



北京林业大学



Quantitative remote sensing for precise forest management

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Content

1. Remote sensing position
2. Why quantitative remote sensing?
3. Framework
4. Our practices
5. The future

Forest Ecosystems Journal

1. Remote sensing position in FM

You can't manage what you don't measure

— Peter F. Drucker

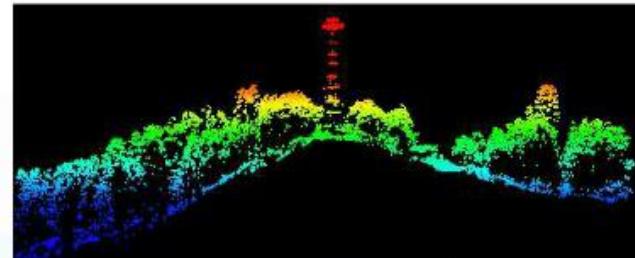
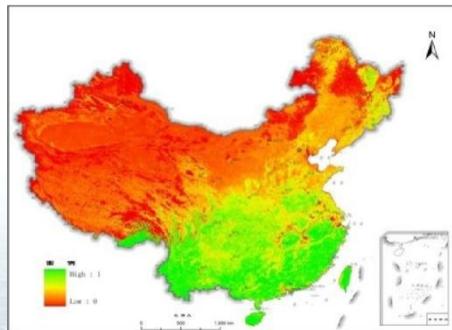
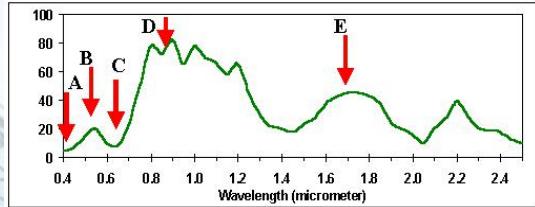
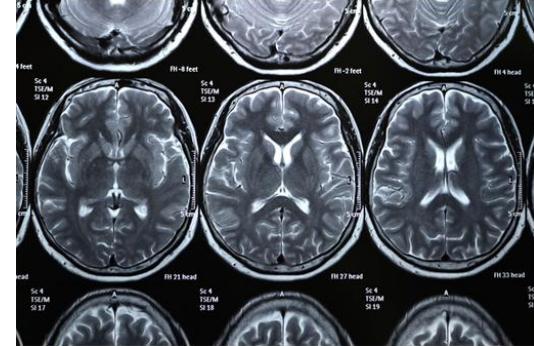
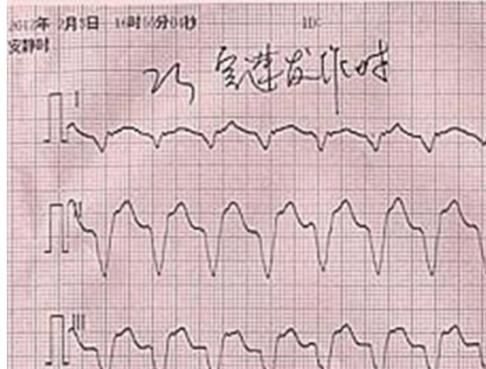
- Forest management
- Forest Measurement (sampling)
- Remote sensing

1. 1 Challenges and revolution

- Just a tool: work for others
- Too simple applications:segmentation and NDVI
- Too universal: everybody know RS, such as silviculture, soil conservation, wildlife...
- What is our special contribution?
 - in time and operational (annual report on whole China)
 - high accuracy (breakthrough the bottleneck)

1.2 Remote sensing Position

- Remote sensing is an important tool: like the CT and B-mode ultrasonography in hospital
- Investigation and diagnosis: earlier,better



1. 3 Mission

- Support the forest quality improvement
 - Remote Measure for management
 - Improve old metrics:precise and practical
 - Volume,biomass, classification and area
 - Discover new things:
 - new metrics, new algorithms,new sensors

2. Why quantitative RS?

- lower maturity comparing to other industries
 - Meteorological: operational predication (FY-4)
 - Land resources: high resolution
 - Agricultural: HOM, easier measurement, money
 - Forest: HET, cloud, rain, hard, less money
- Two inherent problems:
 - Low accuracy (70-90%)
 - Insufficient operational satellites

2. Why quantitative RS?

- Deep into mechanism to explain more and improve accuracy
- Develop simulation models for quantitative inversion
- pre-research to explore frontier and pave the way of prospective layout

2. Why quantitative RS?

2.1 Deep into mechanism

- ✓ Complex land surface: terrain, mixture pixel
- ✓ Saturation: high biomass
- ✓ ill-posed inversion: underdetermined equation
- ✓ Multi-angular: BRDF effect
- ✓ Scale effect: inconsistency
- ✓ Data fusion: optical and microwave

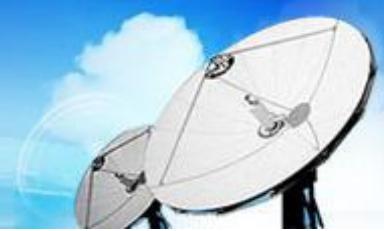
2. Why quantitative RS?

2.2 Simulation models

- **high-spectral simulation:** Clarify the best bands, resolution, and potential for tree species classification
- **Optical imaging:** clarify errors from terrain, mixture pixels; scale correction
- **TIR imaging:** drought, pest effect
- **Lidar:** Clarify footprint size, angle, multiple scattering on tree height
- **BRDF:** extract tree height
- **Microwave imaging:** improve data fusion



2. Why quantitative RS?



2.3 Pre-research for leading edge

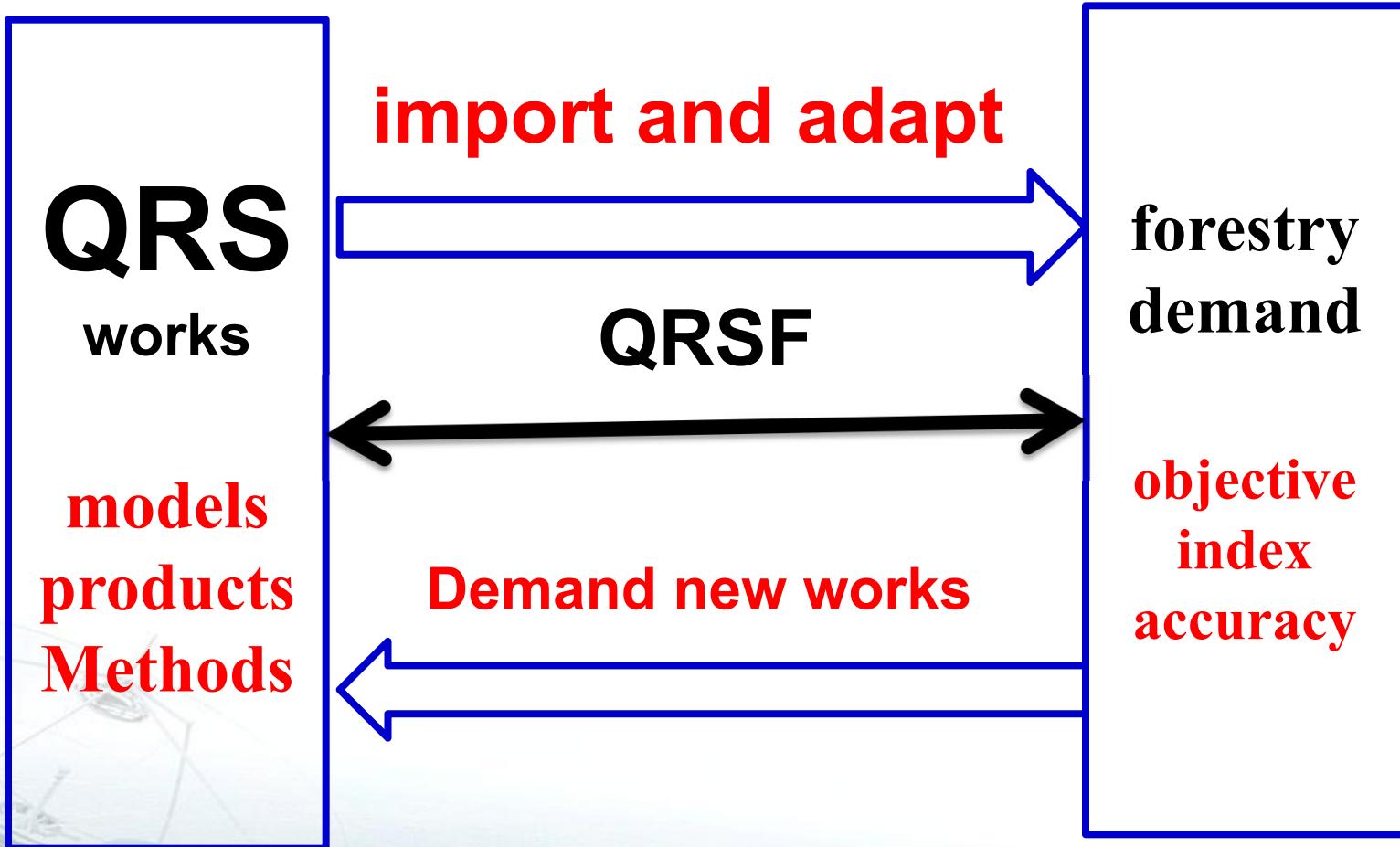
- What new sensors are required?
 - High penetration: microwave INSAR
 - Vertical structure: Space-borne Lidar
 - Tree species: two highs (spatial and spectral) (e.g. GF-5)
 - Single tree: Lacking data in forested area
- How to mine current data potential?
 - What is limit of information contribution?
- How to better fuse? How to better remove noise?

