

Initial Value Problems: Accuracy and Stability



Global error

... is the difference

$$e_k = y_k - y(t_k),$$

where y_k is the computed solution at $t = t_k$ and $y(t)$ is the exact/true solution of the ODE passing through the initial point (t_0, y_0) .

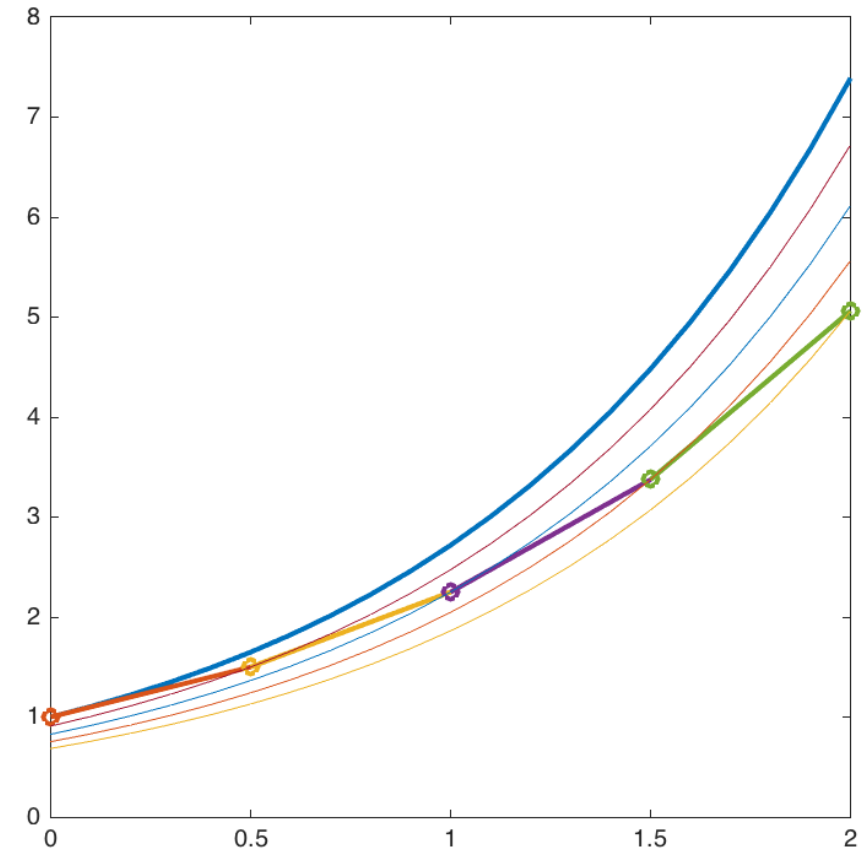
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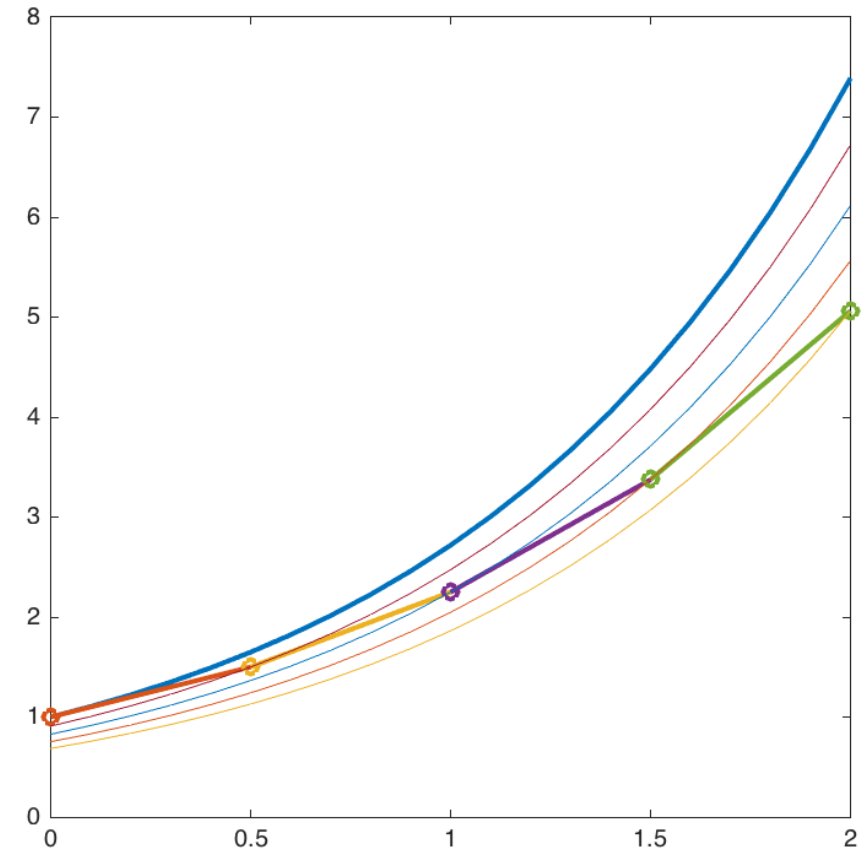
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We see that the local error at a given time step is simply the amount by which the solution of the ODE fails to satisfy the method.



