

Supplementary Notes

(for single non-linear equation)

[P-1]

Multiple zeros

Definition Let $f: \mathbb{R} \rightarrow \mathbb{R}$ and $m \in \mathbb{N}$.

A zero r of f (i.e., $f(r) = 0$) is called a zero of multiplicity m , if f can be written as

$$f(x) = (x-r)^m g(x), \text{ for } x \in N(r)$$

$(N(r) = \text{neighborhood of } r)$

in some neighborhood of r ,

$N(r)$ and for some continuous function $g: N(r) \rightarrow \mathbb{R}$ such that $g(r) \neq 0$.

Remark $g(x)$ represents that portion of $f(x)$ which does not contribute to the zero of f .

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Theorem-1

Let $f: [a, b] \rightarrow \mathbb{R}$ be c^1 .

Then, $r \in (a, b)$ is a simple zero (ie. $m=1$)

of f in (a, b) iff $f(r) = 0 \neq f'(r)$.

proof: \Rightarrow f has simple zero r . Then,

$$f(r) = 0 \text{ and}$$

$$f(x) = (x-r)g(x), \quad x \in N(r),$$

where $N(r) \subset [a, b]$ is a nbd of r

and $g: N(r) \rightarrow \mathbb{R}$ continuous with

$$g(r) \neq 0.$$

Therefore, $f(x) - f(r) = (x-r)g(x)$

$$\forall x \in N(r)$$

$$\Rightarrow \forall x \in N(r), x \neq r$$

$$\frac{f(x) - f(r)}{x - r} = g(x)$$

As f is c^1 and $g(r) \neq 0$, $\lim_{x \rightarrow r} \frac{f(x) - f(r)}{x - r}$ exists

and $f'(r) = g(r) \neq 0$.

\Leftarrow (conversely): Let $f(r) = 0 \neq f'(r)$.

Let $x \in [a, b]$. Let us define

$\gamma: [0, 1] \rightarrow [a, b]$ by

$$\gamma(t) = tx + (1-t)r, \quad t \in [0, 1].$$

We note that γ is diffble and

$$\gamma(0) = r, \quad \gamma(1) = x.$$

$$\gamma'(t) = (x-r), \quad t \in [0, 1].$$

Hence, $f \circ \gamma: [0, 1] \rightarrow \mathbb{R}$ is diffble,

$$f \circ \gamma(t) = f(\gamma(t)) = f(r + t(x-r)),$$

$$t \in [0, 1].$$

$$\text{and } (f \circ \gamma)'(t) = f'(\gamma(t)) \cdot \gamma'(t)$$

$$= f'(r + t(x-r))(x-r).$$

$$\forall t \in [0, 1].$$

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By Fundamental theorem of Calculus

$$\int_0^1 (f \circ g')'(t) dt = (x-r) \int_0^1 f'(r+t(x-r)) dt$$

$$\Rightarrow f \circ g(1) - f \circ g(0) = (x-r) q(x),$$

where, $q: [a,b] \rightarrow \mathbb{R}$ be given by

$$q(x) = \int_0^1 f'(r+t(x-r)) dt,$$

$$x \in [a,b].$$

$$\Rightarrow f(x) - f(r) = (x-r) q(x)$$

$$\Rightarrow f(x) = (x-r) q(x), \quad x \in [a,b].$$

$$(\because f(r) = 0)$$

As f is C^1 , q is continuous.

To show $\lim_{x \rightarrow r} q(x) = f'(r) \neq 0$.

$$\begin{aligned} q(x) - f'(r) &= \int_0^1 f'(r+t(x-r)) dt - f'(r) \\ &= \int_0^1 [f'(r+t(x-r)) - f'(r)] dt \end{aligned}$$

[Supplementary]

As f' is C^1 , so f' is continuous.

