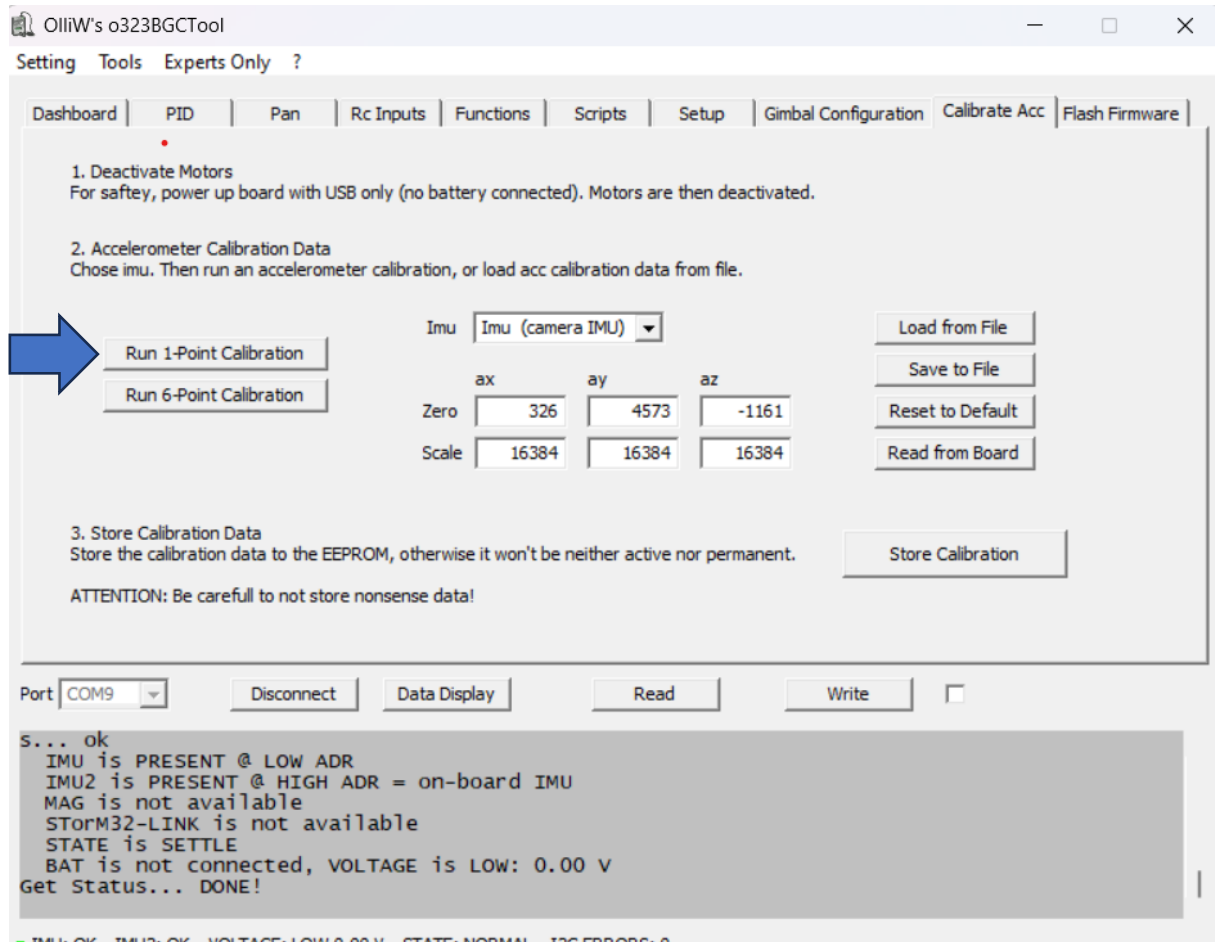


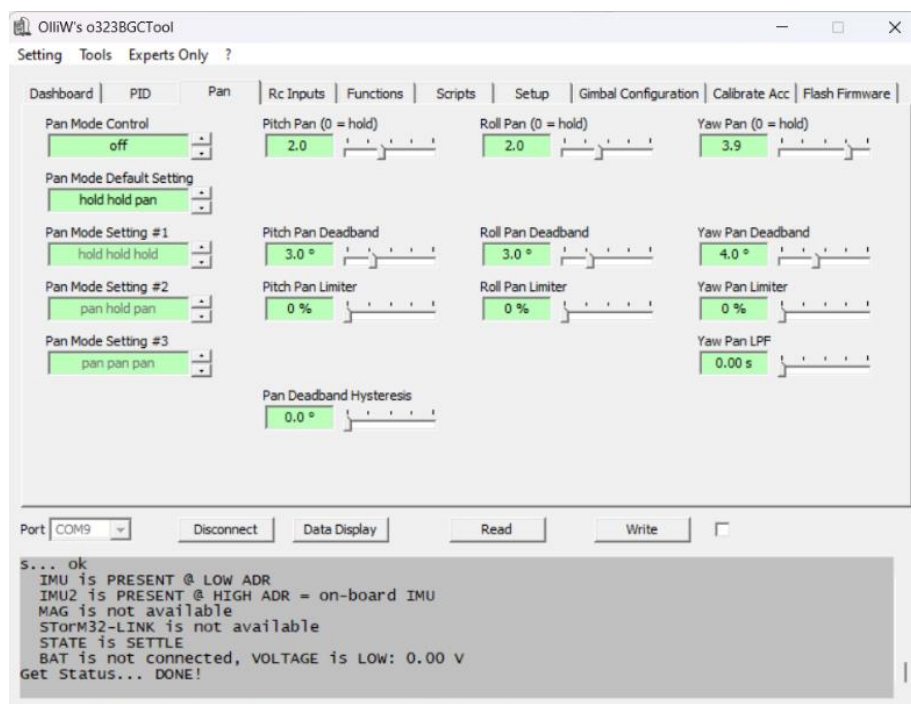
Calibration and Configuration on GUI