3. Framework

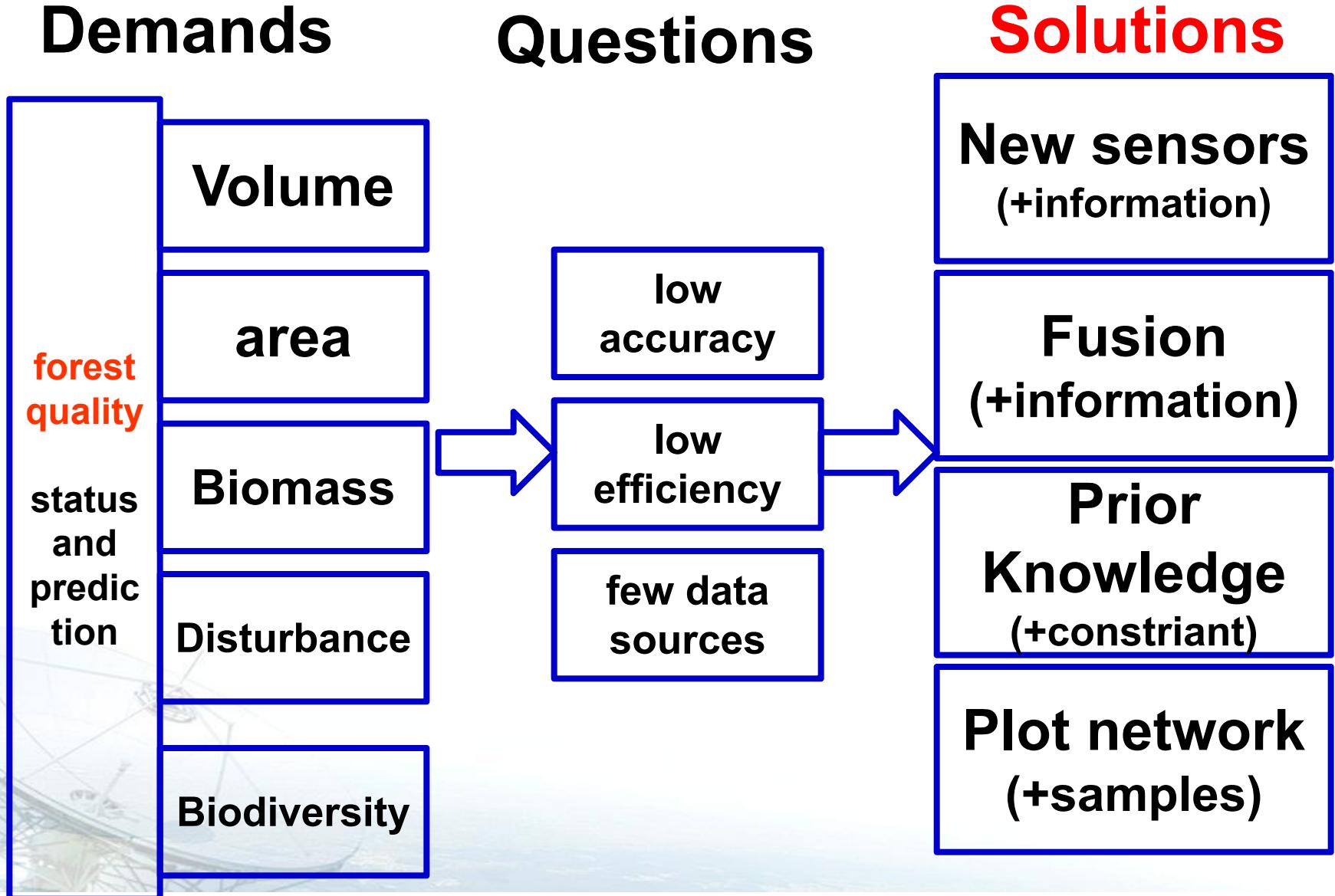
- Basic framework: QRS+application
- Propose scientific questions: demand-oriented
- Make use of current resources

3. Framework

3.1 Basic Framework



3.2 Core scientific questions





Solutions

New sensors
(+information)

Fusion
(+information)

Prior
Knowledge
(+constraint)

Plot network
(+samples)



Scientific questions

What sensors?

Contribution ratio?

How fusion?

unify scale?

Can we improve?

Error transfer?

how to add prior?

Best smapling?

Improve efficiency?

Automatically?

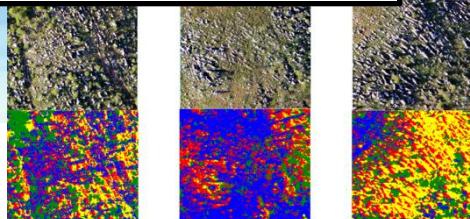
3.3 Mine current rich data sources



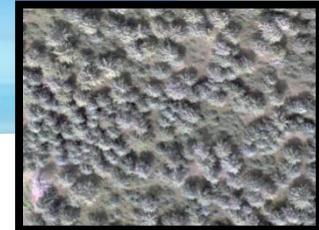
云南虫害图像
无人机2 cm



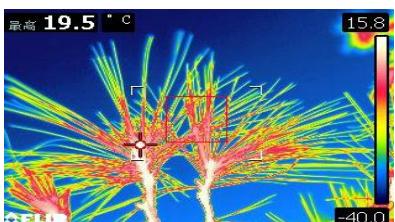
顺义共青林场林木定位
无人机1cm



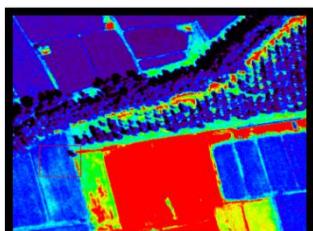
a 云南石林石漠化制图
无人机1cm
c



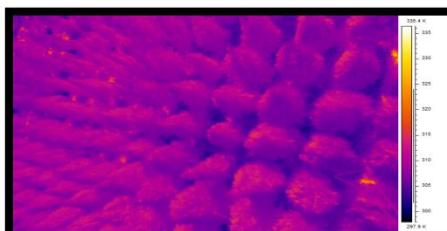
黑河青海云杉分布
航空相片0.1米



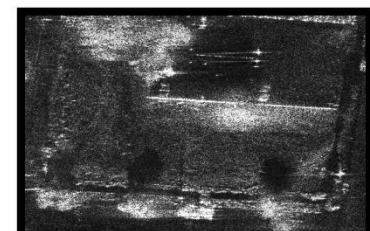
云南松针叶
(地面 FLIR 热温度图像)



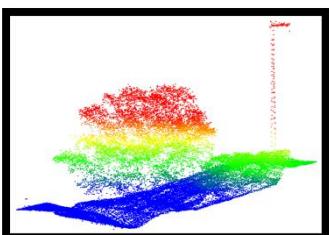
甘肃农田防护林
(机载热红外温度图像)



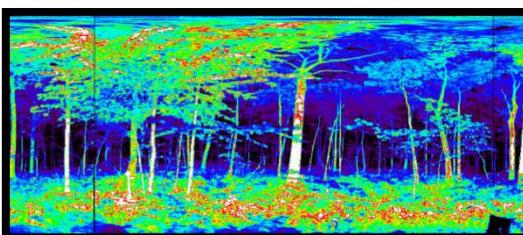
河北侧柏林
(塔吊热红外温度图像)



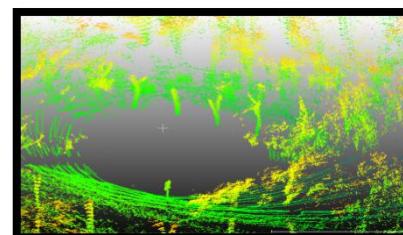
某地X波段雷达图像
(0.1 m SAR)



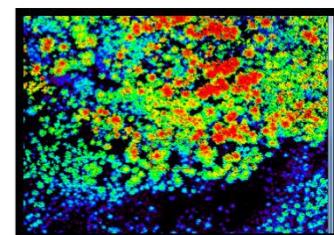
某城区单木和电线杆
(机载激光雷达点云)