Let $\epsilon > 0$, $\exists \delta > 0$ such that

$$\forall z \in [a, b], |z - r| < \delta \Rightarrow |f'(z) - f'(r)| < \frac{\epsilon}{2}$$

Note that for, $t \in [0, 1]$ and

$$|x - r| < \delta \Rightarrow |r + t(x - r) - r| = |t(x - r)| \\ = |t||x - r|$$

$$\leq |x - r| < \delta$$

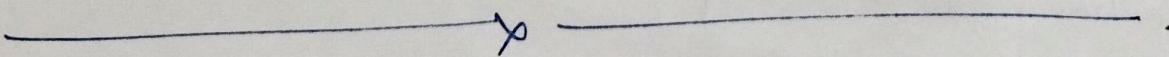
$$\Rightarrow |f'(r + t(x - r)) - f'(r)| < \frac{\epsilon}{2}$$

Hence, for $|x - r| < \delta$,

$$|g(x) - f'(r)| \leq \int_0^1 |f'(r + t(x - r)) - f'(r)| dt \\ \leq \frac{\epsilon}{2} \int_0^1 dt = \frac{\epsilon}{2} < \epsilon.$$

Hence g is continuous and

$$\lim_{x \rightarrow r} g(x) = f'(r) \neq 0.$$



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More generally

Theorem-2 Let $f \in C^m([a, b])$ and f has a zero r of multiplicity $m \in \mathbb{N}$ in (a, b) if and only if

$$f(r) = f'(r) = \dots = f^{m-1}(r) = 0 \neq f^m(r).$$

Modified Newton method

One way to handling the problem of multiple root of an ~~f~~ equation $f(x) = 0$, is to define

$$\mu: N(r) \rightarrow \mathbb{R} \quad \text{by}$$

$$\mu(x) = (x-r) \frac{q(x)}{m q(x) + (x-r) q'(x)},$$

$$x \in N(r).$$

Let f has a zero r of multiplicity $m \in \mathbb{N}$.

$$\text{Then, } f(x) = (x-r)^m q(x), \quad x \in N(r),$$

$q: N(r) \rightarrow \mathbb{R}$ continuous, $q(r) \neq 0$.

Assume further q is C^1 in $N(r)$.

For $x \neq r$, $x \in N(r)$, consider

$$\mu(x) = \frac{f(x)}{f'(x)}$$

$$= \frac{(x-r)^m g(x)}{m(x-r)^{m-1}g(x) + (x-r)^m g'(x)}$$

$$= \frac{(x-r) g(x)}{m g(x) + (x-r) g'(x)}$$

$$= (x-r) \tilde{g}(x),$$

where $\tilde{g}(x) = \frac{g(x)}{m g(x) + (x-r) g'(x)}, x \in N(r).$

Also, $\lim_{x \rightarrow r} \tilde{g}(x) = \frac{g(r)}{m g(r)} = \frac{1}{m} \quad (\because g(r) \neq 0).$

Hence, r is a zero of μ of multiplicity 1.

We can apply Newton-Raphson method to μ .

For μ , the fixed pt. formulation is

$$x = g(x) = x - \frac{\mu(x)}{\mu'(x)}.$$

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$$g(x) = x - \frac{f(x)/f'(x)}{(f(x)/f'(x))'}$$
$$= x - \frac{f(x)/f'(x)}{(f'(x))'' - f(x)f''(x)}$$
$$= x - \frac{f(x)f'(x)}{(f'(x))'' - f(x)f''(x)}.$$

Remark

Theoretically the above method has only two drawbacks

- (i) additional calculation of $f''(x)$
- (ii) lengthy procedure of calculating the iterates.

Practical drawback:

The denominator consists of the difference of two numbers that are both close to 0. It can cause serious round-off error.

Other methods.

Accelerating convergence: Aitken's Δ^r method

The method called Aitken's Δ^r method that can be used to accelerate the convergence of a sequence that is linearly convergent, regardless of its origin.

Let $\{x_k\}_{k \geq 0}$ such that $\lim_{k \rightarrow \infty} x_k = r$ linearly.

Aitken's Δ^r method is ~~based on~~ defined by

$$\begin{aligned}\hat{x}_k &:= x_k - \frac{(\Delta x_k)^r}{\Delta^r x_k} \\ &:= x_k - \frac{(x_{k+1} - x_k)^r}{x_{k+2} - 2x_{k+1} + x_k} \rightarrow \textcircled{1}\end{aligned}$$

Then, $\{\hat{x}_k\}_{k \geq 0}$ converges faster to r in the sense that

$$\lim_{k \rightarrow \infty} \frac{\hat{x}_k - r}{x_k - r} = 0.$$

Ref: Burden & Faires, P-88,
Atkinson, P-83.

