

Properties of w_i

i) We note that $w_i(x_{2i}) = 0$

$$\text{ii) } w_i(x_{2i+2}) = \int_{x_{2i}}^{x_{2i+2}} (t - x_{2i})(t - x_{2i+1})(t - x_{2i+2}) dt$$

$$\begin{aligned} &= \int_{-h}^h (u+h) u (u-h) du \\ &= \int_{-h}^h u(u^2-h^2) du = 0 \quad (\bullet u(u^2-h^2) \text{ is odd fn.}) \end{aligned}$$

$$\therefore w_i(x_{2i+2}) = 0.$$

$$\text{iii) } w'_i(x) = g_i(x) = \begin{cases} > 0, & x_{2i} < x < x_{2i+1} \\ 0, & x = x_{2i+1} \\ < 0, & x_{2i+1} < x < x_{2i+2} \end{cases}$$

$\Rightarrow w_i$ is strictly increasing in $[x_i, x_{2i+1}]$

and w_i'' " " " in $[x_{2i+1}, x_{2i+2}]$

and achieves maximum at $x = x_{2i+1}$

$$\Rightarrow 0 = w(x_{2i}) < w(x) \leq w(x_{2i+1}), \quad x_{2i} < x \leq x_{2i+1},$$

$$0 = w(x_{2i+2}) < w(x) \leq w(x_{2i+1}), \quad x_{2i+1} \leq x < x_{2i+2}.$$

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$$\Rightarrow w_i(x) > 0 \quad , \quad x_{2i} < x < x_{2i+2} .$$

Coming back to $E_{s,i}(f, h)$

$$E_{s,i}(f, h) = \int_{x_{2i}}^{x_{2i+2}} w_i(x) f[x_{2i}, x_{2i+1}, x_{2i+2}, x] dx$$

$$\xrightarrow{\text{using integration by parts formula}} = - \int_{x_{2i}}^{x_{2i+2}} w_i(x) (f[x_{2i}, x_{2i+1}, x_{2i+2}, x])' dx$$

$$+ \left\{ w_i(x) f[x_{2i}, x_{2i+1}, x_{2i+2}, x] \right\}_{x_{2i}}^{x_{2i+2}}$$

" " (by properties of

$$= - \int_{x_{2i}}^{x_{2i+2}} w_i(x) f[x_{2i}, x_{2i+1}, x_{2i+2}, x, x] dx$$

(Assuming f is 4-times continuously differentiable)

$$= - f[x_{2i}, x_{2i+1}, x_{2i+2}, \xi_i, \xi_i] \int_{x_{2i}}^{x_{2i+2}} w_i(x) dx$$

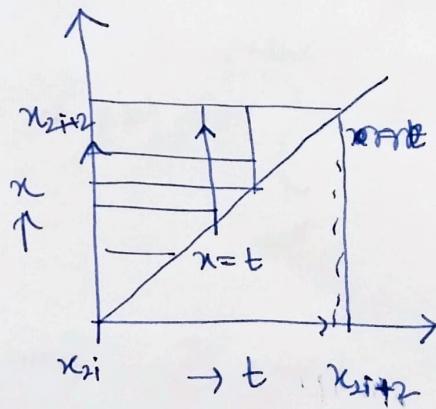
(using weighted M.V.T. for some $\xi_i \in [x_{2i}, x_{2i+2}]$)

$$E_{s,i}(F, h) = - \frac{f^4(n_i)}{L^4} \int_{x_{2i}}^{x_{2i+2}} w_i(x) dx \quad \rightarrow ①$$

(Again by Generalized M.V.T.
 $\exists n_i \in (x_{2i}, x_{2i+2})$

$$f[x_{2i}, x_{2i+1}, x_{2i+2}, \xi_i, \xi_i] \\ = \frac{f^4(n_i)}{L^4}$$

$$\int_{x_{2i}}^{x_{2i+2}} w_i(x) dx = \int_{x_{2i}}^{x_{2i+2}} \int_x g(t) dt dx \\ = \int_{x_{2i}}^{x_{2i+2}} \int_t^{x_{2i+2}} g(t) dx dt \\ = \int_{x_{2i}}^{x_{2i+2}} (x_{2i+2} - t) g(t) dt$$



$$= - \int_{x_{2i}}^{x_{2i+2}} (t - x_{2i}) (t - x_{2i+1}) (t - x_{2i+2}) dt$$

$$= - \int_{-h}^h (r + h) r (r - h) dr$$

$$t - x_{2i+1} = r$$

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$$\begin{aligned}
 &= - \int_{-h}^h (r^2 - h^2) (r^2 - rh) dr \\
 &= - \int_{-h}^h [r^4 - r^2 h^2 - r^3 h + rh^3] dr \\
 &= - 2 \int_0^h [r^4 - r^2 h^2] dr \quad \left[\begin{array}{l} \int_{-h}^h r^3 h dr = 0 \\ \int_{-h}^h rh^3 dr = 0 \\ (\text{odd f.}) \end{array} \right] \\
 &= - 2 \cdot \left[\frac{r^5}{5} - \frac{r^3 h^2}{3} \right]_0^h \\
 &= - \frac{2}{15} (3h^5 - 5h^5)
 \end{aligned}$$

$$\int_{x_{2i}}^{x_{2i+2}} \omega_i(x) dx = \frac{4}{15} h^5. \quad \rightarrow ②$$

$$\text{using } ② \quad \text{From } ① \quad E_{s,i}(f, h) = - \frac{f^4(n_i)}{14} \cdot \frac{4}{15} h^5$$

~~$$-\frac{h^5}{90} f^{iv}(n_i)$$~~

And Total Error.

$$\begin{aligned}
 E_s(f, h) &= - \sum_{i=0}^{n-1} \frac{h^5}{90} f^{iv}(n_i) = - \frac{h^4}{90} \cdot h \sum_{i=0}^{n-1} f^{iv}(n_i) \\
 &= - \frac{h^4}{90} \cdot \frac{(b-a)}{2n} \sum_{i=0}^{n-1} f^{iv}(n_i) \\
 &= - \frac{h^4 (b-a)}{180} \left\{ \frac{1}{n} \sum_{i=0}^{n-1} f^{iv}(n_i) \right\}
 \end{aligned}$$

$$E_s(f,h) = - \frac{h^4(b-a)}{180} f^{(iv)}(n) \quad \text{for some } n \in [a,b].$$

$$|E_s(f,h)| \leq \frac{h^4(b-a)}{180} \max_{x \in [a,b]} |f^{(iv)}(x)| = O(h^4).$$

1. Newton-Cotes integration formula

We now generalize the previous formulas for $(n+1)$ pts. formula.

Let us consider the interval $[c, d]$, $c < d$.

$$\text{for } n \in \mathbb{N}, \quad h = \frac{d-c}{n}, \quad x_i = c + ih$$

$$i = 0, \dots, n$$

We define $I_n(f)$ by replacing f by its interpolating polynomial $P_n(x)$ on the nodes x_0, x_1, \dots, x_n .

$$I(f) = \int_c^d f(x) dx, \quad I_n^c(f) = \int_c^d P_n(x) dx$$

Idea: $I(f) \approx I_n^c(f)$.

