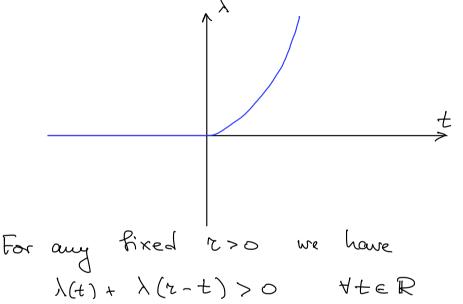
Partitions of unity

Recall that the function $\lambda: \mathbb{R} \to \mathbb{R}$ $\lambda(t) = \begin{cases} 0 & \text{if } t \leq 0, \\ e^{-1/\epsilon} & \text{if } t > 0 \end{cases}$

is smooth.



positive for too positive for 2-t>0 (=> t<2

Define $\gamma_{r}(t) := \frac{\lambda(r-t)}{\lambda(t) + \lambda(r-t)}$,

Which is smooth everywehere on R.

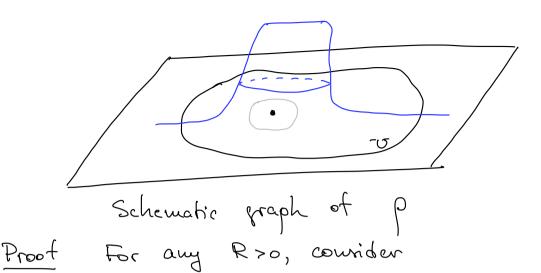
Denote also

$$f_{r}(t) := f_{r}(t-1)$$

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1+2 Lemma For any pt pe R" and any ubhd V > p there exists a ubhd VcV and pe Co(Rn) s.t. the following holds:

- Ply = 1 and PlRmy =0.



If B_{2R}(P) < U, then p vanishes

 $b(x) := \lambda^{1} \left(\frac{b}{|x-b|} \right),$

the ball of radius 2R centered at p

Duside et $B_{2R}(p)$, so vanishes outside et V. Also, $p(x) \equiv 1$ on $B_{R}(p)$ and $p \in C$?

Det For a continuous function on a topological space X the support of f is supp $f = \begin{cases} x \in X \mid f(x) \neq 0 \end{cases}$

In particular, $x \notin \text{supp } f \Longrightarrow f(x) = 0$

Example 1) supp $\lambda = [0, +\infty)$. Notice that $0 \in \text{supp} \lambda$ although $\lambda(0) = 0$ d) If p is as in the above lemma, then supp $p \in U$. 3) For $f(x) = |x|^2 - 1$, $f: \mathbb{R}^n \to \mathbb{R}$, supp $f = \mathbb{R}^n$. Det A (smooth) partion of unity on R is a family of smooth functions { pa I de A? s.t. (i) O E P(x) E I A KE B, AGE A (ii) For any x∈ R Px(x) ≠0 for finitely many d∈ A only. (iii) $\sum_{d \in A} P_d(x) = 1 \qquad \forall x \in \mathbb{R}^n.$ Rem More precisely, (ii) in the above definition should be replaced by the following condition: ∀x∈ R" I a ubhd V > x s.t. the set

{ d∈A | supp pa ∩ V = Ø } is finite. However, we consider mostly finite partitions of unity so that this condition (and

therefore, also (ii)) will be satisfied automatically. Example (A partition of unity on R1) Counter $\{\hat{p}_j(x) \mid j \in \mathbb{Z}^2\}$, where

β; (x) = y, (|x-j|). Notice that fig c [j-2, j+2] j j+2

Notice that
$$\sup_{x \in \mathbb{R}} \hat{p}_{j} \subset [j-2, j+2]$$
 $= \sum_{j \in \mathbb{R}} \hat{p}_{j}(x)$ well-defined, $\sup_{x \in \mathbb{R}} \hat{p}_{j}(x) = \lim_{x \to \infty} \hat{p}_{j}(x)$

is a partition of unity on R?.

Tust like for R, the partition of unity is defined for surfaces.

Theorem (Existence of a partition of unity)

Let $U = \{ \neg v_x \mid d \in A \}$ be any open

covering of a surface S. Then \exists a partition

of unity $\{ d \mid p_B \mid g \in B \}$ s.t. $\{ d \mid g \mid g \in B \}$ supp $\{ p_B \mid g \in B \}$

Froof The proof is given for compact surfaces only.