Steffensen's method.

By applying a modification of Aitken's $\tilde{\Delta}$ ² method to a linearly convergent sequence obtained from fixed-point iteration,

We can accelerate the convergence to quadratic. This method is known as

Steffensen's method:

$$\begin{aligned} x_0, \quad x_1 &= g(x_0), \quad x_2 = g(x_1), \quad \hat{x}_0 = \{\tilde{\Delta}\gamma\}(x_0) \\ x_3 &= g(x_2), \quad \hat{x}_1 = \{\tilde{\Delta}\gamma\}(x_1) \\ x_4 &= g(x_3), \quad \hat{x}_2 = \{\tilde{\Delta}\gamma\}(x_2), \end{aligned}$$

where $\{\tilde{\Delta}\gamma\}$ indicates ① above.

Steffen's method construct the same 1st four terms x_0, x_1, x_2, \hat{x}_0 . At this step we assume that \hat{x}_0 is a better approximation to r than is x_2 and apply fixed point iteration to \hat{x}_0 instead of x_2 .

Supplementary

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$$x_0^{(0)} ; \quad x_1^{(0)} = g(x_0^{(0)}) \quad x_2^{(0)} = g(x_1^{(0)})$$

$$x_0^{(1)} = \{\Delta\} (x_0^{(0)}) \quad x_1^{(1)} = g(x_0^{(1)}), \dots$$

Every 3rd term of the Steffensen's seqn.

is generated by ①, the others use

fixed-point iteration on the previous term.

x

Horner's method

(Synthetic division)

$$\text{Let } P(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

$$a_n \neq 0$$

(polynomial of degree n)

Define $b_n = a_n, \quad b_k = a_k + b_{k+1} x_0 \quad \text{for}$
 $k = n-1, n-2, \dots, 1, 0.$

then, $b_0 = P(x_0)$

Moreover, if $Q(x) = b_n x^{n-1} + b_{n-1} x^{n-2} + \dots + b_2 x + b_1$

then, $P(x) = (x - x_0) Q(x) + b_0.$

proof: See & Burden & Faires, P-92-93,
 Direct computation and comparison.

P-12

$$\text{Eg: } P(x) = x^4 - 2x^3 - 12x^2 + 16x - 40.$$

We want to write,

$$P(x) = (x+2) Q(x) + b_0.$$

Take $x_0 = -2$. Make the table

	Co-eff of x^4	Co-eff of x^3	x^2	x	Const.
-2	1	-2	-12	16	-40
		-2	8	8	-48
-2	$1 = b_4$	$-4 = b_3$	$-4 = b_2$	$24 = b_1$	$(-88) = b_0$
					$= P(x_0)$
			-2	12	-16
	$1 = c_4$	$-6 = c_3$	$8 = c_2$	$(8) = b_0 = Q(x_0)$	

$$P(x) = (x+2) Q(x) \neq -88, \quad P(x_0) = P(-2) = -88$$

~~$$Q(x) = x^3 - 6x^2 + 8x + 8.$$~~

~~$$Q(x) = x^3 - 4x^2 - 4x + 24.$$~~

$$Q(x) = x^3 - 4x^2 - 4x + 24.$$

$$Q(x) = (x+2)(x^2 - 6x + 8) + 8.$$

$$Q(x_0) = Q(-2) = 8.$$

To use Newton's method to locate zeros of polynomial $P(x)$, we need to evaluate $P(x)$ and $P'(x)$ at every iteration.

$$x^k = x^{k-1} - \frac{P(x^{k-1})}{P'(x^{k-1})}$$

Horner's method calculate both $P(x^{k-1}), P'(x^{k-1})$ more efficiently than by direct computation.

