

Prathamesh Pawaskar B.E. Mechatronics Engineering

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Course	College/University	Year	CGPA/%
PNPT	TCM security	ongoing	
B.E. Mechatronics Engineering	Mumbai University	2019-23	8.23
CBSE(11th/12th)	Pace ,VPGS ,(PCM)	2017-19	61
School(SSC)	St Ursula School	2017	92.80

SCHOLASTIC ACHIEVEMENTS			
 Secured 1st rank in E-yantra robotics competition Secured 2nd rank in Gesture controlled robotics competition Cleared elementary, intermediate b grade 	[2022] [2022] [2016]		
WORK EXPERIENCE			
design team lead Eyantra robotics lab,IIT Bombay	[Jun'22-Jul'22]		
modulocopter(quadcopter design)side projects pertaining to startups			
• innovation programming role ESVC Mumbai Univ.	[Jun 21 -Nov 21]		

- o attempt at lane detection
- o interfacing with ESVC vehicle electricals

SKILLS & INTERESTS

- Programming Languages: c-embedded, Python, bash, latex
- Tools & Libraries: arduino ide, raspberry pi terminal ,numpy, joystick.h, Latex, Matplotlib, SPI.h,MFRC522.h., FUSION360, Circuit building and testing, Easyeda, Automation studio, Keil Uvision4, LATEX
- Interests: Functional programming ,product development , cad, strength analysis ,innovation

PROJECTS • UNDERGROUND WIRE FAULT DETECTOR | Prof. Abhijit Chate • Worked on concept development and theory • Also presented • DRIVING GAME CONTROLLER WITH DATA ACQUISITION SYSTEM | Prof. Abhijit Chate • Worked on Implementation, component selection and Programming of arduino leonardo • Lead • Development of Rotary Wing UAV for Drug Delivery in Remote Areas | Dr. Raghvendra Upadhyay • Worked on Implementation, component selection calculation and Programming of the quadcopter • worked on creating a stack which works on ardupilot to move autonomusly • MQTT with TLS on arduino | self • developed and realised the project

Experience in Industrial Components

- Arduino leonardo, Arduino mega, Arduino uno
 Esp32, Raspberry pi, flight controller run on f405(stm electronics chip) microcontroller
- 3d printer (fdm), laser cutter for acrylic, CNC machines
- pneumatic and hydraulic componentery, oscilloscope, electronics testing components

POSITIONS OF RESPONSIBILITY

• Team leader | Design interns team

[jun'22-July'22]

- o Responsible for development of modular quadcopter.
- project report and presentation

• head of innovation | electrical department ESVC

[jun'21-nov'21]

- Managed 2 members
- $\circ~$ trial program for rudimentary autonomus driving system

EXTRACURRICULAR ACTIVITIES

- motorsports
- badminton
- playing electric guitar
- stand up comedy