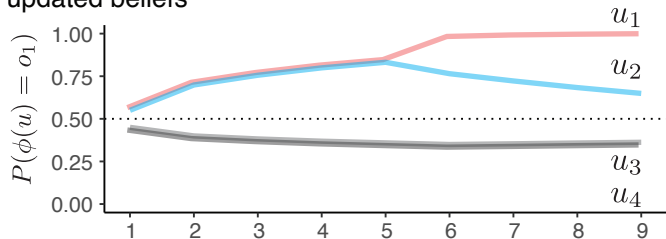


example trajectory →

target	o_1	o_1	o_1	o_1	o_1	o_1	o_1	o_1
utterance	$u_1 u_2$	$u_1 u_2$	$u_1 u_2$	$u_1 u_2$	u_1	u_1	u_1	u_1
response	o_1	o_1	o_1	o_1	o_1	o_1	o_1	o_1

updated beliefs



utterance preferences