Step 1 Let S be any surface. For any pe S and any open WcS_peW , there exist $p \in C^{\infty}(S)$ s.t.

(i) $0 \le p(q) \le 1$ $\forall q \in S$

(ii) supp p c W.

(iii) FX c W open s.t. P/x = 1.

Let (U, φ) be a chart on S s.t. 6 $\varphi(p) = 0 \in V \subset \mathbb{R}^2$ and $U \subset W$. Pick a function $\hat{p} \in C^{\infty}(\mathbb{R}^2)$ s.t. $O \subseteq \hat{P} \subseteq I$, $\hat{P} \mid_{\mathcal{B}_{2r}(o)} = 0$ for some 220 s.t. $B_{22}(0) \subset V$. $p(p) := \begin{cases} \hat{p} \cdot Y(p), & p \in \mathcal{U}. \\ 0, & p \notin \mathcal{U}. \end{cases}$ Then p is smooth everywhere and with $X:= \varphi^{-1}(B_{2}(0))$ satisties (i) -(iii). Alternatively: One can first define a suitable function \tilde{p} on a ubbd of p in \mathbb{R}^3 and define p as the restriction of \tilde{p} to S. Rem The function constructed in Step 1 is called a bump function. Step 2 We prove this thun assuming S is cupt Pick any U_{χ} and any $p \in V_{\chi}$. Then \exists a chart $(U_{p,\chi}, \varphi_{p,\chi})$ s.t. $V_{p,\chi} \subset V_{\chi}$. By Step 1, 3 Xprd C Uprd and a

function pp,d satisfying (i) - (iii). Courider the family of Xp, of IpeS, do A?, which is an open covering of S.

By the compactness of S, I a finite subcovering Xp1,d, 3 ---) Xpn,dn X, X_u Denote $\hat{\beta}_i := \hat{\beta}_{p_i, d_j}$ so that $\hat{\beta}_i|_{x_j} = 1$ and consider $\hat{p}(p):=\sum_{j=1}^{n}\hat{p}_{j}(p)>0 \quad \forall p\in S.$ Then $p_i := \hat{p}_i/\hat{p}_i$ is a partition of unity on S. Moreover, supp fi = supp fi c Vi c Vdj Rem A partition of unity as in the above theorem is called subordinate to U.

Example S = S2, U = { S2 UN?, S2 US] 8 Let p be a bump function on R2 s.t. $P|_{B_1(0)} \equiv 1$ and supp $P \subset B_2(0)$. Define pr:= p . 4n Ps: = 1 - PN L PN, Ps? is a partition of unity Then On S². Integration on surfaces Aim: Define a map S: Co(s) -> R with "the usual" properties of the integral, e.g. We assume in addition that S is compact. Chose an atlas $A = \{(\nabla_x, \varphi_x) \mid d \in A \}$ on S. Let $\{p_j \mid j=1,..., J\}$ be a partition of unity on S s.t. supp p; c Tx; =: Ty;

For any fe C°(S) we have $f = f \cdot 1 = \sum_{j=1}^{T} f_{j} f_{j} = \sum_{j=1}^{T} f_{j}$ and supp f; c supp p; c T;.

Hence, by (8.*) it suffices to define I f; that is we want to define If provided supp f C V, Where (T, 4) is a chart. Viewing 9 as an identification between U and $V \subset \mathbb{R}^2$, we can identify of with its coordinate representation F:= foy"= foy: V -> R. Then F vanishes outside of 4" (supp F), which is cupt. 4 (supp f)

supp F

It is tempting to define $\begin{cases}
f := \int F(u,v) du dv.
\end{cases}$ It may happen, however, that there is another chart $(\hat{U}, \hat{\varphi})$ on S s.4. supp f c Î To show that Sf is well-defined, we must show the equality $\int_{\mathbb{R}^2} F(u,v) \, du \, dv \stackrel{?}{=} \int_{\mathbb{R}^2} \hat{F}(x,y) \, dx \, dy , \quad (**)$ where $\hat{F} = f \cdot \hat{\varphi}^{-1}$ is the coord. rep. of f with respect to $\hat{\varphi}$. Let $\theta = \varphi \cdot \hat{\varphi}^{-1} \iff (u, \sigma) = \Theta(x, y)$ denote the change of coordinates map. Then $\hat{F} = f \cdot \hat{\varphi}^{-1} = f \cdot \varphi^{-1} \cdot \varphi \cdot \hat{\varphi}^{-1} = F \cdot \Theta$, so that (**) is equivalent to JF(u,v) dudo ≧ JF. D(x,y) dxdy

