## 1 Computing the Lasso Solution

## 1.1 Proximal Algorithm : General Solution

A convenient algorithm is given by the FISTA (see Beck and Teboulle (2014) for a clear exposition). Assume you want to minimize the following objective function in  $x \in \mathbb{R}^p$ :

$$f(x) = g(x) + h(x) \tag{1}$$

For which g is convex and differentiable, and h is closed with inexpensive proximal operator. Then do the following:

Set starting values  $x^{(0)} = x^{(-1)}$  and for  $k \ge 1$  repeat:

(1) 
$$y = x^{(k-1)} + \frac{k-2}{k+1}(x^{(k-1)} - x^{(k-2)}).$$

(2) 
$$x^{(k)} = \operatorname{prox}_{t_k h} (y - t_k \nabla g(y)).$$

(3) Increase k by one unit.

Use  $t_k = \frac{1}{L}$  where L is the Lipschitz constant for the gradient  $\nabla g(.)$  or determine  $t_k$  by line search. The proximal operator is given by:

$$\operatorname{prox}_{h}(x) = \arg\min_{u} \left( h(u) + \frac{1}{2} \|u - x\|_{2}^{2} \right)$$
 (2)

## 1.2 Application to Solve the Lasso

For example, this method can be used to resolve the Lasso problem:

$$\min_{\beta} \frac{1}{n} \sum_{i=1}^{n} (y_i - x_i^T \beta)^2 + \lambda \|\beta\|_1$$
 (3)

In this case,  $L = \frac{2}{n}\lambda_{\max}\left(X^TX\right)$  and  $\operatorname{prox}_h(x) = (x-\lambda)_+\operatorname{sign}(x)$ .  $\lambda_{\max}(A)$  denotes the maximal eigenvalue of a matrix A. Note that the proximal operator can also be defined in this case as:  $\operatorname{prox}_h(x) = (x-\lambda)_+ - (-x-\lambda)_+$ . If L is unknown, one can use the backtracking line search procedure.

We finally give the FISTA algorithm for the Lasso in a readily usable form. Set for initialization  $\beta_{(1)} = \alpha_{(1)} = 0_p$ ,  $\theta_{(1)} = 1$  and  $\eta = \left(\frac{2}{n}\lambda_{\max}\left(X^TX\right)\right)^{-1}$ . Repeat until convergence of the sequence  $\beta^{(1)}, \beta^{(2)}, \dots$ 

(1) 
$$\theta_{(k+1)} = \left(1 + \sqrt{1 + 4\theta_{(k)}^2}\right)/2$$
 and set  $\delta_{(k)} = (1 - \theta_{(k)})/\theta_{(k+1)}$ .

(2) 
$$\beta^{(k+1)} = \operatorname{prox}_{\eta \lambda} \left( \alpha_{(k)} - \eta \nabla g(\alpha_{(k)}) \right)$$

(3) 
$$\alpha_{(k+1)} = (1 - \delta_{(k)})\beta^{(k+1)} + \delta_{(k)}\beta^{(k)}$$
.

(4) Increase k by one unit.

Here: 
$$\nabla g(\beta) = -\frac{2}{n} \sum_{i=1}^{n} (y_i - x_i^T \beta) x_i$$
.

## 2 Bibliography

BECK, A. and TEBOULLE, M. (2014): "A fast dual proximal gradient algorithm for convex minimization and applications". Operations Research Letters, 42(1):1-6.