



Cloud Computing NETW1009

Lecture 5

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Recall what we discussed so far..

- Cloud Computing
- Cloud Data Centers
- Compute, Storage, Network Systems
- Virtualization
- Systems Virtualization
- Resource Pooling and Provisioning
- Software Defined Infrastructure
- Infrastructure Deployment Models



Lecture 5: ISS - Intelligent Storage Systems

Lecture Outline

- Intelligent Storage Systems
- Intelligent Storage Systems Components
- Hard Disk Drives (HDD)
- Solid State Drives (SSD)
- Types of Intelligent Storage Systems
- Challenges

Intelligent Storage Systems

Intelligent Storage System

A feature-rich RAID (Redundant Array of Independent Disks) array that provides highly optimized I/O processing capabilities

ISS Features

Supports combination of HDD & SSD

Service massive amounts of IOPS

Scale-out Architecture

Deduplication, Compression, and encryption

Automated Storage tiering

Virtual Storage provisioning

Multi-tenancy

Supports APIs to integrate with SDDC & Cloud

Data Protection

Intelligent Storage Systems Components

Controller

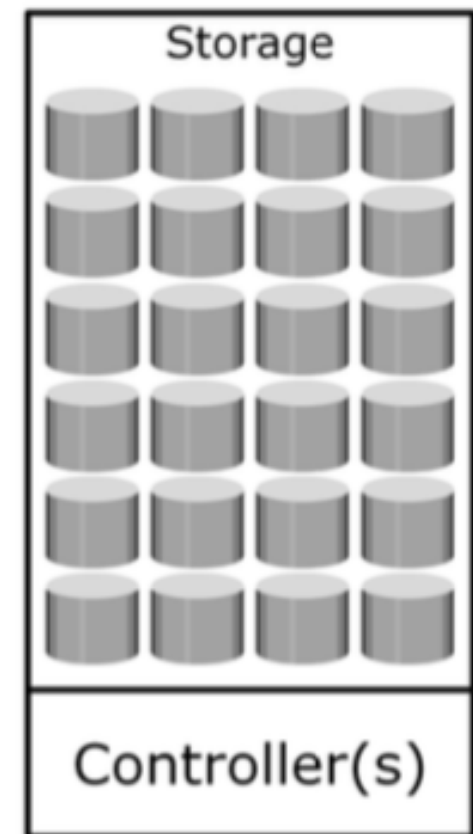
Controls I/O request for reading/writing/data, Could be one of these types:

- Block-based
- File-based
- Object-based
- Unified

Storage

Disks where data is stored, could be one of these types:

- All HDDs
- All SSDs
- Combination of both



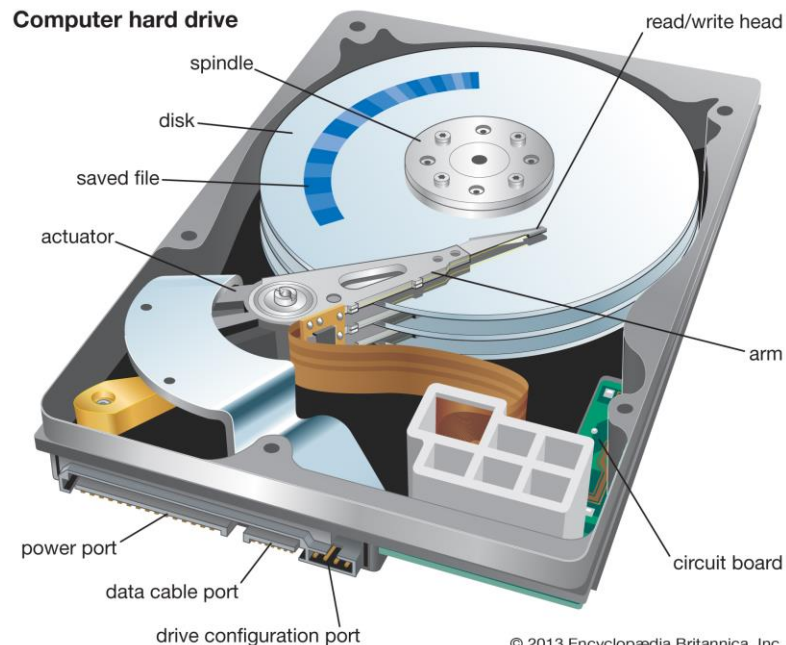


Components of Intelligent Storage Systems I : Hard Disk Drives

Storage – Hard Disk Drives

Hard Disk Drives

A hard disk drive is a persistent storage device that stores and retrieves data using rapidly rotating disks (platters) coated with magnetic material



