

The tangent plane

Let S be a surface and $p \in S$.

Def A vector $v \in \mathbb{R}^3$ is said to be tangent to S at p , if \exists a smooth curve $\gamma : (-\varepsilon, \varepsilon) \rightarrow S$ s.t.

$$\gamma(0) = p \quad \text{and} \quad \dot{\gamma}(0) = v.$$

When computing the tangent vector of γ we think of γ as a curve in \mathbb{R}^3 .

Ex $S = S^2 \Rightarrow p$ arbitrary. Recall the curve

$$\gamma_v(t) = \cos t \cdot p + \sin t \cdot v,$$

where $\|v\| = 1$ and $v \perp p$. Then

$$\dot{\gamma}_v(0) = v. \text{ Hence, } v \text{ is tangent to } S^2 \text{ at } p.$$

$T_p S =$ the set of all tangent vectors to S at p .

Prop Let $\psi : V \rightarrow U$ be a parametrization such that $\psi(u_0, v_0) = p$. Then

$$T_p S = \text{Im } D_{(u_0, v_0)} \psi.$$

In particular, $T_p S$ is a vector space of dim. 2.

Proof

$$\underline{\text{Step 1}} \quad \text{Im } D_{(u_0, v_0)} \Psi \subset T_p S$$

$$\text{Assume } v \in \text{Im } D_{(u_0, v_0)} \Psi \Rightarrow$$

$$\exists w \in \mathbb{R}^2 \text{ s.t. } D_{(u_0, v_0)} \Psi(w) = v$$

Consider the ^{smooth} curve $\beta: (-\varepsilon, \varepsilon) \rightarrow V$

$$\beta(t) = (u_0, v_0) + t \cdot w.$$

Then $\gamma(t) := \Psi \circ \beta(t)$ is a smooth curve in S s.t.

$$\gamma(0) = \Psi(\beta(0)) = \Psi(u_0, v_0) = p,$$

$$\dot{\gamma}(0) = D_{(u_0, v_0)} \Psi(w) = v.$$

$$\Rightarrow v \in T_p S.$$

$$\underline{\text{Step 2}} \quad T_p S \subset \text{Im } D_{(u_0, v_0)} \Psi$$

If $v \in T_p S$, then $\exists \gamma: (-\varepsilon, \varepsilon) \rightarrow S$ s.t.

$$\gamma(0) = p \text{ & } \dot{\gamma}(0) = v. \text{ Can assume}$$

$\text{Im } \gamma \subset V$ by choosing ε smaller if necessary.

If $\varphi = \Psi^{-1}$, then

$$\beta(t) := \varphi \circ \gamma(t) \text{ is a smooth curve}$$

in $V \subset \mathbb{R}^2$ s.t. $\beta(0) = (u_0, v_0)$. (3)

Denote $w := \dot{\beta}(0) \in \mathbb{R}^2$. Then we have

$$\begin{aligned} v &= \dot{\gamma}(0) = (\underbrace{\psi \circ \beta}_u)(0) = (D_{(u_0, v_0)} \psi)(\dot{\beta}(0)) \\ &\quad \psi \circ \psi^{-1} \circ \gamma \\ &= D_{(u_0, v_0)} \psi(w) \in \text{Im } D_{(u_0, v_0)} \psi. \end{aligned}$$

Step 3 $\dim T_p S = 2$.

This follows immediately from the injectivity of $D_{(u_0, v_0)} \psi$. □

Exercise Assume $v \perp p \in S^2$ and $\|v\| = 2$. Find a curve in S^2 through p with the tangent vector v .

Prop Pick $p \in S$ and recall that there exists a nbhd $W \subset \mathbb{R}^3$ of p and a smooth function $\varphi: W \rightarrow \mathbb{R}$ s.t.

$$S \cap W = \{q \in W \mid \varphi(q) = 0\} \text{ and } \nabla \varphi(q) \neq 0 \quad \forall q \in W.$$

Then

$$T_p S = \nabla \varphi(p)^\perp.$$

Proof If γ is any curve in S through P , then

$$\varphi \circ \gamma(t) = 0 \quad \forall t \Rightarrow \left. \frac{d}{dt} \right|_{t=0} \varphi(\gamma(t)) = 0$$

$$\langle \nabla \varphi(P), \dot{\gamma}(0) \rangle$$

$$\Rightarrow T_p S \subset \nabla \varphi(P)^\perp$$

$$\begin{array}{c} \swarrow \quad \searrow \\ \text{both have dimension 2} \end{array} \Rightarrow T_p S = \nabla \varphi(P)^\perp$$