Using Lagrange form of interpolating polynomial

$$P_n(x) = \sum_{i=0}^n L_{i,n}(x) f(x_i) \quad \text{we get}$$

$$I_n^c(f) = \int_c^d P_n(x) dx = \sum_{i=0}^n f(x_i) \int_c^d L_{i,n}(x) dx$$

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$$I_n^c(f) = \sum_{i=0}^n f(x_i) w_{i,n}, \quad \text{---} \quad ①$$

$$\text{where } w_{i,n} = \int_c^d L_{i,n}(x) dx.$$

$$i=0, 1, \dots, n.$$

The $(n+1)$ pt. closed Newton-Cotes formula is given by ①.

Theorem 1

$$\text{Let } h = \frac{d-c}{n}, \quad x_i = a + ih, \quad i=0, \dots, n.$$

Let $(n+1)$ -pt. Newton-Cotes formula is given in ①.

(i) IF n is even and f is of class C^{n+2}
(i.e. f is $(n+2)$ -times continuously differentiable)

Then, $\exists \xi \in (c, d)$ such that

~~$$\int_c^d f(x) dx = I_n^c(f) + \frac{h^{n+3}}{n+2} f^{(n+2)}(\xi) \int_0^n t^n(t-1)\dots(t-n) dt$$~~

$$\text{i.e. the error } E_n(f) = I(f) - I_n^c(f)$$

$$= \frac{h^{n+3}}{n+2} f^{(n+2)}(\xi) \int_0^n t^n(t-1)\dots(t-n) dt.$$

--- ②

(ii) If n is odd and f is of class C^{n+1} ,
then, $\exists \xi \in (c, d)$ such that

$$\int_c^d f(x) dx = I_n^c(f) + \frac{h^{n+2}}{n+1} f^{(n+1)}(\xi) \int_0^n t(t-1)\dots(t-n) dt$$

i.e. the error $E_n(f, h) = I(f) - I_n^c(f)$

$$= \frac{h^{n+2}}{n+1} f^{(n+1)}(\xi) \int_0^n t(t-1)\dots(t-n) dt.$$

→ (3)

Proof: (i) $n = \text{even}$

Using the error formula for interpolation we can
write

$$E_n(f, h) = \int_c^d \underbrace{(x-x_0)(x-x_1)\dots(x-x_n)}_{g_n(x)} f[x, x_1, \dots, x_n, x] dx$$

Define $w_n: [c, d] \rightarrow \mathbb{R}$ by

$$w_n(x) = \int_c^x g_n(t) dt, \quad c \leq x \leq d.$$

Properties of w

i) $w_n(c) = 0$.

ii) $w_n(d) = \int_c^d g_n(t) dt$.

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$$W_n(d) = \int_c^d (t-x_0) \cdots (t-x_n) dt$$

~~t~~ $n = \text{even}$

$$= \int_{x_0}^{x_n} (t-x_0) \cdots (t-x_{n/2}) \cdots (t-x_n) dt$$

~~n~~ $\cancel{n=2k}$

$$= \int_{-\frac{n}{2}h}^{\frac{n}{2}h} (r + \frac{n}{2}h)(r + (\frac{n}{2}-1)h) \cdots (r+h)r(r-h) dr$$

$t - x_{n/2} = r$
 $t - x_i = r + x_{n/2} - x_i$
 $= r + (n/2-i)h.$

$$= \int_{-\frac{n}{2}h}^{\frac{n}{2}h} (r^2 - \frac{n^2 h^2}{4}) (r^2 - (\frac{n}{2}-1)^2 h^2) \cdots (r^2 - 1^2) r dr$$

$$= 0 \quad (\text{odd. integrand})$$

iii) $W_n(x) > 0$, $c < x < d$

$$W'_n(x) = \begin{cases} 0, & x = x_i, i=0, \dots, n. \\ >0, & x_{2k} < x < x_{2k+1}, k=0, \dots, n/2-1 \\ <0, & x_{2k+1} < x < x_{2k+2}, k=0, \dots, n/2-1 \end{cases}$$

Using similar analysis as in case of Simpson's rule

$$W'_n(x) > 0, \quad c < x < d.$$

Now we have

d

$$E_n(f) = \int_c^d w_n(x) f[x_0, x_1, \dots, x_n, x] dx$$

c

$$= - \int_c^d w_n(x) f[x_0, x_1, \dots, x_n, x, x] dx$$

c

$$+ \left\{ w_n(x) f[x_0, x_1, \dots, x_n, x] \right\}_{x_0}^{x_n}$$

" 0.

(using integration
by parts formula)

$$= - \int_c^d w_n(x) f[x_0, x_1, \dots, x_n, x, x] dx$$

c

$$= - f[x_0, x_1, \dots, x_n, \underset{n}{\cancel{x}}, n] \int_c^d w_n(x) dx$$

d

(by weighted M.V.T.)

$$= - \frac{f^{n+2}(?)}{n+2} \int_c^d w_n(x) dx$$

(by generalized
M.V.T as

f is of class
 C^{n+2}).

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$$\begin{aligned}
 \int_c^d w_n(x) dx &= \int_c^d \int_{x_n}^x g(t) dt dx \\
 &= \int_c^d \int_{\underline{x}}^{\bar{x}} g(t) dx dt \\
 &= \int_c^d (d-t) g_n(t) dt \\
 &= \int_{x_0}^{x_n} * (t-x_0) (t-x_1) \cdots (t-x_n) (x_n-t) dt \\
 &= - \int_{x_0}^{x_n} (t-x_0) (t-x_1) \cdots (t-x_{n-1}) (t-x_n)^r dt \\
 &\quad \text{put } t = x_0 + rh. \\
 &= - \int_0^n rh (r-1)h \cdots (r-n+1)h (r-n)^r h^r h dr \\
 &= - h^{n+3} \int_0^n r(r-1) \cdots (r-n+1) (r-n)^r dr \\
 &= - h^{n+3} \int_0^n (n-t)(n-1-t) \cdots (1-t)t^r dt \quad n-r=t \\
 &= - h^{n+3} \int_0^n t^r (t-1) \cdots (t-n) dt
 \end{aligned}$$

($\because n$ is even
no sign change
occurs).

Hence,

$$E_n(f, h) = \frac{h^{n+3} f^{n+2}(\xi)}{n+2} \int_0^n t^r (t-1) \cdots (t-n) dt.$$

(1) $n = \text{odd}$.