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More generally, for a one step method

$$y_{k+1} = y_k + h_k \phi(t_k, y_k, h_k)$$

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In order to assess the effectiveness of a numerical method, we need to characterize both

- a) its local error (**accuracy**), and
- b) the compounding effects over multiple steps (**stability**).

Numerical Analysis & Scientific Computing II

Module 2

Initial Value Problems

2.1 Well-posedness

2.2 Stability

2.3 Euler's method

- Accuracy and Stability



Akash Anand
MATH, IIT KANPUR

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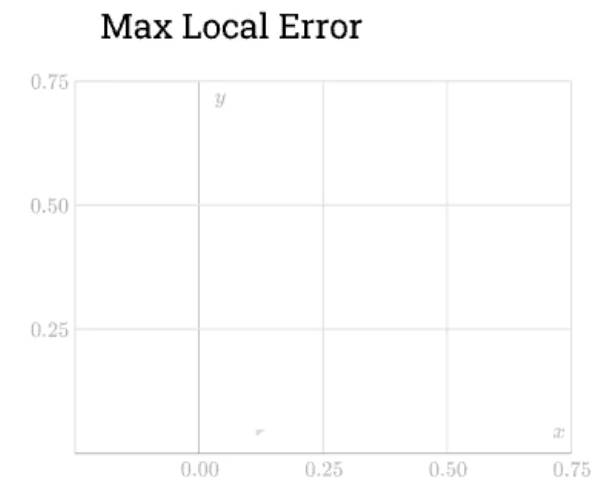
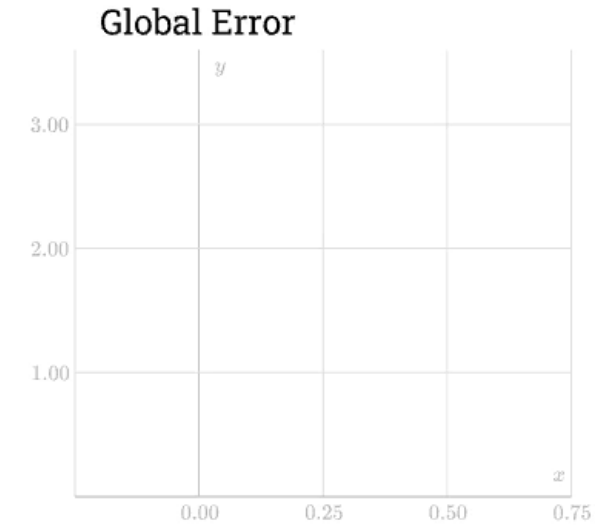
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$$y_k = (1 + \lambda h)^k y_0$$

The quantity $1 + \lambda h$ is called the growth factor.

If $\operatorname{Re}(\lambda) < 0$, then $y(t) \rightarrow 0$ as $t \rightarrow \infty$.

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Initial Value Problems: Accuracy and Stability

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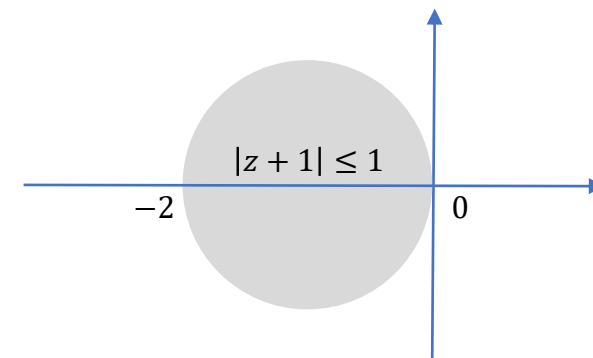
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Thus the global error is multiplied at each step by the factor $(I + h_k f')$ which is called the growth factor or amplification factor.

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which is satisfied if all eigenvalues of $h_k f'$ lie inside the circle in the complex plane of radius 1 and centered at -1 .