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HDD - Components

Platter

- Flat circular disks on which data is recorded in 0s & 1s by polarizing magnetic domains of the disk surface
- A typical HDD consists of one or more platters
- A set of rotating platters is sealed in a case called Head Disk Assembly (HDA)

Spindle

- Connects all platters and is connected to a motor rotating at a constant speed

Read/Write Head

- Reads/writes data from/to the platters by sensing/changing their magnetic polarization
- Drivers have two R/W heads per platter, one for each surface

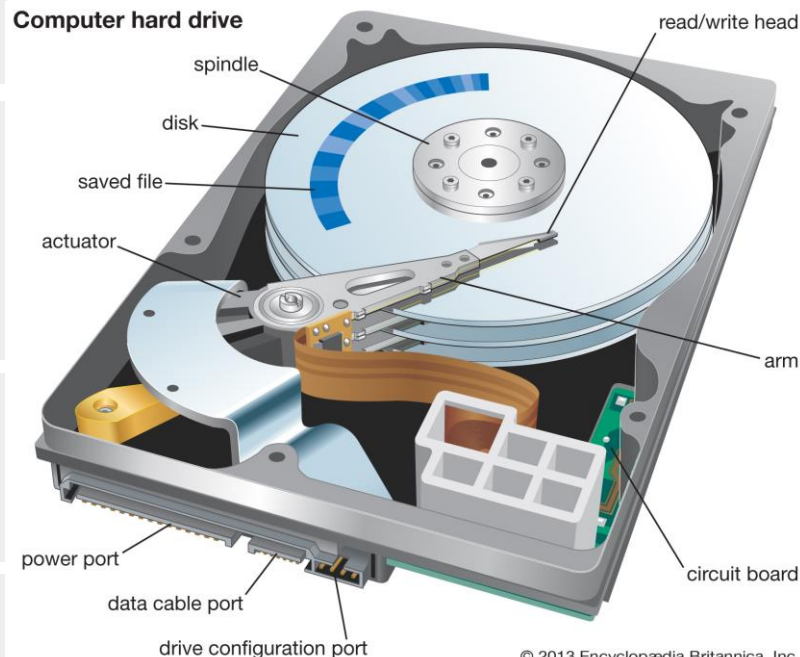
Actuator Arm Assembly

- R/W heads are mounted on the AAA
- It positions R/W head at the location on the platter where data needs to be read/written

Drive Controller Board

- A printed circuit board mounted at the bottom of a disk drive
- Consists of a microprocessor, internal memory, circuitry & firmware