As before $E_n(f, h) = \int\limits_c^d g_n(x) f[x_0, x_1, \dots, x_n, x] dx.$

where $g_n(x) = (x - x_0) \cdots (x - x_n).$

Defined $w_n: [c, d] \rightarrow \mathbb{R}$ by

$$w_n(x) = \int\limits_c^x g(t) dt, \quad c \leq x \leq d$$

$$E_n(f, h) = \int\limits_c^d g_n(x) f[x_0, x_1, x_2, \dots, x_n, x] dx$$

$$= \int\limits_c^{d-h} g_n(x) f[x_0, x_1, x_2, \dots, x_n, x] dx$$

$$+ \int\limits_{d-h}^d g_n(x) f[x_0, x_1, x_2, \dots, x_n, x] dx$$

~~Diagram showing a function f on an interval $[a, b]$ divided into n subintervals $[x_0, x_1], [x_1, x_2], \dots, [x_{n-1}, x_n]$. The width of each subinterval is Δx . The area under the curve is approximated by rectangles. The value of the function at the right endpoint of each subinterval is used to determine the height of the corresponding rectangle. The total area is given by the sum of the areas of these rectangles: $\sum_{i=1}^n f(x_i) \Delta x$.~~

$$\begin{aligned} & \text{Diagram showing a function } f \text{ on an interval } [a, b] \text{ divided into } n \text{ subintervals } [x_0, x_1], [x_1, x_2], \dots, [x_{n-1}, x_n]. \\ & \text{The width of each subinterval is } \Delta x. \\ & \text{The area under the curve is approximated by rectangles. The value of the function at the right endpoint of each subinterval is used to determine the height of the corresponding rectangle.} \\ & \text{The total area is given by the sum of the areas of these rectangles: } \int_a^b f(x) dx. \\ & = \int_{x_0}^{x_n} f(x) dx. \end{aligned}$$

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$$E_n(f) h = L_1 + L_2 \quad \longrightarrow \textcircled{6}$$

where $L_1 = \int_C g_n(x) f[x_0, x_1, \dots, x_n, x] dx$

and $L_2 = \int_{d-h}^{x_n} g_n(x) f[x_0, x_1, \dots, x_n, x] dx$

$$= \int_{x_{n-1}}^{x_n} g_n(x) f[x_0, x_1, \dots, x_n, x] dx$$

$$\left(\begin{array}{l} x_{n-1} = d-h \\ x_n = d \end{array} \right)$$

Note that $g_n(x) = (x - x_0)(x - x_1) \dots (x - x_n) < 0$

$$x_{n-1} < x < x_n$$

By weighted M.V.T. $\exists \xi_2 \in (x_{n-1}, x_n)$.

$$L_2 = f[x_0, x_1, \dots, x_n, \xi_2] \int_{x_{n-1}}^{x_n} g_n(x) dx$$

~~so ξ_2 is between x_{n-1} and x_n .~~

$$L_2 = \underbrace{f^{n+1}(n_2)}_{n+1} \int_{x_{n-1}}^{x_n} g_n(x) dx.$$

for some $n_2 \in (x_{n-1}, x_n)$.

To estimate L_1 .

We note that

~~$(x - x_n) f[x_0, x_1, \dots, x_n, x] = f[x_1, x_2, \dots, x_n, x] - f[x_0, x_1, \dots, x_n]$~~

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$$f[x_0, x_1, \dots, x_{n-1}, x_n, x]$$

$$= \frac{f[x_0, x_1, \dots, x_{n-1}, x] - f[x_0, x_1, \dots, x_{n-1}, x]}{(x - x_n)}$$

$$\Rightarrow (x - x_n) f[x_0, x_1, \dots, x_{n-1}, x_n, x]$$

$$= f[x_0, x_1, \dots, x_{n-1}, x] - f[x_0, x_1, \dots, x_{n-1}, x]$$

Now,

$$\begin{aligned}
 L_1 &= \int\limits_C^{d-h} g_n(x) f[x_0, x_1, \dots, x_n, x] dx \\
 &= \int\limits_{x_0}^{x_{n-1}} \underbrace{(x-x_0) \dots (x-x_{n-1})}_{g_n(x)} \underbrace{(x-x_n) f[x_0, x_1, \dots, x_n, x]} dx \\
 &= \int\limits_{x_0}^{x_{n-1}} w_{n-1}'(x) f[x_0, x_1, \dots, x_{n-1}, x] dx \\
 &\quad - \int\limits_{x_0}^{x_{n-1}} w_{n-1}'(x) f[x_0, x_1, \dots, x_n] dx \\
 &= - \int\limits_{x_0}^{x_{n-1}} w_{n-1}(x) f[x_0, x_1, \dots, x_{n-1}, x, x] dx \\
 &\quad + \left\{ w_{n-1}(x) f[x_0, x_1, \dots, x_{n-1}, x] \right\}_{x_0}^{x_{n-1}}
 \end{aligned}$$

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$$- f[x_0, x_1, \dots, x_n] \int_{x_0}^{x_{n-1}} w_{n-1}'(x) dx$$

$$\Rightarrow L_1 = - \underline{f[x_0, x_1, \dots, x_{n-1}, \eta_1, \epsilon_1]} \int_{x_0}^{x_{n-1}} w_{n-1}(x) dx$$

$$+ 0 + 0 \quad \left[\because w_{n-1}(x_0) = 0 = w_{n-1}(x_{n-1}) \right]$$

$$= - \frac{f^{n+1}(\eta_1)}{n+1} \int_{x_0}^{x_{n-1}} w_{n-1}(x) dx \quad \text{for some } \eta_1 \in (x_0, x_{n-1}).$$

→ ⑧

Combining we have

$$E_n(f, h) = - \frac{f^{n+1}(\eta_1)}{n+1} \int_{x_0}^{x_{n-1}} w_{n-1}(x) dx + \frac{f^{n+1}(\eta_2)}{n+1} \int_{x_{n-1}}^{x_n} g_n(x) dx$$

$$= - \left[\frac{f^{n+1}(\eta_1)}{n+1} A_n + \frac{f^{n+1}(\eta_2)}{n+1} B_n \right]$$

where $A_n = \int_{x_0}^{x_{n-1}} w_{n-1}(x) dx, \quad B_n = - \int_{x_{n-1}}^{x_n} g_n(x) dx$

$$\begin{aligned}
 \text{Now, } \int_{x_0}^{x_{n-1}} g_n(x) dx &= \int_{x_0}^{x_{n-1}} g_{n-1}(x) (x - x_n) dx \\
 &= \int_{x_0}^{x_{n-1}} \omega'_{n-1}(x) (x - x_n) dx \\
 &= - \int_{x_0}^{x_{n-1}} \omega_{n-1}(x) dx \\
 &\quad + \left\{ \omega_{n-1}(x) (x - x_n) \right\}_{x_0}^{x_{n-1}}
 \end{aligned}$$

$$\int_{x_0}^{x_{n-1}} g_n(x) dx = - \int_{x_n}^{x_{n-1}} \omega_{n-1}(x) dx \longrightarrow (*)$$

$$\begin{aligned}
 A_n + B_n &= \int_{x_0}^{x_{n-1}} \omega_{n-1}(x) dx - \int_{x_{n-1}}^{x_n} g_n(x) dx \\
 &= - \int_{x_0}^{x_{n-1}} g_n(x) dx - \int_{x_n}^{x_{n-1}} g_n(x) dx \\
 &= - \int_{x_0}^{x_n} g_n(x) dx \quad (\text{using } *) \\
 &\longrightarrow \textcircled{9}
 \end{aligned}$$