At $x=x_0$. We want to know

$$x_1 = x_0 - \frac{P(x_0)}{P'(x_0)}$$

By synthetic division write $P(x)$ as

$$P(x) = \cancel{\text{some terms}} (x-x_0) Q(x) + b_0.$$

$$\text{So } P(x_0) = b_0.$$

$$\text{Again } P'(x) = Q(x) + (x-x_0) Q'(x)$$

$$P'(x_0) = Q(x_0) = q_1, \text{ where.}$$

$$Q(x) = (x-x_0) R(x) + c_1$$

P-14

Complex zeros: Müller's method.

Ref: ~~8000~~: Bawden & Faires, P-(95-100).

Order of convergence / rate of convergence.

Let $\{x_k\}_{k \geq 0} \subset \mathbb{R}$ be a sequence such

that $\lim_{k \rightarrow \infty} x_k = r$ and $x_k \neq r \quad \forall k \geq 0$.

Defn. If \exists constant $\lambda, \alpha > 0$ such that

$$\lim_{k \rightarrow \infty} \frac{|x_{k+1} - r|}{|x_k - r|^\alpha} = \lambda,$$

then, we say $\{x_k\}_{k \geq 0}$ converges to r
of order α (or rate α) with
asymptotic constant λ .

- (i) IF $\alpha = 1, 0 < \lambda < 1$, then, the seqn. is linearly converging to r .
- (ii) IF $\alpha = 2$, the seqn. is quadratically converging to r .

Eg: 1. In Newton-Raphson method, we have

seen $\lim_{k \rightarrow \infty} \frac{|x_{k+1} - r|}{|x_k - r|^2} = \frac{|f''(r)|}{2|f'(r)|}$

Hence,

~~that~~ Newton-Raphson method quadratically convergent with asymptotic error

$$\text{constant } \lambda = \frac{|f''(r)|}{2|f'(r)|}$$

provided $f''(r) \neq 0 \neq f'(r)$.

2. In Secant method, we have seen

$$\lim_{k \rightarrow \infty} \frac{|x_{k+1} - r|}{|x_k - r|^\alpha} = \left(\frac{|f''(r)|}{2|f'(r)|} \right)^{\frac{1}{\alpha}}$$

$$\alpha = \frac{1 + \sqrt{5}}{2}$$

Hence, Secant method has order of

convergence $\alpha = \frac{1 + \sqrt{5}}{2} \approx 1.68$ with asymptotic

error constant $\lambda = \left(\frac{|f''(r)|}{2|f'(r)|} \right)^{\frac{1}{\alpha}}$

provided $f''(r) \neq 0 \neq f'(r)$.

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3. For fixed point iteration, if

$$g'(r) = 0 = \dots = g^{m-1}(r)$$

$$g^m(r) \neq 0. \quad \text{for } m \in \mathbb{N}$$

Then, $\lim_{k \rightarrow \infty} \frac{|x_{k+1} - r|}{|x_k - r|^m} = \frac{1}{L^m} |g^m(r)|$

Hence, order of convergence is m , with asymptotic error constant

$$\lambda = \frac{1}{L^m} |g^m(r)|.$$

4. If the fn. $f: [a, b] \rightarrow \mathbb{R}$ is convex in the interval with $f(a)f(b) < 0$, we choose $x_0 = a$ and $x_1 = b$.

Then, in Regula-Falsi iteration one of the point x_0 or x_1 is always fixed and other pts. varies with k . If x_0 is fixed, then the error equation for Regula-falsi method becomes $(x_{k+1} - r) = c_k(x_0 - r)(x_k - r)$.

If $x_k \neq r + k \geq 0$, then

$$\lim_{k \rightarrow \infty} \frac{|x_{k+1} - r|}{|x_k - r|} = \lim_{k \rightarrow \infty} |c_k| |x_0 - r| = |x_0 - r| \cdot \frac{|f''(r)|}{2|f'(r)|}.$$

Hence, in this case order of convergence
is 1 with asymptotic error constant

$$\lambda = |x_0 - r| \frac{|f''(r)|}{2|f'(r)|} \quad \text{provided}$$

$$f''(r) \neq 0 \neq f'(r).$$

The convergence is linear if $0 < \lambda < 1$.