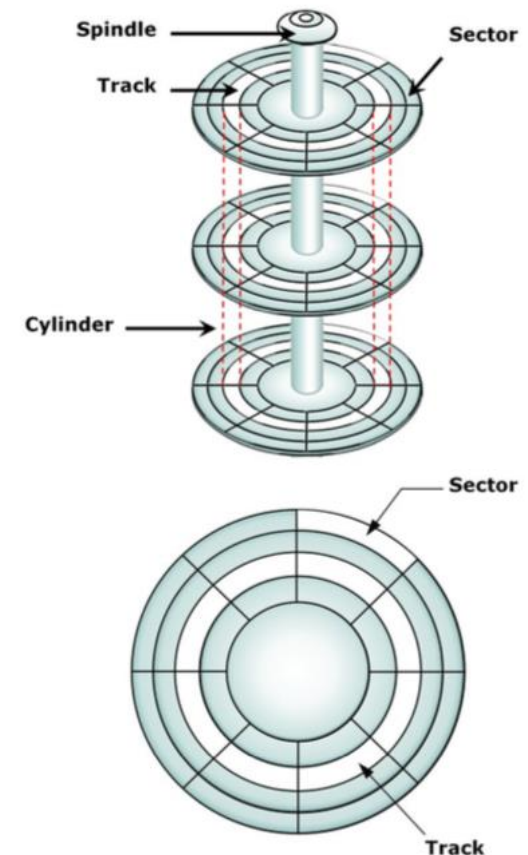
Computer hard drive



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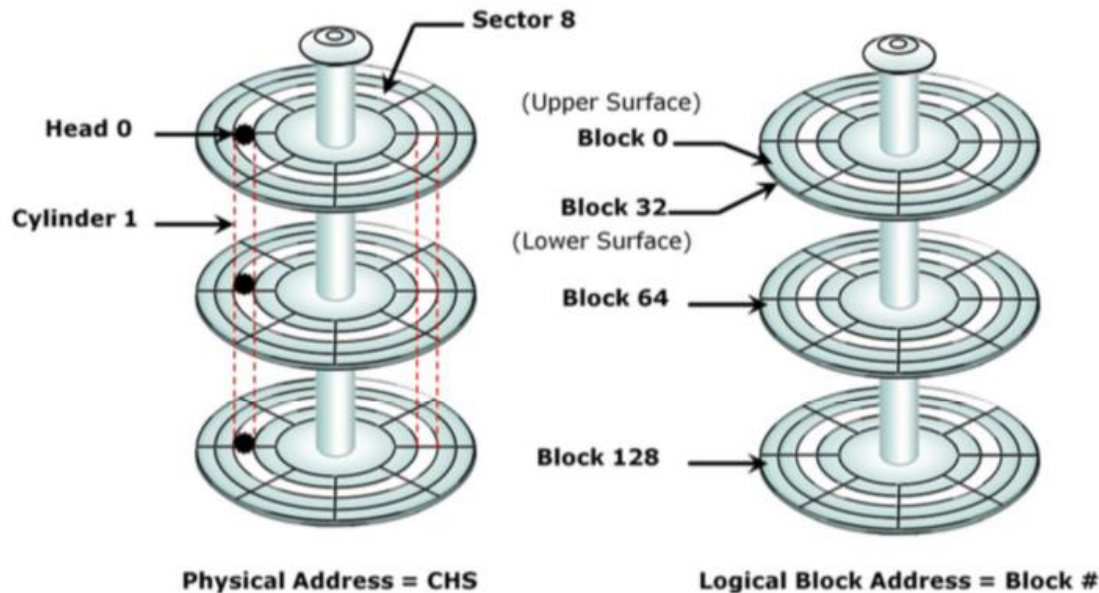
HDD – Physical Disk Structure

Tracks	<ul style="list-style-type: none">• Concentric rings on the platter around the spindle• Numbered from zero from the outer platter edge
Sectors	<ul style="list-style-type: none">• Each track is divided into smaller units called sectors• Sector is the smallest individually addressable unit of storage• Number of sectors per track varies by drive type• Typically a sector holds 512 bytes of data
Cylinder	<ul style="list-style-type: none">• Is a set of identical tracks on both surfaces of each platter



Platter

HDD – Logical Block Addressing



In this example:

- 8 sectors per track
- 6 heads
- 4 cylinders
- Total of $8 \times 6 \times 4 = 192$ blocks ranging from Block 0 to Block 191

- Physical Addresses are defined as (CHS): Cylinder, Head & Sector number
- Logical Block Addresses (LBA) has a linear addressing scheme by block number
- Disk Controller translates LBA to CHS

HDD – Performance

Factors affecting performance of a HDD:

1. Electromechanical device

Impacts the overall performance of the storage system

2. Disk Service Time

Time taken by a disk to complete an I/O request, depend on:

- Seek Time
- Rotational Latency
- Data Transfer Rate

Disk Service Time = Seek Time + Rotational Latency + Data Transfer Rate

HDD – Performance

Seek Time

Seek Time

Is the time taken to position the read/write heads across the platter moving along the radius of the platter, thus settling over the correct track

- The lower the seek time, the faster the I/O operation
- Seek time of a disk is specified by its manufacturer in ms
- Seek time specifications include:

Full Stroke

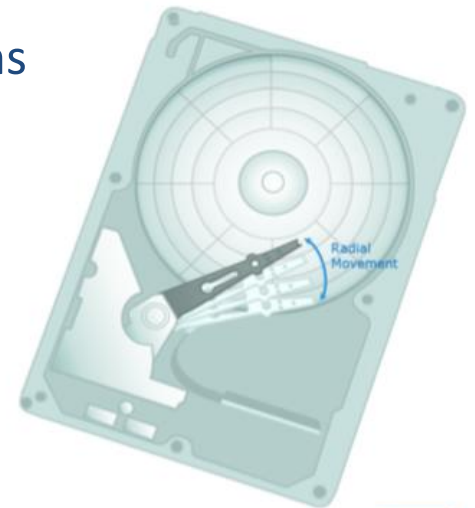
It is the time taken by the R/W head to move across the entire width of the disk, from innermost to outermost track