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Using ⑨ we have

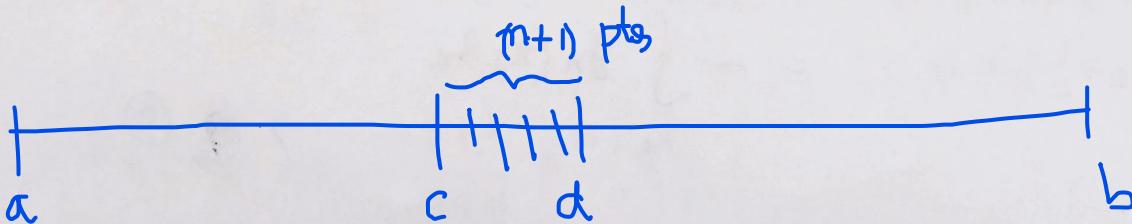
$$E_n(f, h) = - \left[\frac{f^{n+1}(n_1)}{n+1} \frac{A_n}{A_n + B_n} + \frac{f^{n+1}(n_2)}{n+1} \frac{B_n}{A_n + B_n} \right] (A_n + B_n)$$

$$= - \frac{f^{n+1}(n)}{n+1} \cdot (A_n + B_n) \quad \text{for some } n \in (x_0, x_n).$$

$$E_n(f, h) = \frac{f^{n+1}(n)}{n+1} \int_{x_0}^{x_n} g_n(x) dx$$

$$E_n(f, h) = h \frac{n+2}{n+1} \frac{f^{n+1}(n)}{n+1} \int_0^n t(t-1) \cdots (t-n) dt$$

$\rightarrow n \in (x_0, x_n)$ using a change
of variable as
before \circ in case ①.



To get composite N-C formula, we divide $(b-a)/N$,
where $N = kn$, $k \in \mathbb{N}$.

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Examples:

N=1 : Trapezoidal rule

$$I_1(f) = \frac{h}{2} (f(x_0) + f(x_1))$$

$$E_1(f) = -\frac{h^3}{12} f''(\xi), \quad x_0 < \xi < x_1$$

N=2 : Simpson's $\frac{1}{3}$ rule

$$I_2(f) = \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2))$$

$$E_2(f) = -\frac{h^5}{90} f^{IV}(\xi), \quad x_0 < \xi < x_2$$

N=3 : Simpson's $\frac{3}{8}$ rule.

$$I_3(f) = \frac{3h}{8} (f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3))$$

$$E_3(f) = -\frac{3h^5}{80} f^{IV}(\xi)$$

N=4 : ~~Milne's~~ rule

$$I_4 = \frac{2h}{45} (7f(x_0) + 32f(x_1) + 12f(x_2) + 32f(x_3) + 7f(x_4))$$

$$E_4(f) = -\frac{8h^7}{945} f^{VI}(\xi).$$

N=6 : Weddle's rule.

2. Open Newton-Cotes Formulae

The open Newton-Cotes formulae do not include the end points of $[c, d]$ as nodes:

If we use grids $x_i = x_0 + ih$,

$$i = 0, \dots, n$$

$$h = \frac{d-c}{(n+1)}, \quad x_0 = c+h.$$

$$\begin{aligned} x_n &= x_0 + nh \\ &= d-h. \end{aligned}$$

We label the end points as $x_{-1} = c$, $x_{n+1} = d$.

open

The N -C quadrature formula is given by

$$I_n^o(f) = \sum_{i=0}^n w_{i,n} f(x_i), \quad \rightarrow ⑩$$

$$w_{i,n} = \int_c^d L_{i,n}(x) dx.$$

Theorem 2] Let $\textcircled{10}$ denotes the $(n+1)$ pts open Newton-Cotes Formula with $x_1 = c$, and $x_{n+1} = d$,

$$h = \frac{d-c}{n+2}.$$

(i) If n is even and f is of class C^{n+2} .

Then, $\exists \xi \in (c, d)$ such that

$$\int_c^d f(x) dx = I_n^0(f) + \frac{h^{n+3} f^{n+2}(\xi)}{n+2} \int_{-1}^{n+1} t^n(t-1)\dots(t-n) dt$$

i.e. the error term $E_n(f, h) = I(f) - I_n^0(f)$ is given by

$$E_n(f, h) = \frac{h^{n+3}}{n+3} f^{n+2}(\xi) \int_{-1}^{n+1} t^n(t-1)\dots(t-n) dt$$

(ii) If n is odd and f is of class C^{n+1} .

then, $\exists \xi \in (c, d)$ such that

$$\int_c^d f(x) dx = I_n^0(f) + \frac{h^{n+2} f^{n+1}(\xi)}{n+1} \int_{-1}^{n+1} t(t-1)\dots(t-n) dt$$

and the error term $E_n(f, h) = I_n(f) - I_n^0(f)$ is given by

$$E_n(f, h) = \frac{h^{n+2}}{n+1} f^{n+1}(\xi) \int_{-1}^{n+1} t(t-1)\dots(t-n) dt.$$

[P-16]

$N=0$: Midpoint rule.

$$I_0(f) = 2h f(x_0)$$

$$E_0(f) = \frac{h^3}{3} f''(\xi), \quad x_0 < \xi < x_1$$

$N=1$,

$$I_1(f) = \frac{3h}{2} (f(x_0) + f(x_1))$$

$$E_1(f) = \cancel{\frac{h^3}{2}} \frac{3h^3}{4} f''(\xi), \quad x_{-1} < \xi < x_2$$

$N=2$.

$$I_2(f) = \frac{4h}{3} (2f(x_0) - f(x_1) + 2f(x_2))$$

$$E_2(f) = \frac{16h^5}{45} f'''(\xi), \quad x_{-1} < \xi < x_3.$$

Defn (Degree of accuracy or precision of a quadrature rule).

The degree of accuracy of a quadrature rule is the largest positive integer n such that, the formula is exact for polynomial of degree less than or equal to n . (ie. $E(x^k) = 0$ for Eqn_z $k=0, \dots, n$.)

Eg: (1) Trapezoidal, degree of accuracy = 1

(2) Simpson's $\frac{1}{3}$, " " " = 3

(4) ~~Newton-Cotes~~ $\rightarrow n+1$, n even
 $\rightarrow n$, n odd.

1. Gauss Quadrature rule:

So far we have discussed numerical integration ~~rules~~ of the form

$$\int_a^b f(x) dx \approx w_0 f(x_0) + w_1 f(x_1) + \dots + w_n f(x_n),$$

where we ~~fixed~~ the nodes/grids $x_i \in [a, b]$

and we adjust the weights. we get certain degree of accuracy. For example;

Trapezoidal rule:

$$x_0 = a, \quad x_1 = b, \quad \text{and} \quad w_0 = w_1 = \frac{b-a}{2}$$

Simpson's rule:

$$x_0 = a, \quad x_1 = \frac{a+b}{2}, \quad x_2 = b,$$

$$w_0 = w_2 = \frac{1}{6}(b-a), \quad w_1 = \frac{2}{3}(b-a)$$

To ~~increase~~ increase the degree of accuracy

We use the idea of Gauss.

Idea: Allow both the nodes x_i and the weights w_i to be adjusted to achieve high accuracy.

P-2

Gaussian quadrature rule chooses the nodes x_i and weight ω_i ($i=0, 1, \dots, n$) such that the algorithm gives the exact value for a polynomial function p of highest possible degree m :

$$\int_a^b p(x) dx = \omega_0 p(x_0) + \omega_1 p(x_1) + \dots + \omega_n p(x_n),$$

:= G(p) if p is a polynomial
of degree m .

① ←

Here m is called the degree of precision.

