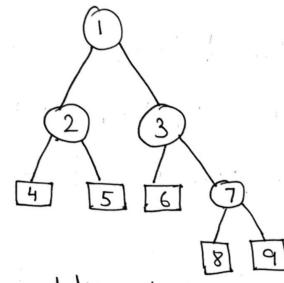
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Remark: Regression trees look very much the same as clamification trees, with optit variables & split points. The terminal nudes are characterised by any of

response van able values (in contrart to (43) class labels as in classification trees) of patterns in the learning set & that reaches a particular terminal node. Kemark: As in the clarification trees, regression trees also induce a partition of the feature vector sopree. The predicted value of the response of a feature rector reaching a particular terminal node (i.e. belonging to the corresponding partition) would typically be the average of all the responses in the learning set (under whose sq error loss), teature vectors

pattores belongs to that partition.

Remark: Suppose the following is a classification or a regression tree



T: tree defined by the nodes {1,2,..,9}

T: set of terminal nodes = {4,5,6,8,9} Partition induced by the tree is defined through the terminal nodes U(4), U(5), U(6), U(8), U(9) each U(i) E X < feature space

> (i) nu(i) = \$ i + j ; i,j=4,5,6,8,9.

D(A) OD(2) OD(8) OD(B) OD(B) = X

Towards tree construction

Some basic definitions

Tree: A tree is defined to be a set T of positive integers together with 2 functions I(.) and r(.) from T to TU{0}.

Each member of T corresponds to a node in the tree.

l(t) and r(t) are left node and right node Values of E(+ t ET) >

- (1) # EET, either l(t) and r(t) are both

 O (in such a of situation to a terminal)

 or l(t) and r(t) are both > 0 (internal

 node)

Sub tree A subtree is a non-empty subset T, of T together with 2 frs l, (.) and r, (.) > $l_1(t) = \{l(t), T \} l(t) \in T_1$

 $v_{i}(t) = \{v(t), T \mid v(t) \in T_{i} \in$

and T, l, (.) and r, (.) form a tree.

Prunned subtree: A subtree that has some root as the original tree

Terminal node set:

T: set of terminal nodes.

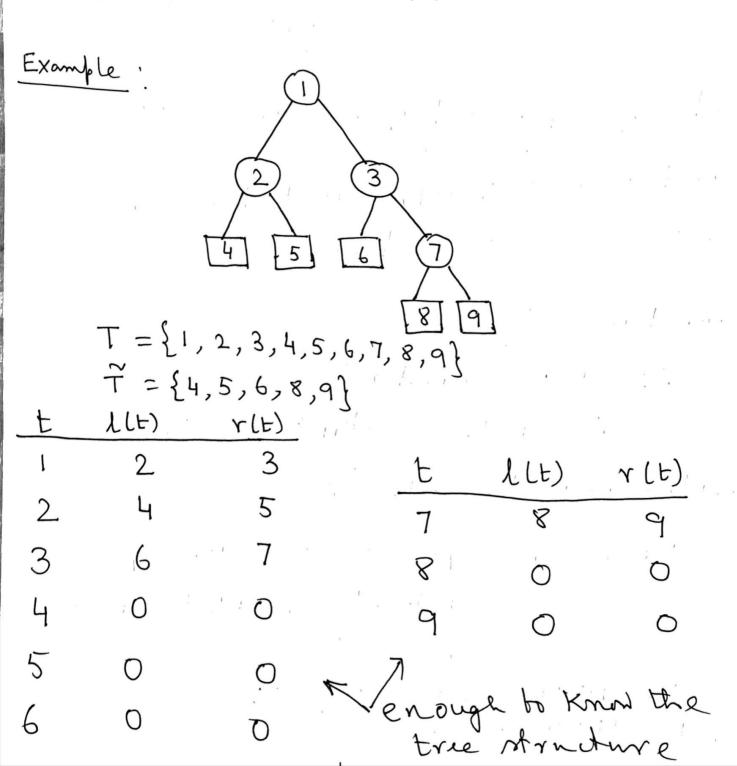
T={b1, b2, -.., bm}; bi ET

Partition induced by a tree T

{U(t): t & T}: partition of feature space induced by T with terminal node set T

D(F) Un(y) = \$ + F = y; F, 26 I and UU(t) = 2c

Remember that arrociated with every non-terminal node t, there is a subspace U(t) of H, which is union of the subspaces of the terminal nodes that are its descendants.



Let
$$T_1 = \{3, 6, 7, 8, 9\}$$
 $T_1 = \{3, 6, 7, 8, 9\}$
 $T_2 = \{3, 6, 7\}$
 $T_3 = \{3, 6, 7\}$
 $T_4 = \{3, 6, 7\}$
 $T_5 = \{3, 6, 7\}$
 $T_7 = \{3, 6, 7\}$

t 12(t) 12(t) 3.6.7. 6 0 0

en in demonstration in