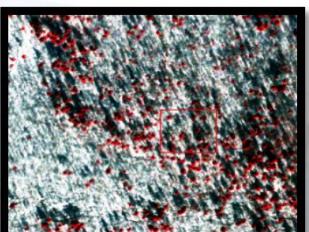
哈佛大学林场森林样地
(地基 激光雷达点云)



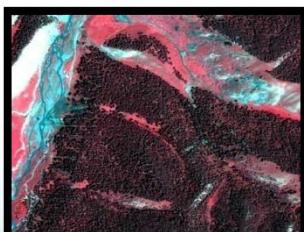
北京林业大学主楼前
(VLP-16 激光雷达点云)



根河落叶松林
(激光雷达提取的树高)



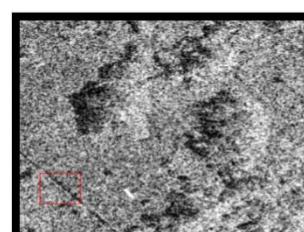
蛟河红松分布
RapidEye 卫星5米



黑河青海云杉分布
Quickbird 卫星0.6米



额济纳胡杨林
(quickbird 2 m)



夏威夷雷达图像
(TerraSAR 2 m)



浙江将乐林场图像
(Worldview-2 0.5m)

3.3 Make use of current QRS models



PROSAIL = PROSPECT + SAIL

<http://teledetection.ipgp.jussieu.fr/prosail/>

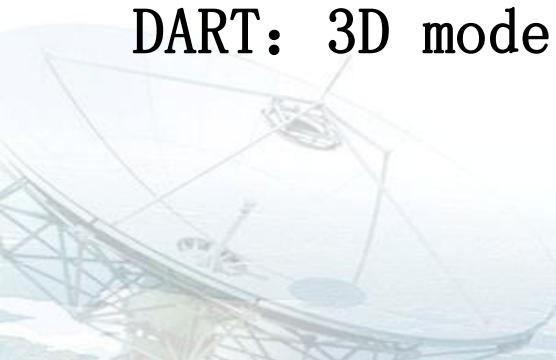
ARTMO platform:

<http://ipl.uv.es/artmo/>

GOMS: Geometrical-optics

GORT: Geometrical-optics and radiative transfer

DART: 3D models



3.3 Make use of rich QRS products



- Structural: tree height, forest cover, LAI, LAD
- Biochemical: chlorophyll, water, fluorescence, evapotraspiration

<http://earthexplorer.usgs.gov/>

<https://scihub.copernicus.eu/dhus/#/home>

<http://www.eorc.jaxa.jp/ALOS/en/aw3d30/>

<http://landcover.org/>

<http://glass-product.bnu.edu.cn/>

4. Our practices

➤ 4.1 3D model **RAPID**:

- Top level、full band、Chinese brand

➤ 4.2 Ground observation:

- LAI-Mobile for fast LAI
- Line scanning lidar for fast forest strcuture

➤ 4.3 Inversion:

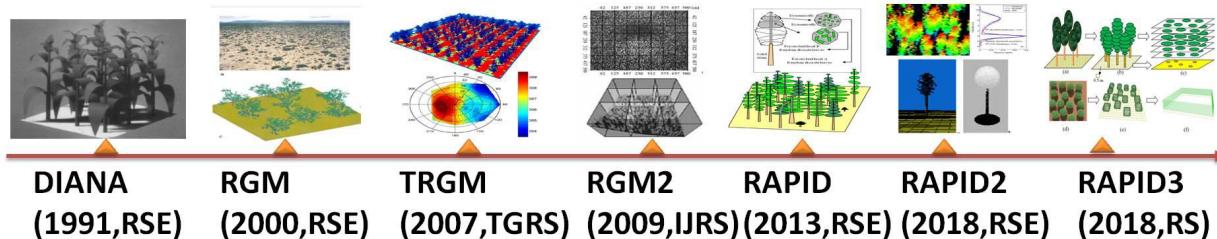
- Chl、LAI、Rocky desertification

4.1 RAPID (Top level、full band、Chinese brand)

Support VNIR, TIR, microwave, Lidar

<http://www.3dforest.cn/>

3D simulation model on remote sensing signals (RAPID)



@Remote sensing of forest group

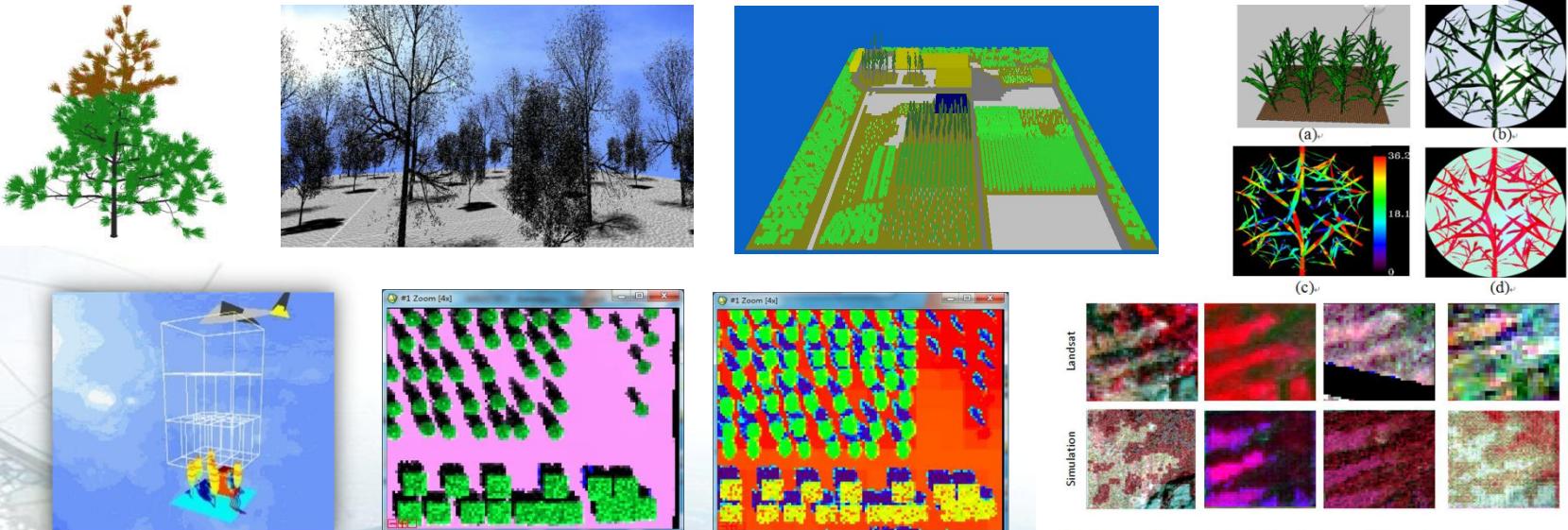


Fig. 11 Comparison between simulated and Landsat images with false color composition

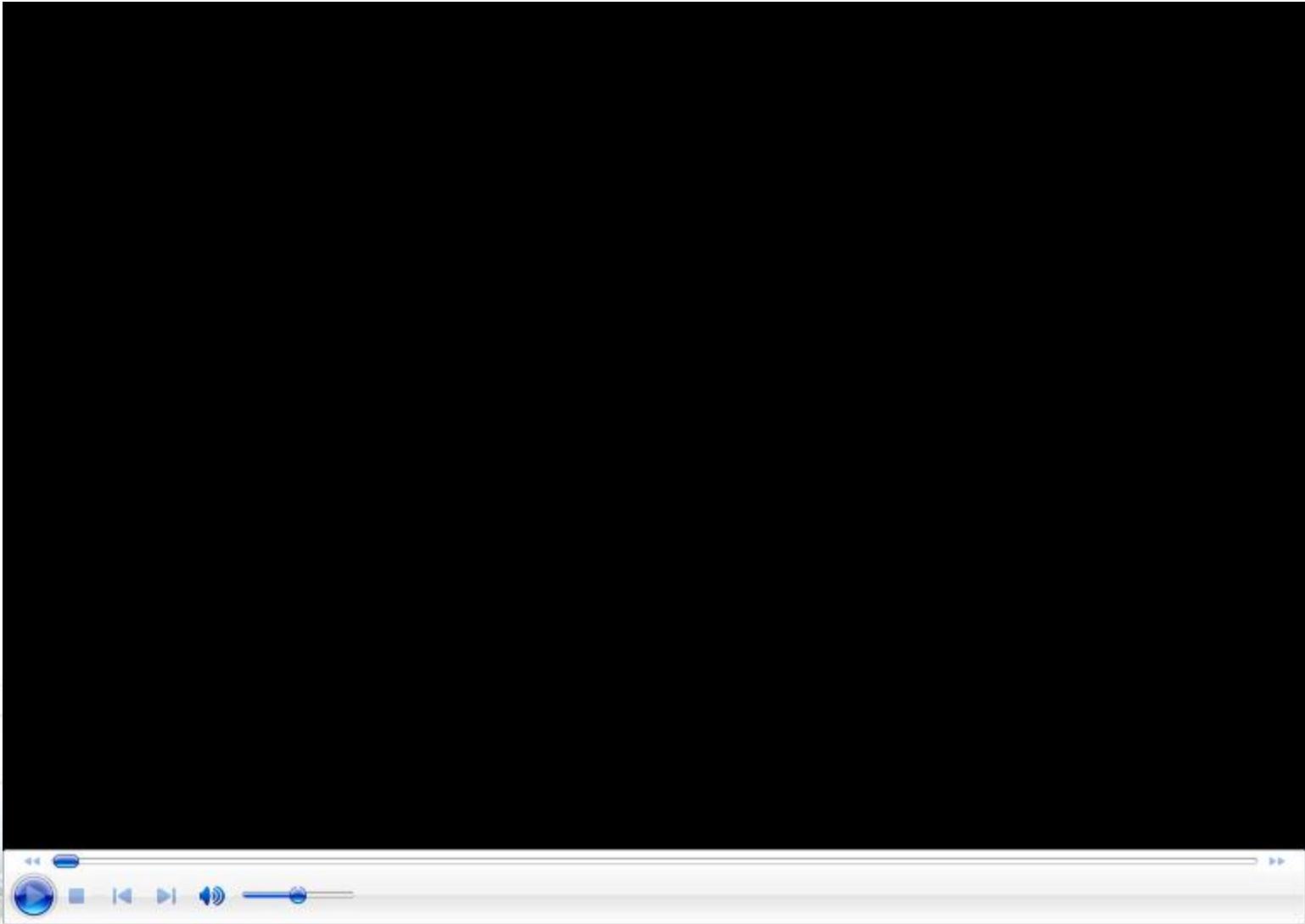
	Optical(VNIR)	TIR	Microwave
Small scale	RGM 2000	TRGM 2007	x
Stand scale	RAPID 2013	RAPIDEB 2018	RAPID2 2016, 2018
Landscape scale	RAPID3 2018	ongoing	ongoing