The weights $\omega_0, \omega_1, \dots, \omega_n$ in the approximation formula are arbitrary and the nodes x_0, x_1, \dots, x_n are restricted only by the fact that $x_i \in [a, b] \quad \forall i=0, \dots, n$

This gives us $2(n+1)$ parameters, to choose.

If the coefficients of a polynomial are considered parameters, the class of polynomials of degree at most $2n+1$ also contains $2n+2$ parameters.

Therefore, this is the largest degree of polynomials for which it is reasonable to expect the formula to be exact.

① (R.H.S)

We now explain the situation for particular case.
Let us consider the interval $[-1, 1]$.

Case: 1. ~~n=0~~ $n=0$

There are two parameters ω_0, x_0 . We consider requiring

$$\int_{-1}^1 P(x) dx = \omega_0 P(x_0),$$

P is a polynomial of degree 1.

$$(\because 2n+1 = 2 \times 0 + 1 = 1)$$

$$\text{Take } P(x)=1 \Rightarrow \int_{-1}^1 1 dx = \omega_0 \Rightarrow \omega_0 = 2$$

$$P(x)=x \Rightarrow \int_{-1}^1 x dx = \omega_0 x_0 \Rightarrow \omega_0 x_0 = 0 \\ \Rightarrow x_0 = 0 (\because \omega_0 = 2)$$

Thus the formula becomes

$$G_2(P) = 2P(0).$$

$$\therefore I(f) \approx G_2(f) = 2f(0). \longrightarrow ②$$

P-4

Case: 2. $n = 1$

There are four parameters $\omega_0, \omega_1, x_0, x_1$.

We consider requiring

$$\int_{-1}^1 p(x) dx = \omega_0 p(x_0) + \omega_1 p(x_1),$$

for p polynomial of degree 3.

$$(\because 2 \times 1 + 1 = 3.)$$

$$\text{Take } p(x) = 1 \Rightarrow \omega_0 + \omega_1 = \int_{-1}^1 1 dx = 2 \quad \left. \right\}$$

$$p(x) = x, \Rightarrow \omega_0 x_0 + \omega_1 x_1 = \int_{-1}^1 x dx = 0 \quad \left. \right\} \rightarrow ③$$

$$p(x) = x^2, \Rightarrow \omega_0 x_0^2 + \omega_1 x_1^2 = \int_{-1}^1 x^2 dx = \frac{2}{3} \quad \left. \right\}$$

$$p(x) = x^3, \Rightarrow \omega_0 x_0^3 + \omega_1 x_1^3 = \int_{-1}^1 x^3 dx = 0. \quad \left. \right\}$$

System ③ (non-linear) has unique soln.

$$\omega_0 = \omega_1 = 1, \quad x_0 = -\frac{1}{\sqrt{3}}, \quad x_1 = \frac{1}{\sqrt{3}}.$$

Therefore, the Trapez quadrature formula becomes

$$G(p) = p(-\frac{1}{\sqrt{3}}) + p(\frac{1}{\sqrt{3}}).$$

$$\therefore I(f) \approx G(f) = f(-\frac{1}{\sqrt{3}}) + f(\frac{1}{\sqrt{3}}) \longrightarrow ④$$

Case 3. General n.

There are $2n+2$ free parameters $\{w_i\}_{i=0}^n$ and $\{x_i\}_{i=0}^n$. We would guess that there is a formula $G_2(f) = \sum_{i=0}^n w_i f(x_i)$ that uses $(n+1)$ nodes and gives a degree of precision $2n+1$.

The equation to be solved here are

$$\sum_{i=0}^n w_i x_i^k = \begin{cases} 0, & k = 1, 3, \dots, 2n+1 \\ \frac{2}{k+1}, & k = 0, 2, \dots, 2n \end{cases}$$

→ ⑤

System ⑤ is a system of non-linear equations and their solvability is not at all obvious.

There is general technique to get solns of ⑤ (see: Atkinson, p-272).

We will describe here particular technique, which uses the Legendre polynomials.

~~This~~ This technique is used to determine the nodes and weights for $G_2(f)$.

P-6

Defn (Legendre polynomials)

It is a collection of polynomials

$\{P_0, P_1, \dots, P_n, \dots\}$ with the properties.

(i) For each $n \in \mathbb{N} \cup \{0\}$, P_n is a monic polynomial of degree n .

(ii) $\int_{-1}^1 P(x) P_n(x) dx = \langle P, P_n \rangle_{L^2(-1,1)} = 0$,

for any polynomial P of degree less than n .

There are other definitions of Legendre polynomials.

For eg. (1) They are soln. of the 2nd order ODE

$$(1-x^2) P_n''(x) - 2x P_n'(x) + n(n+1) P_n(x) = 0$$

$$|x| < 1.$$

(2) Rodrigues' formula:

$$P_n(x) = \frac{1}{2^n n!} \frac{d^n}{dx^n} (x^n - 1)^n.$$

Other defns ~~are~~ are also there.

First few Legendre polynomials are:

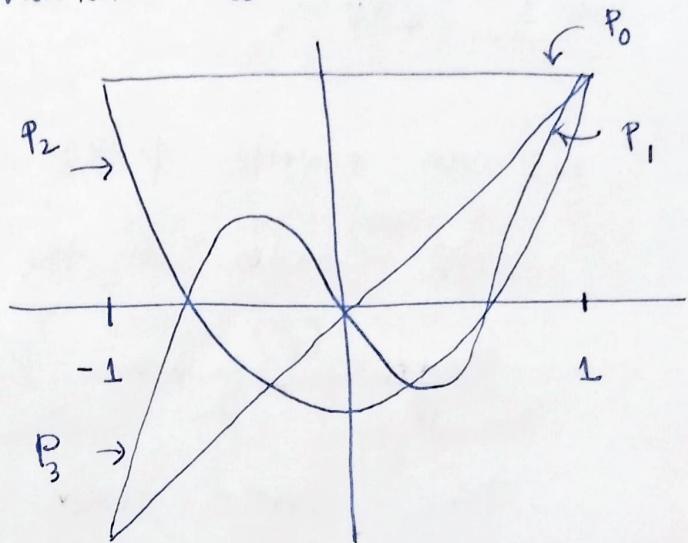
$$P_0(x) = 1$$

$$P_1(x) = x$$

$$P_2(x) = x^2 - \frac{1}{3}$$

$$P_3(x) = x^3 - \frac{3}{5}x$$

$$P_4(x) = x^4 - \frac{6}{7}x^2 + \frac{3}{35}$$



We observe that

-
- (i) The roots of these polynomials are ^{real} distinct and lie in the interval $(-1, 1)$.
 - (ii) They are symmetrically spaced with respect to origin.

Theorem 1 Let $\{x_0, x_1, \dots, x_{n-1}\}$ are the roots of the n th Legendre polynomials P_{n+1} for $n \in \mathbb{N} \cup \{0\}$.

Then, $\int_{-1}^1 P(x) dx = \sum_{i=0}^n w_i P(x_i)$,

for any polynomial P of degree less than $2n+2$,

where w_i s are given by

$$w_i = \int_{-1}^1 \prod_{k=0, k \neq i}^n \frac{(x-x_k)}{(x_i-x_k)} dx.$$

$$i=0, \dots, n.$$

P-8 proof

case 1: ~~Let~~ P be a polynomial of degree less than $n+1$.