□

Ex 1) $\forall P \in S^2 \quad T_p S^2 = P^\perp$

Indeed, for $\varphi(x, y, z) = x^2 + y^2 + z^2 - 1$
we have $\nabla \varphi(x, y, z) = 2(x, y, z)$.

$$2) P = (x, y, z) \in H = \left\{ \underbrace{x^2 + y^2 - z^2 - 1}_{\varphi(x, y, z)} = 0 \right\}$$

$$\nabla \varphi(P) = 2(x, y, -z) \neq 0$$

$$\Rightarrow T_p H = (x, y, -z)^\perp$$

$$= \left\{ \mathbf{v} = (v_1, v_2, v_3) \in \mathbb{R}^3 \mid x v_1 + y v_2 - z v_3 = 0 \right\}$$

$$3) P = (x, y, z) \in C = \left\{ x^2 + y^2 = 1 \right\}$$

$$T_p C = \left\{ \mathbf{v} = (v_1, v_2, v_3) \mid x v_1 + y v_2 = 0, v_3 \text{ arbitrary} \right\}$$

Differential of a smooth map

Let S be a surface and $f \in C^\infty(S)$.

Define a map $d_p f: T_p S \rightarrow \mathbb{R}$ as follows:

for $v \in T_p S$ choose a smooth curve

γ through p with $\dot{\gamma}(0) = v$ and set

$$d_p f(v) = \left. \frac{d}{dt} \right|_{t=0} f \circ \gamma(t).$$

Prop $d_p f$ is a well-defined linear map.

Proof $d_p f$ is well-defined.

If γ_1 and γ_2 are two curves through p
s.t. $\dot{\gamma}_1(0) = v = \dot{\gamma}_2(0)$, then for $\beta_j := \psi^{-1} \circ \gamma_j$
we have

$$\gamma_j(t) = \psi \circ \beta_j(t) \Rightarrow v = D_\psi(\dot{\beta}_j(0)) = D_\psi(\dot{\beta}_2(0))$$

$$\Rightarrow \dot{\beta}_1(0) = \dot{\beta}_2(0) =: w$$

$$\left. \frac{d}{dt} \right|_{t=0} f \circ \gamma_1(t) = \left. \frac{d}{dt} \right|_{t=0} \left(f \circ \psi \circ \psi^{-1} \circ \gamma_1(t) \right)$$

$$= \left. \frac{d}{dt} \right|_{t=0} (f \circ \beta_1(t))$$

$$= D_f(w)$$

injective

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$$\text{Similarly, } \left. \frac{d}{dt} \right|_{t=0} f \circ \gamma_2(t) = D_\gamma F(w)$$

$$\Rightarrow \left. \frac{d}{dt} \right|_{t=0} (f \circ \gamma_1(t)) = \left. \frac{d}{dt} \right|_{t=0} (f \circ \gamma_2(t)).$$

Step 2 $d_p f \circ D_\gamma \psi = D_\gamma F$, where $F := f \circ \psi$.
 This follows from the pf of Step 1.

Step 3 $d_p f$ is linear

$$d_p f \circ D_\gamma \psi = D_\gamma F$$

$$\begin{matrix} \swarrow & \searrow \\ \text{linear} & \end{matrix} \Rightarrow d_p f \text{ is linear}$$

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Exercise If $h \in C^\infty(\mathbb{R}^3)$ and $f = h|_S$,
 then $\forall p \in S$ we have

$$d_p f = D_p h|_{T_p S}.$$

Def A point $p \in S$ is called critical for
 $f \in C^\infty(S)$, if $d_p f = 0$, that is $d_p f(v) = 0$
 $\forall v \in T_p S$.

Prop If p is a pt of loc. max. (min) for f ,
 then p is critical for f .

Proof p is a pt of loc. max for $f \Rightarrow$
 \exists curve γ through p , o is a pt of loc. max for $f \circ \gamma$

$$\Rightarrow \left. \frac{d}{dt} \right|_{t=0} f \circ \gamma = 0$$

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Prop Let $h, \varphi \in C^\infty(\mathbb{R}^3)$. Assume $\nabla \varphi(p) \neq 0$ for any $p \in S = \varphi^{-1}(0)$. If $p \in S$ is a pt of loc. max. for $f = h|_S$, then

$$\nabla h(p) = \lambda \nabla \varphi(p)$$

for some $\lambda \in \mathbb{R}$.