1-) Calibration of accelerometer :

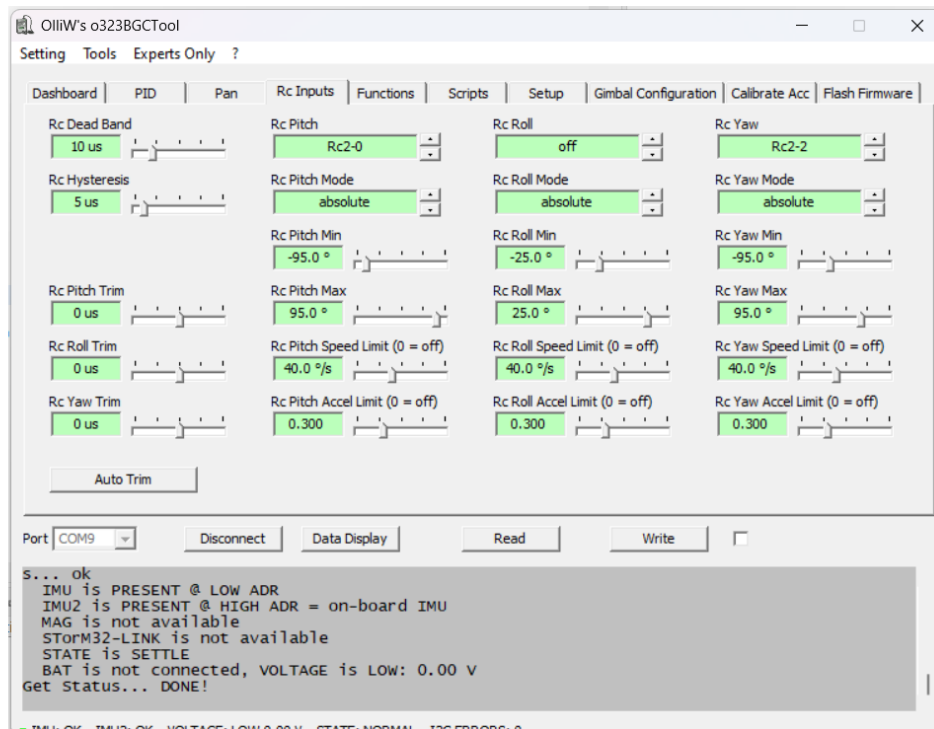
Before this step, gimbal must be connected to computer.