We can rewrite $P(x)$ in terms of Lagrange form with nodes at the roots of the $(n+1)$ th ~~degree~~ Legendre Polynomial $P_{n+1}(x)$.

The error term for this representation involves $(n+1)$ derivative of P .

Since degree of P is less than $(n+1)$, so the error term is zero.

$$P(x) = \sum_{i=0}^n L_{i,n}(x) P(x_i) + \frac{P^{n+1}(e_1) \gamma_n(x)}{n+1}$$

$$\gamma_n(x) = (x-x_0) \dots (x-x_n).$$

$$\therefore P(x) = \sum_{i=0}^n L_{i,n}(x) P(x_i)$$

$$L_{i,n}(x) = \prod_{\substack{k=0 \\ k \neq i}}^n \frac{(x-x_k)}{(x_i-x_k)}$$

$$\text{Now, } \int_{-1}^1 P(x) dx = \sum_{i=0}^n P(x_i) \int_{-1}^1 L_{i,n}(x) dx = \sum_{i=0}^n w_i P(x_i). \quad (\underline{\text{proved}})$$

[Lecture - 37]

[P-9]

Case 2: degree of P greater than equal to (n+1) but less than $2n+2$.

Divide the polynomial by the $(n+1)$ the

Legendre polynomial $P_{n+1}(x)$.

Using division algorithm, \exists unique polynomial Q and R such that

$$P(x) = Q(x) P_{n+1}(x) + R(x),$$

⑥ \leftarrow

so that $R(x) \equiv 0$ or

and $0 \leq \text{degree } R < n+1$

As $\{x_i\}_{i=0}^n$ are the roots of $P_{n+1}(x)$, so we have

$$P(x_i) = Q(x_i) P_{n+1}(x_i) + R(x_i) = R(x_i)$$

⑦ \leftarrow

$$P_{n+1}(x_i) = 0$$

$$i=0, \dots, n.$$

From ⑥, integrating

$$\int_{-1}^1 P(x) dx = \int_{-1}^1 Q(x) P_{n+1}(x) dx + \int_{-1}^1 R(x) dx.$$

P-10

$$\int_{-1}^1 P(x) dx = \int_{-1}^1 R(x) dx \quad \left[\begin{array}{l} \text{: using prop (ii) of defn.} \\ \text{of Legendre polynomial} \\ \text{as } \deg Q < n+1 \end{array} \right]$$

$$= \sum_{i=0}^n w_i R(x_i) \quad \left[\begin{array}{l} \text{by case 1 as} \\ \text{degree } R < n+1 \end{array} \right]$$

$$\int_{-1}^1 P(x) dx = \sum_{i=0}^n w_i P(x_i) \quad [\text{by ⑦}] .$$

This proves the result.

2. Gaussian quadrature formula for arbitrary intervals.

The integral $\int_a^b f(x) dx$ can be transformed

into an integral over $[-1, 1]$.

$$\text{Take } x = \frac{1}{2}(b-a)t + \frac{(a+b)}{2}, \quad dx = \frac{1}{2}(b-a)dt$$

$$x=a \Rightarrow t=-1, \quad x=b \Rightarrow t=1$$

$$\begin{aligned} \int_a^b f(x) dx &= \int_{-1}^1 f\left(\frac{1}{2}(b-a)t + \frac{(a+b)}{2}\right) \frac{(b-a)}{2} dt \\ &= \int_{-1}^1 g(t) dt; \end{aligned}$$

$$\text{where } g(t) = \frac{(b-a)}{2} f\left(\frac{1}{2}(b-a)t + \frac{(a+b)}{2}\right), -1 \leq t \leq 1.$$

In polynomial interpolation we have seen approximation of a given function by using ~~poly~~ interpolating polynomials.

For a function $f: [a,b] \rightarrow \mathbb{R}$, let $x_0, x_1, \dots, x_n \in [a,b]$ be distinct pts in the interval.

Let ~~P~~. $P_n(\cdot)$ be the polynomial which interpolates f . (Assuming degree of $P_n \leq n$).

- ④ Existence and uniqueness of P_n is already proved in Polynomial interpolation.

P_n can be written as, $P_n: [a,b] \rightarrow \mathbb{R}$

$$P_n(x) = \begin{cases} \sum_{i=0}^n L_{i,n}(x) f(x_i) & \rightarrow \text{Lagrange} \\ \cancel{f(x_0)} + \sum_{i=1}^n \Psi_{i-1}(x) f[x_0, x_1, \dots, x_i] & \rightarrow (\text{Newton divided difference}) \end{cases}$$

where, $L_{i,n}(x) = \prod_{\substack{j=0 \\ j \neq i}}^n \frac{(x-x_j)}{(x_i-x_j)}$, $i=0, 1, \dots, n$

and

$$\Psi_i(x) = \prod_{j=0}^i (x-x_j) = (x-x_0)(x-x_1) \dots (x-x_i),$$

$i=0, 1, \dots, n-1$.

P-2 Let E_n be the error in this approximation.

Then E_n is given by

$$E_n(x) = \begin{cases} \frac{f^{n+1}(\xi(x))}{(n+1)!} \cdot \varphi_n(x), & a < \xi(x) < b, \text{ and} \\ & f \in C^{n+1}[a, b] \\ \text{or,} \\ f[x_0, x_1, \dots, x_n, x_{n+1}] \varphi_n(x), & \text{if } x \neq x_0, \dots, x_n \\ 0 & \text{if } x = x_i \\ & i=0, \dots, n. \end{cases}$$

(1). Use of Numerical differentiation:

- (i) We can calculate derivatives of functions, whose values are given as data set, which is obtained empirically.
- (ii) Numerical differentiation formulas are used in deriving numerical methods for solving ordinary and partial differential equations.

(2). Disadvantage of Numerical differentiation:

It is an unstable process. We cannot expect good accuracy even if the original data is accurate. We discuss this later in Round off Error instability.

③ Main ideas for Numerical differentiation:

The main approaches to deriving a numerical approximation to $f'(x)$ is to use the derivative of the interpolating polynomial $P_n(x)$, which interpolates f at a given set of distinct points x_0, x_1, \dots, x_n .

$$\text{Therefore, } f(x) = P_n(x) + E_n(x), \quad x \in [a, b].$$

Assuming that the differentiation on both sides are justified, we get

$$f'(x) = P'_n(x) + E'_n(x).$$

To approximate derivative at $x \in [a, b]$ we use

$$f'(x) \approx P'_n(x).$$

The error in this approximation is $E'_n(x)$.

$$E'_n(x) = \left\{ \begin{array}{l} \frac{Y'_n(x) f^{n+1}(g(x))}{n+1} + Y_n(x) \frac{d}{dx} (f^{n+1}(g(x))) \\ \text{or,} \\ Y'_n(x) f[x_0, x_1, \dots, x_n, x] + Y_n(x) \frac{d}{dx} (f[x_0, x_1, \dots, x_n, x]) \end{array} \right.$$

Hence, if $f \in C^{n+2}[a, b]$, the error for differentiation is given by

$$E_n'(x) = \psi_n'(x) \frac{f^{n+1}(\xi_1(x))}{\underline{n+1}} + \psi_n(x) \frac{f^{n+2}(\xi_2(x))}{\underline{n+2}}$$

(2) ←

for $a < \xi_1(x), \xi_2(x) < b$ ~~Higher order differentiation formulas and~~

$$P_n'(x) = \left\{ \begin{array}{l} \sum_{i=0}^n L'_{i,n}(x) f(x_i) \\ \text{or} \\ \sum_{i=1}^n \psi'_{i-1}(x) f[x_0, x_1, \dots, x_i] \end{array} \right.$$

(3) ←

Higher order differentiation formula and their error can be obtained by further differentiation of

(3) and (2) respectively.