Proof Notice: S is a surface and

$$T_p S = \{ v \in \mathbb{R}^3 \mid \langle v, \nabla \varphi(p) \rangle = 0 \}$$

$$d_p f = 0 \Leftrightarrow D_p h|_{T_p S} = 0$$

$$\Leftrightarrow \langle v, \nabla h(p) \rangle = 0 \quad \forall v \in T_p S$$

$$\Leftrightarrow \nabla h(p) = \lambda \nabla \varphi(p) \text{ for some } \lambda \in \mathbb{R} \quad \square$$

Reem This proof is in a sense more conceptual than the pf of Thm 1 on P. 4 of Part 1.

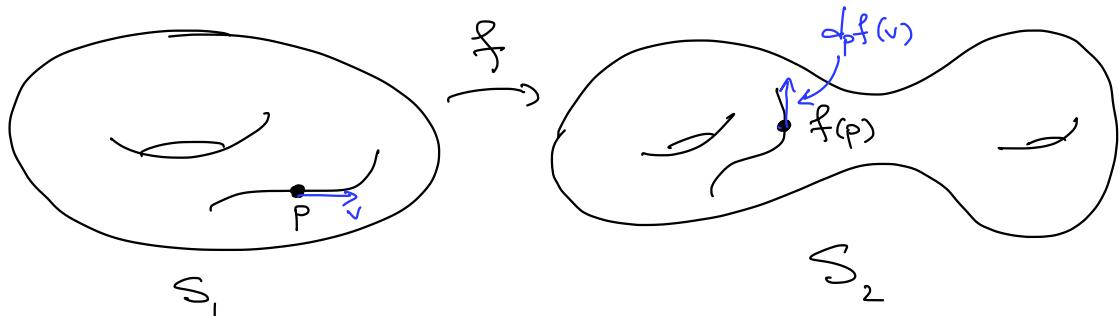
More generally, for any $f \in C^\infty(S; \mathbb{R}^n)$ the differential $d_p f: T_p S \rightarrow \mathbb{R}^n$ is defined by the same formula.

Also, the differential is well-defined for maps $f: \mathbb{R}^n \rightarrow S$, $d_p f: \mathbb{R}^n \rightarrow T_{f(p)} S$

$$f: S_1 \rightarrow S_2, \quad d_p f: T_p S_1 \rightarrow T_{f(p)} S_2$$

In the latter case, if $\dot{f}(0) = v \in T_p S_1$, then

$$D_p f(v) = \left. \frac{d}{dt} \right|_{t=0} (f \circ \gamma(t))$$



Prop Let S_1, S_2, S_3 be smooth surfaces. For any smooth maps $f: S_1 \rightarrow S_2$ and $g: S_2 \rightarrow S_3$ and any pt $p \in S_1$, we have

$$\boxed{D_p(g \circ f) = D_{f(p)} g \circ D_p f.}$$

This also holds if any of S_i is replaced by an open subset of \mathbb{R}^n .

Proof Let γ_1 be any smooth curve in S_1 through p . Denote $\gamma_2 = f \circ \gamma_1$, which is a smooth curve in S_2 through $f(p)$. If $\dot{\gamma}_1(0) = v_1$, then $v_2 := \dot{\gamma}_2(0) = D_p f(v_1)$ by the definition of $D_p f$. Hence,