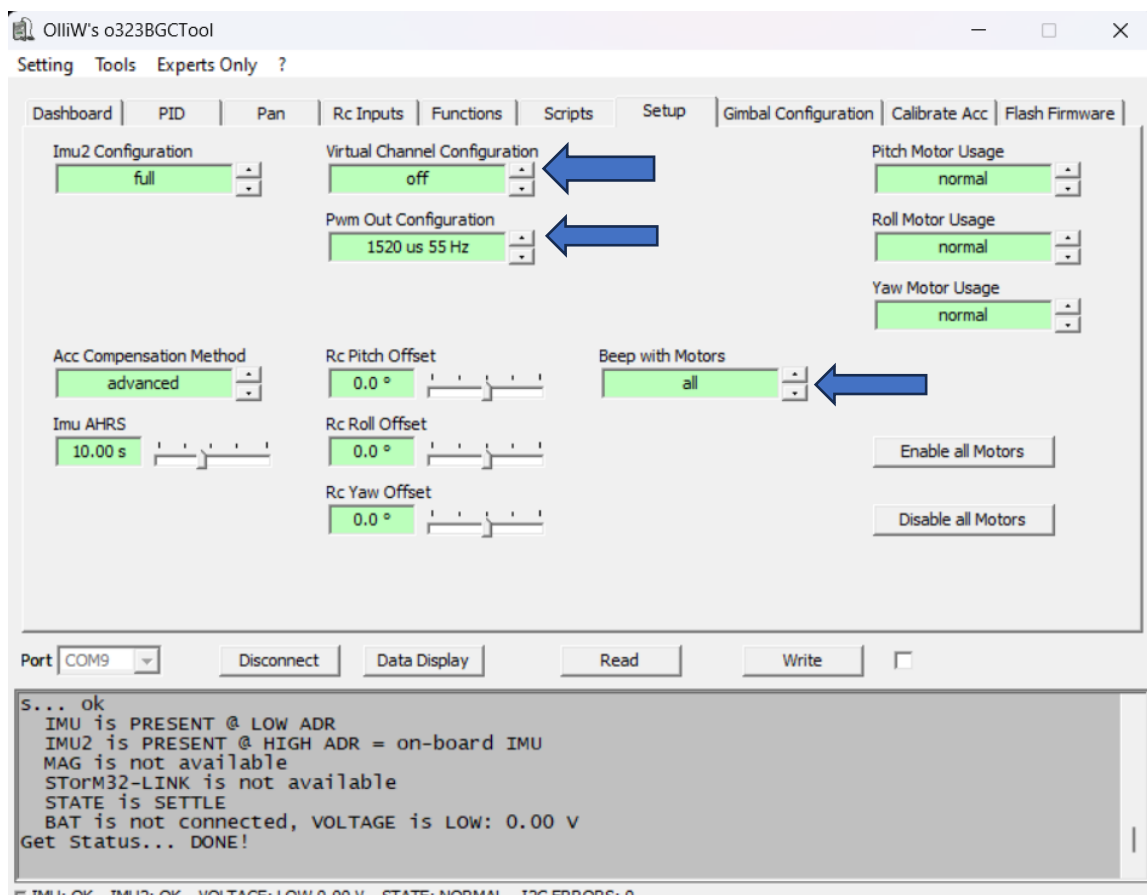
2-) RC Inputs and Hold-Pan Settings :



