

# R SOORYA NARAYANAN

+91 860 680 8316 sooryanarayanan017@gmail.com https://github.com/havok69

#### **EDUCATION**

Chennai, India IIITDM Kancheepuram 2020 - 2024

- B. Tech in Smart Manufacturing. CGPA of 8.07
- Relevant courses:
- Image Processing
  Machine Learning
  Data Science in Python
- Computer Vision
  Natural Language Processing
  Microcontrollers

#### Kerala, India Kailasanadha Vidyanikethan

Class XII (Central Board of Secondary Education) | Percentage: 90.8% 2019 – 2020 Class X (Central Board of Secondary Education) | CGPA: 9.16(10) 2017 – 2018

#### **EXPERIENCE**

# Intern Talakunchi Networks Pvt Ltd IT Sept - Nov 2021 and Network Security Services

- Learnt softwares and operating systems relevant in the field of cybersecurity and penetration testing.
- Tasked with penetration testing and securing websites with varying security.
- Practiced penetration testing and ethical hacking on devices.

Intern TiHAN IIT - Hyderabad May 15 - Present

- Working on Monocular depth analysis controlled, GPS denied AGV navigation for seamless tracking.
- Currently developing an AGV for industrial application, with pedestrian detection, tracking and trajectory prediction for occlusion detection and occlusion delay.
- Monocular depth estimation and panoptic segmentation integrated for better depth estimation of pedestrians.
- Primary tasks involve hardware integration, algorithm optimization, benchmarking, etc.

# Intern Veyyil Robotics Private Limited Sept 25 - Present

- Strategic Image/Video Data collection and annotation.
- Training Object detection, segmentation, pose estimation and tracking models for industrial scenarios.

#### **TECHNICAL SKILLS**

- Languages: C, C++, Python, HTML, CSS, PHP
- Databases: SQL, MongoDB
- Software/OS: Windows, Linux, ROS, AutoCAD, Fusion 360, MS Office, Unity, Visual Studio Code, PyCharm
- Version Control: Git, Github
- Cloud Platforms: AWS
- Microcontrollers/Boards: (TM4C123GH6PM), ESP8266, ESP32, Arduino, Raspberry Pi, Jetson Nano, Jetson Xavier NX

- Object Detection, Object Tracking and Re-identification, Pose Estimation, Trajectory Prediction, OpenCV, YOLO, MiDaS, SLAM, Tensorflow, Keras, PyTorch, GANs
- Point cloud processing, Meshing, Open3D, PPTK, Photogrammetry, Agisoft Metashape/PhotoScan, 3DF Zephyr, Meshroom, NeRF, Luma AI, Nerfstudio, Instant-NGP, COLMAP

#### **POSITIONS OF RESPONSIBILITY**

- Member of Computer Vision team in AUV Technical Club (Dec 2022 July 2023).
- Mentor for AUV Society IIITDM (July 2023 Present).
- Member of the CS team in FROST club formed to educate and train new recruits for technical clubs.
- Coordinator of Decor Club Samgatha 2022 (cultural event).

#### **PROJECTS/ACHIEVEMENTS**

### Secured 3<sup>rd</sup> position globally in the 2023 MATE NOAA Ocean Exploration Video Challenge, USA

- o Trained a custom object detection and classification model for detecting and classifying deep-sea organisms in the NOAA ship *Okeanos Explorer*.
- o Model judged on the basis of accuracy of classification and localizations of bounding boxes when applied on test data.
- o Project github link: https://github.com/havok69/2023-MATE-NOAA-Ocean-Exploration-Computer-Coding-Challenge

#### Web Application developed for ordering food in hostels of IIITDM-K

- o Designed a web app for online food ordering.
- o User-friendly form for ordering food items and storage of ordered food items in a PHP file on the server
- o Technologies used were HTML, CSS and PHP and managed Databases using MySQL
- O Using the data obtained as the test data for initial orders we explored the data using python for Scheduling and Forecasting

#### Implemented a KNN and K-means multi-classification on Kaggle datasets

- o Pre-processed a Kaggle dataset for Basketball players and their performance
- o Evaluated model performance using metrics like accuracy, precision, recall, and F1 score

#### • Computer Vision projects for AUV Technical Club

- o Responsible for training multiple object detection data models to detect various objects and organisms underwater for AUV club competitions
- o Developed models to detect underwater gates, buoys, and perform animal life classification
- o Additionally, worked on photogrammetry of underwater biome replicas

#### Multilingual Speech Recognition Model for RAG chat-bot without Training

- o Built a multilingual speech recognition model to enable RAG to perform tasks in multiple languages.
- o Used LangChain, OpenAI and Pinecone vector DB to build chat-bot capable of learning using RAG.
- o Can input queries from audio/video files in multiple languages.

# Designed and developed a smart projector for 2-wheeler safety

- o Projector serves as indicator lamps for the rider, with a simple installation of our product.
- o Eliminates the risks due to absence of an indicator lamp in 2-wheelers.