Average

It is the average time taken by the R/W head to move from one random track to another, normally listed as 1/3 full stroke

Track-to-track

It is the time taken by the R/W head to move between adjacent tracks



HDD – Performance

Rotational Latency

Rotational Latency

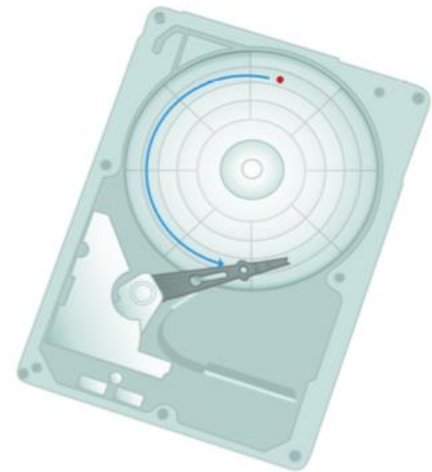
Is the time taken by the platter to rotate and position the data under the R/W head

- Depends on the rotation speed of the spindle
- Measured as one half of the time taken for a full rotation

Example:

- For 'X' rpm, drive latency is calculate in milliseconds as:

$$= \frac{\frac{1}{2} * 1000}{\frac{x}{60}} = \frac{500}{\frac{x}{60}} = \frac{30000}{x}$$

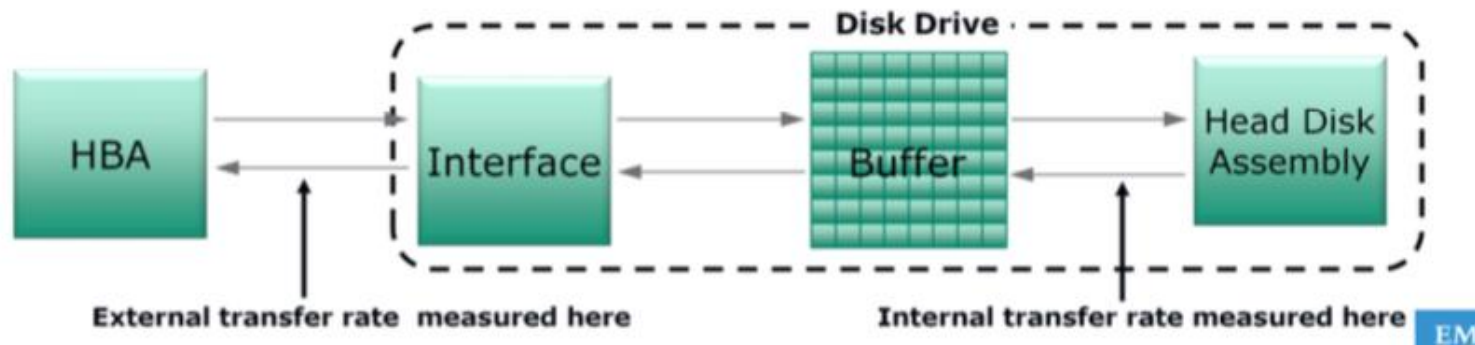


HDD – Performance

Data Transfer Rate

Data Transfer Rate

The average amount of data per unit time that the drive can deliver to the Host Bus Adapter (HBA)



- Internal Transfer Rate: Speed at which data moves from a platter's surface to the internal buffer of the disk
- External Transfer Rate: Rate at which data move through the interface to the HBA

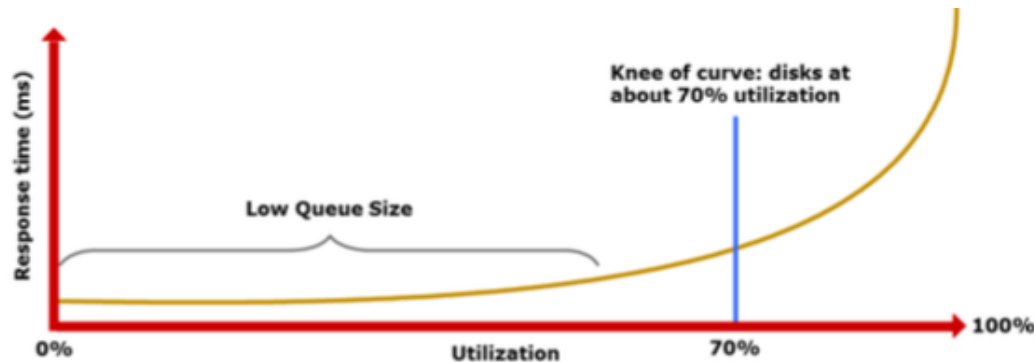
HDD – Performance

Utilization vs. Response Time

- Based on fundamental laws of disk drive performance:

$$\text{Average Response Time} = \frac{\text{Service Time}}{1 - \text{Utilization}}$$

