# Chris Hayner

Ph.D. student working on Optimization for Robotics at the University of Washington  $\Box +1 \ 360 \ 961 \ 7228$ in Chris Hayner Google Scholar ■ chayner@pnwsoft.com

#### EDUCATION

June 2026 (expected) Ph.D. Department of Aeronautcial and Astronautical Engineering

University of Washington

Co-Advised by Prof. Behçet Açıkmeşe and Prof. Karen Leung

June 2021

**BS** in Applied Physics

University of Washington

Minor in Aeronautical Astronautical Engineering

## Publications

#### Journals

[J1] Kazuya Echigo, Christopher R. Hayner, Avi Mittal, Selahattin Burak Sarsılmaz, Behçet Açıkmeşe, Matthew Harris, "Linear Program Approach to Close Proximity Operation with Element-wise Quantized Control," IEEE L-CSS.

#### Conferences

- [C1] Christopher R. Hayner\*, Natalia Pavlasek\*, Purnanand Elango, Aman Tiwary, Benjamin Chung, Karen Leung, Behçet Açıkmeşe, "Active View Planning with Guaranteed Keypoint Coverage," 2024 IEEE ICRA. (In Review)
- [C2] Christopher R. Hayner\*, Samuel C. Buckner\*, Daniel Broyles, Evelyn Madewell, Karen Leung, Behçet Açıkmeşe, "HALO: Hazard-Aware Landing Optimization for Autonomous Systems," 2023 IEEE ICRA.
- [C3] Kazuya Echigo, Christopher R. Hayner, Avi Mittal, Selahattin Burak Sarsılmaz, Behçet Açıkmeşe, Matthew Harris, "Convex Trajectory Planning for Proximity Operations using Electric Propulsion with Quantized Thrust," AIAA 2023-0493. AIAA Scitech 2023 Forum.
- [C4] Daniel Broyles\*, Christopher R. Hayner\*, Karen Leung, "WiSARD: A Labeled Visual and Thermal Image Dataset for Wilderness Search and Rescue," 2022 IEEE IROS.
- [C5] Christopher R. Hayner, Timothy Zhou, Neil Gupta, Echo Liu, Parker Mayhew, and Juris Vagners. "Real-time Human Detection with integration of Visual and Thermal Data from High Altitude sUAS," AIAA 2021-0397. AIAA Scitech 2021 Forum.

#### Workshops

[W1] Natalia Pavlasek, Christopher R. Hayner, Sarah Li, Behçet Açıkmeşe, Meeko Oishi, and Claus Danielson. "Generating Blamelessly Optimal Control for Prioritized Constraint Sets," 2023 RSS Workshop: Towards Safe Autonomy: New Challenges and Trends in Robot Perception.

## Symposium Presentations

[P1] Christopher R. Hayner, Echo Liu, Howard Peng. Parker Mayhew, Neil Gupta, Helen Kuni, Juris Vagners, "An Autonomous Machine Learning Approach to Search and Locate Operations," AIAA PNW Symposium 2020.

## Reviewer

IEEE/RSJ IROS · IEEE ICRA

## AWARDS AND FELLOWSHIPS

NASA Space Technology Graduate Research Opportunities (NSTGRO) Fellow, Article: Chris Hayner awarded NASA NSTGRO Fellowship

Washington NASA Space Grant Fellowship

AA Student Excellence Award for Doctoral Research, Article: A&A Student Excellence Awards 2023

1st Place Poster - UW Graduate Research Showcase, Article: 2023 A&A Graduate Research Showcase

2023 - 2027

2022 - 2024

2023 2023

<sup>\*</sup> Denotes equal contribution

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## EMPLOYMENT RECORD

#### Dec. 2021 - Present

## University of Washington - Graduate Research Assistant

- Participate in research across the Autonomous Controls Laboratory (ACL) and Control and Trustworthy Robotics Laboratory (CTRL).

#### June - Sept. 2022

#### Air Force Research Laboratory - Graduate Intern

- Worked on vision-based algorithms for alternative forms of navigation for autonomous systems.

#### Sept. - Dec. 2021

#### University of Washington - Teaching Assistant

- AA310 Orbital and Space Flight Mechanics: Worked to develop homework assignments and exam problems for a class of >70 students.
- Held office hours, mentored students to think critically and logically about engineering problems.