Formula (3) is called an $(n+1)$ pt. formula to approximate $f'(x)$.

The most common application of the above formula is used for $x = x_i$, $i=0, \dots, n$ and the grid points are evenly spaced i.e.

$$x_i = x_0 + ih, \quad i=0, \dots, n.$$

In this case, $\psi_n(x_i) = 0$

$$\psi_n(x) = (x-x_0)(x-x_1) \dots (x-x_n)$$

$$\psi_n(x) = \prod_{j=0}^n (x-x_j)$$



$$\psi_n'(x) = \sum_{i=0}^n \prod_{\substack{j=0 \\ j \neq i}}^n (x-x_j) \quad (\text{Leibniz Rule})$$

$$\psi_n'(x_k) = \prod_{\substack{j=0 \\ j \neq k}}^n (x_k - x_j) \quad k=0, \dots, n.$$

$$\therefore E_n'(x_k) = \frac{f^{n+1}(\xi_1(x))}{(n+1)!} \prod_{\substack{j=0 \\ j \neq k}}^n (x_k - x_j) \rightarrow ④$$

P-6

$$P_n'(x_k) = \begin{cases} \sum_{i=0}^n L_{i,n}'(x_k) f(x_i) \\ \text{or} \\ \sum_{i=1}^n \psi_{i-1}'(x_k) f[x_0, \dots, x_i] \end{cases}$$

⑤ ←

for $k = 0, \dots, n$.

④ Let us consider particular examples.

(1) First order derivative.

Eg. (1) $n = 0$. $P_0(x) = f(x_0) \dots P_0'(x) = 0$.

This is not a very good approximation.

(2) $n = 1$. $P_1(x) = f(x_0) + \psi_0(x) f[x_0, x_1]$

$$P_1(x) = f(x_0) + (x - x_0) f[x_0, x_1]$$

$$\therefore P_1'(x) = f[x_0, x_1]$$

⑤ Let $x = x_0 = a$, $x_1 = x_0 + h = a + h$, $h > 0$.

$$\begin{aligned} \therefore P_1'(a) &= f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0} \\ &= \frac{f(a+h) - f(a)}{h} \end{aligned}$$

$$\therefore f'(a) \approx P_1'(a) = \frac{f(a+h) - f(a)}{h} \quad \begin{array}{l} \text{Euler forward} \\ \text{difference} \\ \text{appr. of} \\ \text{derivative.} \end{array}$$

By ④

$$E'_1(a) = \frac{f^2(\epsilon_1)}{12} (x_0 - x_1) = -\frac{h}{2} f^2(\epsilon_1)$$

 $\epsilon_1 < a$ (a th.)

∴ Again for $x = x_1 = a$, ~~then $x_1 = x_0 + h$~~ .

$$\text{Then, } x_1 = x_0 + h \Rightarrow a = x_0 + h, h > 0.$$

$$\Rightarrow x_0 = a - h, h > 0$$

$$\therefore P'_1(a) = f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

$$= \frac{f(a) - f(a-h)}{h}.$$

(Enter backward difference formulae
of derivative),

By ④

$$E'_1(a) = \frac{f^2(\epsilon_1)}{12} (x_1 - x_0) = \frac{h}{2} f^2(\epsilon_1).$$

$$\text{∴ For } x = \frac{x_0 + x_1}{2} = a. \quad \text{Let } x_1 - a = h = a - x_0 > 0$$

$$P'_1(a) = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{f(a+h) - f(a-h)}{2h}$$

(centred difference
formula).

P-8

By ②

$$E'_1(a) = \underline{\psi_1'(a)} \frac{f^2(\xi_1)}{L^2} + \underline{\psi_2(a)} \frac{f^3(\xi_2)}{L^3}$$

$$\begin{aligned}
 &= \left(\frac{x_0+x_4}{2} - x_0 \right) \left(\frac{x_4+x_4}{2} - x_4 \right) \frac{f^3(\xi_2)}{L^3} \\
 &= -\frac{(x_1-x_0)^2}{4} \cdot \frac{f^3(\xi_2)}{L^3} \\
 &= -\frac{h^2 f^3(\xi_2)}{6}, \quad x_0 < \xi_2 < x_4.
 \end{aligned}$$

$$\begin{cases}
 \psi_1'(x) = (x-x_0) + (x-x_4) \\
 = 2x - (x_0+x_4) \\
 \psi_1'(a) = 2a - (x_0+x_4) \\
 = 2 \left(\frac{x_0+x_4}{2} \right) - (x_0+x_4) \\
 = 0.
 \end{cases}$$

[Comparative study] with $h > 0$

	Dervative approx.	Error
Forward	$f'(a) \sim \frac{f(a+h) - f(a)}{h}$	$O(h)$
Backward	$f'(a) \sim \frac{f(a) - f(a-h)}{h}$	$O(h)$
Centred	$f'(a) \sim \frac{f(a+h) - f(a-h)}{2h}$	$O(h^2)$.

Eg. (3) $n=2$ (i.e. 3 pt. formula to approximate $f'(x)$)

$$P_2(x) = f(x_0) + (x-x_0) f[x_0, x_1] \\ + (x-x_0)(x-x_1) f[x_0, x_1, x_2]$$

$$P_2'(x) = f[x_0, x_1] + (2x - x_0 - x_1) f[x_0, x_1, x_2]$$

[3 pt. end pt. formula]

⑤ If $x=a=x_0$ and $x_1=x_0+h=a+h$, $h>0$
 $x_2=x_0+2h=a+2h$.

~~REMARKS~~

$$f'(a) \approx P_2'(a) = f[a, a+h] + (-h) f[a, a+h, a+2h]$$

$$= \frac{f(a+h) - f(a)}{h} + \frac{(-h)}{2h} \left(\frac{f(a+2h) - f(a+h)}{h} - \frac{f(a+h) - f(a)}{h} \right)$$

$$= \frac{2f(a+h) - 2f(a) - f(a+2h) + f(a+h) + f(a+h) - f(a)}{2h}$$

$$= \frac{-f(a+2h) + 4f(a+h) - 3f(a)}{2h}$$

By ④.