RAPID3 (RS, 2018) can run a 500 m scene in 13 minutes on a notebook



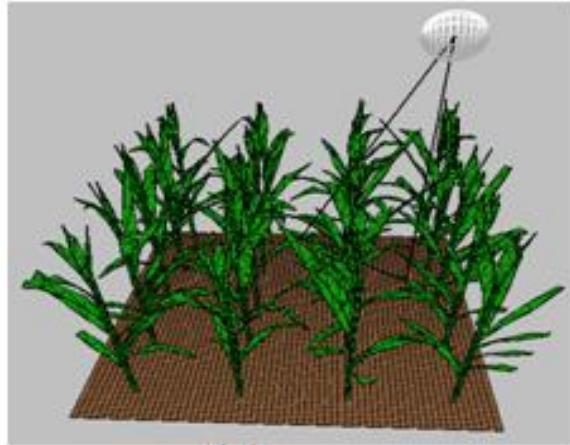


RAPID demo Video



Multi-sensors

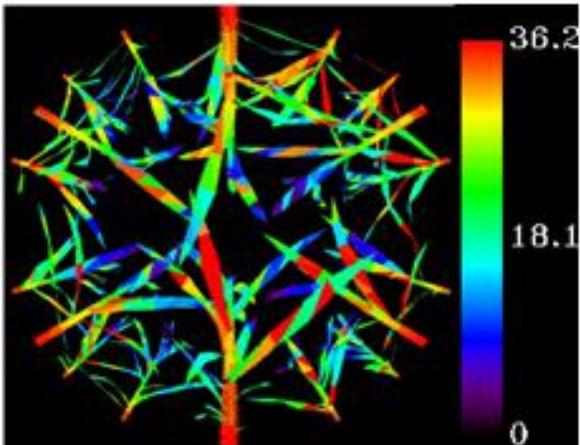
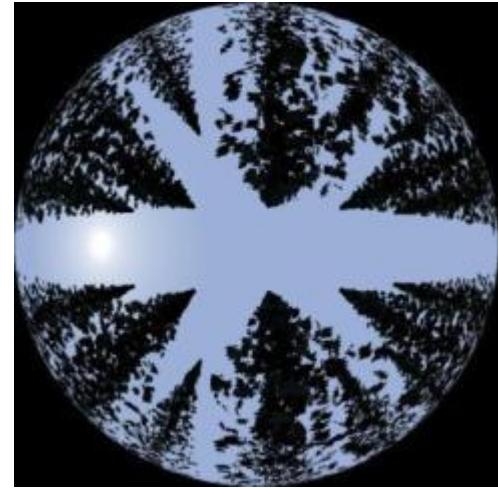
Simulating fish-eye images in RGB, NIR, and TIR



