



## ALGORITHMIQUE NUMÉRIQUE - ANUM

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### Additional Notes



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\*This note only contains additional information to lecture slides. This note may be useful only if use with lecture slides.

# Contents

I. Possibly useful study materials	3
II. Lecture 1: Introduction to MATLAB and to floating-point arithmetic	3
III. Lecture 2: Matrix computation	4

## I. Possibly useful study materials

1. Scientific Computing, An Introductory Survey, Michael T. Heath, McGraw-Hill, 2002  
[Available online](#) (I also have an pdf copy)
2. A First Course in Numerical Methods, Uri M. Ascher, Chen Greif, SIAM, 2011: should be available at the library on campus
3. Introduction to Scientific Computing and Data Analysis, Mark H. Holmes, Springer, 2016: should be available at the library on campus

## II. Lecture 1: Introduction to MATLAB and to floating-point arithmetic

### Rounding

- *Machine numbers*: Real numbers that are exactly representable in a given floating-number system.
- In other cases, it is approximated by a "nearby" floating-point number. This approximation is called *rounding* and the error caused by this approximation is called *rounding error*.
- The most accurate rounding method is *rounding to nearest* but it is more expensive to implement. It is also a default set by IEEE.

### Cancellation\*

- An source of rounding error that occurs with subtraction.
- It occurs when subtracting two nearby numbers. the most significant digits in operand matches and cancel each other
- Suppose  $a$  and  $b$  already contain some rounding error, perform subtraction on these number leads to large error. Example : consider three floating-number  $a = 1.22, b = 3.34, c = 2.27$  and perform  $b^2 - 4ac$ . The exact result of this is 0.0292, however, with rounding:  $b^2 = 11.1556$  round to 11.2 and  $4ac = 11.0776$  round to 11.1, then result of subtraction is 0.1. \*note that this is just a example and result might differ in different settings.

### Absorption

- with floating-point we lose some algebraic property of real number. For instance, we might face the situation where:

$$(a + b) + c \neq a + (b + c)$$

### III. Lecture 2: Matrix computation

- Transpose:  $a_{ij} \rightarrow a_{ji}^T$
- SVD can solve most of problems but it is quite expensive. It referred as Swiss knife
- Between dense and sparse, there is no specified boundry.

Algebraic properties of SVD:

- SVD can be rewritten as follow by writing  $V = [v_1, v_2, \dots, v_n]^T$ , and:  $U = [u_1, u_2, \dots, u_n]^T$ :

$$A = U\Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

Perron-Frobenius theorem:

(1) If  $A \in \mathbb{R}^{n \times n}$  is nonnegative then

- $\rho(A)$  is an eigenvalue of  $A$ .
- there is a nonnegative eigenvector  $x$  such that  $Ax = \rho(A)x$ .

(2) If  $A \in \mathbb{R}^{n \times n}$  is nonnegative and irreducible then

- $\rho(A)$  is an eigenvalue of  $A$ .
- $\rho(A) > 0$
- there is a nonnegative eigenvector  $x$  such that  $Ax = \rho(A)x$ .
- $\rho(A)$  is a simple eigenvalue.

(3) If  $A \in \mathbb{R}^{n \times n}$  is positive then (2) holds and, in addition,  $|\lambda| < \rho(A)$  for any eigenvalue  $\lambda$  with  $\lambda \neq \rho(A)$ .

Stochastic matrix:

A matrix  $P \in \mathbb{R}^{n \times m}$  said to be stochastic if:

$P \geq 0$  and,

$$\sum_{j=1}^n P_{ij} = 1 \quad \text{all } i = 1, 2, \dots, n$$