#### June - Sept. 2021

## Applewhite Aero - Intern

- Tested and tuned various UAV platforms. Integrated a variety of sensors and embedded computing payloads with computer vision algorithms onto UAV platforms. Assisted in the design of UAVs.

## Dec. 2018 - June 2021 University of Washington - Undergraduate Research Assistant

## Projects

## Perception-Aware Trajectory Planning [C1],[C2]

- Designed a tightly coupled perception and planning system to determine multiple safe landing sites and plan robust contingency-aware trajectories to them. A video demonstration can be found *here*.
- Developed a method for selecting sensor pointing angle with guarantees on containment of keypoints.
- Implemented successive convex programming (SCP) to solve for a control trajectory.

#### Real-time optimization-based trajectory planning for spacecraft, [C3], Article: Tugs in Space

- Formulated and implemented real-time convex optimization methods to compute trajectories for spacecraft rendezvous, proximity operations and docking with electric propulsion subject to quantized thrust constraints.

## Wilderness Search and Rescue, [P1], [C4], [C5], Article: Hide and Seek: Training a drone to save lives

- Created and compiled a large visual and thermal dataset for human identification in a wilderness environment.
- Used a variety of computer vision algorithms to train models.
- Tested models on UAV platforms using onboard- and ground-based computing for inference on live thermal and visual imagery.

## Aerial Mapping of Fire Behavior

- Created orthomosaic maps and point clouds of land utilizing visual and SWIR UAV based photogrammetry for calculating biomass to predict wild fire propagation.

## Drone Based Air Quality Surveys, Article: Can Trees Clean Jet Pollution

- Integrated drone-mounted sensors to detect pollutants near SeaTac airfield and surrounding highways.

## Ground Penetrating Radar, Article: Peering into Snow

- Integrated large GPR payloads as well as RTK GNSS onto UAV with the goal of remotely sensing and mapping snow depth.

## MENTORSHIP

## Masters Students

Aman Tiwary (MS in Mechanical Engineering at the University of Washington) - Publication [C1]

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#### Undergraduate Students

Annika Singh (Now an Intern at Goldman-Sachs)

Avi Mittal (Now a Ph.D. Student at the University of Washington) - Publications [C3], [J1]

#### HIGH SCHOOL STUDENTS

Neil Gupta (Now an Undergraduate at University of Massachusetts Amherst) - Publication [C5] Timothy Zhou (Now an Undergraduate at University of Illinois Urbana-Champagne) - Publication [C5] Saket Gollapudi (Now an Undergraduate at University of Washington Seattle)

#### Public Outreach

2022 - Current

2019

**UW Women of Aerospace** - Worked to expand women's opportunities for leadership and increase their visibility in the aerospace community through mentorship and outreach activities.

**UW Discovery Days Volunteer** - Set up interactive stand for 4th - 8th graders which showed off my lab's current research projects in an effort to increase students' interest in STEM.

## SKILLS

PROGRAMMING LANGUAGES

Competent with MATLAB, Python (PyTorch, NumPy, SciPy), Julia, C. Working knowledge in C++.

Frameworks and Libraries

SciKit Learn, PyTorch, CVX, OpenCV

OPERATING SYSTEMS

Linux (Ubuntu, CentOS), MacOS, Windows

Hardware & Software

Competent in working with EO/IR sensors and embedded systems (NVIDIA Jetson family) as well as Solidworks and Unreal Engine. Participated in and piloted UAV's at a variety of different flight tests.

## References

#### Behçet Açıkmeşe

- Position: Professor, Aeronautics and Astronautics Department, University of Washington
- Relationship: PhD Co-Advisor, Autonomous Controls Lab PI
- Email: behcet@uw.edu

## Karen Leung

- Position: Assistant Professor, Aeronautics and Astronautics Department, University of Washington
- Relationship: PhD Co-Advisor, Control and Trustworthy Robotics Lab PI
- Email: kymleung@uw.edu

## Juris Vagners

- Position: Professor Emeritus, Aeronautics and Astronautics Department, University of Washington
- Relationship: Undergraduate Advisor, Autonomous Flight Systems Lab PI
- Email: vagners@uw.edu

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## DAVID SHEAN

• **Position:** Assistant Professor, Civil and Environmental Engineering Department, University of Washington

- Email: dshean@uw.edu