(a) ↵



(b) ↵ RGB

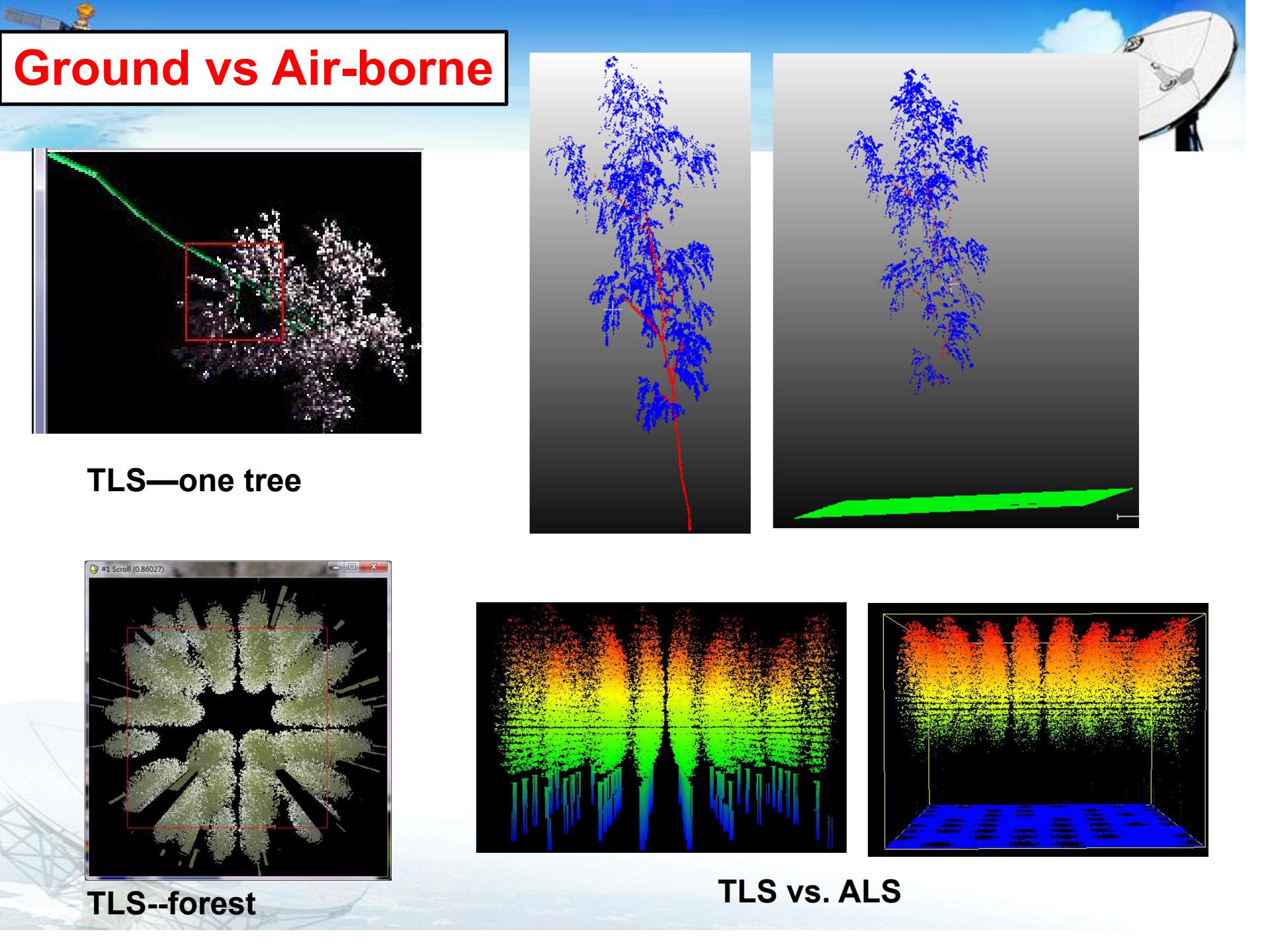


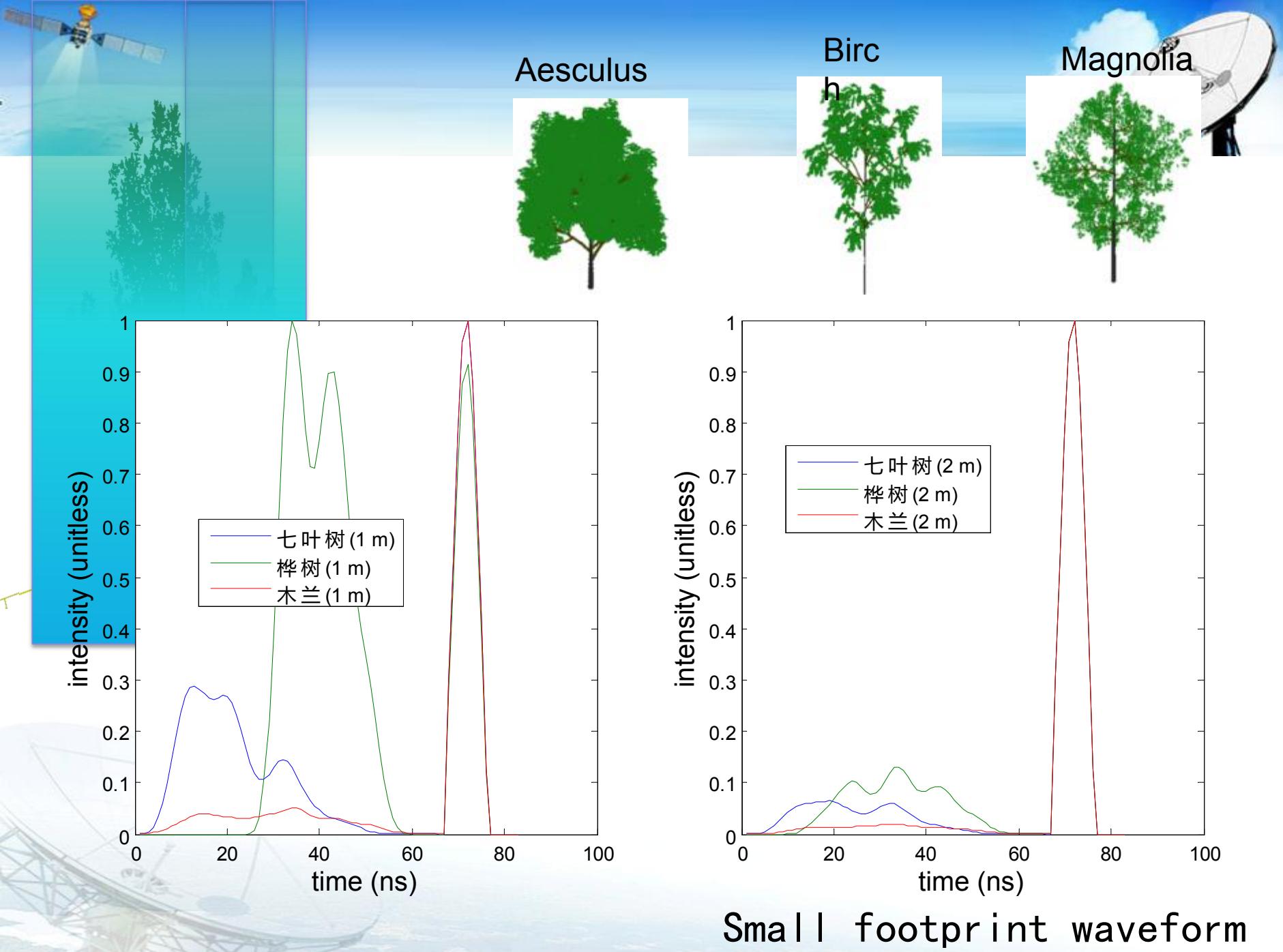
(c) ↵ TIR

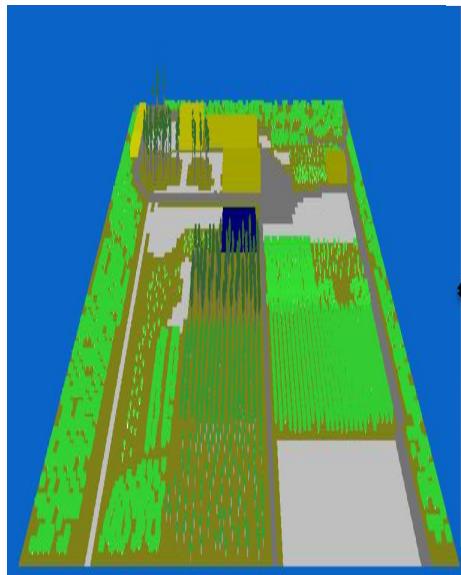


(d) ↵ NIR

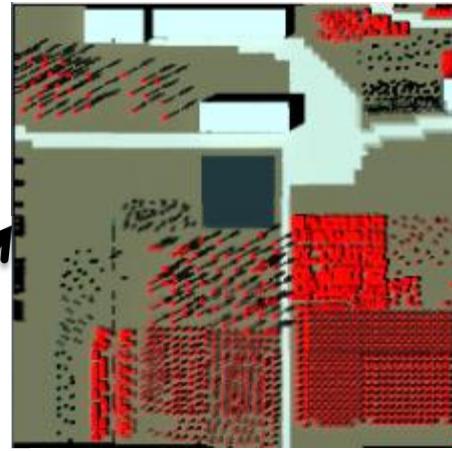








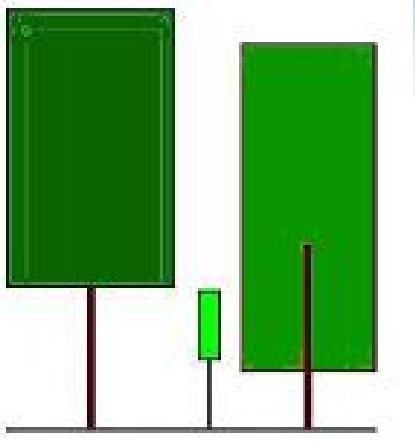
100m by 300m



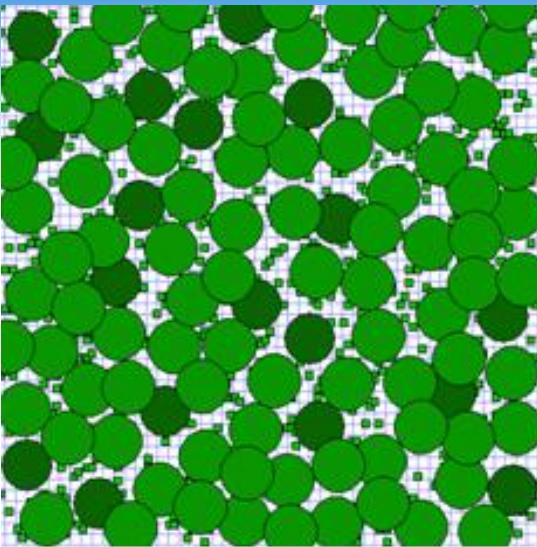
(a) VNIR (NIR,R,G)



