

Exercise 7

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(x) = \frac{1}{2} \langle Ax, x \rangle - \langle b, x \rangle = \frac{1}{2} x^T A x - b^T x$$

A is symmetric matrix of $n \times n$.

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

~~$$\nabla f(x) = \begin{pmatrix} \frac{df}{dx_1} \\ \vdots \\ \frac{df}{dx_n} \end{pmatrix}$$~~

complicated to
compute derivative of $f(x)$ herer, buddy.

0, not zero.

$$f(x+h) = f(x) + \nabla f(x)^T h + o(\|h\|)$$

$$h \in \mathbb{R}^n$$

$$f(x+h) = \frac{1}{2} (x+h)^T A (x+h) - b^T (x+h)$$

$$= \frac{1}{2} x^T A x + \frac{1}{2} h^T A x + \frac{1}{2} x^T A h + \frac{1}{2} h^T A h - b^T x - b^T h$$

$$= \underbrace{\left(\frac{1}{2} x^T A x - b^T x \right)}_{f(x)} + \underbrace{x^T A h - b^T h}_{(\underbrace{Ax-b}_{\nabla f(x)})^T h} + \underbrace{\frac{1}{2} h^T A h}_{o(\|h\|)}$$

$$\hookrightarrow \nabla f(x) = Ax - b$$

$$2) \nabla f(x+h) = \nabla f(x) + Hf h + O(\|h\|)$$

$$\nabla f(x+h) = A(x+h) - b = \underbrace{Ax - b}_{\nabla f(x)} + Ah$$

$$\text{so } Hf(x) = A$$

$$3) \text{ let } f(x) = x^T A x - b x$$

The only critical point of A is a solution of
 $\nabla f(x) = 0 = Ax - b$

$$\text{let } x_0 = A^{-1}b$$

Moreover, the $H_f(x_0)$ is SPD so x_0 is a local minimum clearly also global because $\forall x$ $H_f(x)$ is SPD.

Exercise 8

$$f: \mathbb{R}^n \rightarrow \mathbb{R}, \quad n \geq 2.$$

$$f(x_1, x_2, \dots, x_n) = \sum_{k=1}^n x_k^2 + \left(\sum_{k=1}^n x_k \right)^2 - \sum_{k=1}^n x_k.$$

1.) f is polynomial in x_1, \dots, x_n , so it is C^∞ ,
 $n \geq 2$.

$$\nabla f(x_1, \dots, x_n) = \begin{pmatrix} \frac{df}{dx_1}(x_1, \dots, x_n) \\ \vdots \\ \frac{df}{dx_n}(x_1, \dots, x_n) \end{pmatrix} = \begin{pmatrix} 2x_1 + 2\left(\sum_{k=1}^n x_k\right) - 1 \\ 2x_2 + 2\left(\sum_{k=1}^n x_k\right) - 1 \\ \vdots \\ 2x_n + 2\left(\sum_{k=1}^n x_k\right) - 1 \end{pmatrix}$$

$$H_f(x) = \left(\frac{d^2 f}{dx_i dx_j} \right) = \begin{pmatrix} 4 & 2 & \dots & 2 \\ 2 & 4 & \dots & 2 \\ \vdots & \vdots & \ddots & \vdots \\ 2 & 2 & \dots & 4 \end{pmatrix} \quad \begin{matrix} (0,0) \\ \Rightarrow 2 + 2. \end{matrix}$$

2) \bar{x} is a critical point $\nabla f(\bar{x}) = 0$

$$\Leftrightarrow \begin{cases} 2\bar{x}_1 = 1 - 2\left(\sum_{k=1}^n \bar{x}_k\right) \\ 2\bar{x}_2 = 1 - 2\left(\sum_{k=1}^n \bar{x}_k\right) \\ \vdots \\ 2\bar{x}_n = 1 - 2\left(\sum_{k=1}^n \bar{x}_k\right) \end{cases}$$

$$\text{So, } \bar{x}_1 = \bar{x}_2 = \dots = \bar{x}_n.$$

$$\text{and } 2\bar{x}_1 = 1 - 2\left(\sum_{k=1}^n \bar{x}_k\right) = 1 - 2n\bar{x}_1 = \frac{1}{2(n+1)}$$

$$2\bar{x}_2 = 1 - 2\left(\sum_{k=1}^n \bar{x}_k\right) = 1 - 2n\bar{x}_2 = \frac{1}{2(n+1)}$$

$$\bar{x}_n = \frac{1}{2(n+1)}$$

$$\text{So, the critical point is } x = \frac{1}{2(n+1)} \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$

Ex. 8

3) a) Let, $I = Id$, and $J = \begin{pmatrix} 1 & -2 \\ 1 & 1 \\ 2 & -1 \end{pmatrix}$

So, $2(I_n + J_n) = 2 \begin{pmatrix} 2 & 1 & -2 \\ 1 & 2 & 1 \\ (2) & 1 & 1 \end{pmatrix} = \begin{pmatrix} 4 & 2 & -2 \\ 2 & 2 & 1 \\ 1 & 2 & 4 \end{pmatrix} = H_A(x)$

b) $J_n = \begin{pmatrix} 1 & -1 \\ 1 & (2) & 1 \\ 2 & -1 \end{pmatrix}$

$\text{Im}(J_n) = \text{span} \left(\begin{pmatrix} 1 \\ \vdots \\ 2 \end{pmatrix} \right)$ so $\text{rk}(J_n) = 1$.

With rank theorem. $\dim(\ker(J_n)) = n - \text{rk}(J_n)$
 $= n - 1 \geq 1$

So, $\ker(J_n)$ is non-empty so there exists $x \neq 0$ such that $J_n x = 0$ which means the 0 is eigenvalue of J_n .

$(J_n x = \lambda x)$

c) $J_n \begin{pmatrix} 1 \\ \vdots \\ 2 \end{pmatrix} = \begin{pmatrix} n \\ \vdots \\ n \end{pmatrix} = n \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$ so n is also eigenvalue of J_n .

- $E_n(J_n)$ eigenspace of eigenvalue n .

- $E_0(J_n)$ eigenspace of eigenvalue 0 .

then, $\dim E_n \geq 1$ and $\dim(E_n) + \dim(E_0) \leq n$.

So $\dim(E_n) = 1$.

As a consequence, the only eigenvalues of J_n are 0 and n .

$$d) H_f(\bar{x}) = \begin{pmatrix} 4 & 2 & -2 \\ 2 & 2 & 1 \\ 1 & 2 & 2 \\ 2 & -2 & 4 \end{pmatrix} = 2(I_n + J_n)$$

so the eigenvalues of $H_f(\bar{x})$ are 2 and $2(n+1)$.

So, $H_f(x)$ is symmetric positive-definite so \bar{x} is a local minimum.

Moreover, as $H_f(x)$ is always SDP, it means that f is strictly convex as \bar{x} is indeed a global minimum.