 $\int F(u,v) du dv = \int F_0 \Theta(x,y) | det D\Theta| dx dy$ \mathbb{R}^2 Thus, our naive approach to define § f by (10.*) is false in general. To solve this problem, recall the following fact. Suppose $V \subset \mathbb{R}^3$ be a bounded open set such that $S := \partial V$ is a smooth surface. Then $\int \operatorname{div} \sigma = \int \langle \sigma, n \rangle dS$ where n is the unit normal field pointing outwards. If Y = Y(u,v) is a parametrization of S, the right hand side is defined by Following this hint, for fe (°(s) with

The last equality is false in general, (1) since by a thun from analysis

supp
$$f \in \mathcal{T}$$
, where \mathcal{T} is a coord. (12) chart, we define

$$\int_{\mathcal{T}} f := \int_{\mathcal{T}} F(u,\sigma) | \Im_{u} \psi \times \Im_{\sigma} \psi | du d\sigma \quad (*)$$
Then, if $(\hat{\mathcal{T}}, \hat{\psi})$ is another chart just like above, we have

$$\hat{F} = F \circ \theta, \qquad \theta = \psi \circ \hat{\psi}^{-1} = \psi^{-1} \cdot \hat{\psi}$$

$$\hat{\Psi} = \psi \cdot \theta \Rightarrow \qquad (\Im_{x} \hat{\psi}, \Im_{y} \hat{\psi}) = (\Im_{u} \psi, \Im_{\sigma} \psi) \cdot D\theta$$

$$\Rightarrow |\Im_{x} \hat{\psi} \times \Im_{y} \hat{\psi}| = |\Im_{u} \psi \times \Im_{\sigma} \psi| \cdot |\operatorname{det} D\theta|$$
Hence, we have
$$\int_{\mathcal{F}} \hat{F}(x,y) |\Im_{x} \hat{\psi} \times \Im_{y} \hat{\psi}| dxdy = \Re^{2}$$

That is (12.*) does not depend on the choice of the parametrization of S. Thus, for any fe Co(S) we may set $\begin{cases}
f := \sum_{i=1}^{n} \int_{S} f_{i} = f_{i}
\end{cases}$ = \(\int \) \(\int \ Prop St is well-defined, that is It does not depend on the choice of an atlas. Proof Let $\hat{U} = \{(\hat{U}_{\beta}, \hat{Y}_{\beta}) \mid \beta \in B\}$ be another atlas on S. Choose a partition of unity $\{\{y_{k} \mid k=1,...,K\}\}$ subordinate to \hat{U} . We need to show

That

\[\sum_{j \in \text{S}} \left(\right) \frac{2}{\text{E}} \sum_{k \in \text{S}} \left(\mu_k \frac{\psi}{\psi}) \]

Notice that \[\left(\frac{\psi_{k \in \text{S}}}{\psi_{k \in \text{S}}} \left(\frac{\psi_{k \in \text{S}}}{\psi_{k \in \text{S}}} \right) \]

is also a partition of unity and

supp λ_{jk} $\subset U_{j} \cap \widehat{U}_{k}$.

With this understood, consider $\frac{J}{j^{2}} \sum_{k=1}^{K} \int_{S_{ij}} \lambda_{jk} f = \int_{j^{2}} \int_{S_{ij}} \left(P_{ij} \sum_{k=1}^{K} \mu_{k} f \right)$

 $= \sum_{j=1}^{n} \sum_{s=1}^{n} S_{j} + \sum_{s=1}^{n} S_{j}$

 $\sum_{k=1}^{K} \sum_{j=1}^{T} S(\lambda_{jk} \xi) = \sum_{k} \left(\sum_{j=1}^{T} P_{j} \xi \right)$ $= \sum_{k} \sum_{j=1}^{T} P_{j} \xi$

It follows immediately from the definition that S has the usual properties known

from the analysis course, for example:

() (\lambda + \mu g) = \lambda \lambda + \mu \lambda g;

 $\begin{array}{ccc}
 & S(\lambda f + \mu g) = \lambda S f + \mu S g; \\
 & S & S & S & S & S
\end{array}$

• $\begin{cases} f = 0 \text{ and } f \geqslant 0 \Rightarrow f \equiv 0 \end{cases}$