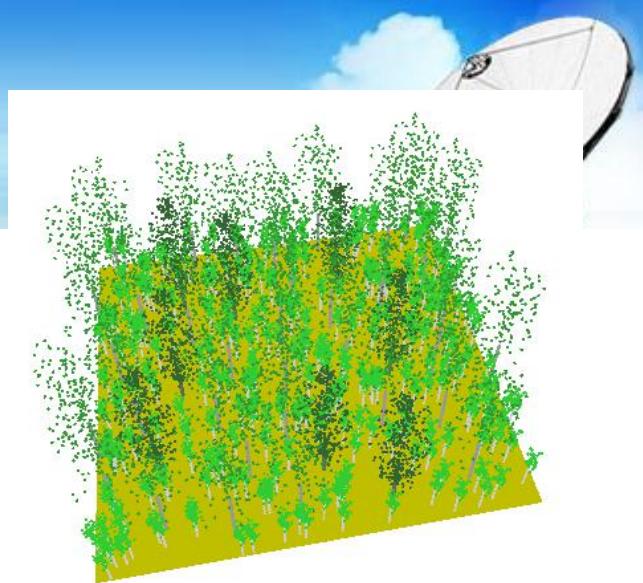
(b) TIR image



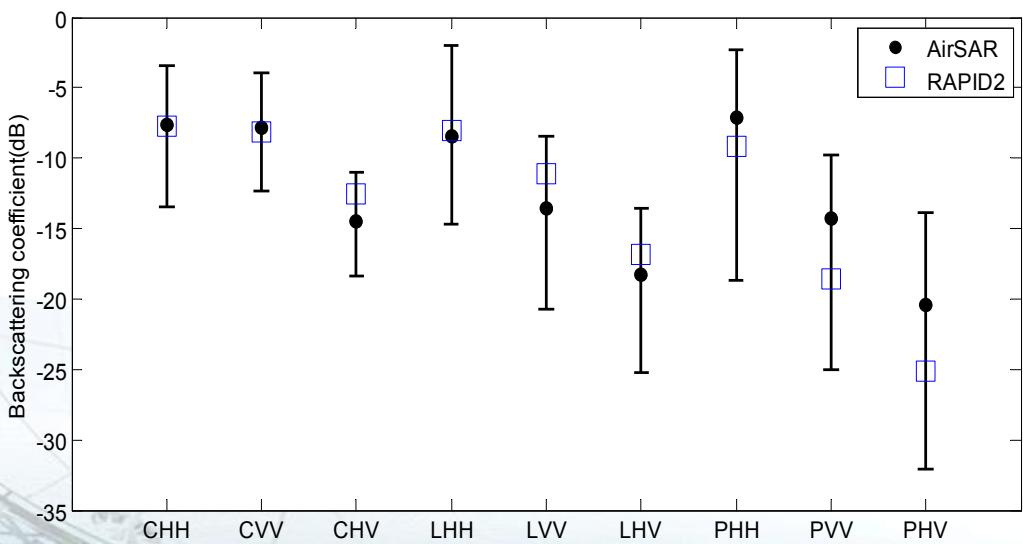
Relative tree size



2D scenes of RAPID2



3D scenes of RAPID2



microwave

accepted in RSE

Annual Landsat image simulation

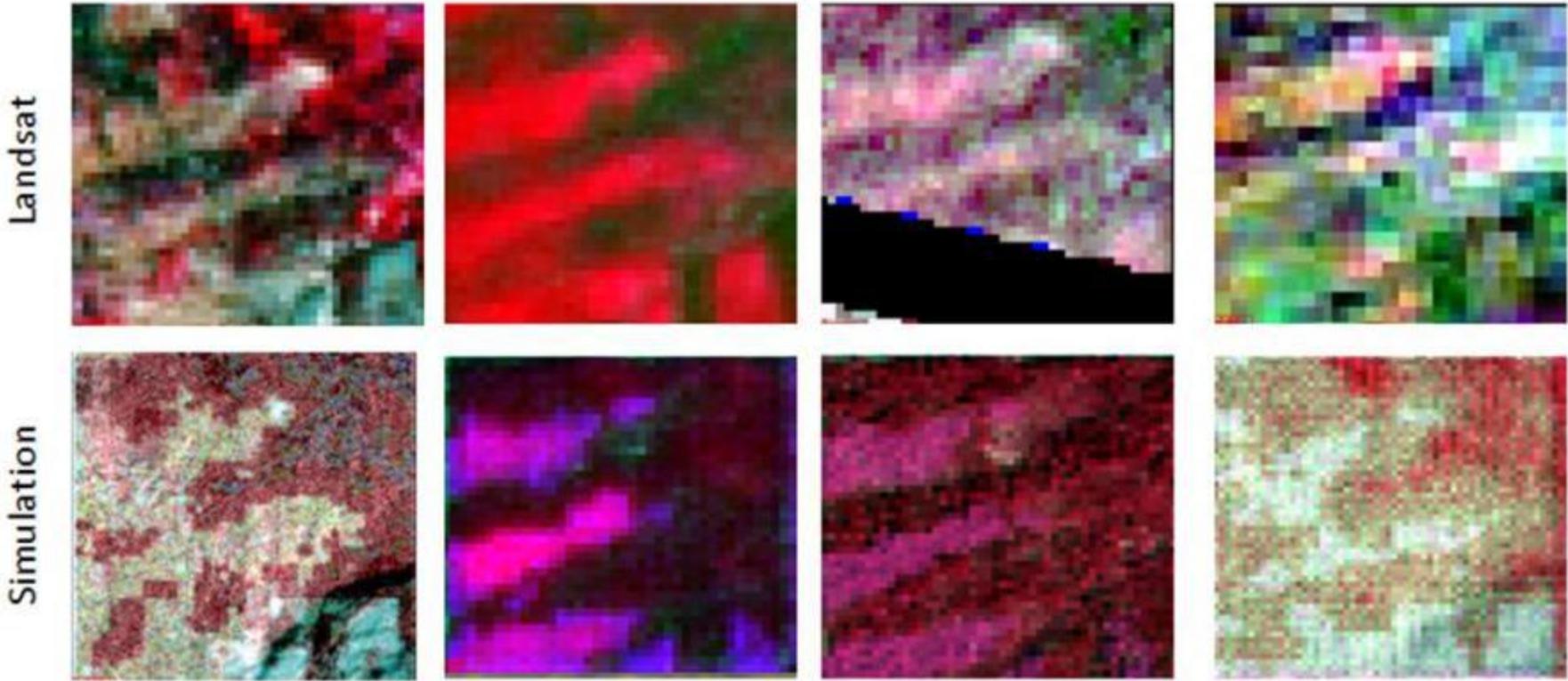
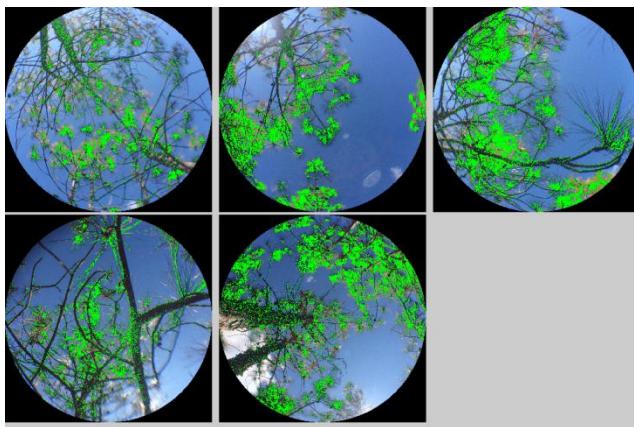
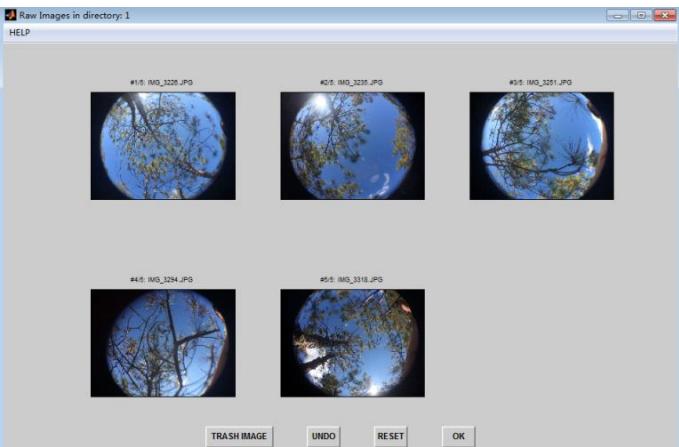


Fig. 11 Comparison between simulated and Landsat images with false color composition

Huang and Lian, 2015, Forest Ecosystems

4.2 Ground observation

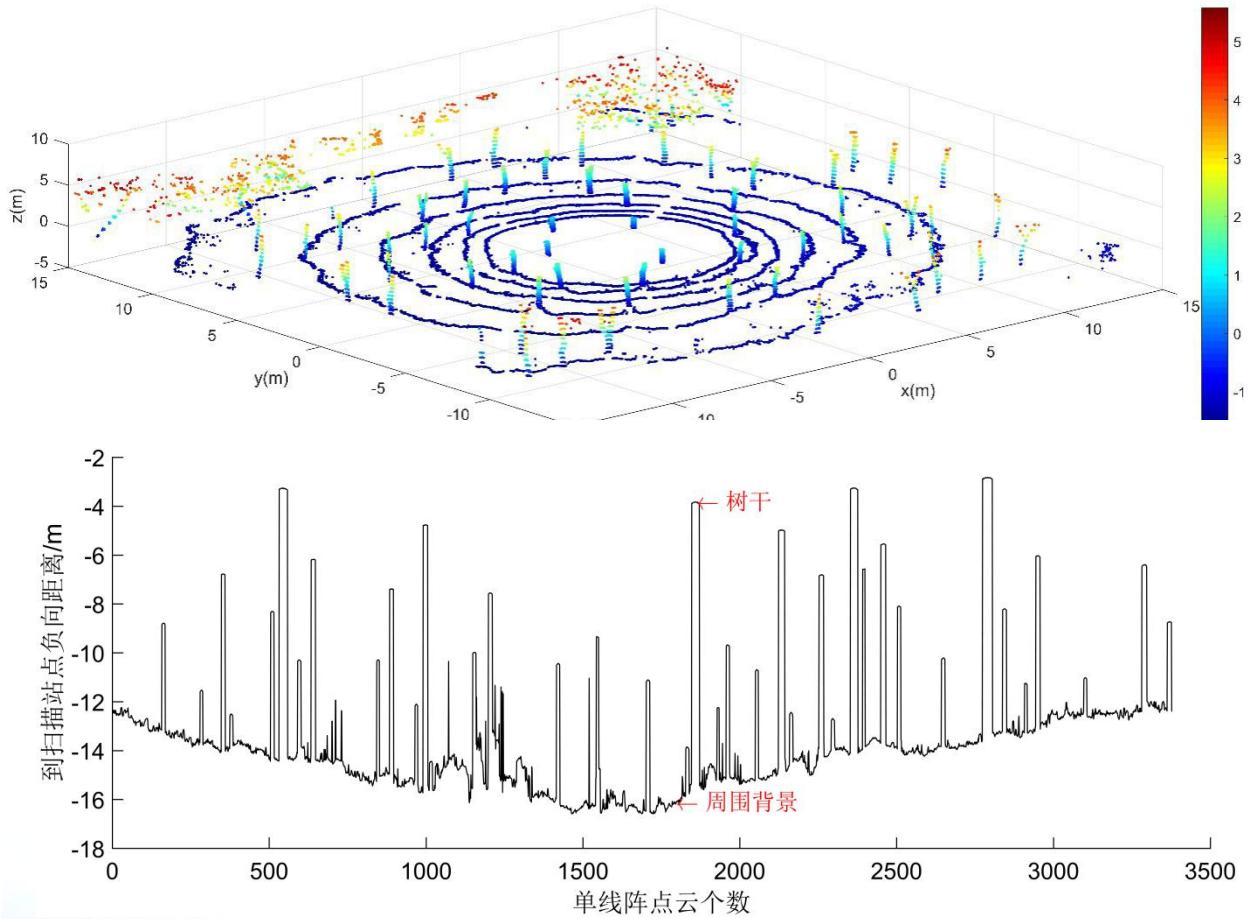
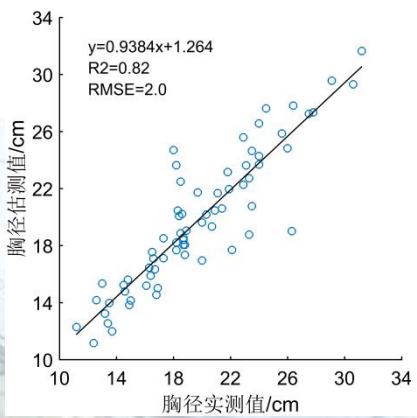
LAI-Mobile for fast LAI obvervations