- Service time is taken by the controller to serve an I/O
- For performance-sensitive applications disks are commonly utilized below **70%** of their I/O serving capability



HDD – Performance

Storage Design: Application Requirements vs. Disk Drive Performance

- Disks required to meet an application's capacity need (**DC**):

$$DC = \frac{\text{Total capacity required}}{\text{Capacity of a single disk}}$$

- Disks required to meet an application's performance need (**DP**):

$$DP = \frac{\text{IOPS generated by an application at peak workload}}{\text{IOPS serviced by a single disk}}$$

- IOPS serviced by a disk (*S*) depends upon Disk Service Time (T_s):

$$T_s = \text{Seek time} + \frac{0.5}{(\text{Disk rpm}/60)} + \frac{\text{Data Block Size}}{\text{Data Transfer Rate}}$$

- T_s is the time taken for an I/O to complete, therefore IOPS serviced by a disk (*S*) is equal to $(1/T_s)$
 - For performance sensitive applications $S = 0.7 * \frac{1}{T_s}$

$$\text{Disks Required for an Application} = \max(DC, DP)$$



Components of Intelligent Storage Systems II : Solid State Drives

Storage – Solid State Drives

Solid State Drives

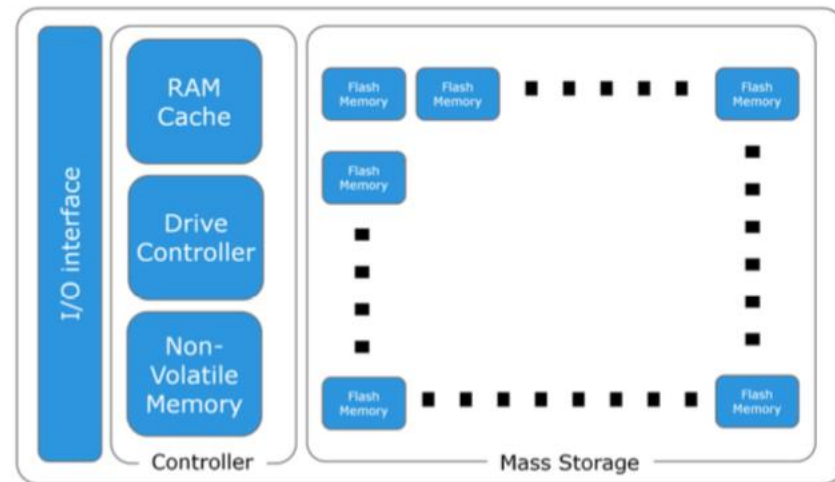
A solid state drive is a storage device that uses integrated circuit assemblies & semiconductor technology to store data persistently, typically using flash memory.

- SSD are superior to mechanical hard disk drives in terms of performance, power use, and availability
- Especially well suited for low-latency applications requiring consistent, low (less than 1 ms) read/write response times.