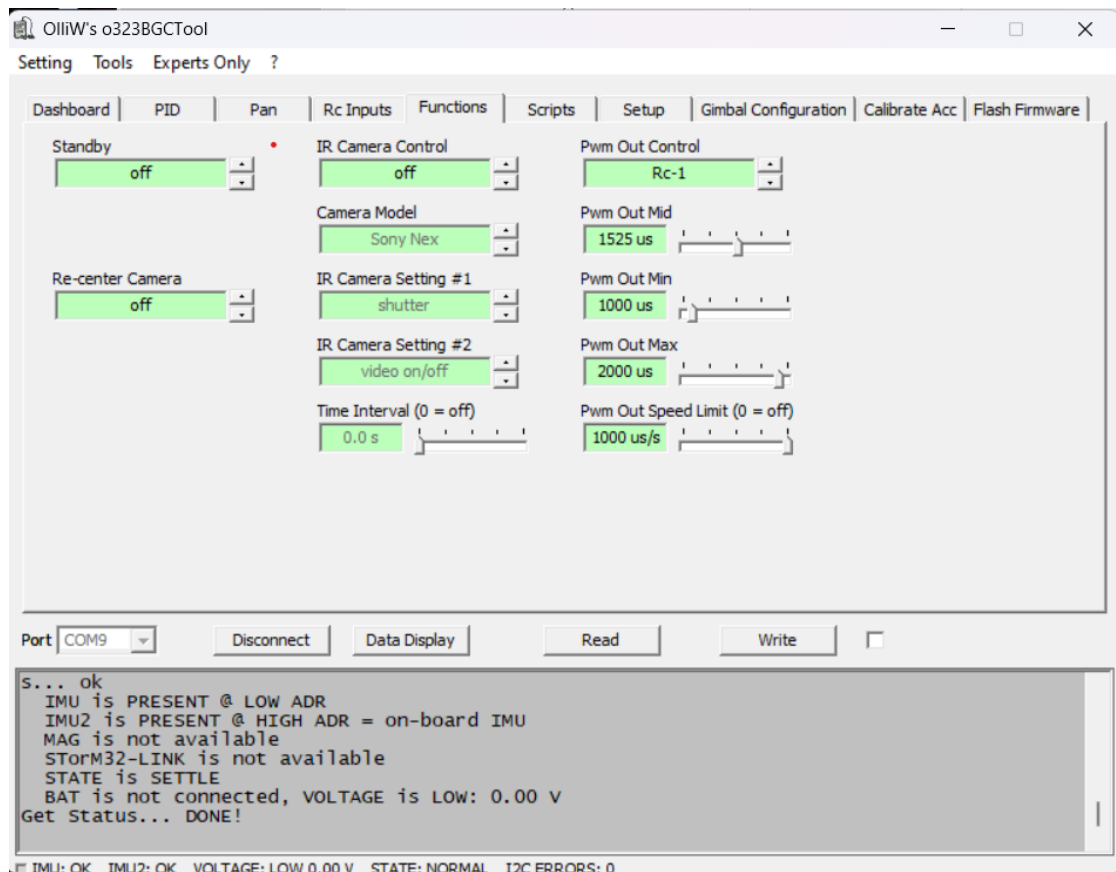
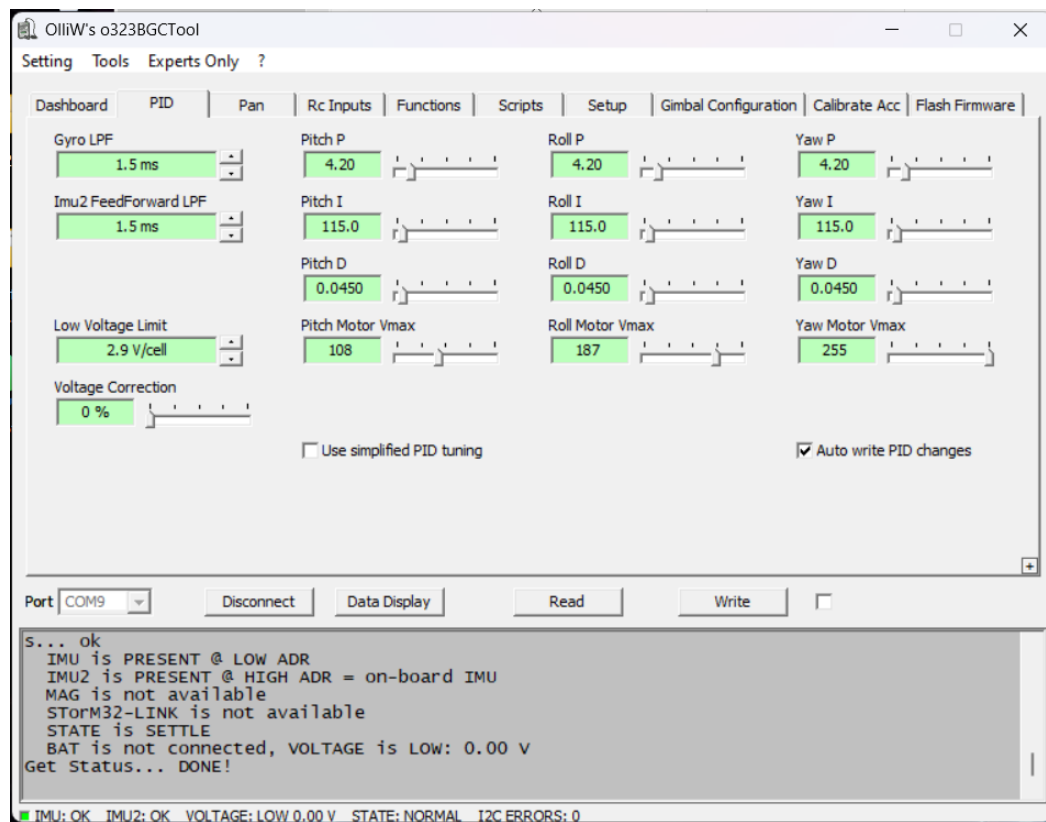
*** We adjust only 2 axis to configure and use, RC2-0 and RC2-2 :