Wang et al., 2018, Remote Sensing Letters

4.2 Ground observation

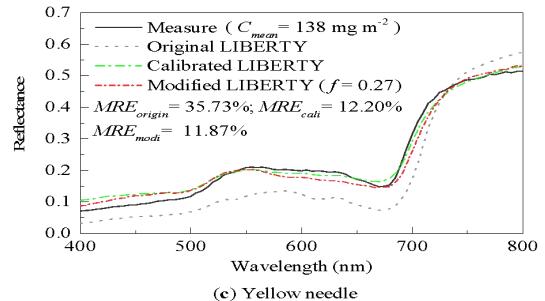
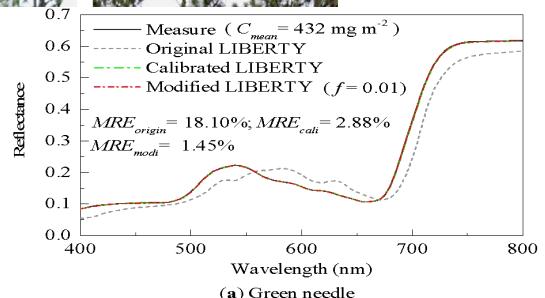
VLP-16 for forest volume estimation



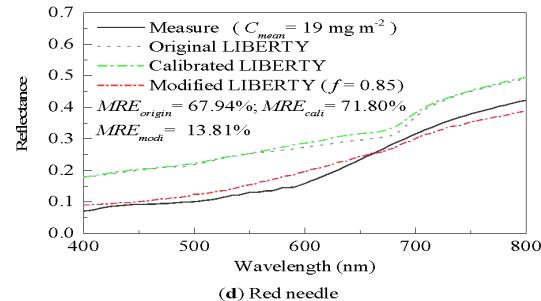
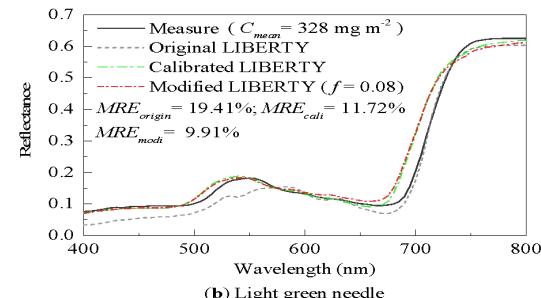
Ma et al., 2018, Journal of Beijing Forestry University

4.3 Inversion

Chl, Modifying LIBERTY model to consider pest



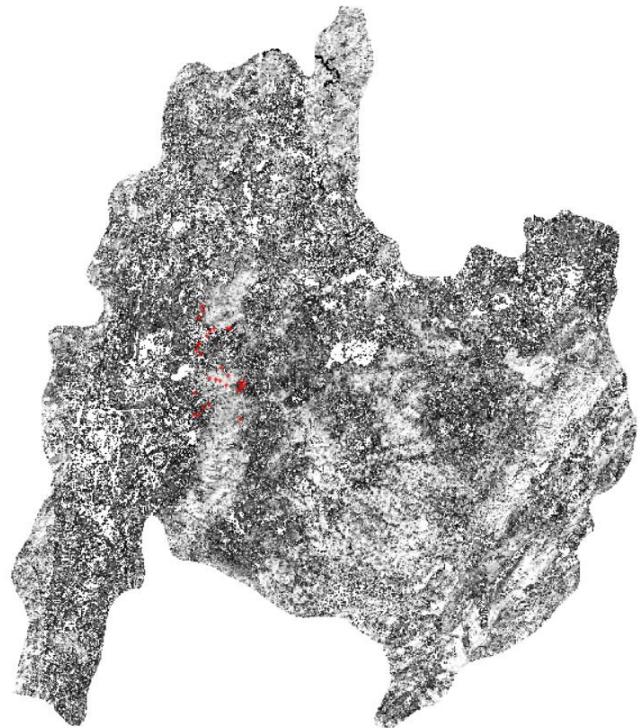
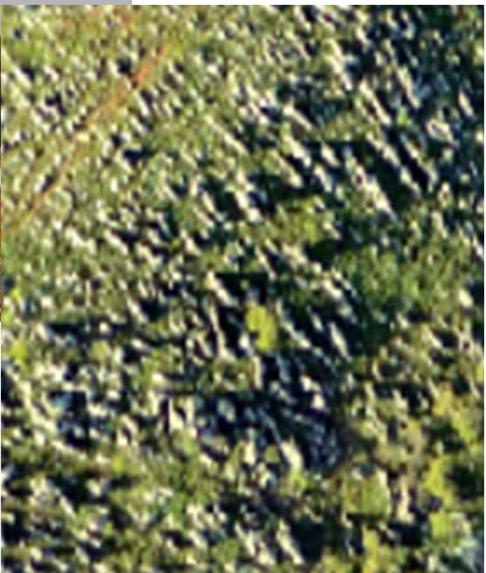
A new yellow index



(Lin et al., 2018, Remote Sensing)

4.3 Inversion

Rocky desertification using G0 idea

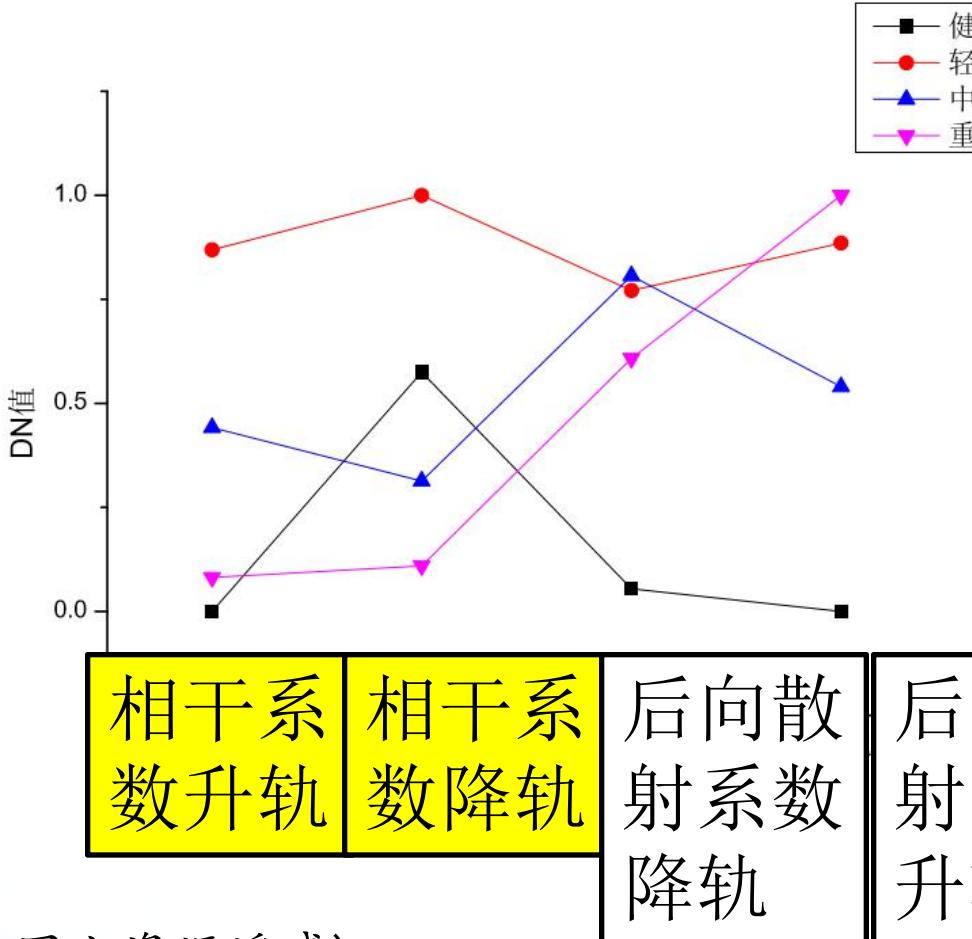
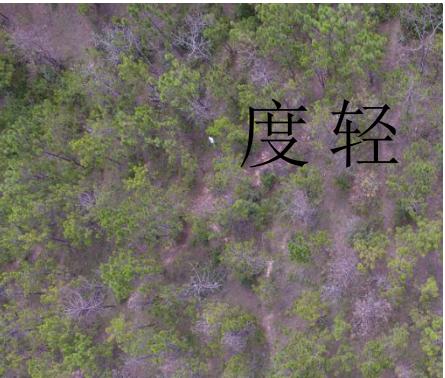