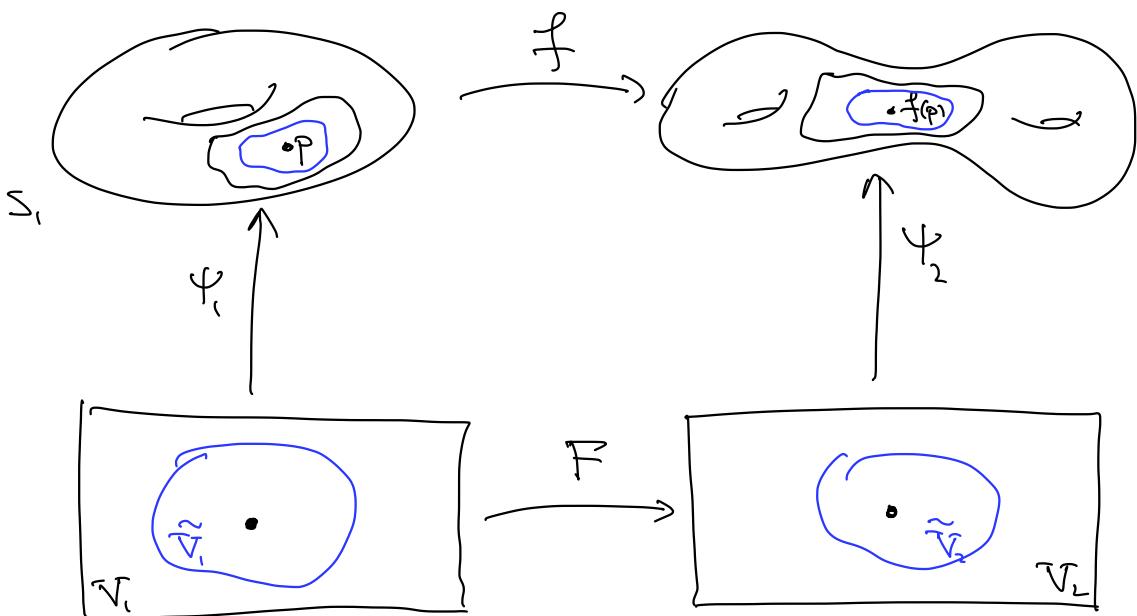
$$\begin{aligned} D_p(g \circ f)(v_1) &= \left. \frac{d}{dt} \right|_{t=0} (g \circ f \circ \underbrace{\gamma_1}_{\gamma_2}(t)) \\ &= \left. \frac{d}{dt} \right|_{t=0} (g \circ \gamma_2(t)) = D_{f(p)} g(v_2) \\ &= D_{f(p)} g(D_p f(v_1)) \end{aligned}$$

Cor If $f: S_1 \rightarrow S_2$ is a diffeomorphism, ⑨
 then $\forall p \in S_1, d_p f: T_p S_1 \rightarrow T_{f(p)} S_2$
 is an isomorphism. \square

Def A map $f: S_1 \rightarrow S_2$ is called a local diffeomorphism if $\forall p \in S_1, \exists$ a nbhd $U_1 \subset S_1$ and a nbhd $U_2 \subset S_2$ of $f(p)$ s.t. $f: U_1 \rightarrow U_2$ is a diffeomorphism.

Thm Let $f: S_1 \rightarrow S_2$ be a smooth map s.t. $\forall p \in S_1, d_p f: T_p S_1 \rightarrow T_{f(p)} S_2$ is an isomorphism. Then f is a local diffeomorphism.

Proof Pick any $p \in S_1$ and parametrizations $\psi_1: V_1 \rightarrow W_1 \subset S_1$ and $\psi_2: V_2 \subset W_2 \subset S_2$



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Without loss of generality $\psi_1(0) = p$ and
 $\psi_2(0) = f(p)$.

$$F = \psi_2^{-1} \circ f \circ \psi_1 \Rightarrow d_o F = d_{\psi_1(p)} \psi_2^{-1} \circ d_p f \circ d_o \psi_1$$

$d_o \psi_1: \mathbb{R}^2 \rightarrow T_p S_1$ is an iso.

$d_{f(p)} \psi_2: T_{f(p)} S_2 \rightarrow \mathbb{R}^2$ is an iso.

$d_p f$ is an iso $\Rightarrow d_o F$ is an iso.

From analysis, it is known that \exists a nbhd $0 \in \tilde{V}_1 \subset V_1$ and a nbhd $\tilde{V}_2 \subset V_2$ of 0 such that $F: \tilde{V}_1 \rightarrow \tilde{V}_2$ is a diffeomorphism.

Denote $U_1 = \psi_1(\tilde{V}_1)$, $U_2 = \psi_2(\tilde{V}_2)$.

Then

$$f|_{U_1} = \psi_2 \circ F \circ \psi_1^{-1}|_{U_1}: U_1 \rightarrow U_2$$

is a diffeomorphism, since it is a composition of diffeomorphisms. □

Rem It follows from the proof, that

$$d_p f = \underbrace{d_o \psi_2}_{\text{iso}} \circ \underbrace{d_o F}_{\text{iso}} \circ \underbrace{d_p \psi_1^{-1}}_{\text{iso}}.$$

In particular,

$$\begin{array}{ccc} d_p f \text{ is injective} & \Leftrightarrow & D_{\psi(p)} \text{ is injective} \\ \text{surj.} & \Leftrightarrow & \text{surj.} \\ \text{iso} & \Leftrightarrow & \text{iso} \end{array}$$

Let $f \in C^\infty(S_1; S_2)$.