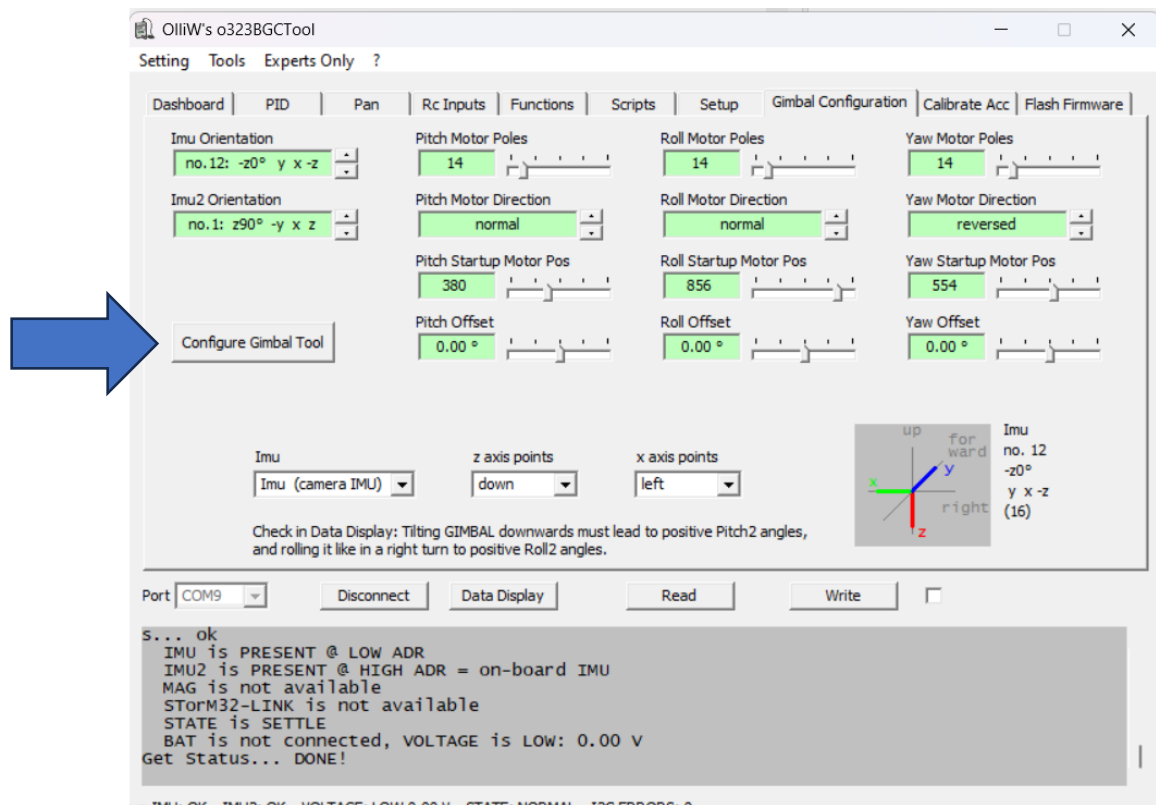
3- "Virtual Channel Configuration" have to be maintained as off to control motors by PWM .



4- PID and Functions :



4- Gimbal Configuration :



At this final step, camera or any object can be used to optimize the configuration. It can be failed due to grossly PID settings or too much vibration during this step.