four components : rock、 veg、 soil、 shadow

(Meng, 2017, Master Thesis)

4.3 Inversion

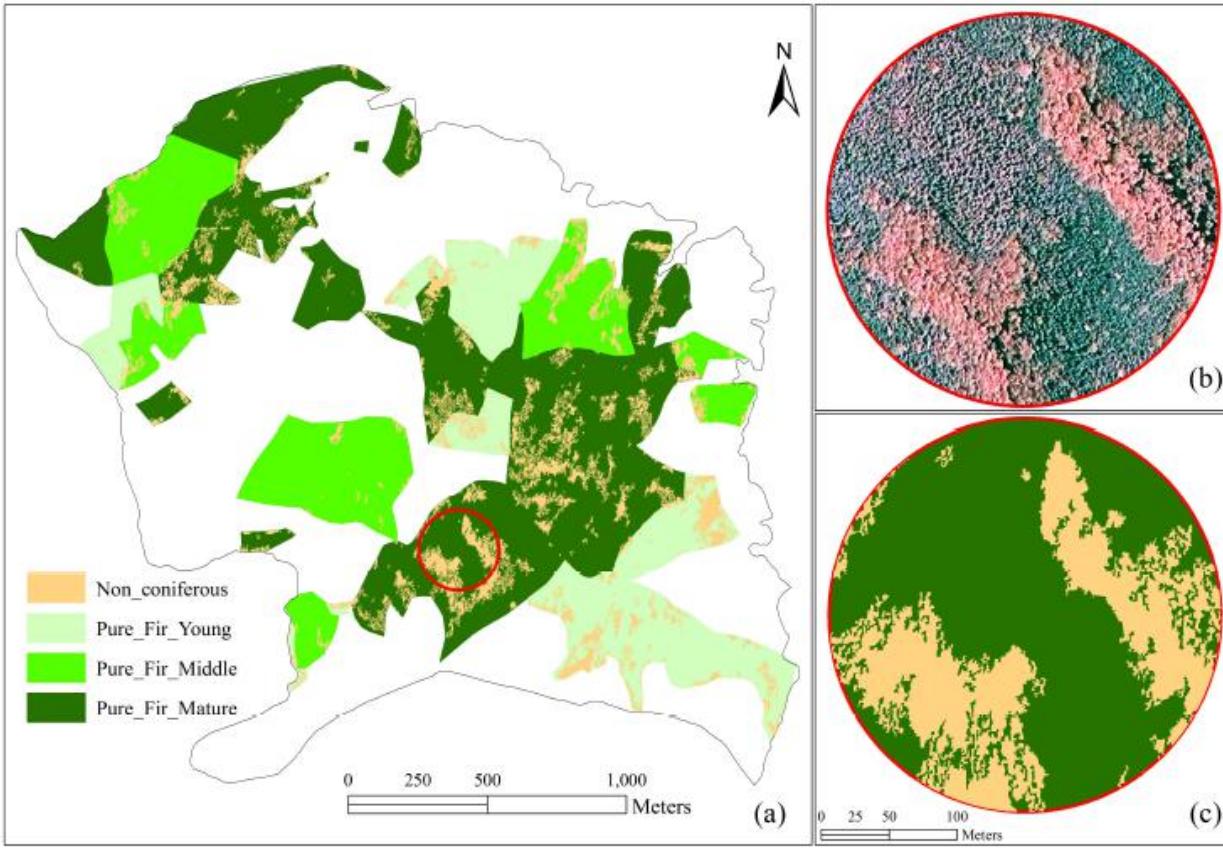
Microwave InSAR detect forest pest



(Xue et al., 2018, 国土资源遥感)

4.3 Inversion

Machine learning to classify tree species



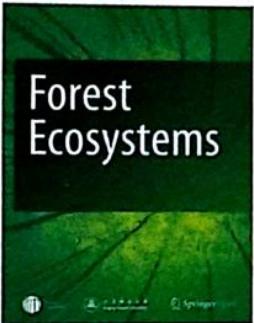
(Chen et al., accepted, IEEE-JSTARS)

5. Future

- Foundation of Smart forestry
- Big data plus QRS
- Operational use of Chinese satellites
- Data fusion of all sensors
- General cooperation

Forest Ecosystems

《森林生态系统》英文



《森林生态系统》（英文）是由教育部主管、北京林业大学主办的生态学、林学类学术期刊，主要发表森林、树木、生态、生物多样性、大数据、气候变化等方向的原创性研究和综述类论文。本刊致力于为中外学者搭建高水平的学术交流平台，提升我国在相关学科的国际影响力。

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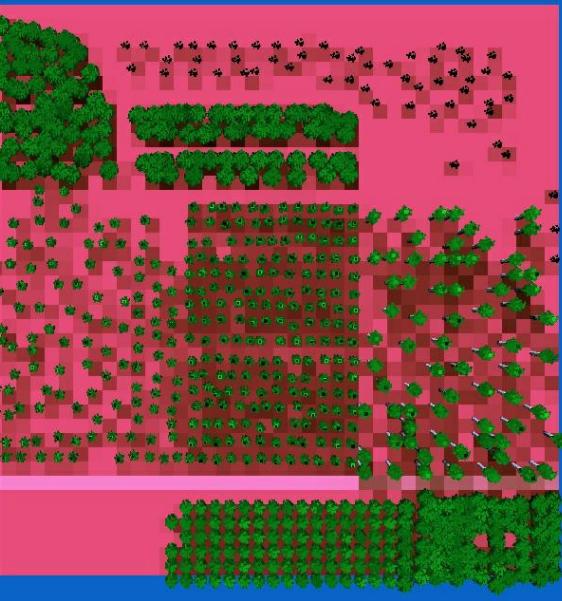
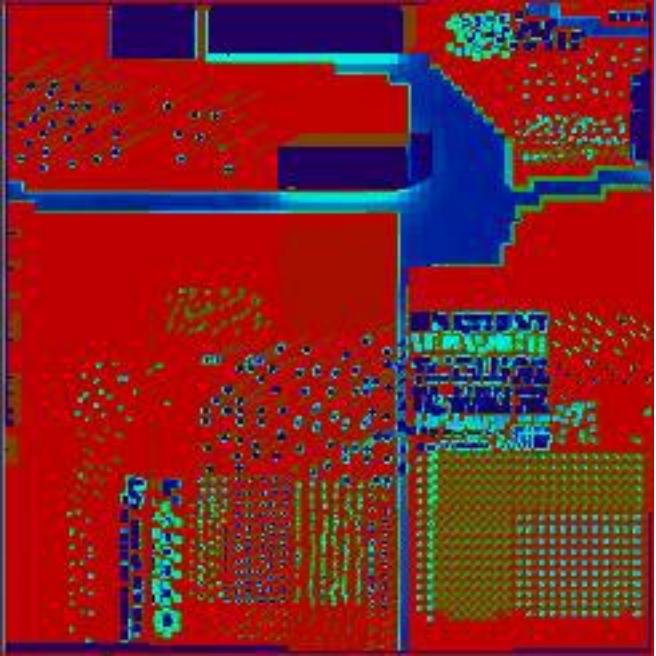
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Thanks!

My blog

<http://blog.sciencecn.com/home.php?mod=space&uid=768960>

RAPID网址: <http://www.3dforest.cn/>