Also, $E_2'(a) = \frac{P_2'(a)}{3} = \frac{(-h)(-2h)f^3(\xi)}{3} = \frac{h^2 f^3(\xi)}{3}$

P-10

[3 pt. mid pt. formula]

$$\textcircled{1} \quad x = a = x_1, \quad x_1 = x_0 + h \Rightarrow x_0 = a - h.$$

$$x_2 = x_1 + h \Rightarrow x_2 = a + h.$$

$$\therefore f'(a) \sim P'_2(a) = f[a-h, a] + h f[a-h, a, a+h]$$

$$= \frac{f(a) - f(a-h)}{h} + h \left\{ \frac{f(a+h) - f(a)}{h} - \frac{f(a) - f(a+h)}{h} \right\}$$

$2h$

$$= \frac{2f(a) - 2f(a-h) + f(a+h) - f(a) - f(a) + f(a-h)}{2h}$$

$$= \frac{f(a+h) - f(a-h)}{2h}$$

$$E'_2(a) = Y'_2(a) \frac{f'''(e_1)}{\boxed{13}} = -\frac{h}{6} f'''(e_1).$$

[3 pt. end pt. formula]

$$\textcircled{2} \quad x = a = x_2, \quad x_2 = x_1 + h \Rightarrow x_1 = a - h$$

$$x_1 = x_0 + h \Rightarrow x_0 = a - 2h.$$

$$f'(a) \sim P'_2(a) = f[a-2h, a-h] + 3h \left\{ f[a-2h, a-h, a] \right\}$$

$$= \frac{f(a-h) - f(a-2h)}{h} + 3h \left\{ \frac{f(a) - f(a-h)}{a - (a-h)} - \frac{f(a-h) - f(a-2h)}{a-2h-a+2h} \right\}$$

$$= \frac{f(a-h) - f(a-2h)}{h} + \frac{3f(a) - 3f(a-h) - 3f(a-1) + 3f(a-2h)}{2h}.$$

$$= \frac{2f(a-h) - 2f(a-2h) + 3f(a) - 6f(a-h) + 3f(a-2h)}{2h}$$

$$P_2'(a) = \frac{3f(a) - 4f(a-h) + f(a-2h)}{2h}$$

and $E_2'(a) = \frac{h}{3} f'''(\xi)$.

(B) 2nd order derivative.

We again note that

$$f(x) = P_n(x) + E_n(x)$$

$$f(x) = P_n(x) + \psi_n(x) f[x_0, x_1, \dots, x_n, x]$$

$$f'(x) = P_n'(x) + \psi_n'(x) f[x_0, x_1, \dots, x_n, x]$$

$$+ \psi_n(x) f[x_0, x_1, \dots, x_n, x, x]$$

Differentiating again

$$\begin{aligned} f''(x) &= P_n''(x) + \psi_n''(x) f[x_0, x_1, \dots, x_n, x] \\ &\quad + 2\psi_n'(x) f[x_0, x_1, \dots, x_n, x, x] \\ &\quad + \psi_n(x) f[x_0, x_1, \dots, x_n, x, x, x] \end{aligned}$$

P-W 12 Again we ~~just~~ assume that f is $(n+3)$ times continuously differentiable to justify the ~~the~~ above differentiation on the R.H.S.

We use $P_n''(x)$ to approximate $f''(x)$.

Eg: (1) $n = 2$, ~~so~~ $x = x_0 = a$, $x_1 = x_0 + h = a+h$, $x_2 = a+2h$. For $h > 0$

$$\therefore P_2(x) = f(x_0) + (x-x_0) f[x_0, x_1] + (x-x_0)(x-x_1) f[x_0, x_1, x_2]$$

$$\Rightarrow P_2'(x) = f[x_0, x_1] + (2x - x_0 - x_1) f[x_0, x_1, x_2]$$

$$P_2''(x) = 2f[x_0, x_1, x_2]$$

$$f''(a) \approx P_2''(a) = 2f[a, a+h, a+2h]$$

$$= 2 \cdot \frac{f[a+h, a+2h] - f[a, a+h]}{(a+2h)-a}$$

$$= \frac{\frac{f(a+2h) - f(a+h)}{h} - \frac{f(a+h) - f(a)}{h}}{h}$$

$$= \frac{f(a+2h) - 2f(a+h) + f(a)}{h^2}$$

$$E_2''(a) = 2f[a, a+h, a+2h, a, a] (a-x_1)(a-x_2)$$

$$+ 2f[a, a+h, a+2h, a] (2a-x_1-x_2)$$

$$= \frac{h^2}{6} f^{iv}(\xi_1) - h f'''(\xi_2)$$

Similarly

For, $x=x_1=a$, $x_0=a-h$, $x_2=a+h$, with $h>0$

$$f''(a) \approx P_2''(a) = \frac{f(a-h) - 2f(a) + f(a+h)}{h^2}$$

$$E_2''(a) = -\frac{h^2}{12} f^{iv}(\xi).$$

and $x=x_2=a$, $x_0=a-2h$, $x_1=a-h$, with $h>0$.

$$f''(a) \approx P_2''(a) = \frac{f(a) - 2f(a-h) + f(a+2h)}{h^2}$$

$$E_2''(a) = \frac{h^2}{6} f^{iv}(\xi_1) + h f'''(\xi_2)$$

Remark: In the above ~~approximation~~ we have used Newton divided difference form of interpolating polynomial to derive the approximation of ~~the~~ derivative. Similarly Lagrange form

[P-1b] of interpolating polynomial could be ~~use~~ we to derive the same.

⑤ Round off Error instability

Let us consider the centred difference formula or 3 pt. mid. pt. formula.

$$\text{we have } f'(a) = P_1'(a) + E_1'(a),$$

$$f'(a) = \frac{f(a+h) - f(a-h)}{2h} - \frac{h^2}{6} f'''(\xi).$$

Let us assume that in evaluating $f(a+h)$ and $f(a-h)$ we commit round off errors $e(a+h)$ and $e(a-h)$ respectively.

The computer actually use the round off approximation $\bar{f}(a+h)$ and $\bar{f}(a-h)$ respectively.

$$\text{i.e. } f(a+h) = \bar{f}(a+h) + e(a+h)$$

$$\text{and } f(a-h) = \bar{f}(a-h) + e(a-h).$$

Total error in this approximations

$$E(f'(a)) = f''(a) - \frac{\bar{f}(a+h) - \bar{f}(a-h)}{h}$$

$$= \underbrace{\frac{e(a+h) - e(a-h)}{h}}_{\text{Round off error}} - \underbrace{\frac{h^2}{6} f'''(\xi)}_{\text{Truncation error}}$$

Round off error

Truncation error.

$$\therefore |E(f'(a))| = \left| \underbrace{\frac{e(a+h) - e(a-h)}{h}}_{\text{Round off error}} - \frac{h^2}{6} f'''(\xi) \right|$$

$$\leq \left| \frac{e(a+h)}{h} \right| + \left| \frac{e(a-h)}{h} \right| + \frac{h^2}{6} |f'''(\xi)|$$

$$\leq \frac{2\varepsilon}{h} + \frac{h^2}{6} M \quad \rightarrow \textcircled{6}$$

(Assume $|e(a+h)| \leq \varepsilon$ and $|f'''(\xi)| \leq M$.

for some $\varepsilon, M > 0$) .

We note that Round off error $\rightarrow 0$ as $h \rightarrow \infty$

and Truncation error $\rightarrow 0$ as $h \rightarrow 0$.

Therefore, we cannot take h very small to reduce the error because round off error may increase. To reduce error we use optimum value of h .

Here in the case above optimum value of h is

$$\text{Optimum } h_{\text{opt}} = \left(\frac{3E}{M} \right)^{\frac{1}{3}} \rightarrow (7)$$