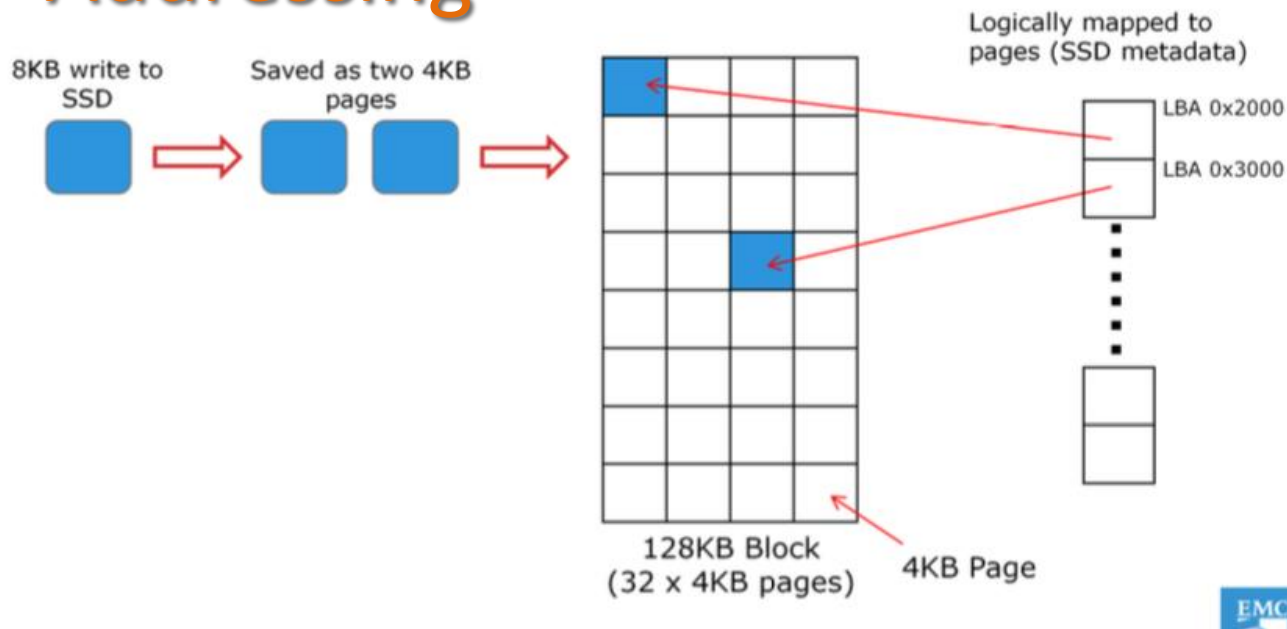


SSD - Components

I/O Interface	<ul style="list-style-type: none">• Enables connecting power and data connections to SSD Drive
RAM Cache	<ul style="list-style-type: none">• Used in the management of data being read & written from the SSD as a cache• Used for SSD's operational programs & mapping tables• Enhances the overall performance of the SSD
Drive Controller	<ul style="list-style-type: none">• Manages all drive functions, e.g. (encryption/decryption, write coalescing)
Non-Volatile Memory	<ul style="list-style-type: none">• Stores The SSD's operational software & data• Not all SSD models have it, some store their programs and data to the driver's mass storage
Flash Memory	<ul style="list-style-type: none">• Number and capacity of flash memory chips vary directly with the SSD's capacity• Consume less power than HDDs• Require much less cooling as they don't have moving parts as HDDs• Have multiple parallel I/O channels to the controller, thus higher internal bandwidth

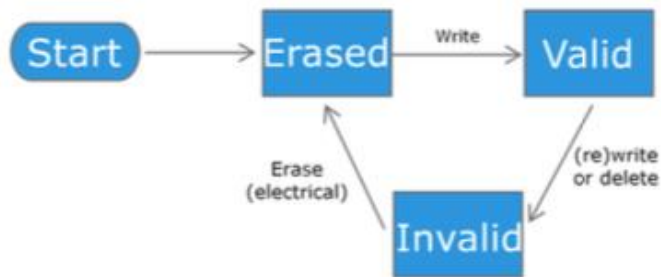


SSD –Addressing

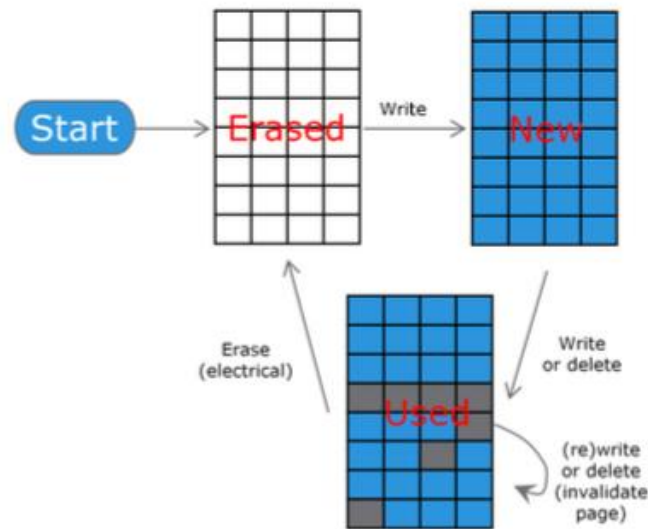


- A Page is the smallest object that can be read/written on a solid state drive
- Page's capacity is not standard like sectors in HDD, they depend on architecture of the solid state memory chip. Typical page capacities are 4 KB, 8 KB and 16 KB
- A block is made up of pages, and only entire blocks can be written/erased. Pages are assembled into full blocks in the cache RAM then written to the block storage object