Def 1) A pt $p \in S_1$ is called a critical pt of f if $d_p f$ is not surjective $\Leftrightarrow d_p f$ is not injective $\Leftrightarrow d_p f$ is not an iso.

a) $q \in S_2$ is called a regular value of f , if $\forall p \in f^{-1}(q)$ is regular (non-critical), i.e., if $\forall p \in f^{-1}(q)$ $d_p f$ is surjective $\Leftrightarrow d_p f$ is injective $\Leftrightarrow d_p f$ is an iso.

Ex $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \cong \mathbb{C}$, $f(z) = z^n$, $n \in \mathbb{Z}$, $n \geq 2$. It is known from analysis that $D_z f: \mathbb{C} \rightarrow \mathbb{C}$ can be identified with the map $h \mapsto f'(z) \cdot h$. Hence, z is critical iff $f'(z) = 0 \Leftrightarrow n z^{n-1} = 0 \Leftrightarrow z = 0$. Hence, f has a single critical pt $z=0$ and a single critical value, the zero. All other pts are regular and any non-zero value is also regular.

Thm (The fundamental theorem of algebra)

Let $g(z) = z^n + a_{n-1}z^{n-1} + \dots + a_1z + a_0$

be a polynomial of degree $n \geq 1$ with cx. coefficients. Then p has at least one cx. root.

Proof Recall that the map $f: S^2 \rightarrow S^2$,

$$f(p) = \begin{cases} N & p = N, \\ \psi_N \circ g \circ \psi_N^{-1} & p \neq N, \end{cases}$$

is smooth.

Step 1 f has at most $n-1$ crit pts (values).

$p \in S^2 \setminus \{N\}$ is critical $\iff z := \psi_N(p)$ is critical for $g \iff g'(z) = 0$, that is

$$nz^{n-1} + (n-1)a_{n-1}z^{n-2} + \dots + a_1 = 0$$

This can have at most $(n-1)$ roots.

Step 2 Denote by $R(f)$ the set of regular values of f . Then for any $r \in R(f)$ the set $f^{-1}(r)$ is finite and the map

$$r \mapsto \# f^{-1}(r)$$

is constant.

Let $p \in f^{-1}(r)$, $r \in R(f) \implies$

$$f(p) = r \text{ & } df_p \text{ is an iso}$$

$\Rightarrow \exists$ a nbhd U_p of p and a nbhd W_r s.t.

$f: U_p \rightarrow W_r$ is a diffeo. In particular, $f^{-1}(r) \cap U_p = \{p\} \Rightarrow f^{-1}(r)$ is discrete.

However, $f^{-1}(r)$ is a closed subset of S^2 , hence compact. But a compact discrete set must be finite.

Denote $f^{-1}(r) = \{p_1, \dots, p_m\}$ and the corresponding nbhds $U_1, \dots, U_m, W_1, \dots, W_m$.

Set $W := W_1 \cap \dots \cap W_m$ and

$\tilde{U}_j := f^{-1}(W) \cap U_j$. Then for each $j \leq m$

the map $f: \tilde{U}_j \rightarrow W$ is a diffeomorphism.

In particular, $\forall r' \in W \exists! p'_j \in \tilde{U}_j$ s.t.

$f(p'_j) = r'$. Hence, $\# f^{-1}(r') = \# f^{-1}(r)$ $\forall r' \in W$, so that the function

$$R(f) \rightarrow \mathbb{Z}, \quad r \mapsto \# f^{-1}(r) \quad (*)$$

is locally constant.

However, $R(f)$ is the complement of a finite number of pts in S^2 , hence connected. Therefore, $(*)$ is (globally) constant.

Step 3 We prove this thus.

Pick any pairwise distinct pts $p_1, \dots, p_n \in S^2 \setminus \{N\}$ s.t. $f(p_1), \dots, f(p_n)$ are also pairwise distinct. Since f has at most $n-1$ critical values, at least one pt from $\{f(p_1), \dots, f(p_n)\}$ is a regular value and (*) does not vanish at this pt. Hence, (*) vanishes nowhere on $R(f)$.

If S is a critical value of S , then $f^{-1}(S) \neq \emptyset$, since $f^{-1}(S)$ contains a critical pt. However,

$$f^{-1}(S) \neq \emptyset \iff g^{-1}(0) \neq 0.$$

If S is a regular value, then by Step 2 $\#\ f^{-1}(S) \geq 1 \Rightarrow f^{-1}(S) \neq \emptyset$.

This finishes the proof. □