5. For Bisection method it is said that
the convergence is linear, but I did
not find any proof.

Only we know

$$\lim_{k \rightarrow \infty} |x_k - r| \leq \lim_{k \rightarrow \infty} \frac{1}{2^{k+1}} (b-a) = 0.$$

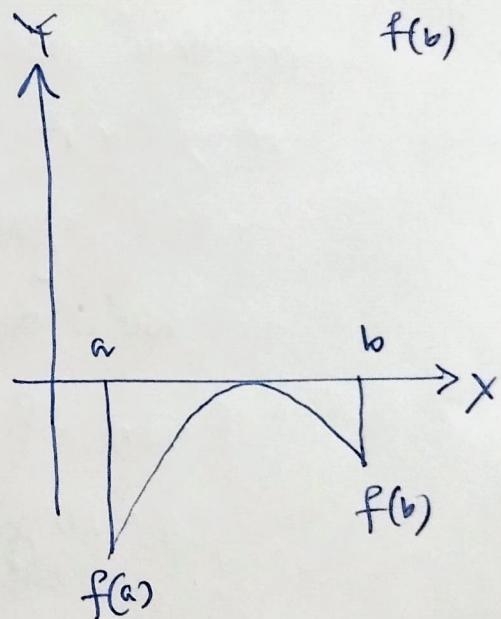
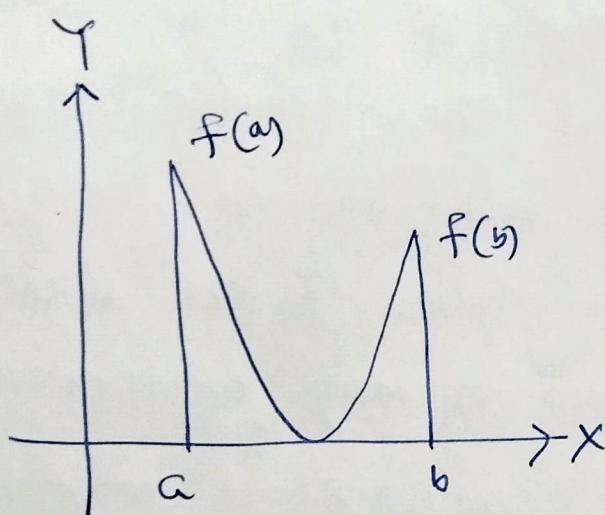
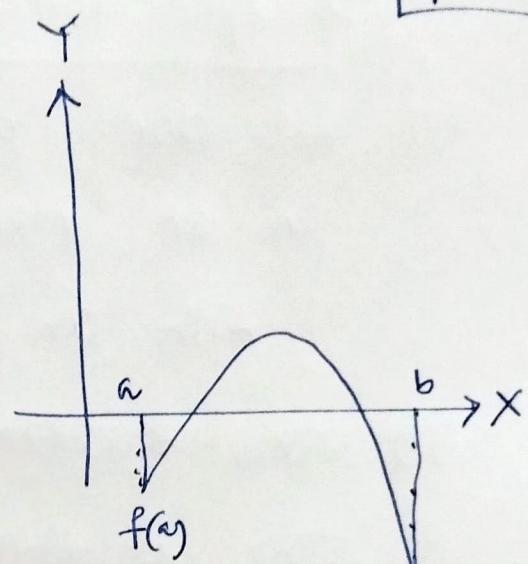
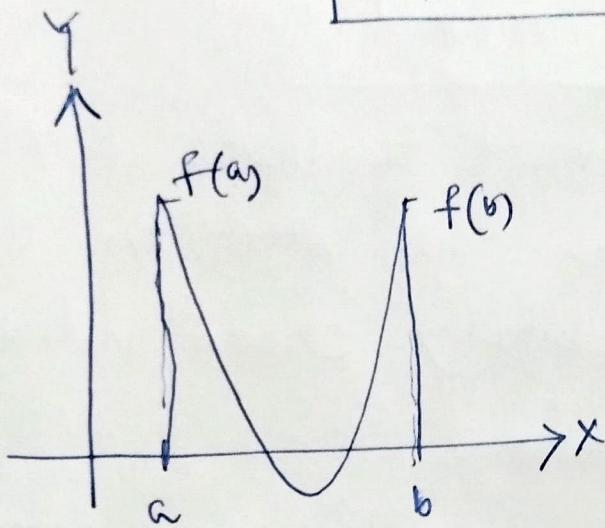
6. ~~Converge~~ Order of convergence for
Müller's method is nearly 1.84.
(out of scope).