SSD – Page & Block States



Flash memory page states



Block state diagram

SSD – Performance

1. Access Type

- SSD performs random reads the best
- SSDs use all internal I/O channels in parallel for multi-threaded large block I/Os

2. Drive State

- New SSD or SSD with substantial unused capacity offers best performance

3. Workload Duration

- SSDs are best for workloads with short bursts of activity

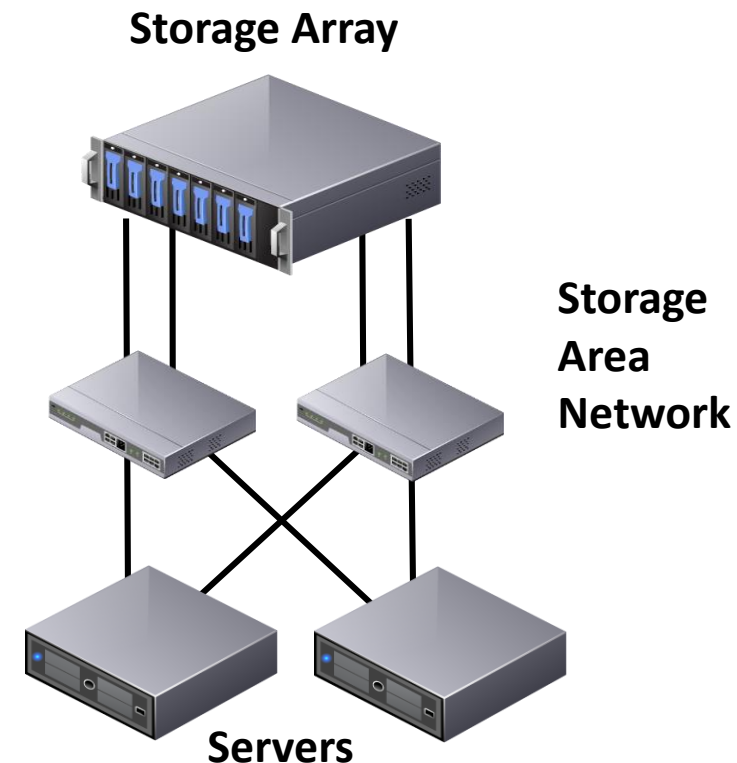
HDD vs. SSD - A detailed view



Intelligent Storage Systems

Storage Hardware: Challenges

- Configuring very large amounts of storage to a server is complex, large number of drives may be required
- Having many drives leads to an increased risk of drive failures
- RAID provides a way to aggregate and manage multiple drives
- SAN & NAS RAID arrays provide network based, high capacity storage solutions and deliver incredibly high performance



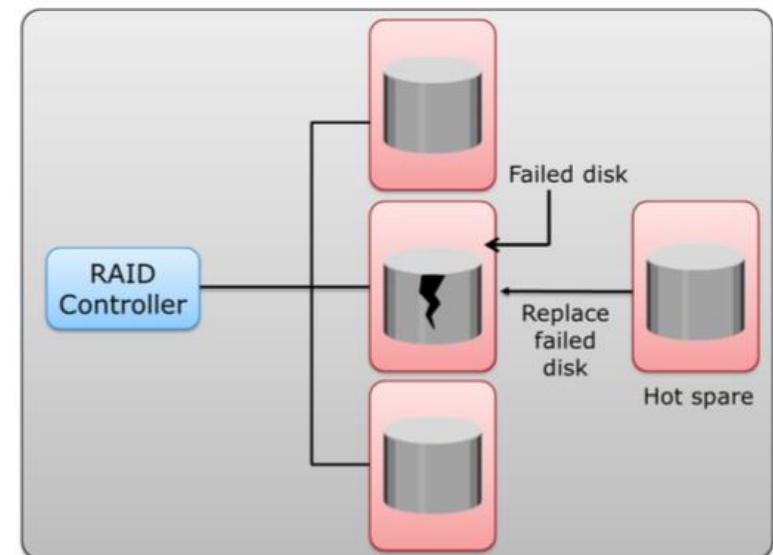
Storage Hardware: Challenges

Dynamic Disk Sparing (Hot Sparing)

