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and choose  $\gamma > 0$  to minimize

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$$y(t) = \frac{s}{\lambda} (e^{\lambda t} - e^{-\lambda t}).$$

## Numerical Analysis & Scientific Computing II

Lesson 3

# Boundary Value Problems for ODEs

- 3.1 Well-posedness
- 3.2 Shooting Method
- 3.3 Finite Difference Method



#### **Boundary Value Problems: Finite Difference Method**

In the shooting method, we start by approximately satisfying the ODE (using an IVP solver) and iterate until the boundary conditions are satisfied.

Alternatively, we can start by satisfying the boundary conditions and iterate until the ODE is satisfied approximately.

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with boundary conditions

$$u(a) = \alpha, \qquad u(b) = \beta.$$

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$$a = t_0 \qquad t_1 \qquad t_2 \qquad t_3 \qquad t_4$$

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$$u'(t_i) \approx \frac{u_{i+1} - u_{i-1}}{2h}, \ u''(t_i) \approx \frac{u_{i+1} - 2u_i + u_{i-1}}{h^2}.$$

$$a = t_0$$
  $t_1$   $t_2$   $t_3$   $t_4$   $t_i = a + ih$   $t_{n-1}$   $t_n$   $t_{n+1} = h$ 

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This yields a system of algebraic equations

$$\frac{u_{i+1}-2u_i+u_{i-1}}{h^2}=f\left(t_i,u_i,\frac{u_{i+1}-u_{i-1}}{2h}\right), i=1,\ldots,n,$$

to be solved for the unknowns  $u_i$ , i = 1, ..., n.

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*In the matrix form, we have* 

$$\frac{1}{h^2} \begin{bmatrix} -2 & 1 & 0 & & \cdots & 0 \\ 1 & -2 & 1 & & & & \\ \vdots & \vdots & & \ddots & \vdots & & \vdots \\ 0 & \cdots & & 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} = \begin{bmatrix} f\left(t_1, u_1, \frac{u_2 - \alpha}{2h}\right) \\ f\left(t_2, u_2, \frac{u_3 - u_1}{2h}\right) \\ \vdots \\ f\left(t_n, u_n, \frac{\beta - u_n}{2h}\right) \end{bmatrix}$$

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which is denoted as

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Thus, the Newton's method for solving the system of algebraic equations is given by

$$u^{(m+1)} = u^{(m)} - \left[\frac{1}{h^2}A - F'(u^{(m)})\right]^{-1} \left[\frac{1}{h^2}Au^{(m)} - F(u^{(m)}) - g\right]$$

where the Jacobian matrix is given by  $[F(u)]_{ij} = [\partial f(t_i, u_i, (u_{i+1} - u_{i-1})/(2h))/\partial u_i].$