7. Order of convergence of Chebychev's
method is 3 (out of scope).

Comparisons of different method.

I. closed domain method.

- (i) We need to find initially an interval $[a, b]$ such that $f(a)f(b) < 0$
- (ii) These methods surely converge.
- (iii) Bisection method converges slower than Regula-Falsi method
- (iv) There might be more than one solution of $f(x) = 0$ in $[a, b]$, but these methods find only one.
- (v) It may also happen that, in case of more than one solution, ~~Bisection~~ the solution found by Bisection method be different from the solution found by Regula-Falsi method.
- (vi) If $f(a)f(b) < 0$ does not satisfy, then these method cannot locate solution in $[a, b]$, even if there is really a solution of $f(x) = 0$.



In all of the above cases

$f(a)f(b) > 0$. and $\exists r \in (a, b)$

such that $f(r) = 0$.

2. Open domain method

(i) We don't ~~need~~ need to locate a root in an interval. We start the iteration with an arbitrary chosen initial choice.

~~Disadvantages~~

(ii) The disadvantage of the open domain method is that the iterative sequence may not be well-defined for all initial guesses. Even if the sequence is well-defined it may not converge.

Even if it converge, it may not converge to a specific root.

(iii) In situations where both open and closed domain methods converge, Open domain method are generally faster compared to closed domain methods.

(iv) These method may stuck in a cycle.

Eg, $f(x) = x^3 - x - 3$, $f(x) = 0$. (eqn).

Take $x_0 = 0$,

(v) IF $f(x)=0$ has no real root, there is no indication by these methods and the iterative sequence may simply oscillate.

For E.g.: $f(x)=0$ with $f(x)=x^5-4x+5$.

N-R iteration oscillates.

Secant method	Newton-Raphson method
(i) Need two initial guesses x_0, x_1 to start the iteration.	(i) Need only one initial guess x_0 to start the iteration.
(ii) No need to compute $f'(x_{k-1})$.	(ii) Need to compute $f'(x_{k-1})$ at each iteration.
(iii) Order of convergent is ≈ 1.68 i.e., converges slower than N-R method.	(iii) Order of convergent is 2 i.e., converges faster than Secant method.

P-22

Exercises (1) (Conte & de Boor, p-104, thm-3.2)

Let $a, b \in \mathbb{R}$, $a < b$ and $f: [a, b] \rightarrow \mathbb{R}$ be C^2 .

~~f satisfy $f''(x) \neq 0$~~ Let f satisfy the following:

(i) Either $f''(x) \geq 0 \quad \forall x \in [a, b]$

or $f''(x) \leq 0 \quad \forall x \in [a, b]$

(ii) $f'(x) \neq 0 \quad \forall x \in [a, b]$.

(iii) $f(a)f(b) < 0$

(iv) $\max \left\{ \frac{|f(a)|}{|f'(a)|}, \frac{|f(b)|}{|f'(b)|} \right\} < b-a$.

Then, N-R converges to the unique

root of $f(x) = 0$ in $[a, b]$

for any choice of initial guess $x_0 \in [a, b]$.

Exercise (2) (Atkinson, p-77, Lemma-2.5)

Let $a, b \in \mathbb{R}$, $a < b$ and $g: [a, b] \rightarrow [a, b]$ be continuous.

Let g satisfy the following:

$\exists L \in (0, 1)$ such that

$|g(x) - g(y)| \leq L|x-y|, \quad \forall x, y \in [a, b]$.

Then, (i) g has a unique fixed pt. $r \in [a, b]$.

(ii) for any $x_0 \in [a, b]$, the seqn.

$$x_k = g(x_{k-1}), \quad k \geq 0$$

satisfies $\lim_{k \rightarrow \infty} x_k = r$, and $|x_k - r| \leq \frac{L^k}{1-L} |x_0 - r| \quad \forall k \geq 1$.