Hot Sparing

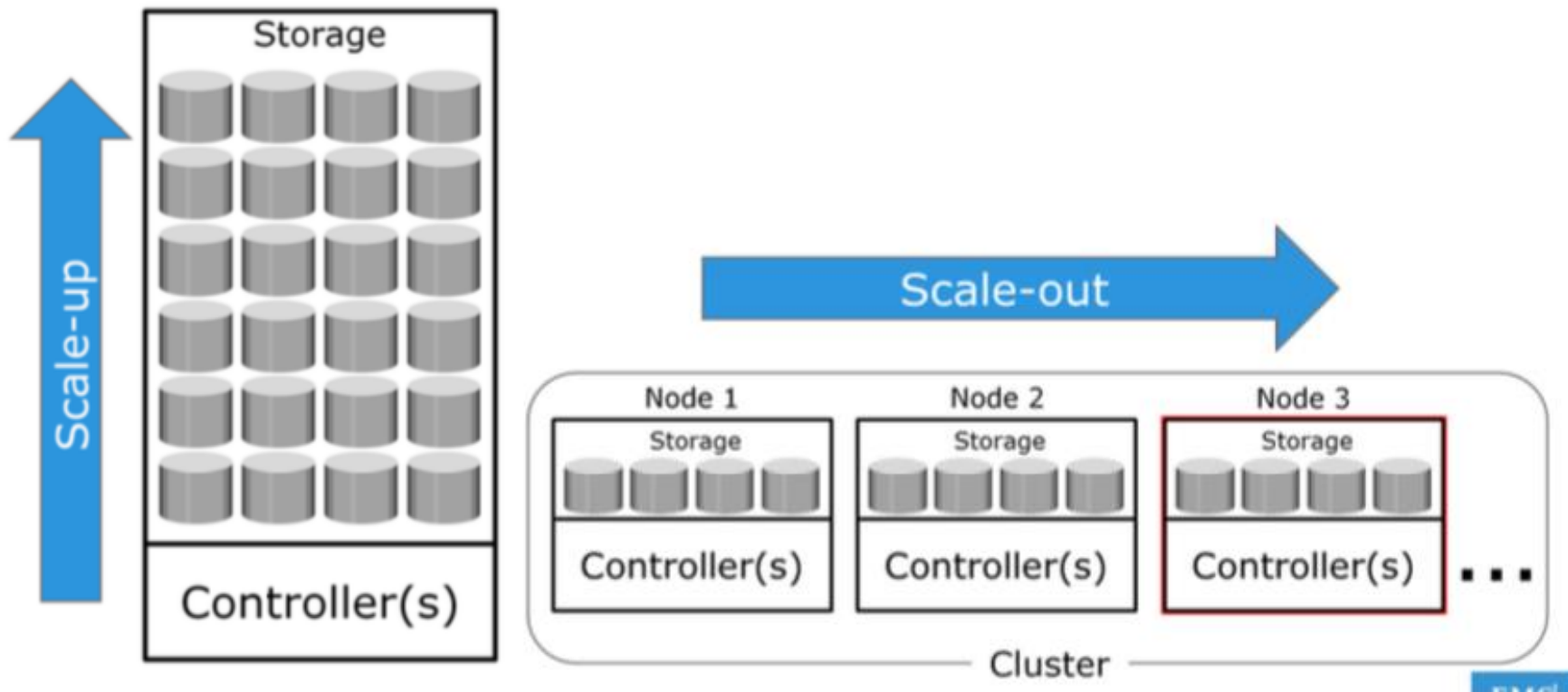
Refers to the process that temporarily replaces a failed disk drive with a spare drive in a RAID array by taking the identity of the failed disk drive.

- After the dynamic disk sparing process; when a new disk is added to the system, data from the hot spare is copied to it
- Hot spare then returns to its idle state, ready to replace the next failed drive
- Some systems implement multiple hot spares to improve data availability



ISS Architectures

Scale-up vs. Scale-out



ISS Architectures

Scale-up vs. Scale-out

Scale-up Architecture

- Involves upgrading or adding controllers & storage
- Provides the capability to scale the capacity and performance of a single storage system
- Has a fixed capacity ceiling and limited scalability
- Performance starts degrading when reaching the capacity limit

Scale-out Architecture

- Involves upgrading and adding controllers & storage
- Provides the capability to maximize the capacity by adding nodes without causing any downtimes
- Pools the resources in the cluster and distributes the workload across all nodes
- Performance improves linearly as more nodes are added to the system

References

- “Cloud Infrastructures and Services - CIS” Course by Dell Technologies
- “Information Storage and Management – ISM” Course by Dell Technologies
- “IT Solutions for Digital Businesses - Virtualization and the Journey to the Modern Digital Workspace” Course by VMware

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